# Propagation of Structured Light Waves

# Vishal vishwakarma

# July 29, 2024

# Contents

1	Intr	troduction	
2	Inte	terference	
	2.1	Definition	
	2.2		
	2.3	3 Coherence and Interference Patterns	
		2.3.1 Temporal Coherence	
		2.3.2 Spatial Coherence	
	2.4		
		2.4.1 Optical Vortices	
		2.4.2 Interferometric Techniques	
	2.5		
		2.5.1 Coherence	
		2.5.2 Path Difference and Phase	
3	Diff	iffraction	
	3.1		
	3.2	2 Mathematical Framework	
		3.2.1 Fraunhofer Diffraction (Far-Field)	
		3.2.2 Fresnel Diffraction (Near-Field)	
	3.3		
		3.3.1 Rectangular Aperture	
	3.4		
		3.4.1 Resolution Limits	
		3.4.2 Diffraction and Structured Light	
	3.5	9	
		3.5.1 Beam Shaping	
		3.5.2 Optical Trapping	
		3.5.3 Applications in Imaging	
4	Fou	ourier Optics	
	4.1	<del>-</del>	
	4.2		
		4.2.1 Fourier Transform of a Light Field	
	43		

	4.3.1 Fraunhofer Diffraction and Fourier Transform	
	4.3.2 Example: Circular Aperture and Airy Pattern	
5	Lasers	
	5.1 Introduction to Lasers	
	5.2 Basic Theory of Lasers	
	5.3 Mathematical Representation	
	5.4 Types of Lasers	
	5.5 Applications of Lasers	
_		_
h	Conclusion	

# 1 Introduction

Structured light waves are beams of light that are carefully engineered to have specific spatial and temporal properties. These beams can exhibit unique behaviors, such as carrying orbital angular momentum (OAM), maintaining their structure over long distances, and being manipulated in complex ways. This makes them valuable for applications such as optical communications, advanced imaging techniques, material processing, and quantum information processing.

To understand how these structured light waves behave and can be manipulated, we delve into several key physical principles: interference, diffraction, and Fourier optics. These concepts are essential for creating, analyzing, and using structured light beams effectively.

# 2 Interference

## 2.1 Definition

Interference occurs when two or more light waves superpose, leading to patterns of constructive (bright) and destructive (dark) interference. The superposition principle is at the heart of interference, and it demonstrates the wave nature of light.

# 2.2 Mathematical Representation

Consider two coherent light waves described by the electric fields  $E_1$  and  $E_2$ :

$$E_1 = A_1 e^{i(kz - \omega t + \phi_1)} \tag{1}$$

$$E_2 = A_2 e^{i(kz - \omega t + \phi_2)} \tag{2}$$

where:

- $A_1$  and  $A_2$  are the amplitudes of the waves.
- $k = \frac{2\pi}{\lambda}$  is the wave number, where  $\lambda$  is the wavelength.
- $\omega = 2\pi f$  is the angular frequency, where f is the frequency.

•  $\phi_1$  and  $\phi_2$  are the phase angles.

When these waves overlap, the resultant electric field  $E_R$  is given by:

$$E_R = E_1 + E_2 = A_1 e^{i\phi_1} + A_2 e^{i\phi_2} \tag{3}$$

The intensity I of the combined wave, which is proportional to the square of the amplitude, is:

$$I = |E_R|^2 = |A_1 e^{i\phi_1} + A_2 e^{i\phi_2}|^2 \tag{4}$$

This simplifies to:

$$I = A_1^2 + A_2^2 + 2A_1A_2\cos(\Delta\phi) \tag{5}$$

where  $\Delta \phi = \phi_2 - \phi_1$  is the phase difference between the two waves.

#### 2.3 Coherence and Interference Patterns

For interference to occur, the waves must be coherent, meaning they have a constant phase relationship. Coherence can be spatial or temporal:

## 2.3.1 Temporal Coherence

Related to the spectral width of the source. A narrow spectral width (monochromatic light) implies a long coherence time.

#### 2.3.2 Spatial Coherence

Related to the spatial extent of the source. A smaller source size results in higher spatial coherence.

Interference patterns depend on the path difference  $\Delta L$  between the waves:

- Constructive Interference:  $\Delta \phi = 2n\pi$  or  $\Delta L = n\lambda$ , where n is an integer.
- Destructive Interference:  $\Delta \phi = (2n+1)\pi$  or  $\Delta L = (n+\frac{1}{2})\lambda$ .

# 2.4 Applications in Structured Light

#### 2.4.1 Optical Vortices

Optical vortices are phase singularities in light beams, where the intensity is zero, and the phase is undefined. Beams like Laguerre-Gaussian (LG) beams can carry orbital angular momentum and create these vortices due to their helical wavefronts.

#### Mathematical Form of LG Beams

$$E(r,\phi,z) = \frac{C}{w(z)} \left(\frac{r\sqrt{2}}{w(z)}\right)^{|l|} L_p^{|l|} \left(\frac{2r^2}{w(z)^2}\right) e^{-\frac{r^2}{w(z)^2}} e^{-i\frac{kr^2}{2R(z)}} e^{il\phi} e^{-i(2p+|l|+1)\zeta(z)}$$
(6)

where:

- C is a normalization constant.
- w(z) is the beam waist.
- $L_p^{|l|}(x)$  is the associated Laguerre polynomial.
- R(z) is the radius of curvature.
- $\zeta(z)$  is the Gouy phase.
- l is the azimuthal index (OAM), and p is the radial index.

## 2.4.2 Interferometric Techniques

Techniques like digital holography utilize interference patterns to capture and reconstruct the phase and amplitude of structured beams. This is useful in imaging applications, where the wavefront's complete information is necessary.

# 2.5 Key Concepts

## 2.5.1 Coherence

For interference to occur, light waves need to be coherent, meaning they maintain a constant phase relationship. Coherence involves both:

- Temporal Coherence: Related to the spectral width of the light source.
- Spatial Coherence: Related to the size and geometry of the source.

## 2.5.2 Path Difference and Phase

Interference patterns depend on the path difference between the waves:

- Constructive Interference: Occurs when  $\Delta \phi = 2n\pi$ .
- Destructive Interference: Occurs when  $\Delta \phi = (2n+1)\pi$ .

# 3 Diffraction

#### 3.1 Definition

Diffraction is the bending and spreading of light waves as they encounter an obstacle or aperture. It's a fundamental property of waves, illustrating that light doesn't travel in straight lines under certain conditions. Diffraction limits the resolution of optical systems and plays a crucial role in the design of structured light beams.

#### 3.2 Mathematical Framework

#### 3.2.1 Fraunhofer Diffraction (Far-Field)

Fraunhofer diffraction occurs when both the light source and the observation screen are at a sufficiently large distance from the diffracting aperture, simplifying the mathematical analysis using Fourier transforms.

**Single Slit Diffraction** For a single slit of width a, the intensity distribution  $I(\theta)$  as a function of angle  $\theta$  is given by:

$$I(\theta) = I_0 \left(\frac{\sin(\beta)}{\beta}\right)^2 \tag{7}$$

where

$$\beta = \frac{\pi a \sin(\theta)}{\lambda} \tag{8}$$

-  $I_0$  is the maximum intensity. -  $\lambda$  is the wavelength of light.

Multiple Slit Diffraction (Gratings) For N slits, the intensity pattern becomes more complex due to additional interference terms:

$$I(\theta) = I_0 \left(\frac{\sin(N\gamma)}{\sin(\gamma)}\right)^2 \left(\frac{\sin(\beta)}{\beta}\right)^2 \tag{9}$$

where

$$\gamma = \frac{\pi d \sin(\theta)}{\lambda} \tag{10}$$

- d is the distance between slits.

## 3.2.2 Fresnel Diffraction (Near-Field)

Fresnel diffraction occurs when the source or observation screen is at a finite distance from the aperture, requiring more complex analysis.

**Kirchhoff's Diffraction Formula** The Fresnel diffraction pattern U(P) at a point P is given by:

$$U(P) = \frac{e^{ikr}}{i\lambda r} \int \int_{A} U(Q) \frac{e^{ik|P-Q|}}{|P-Q|} \cos(\nu, dS) dS$$
 (11)

- U(Q) is the disturbance at point Q on the aperture. - r is the distance from the aperture to point P.

# 3.3 Diffraction and Aperture Shape

The shape of the aperture affects the diffraction pattern:

#### 3.3.1 Rectangular Aperture

The diffraction pattern for a rectangular aperture is described by:

$$I(x,y) = I_0 \left(\frac{\sin(\alpha)}{\alpha}\right)^2 \left(\frac{\sin(\beta)}{\beta}\right)^2 \tag{12}$$

where

$$\alpha = \frac{\pi a \sin(\theta_x)}{\lambda}, \quad \beta = \frac{\pi b \sin(\theta_y)}{\lambda}$$
 (13)

-  $\theta_x$  and  $\theta_y$  are angles in the x and y directions.

Circular Aperture (Airy Disk) The diffraction pattern from a circular aperture results in an Airy disk:

$$I(\theta) = I_0 \left( \frac{2J_1(ka\sin(\theta))}{ka\sin(\theta)} \right)^2$$
(14)

where  $J_1$  is the Bessel function of the first kind, and  $k = \frac{2\pi}{\lambda}$  is the wave number.

# 3.4 Key Concepts

#### 3.4.1 Resolution Limits

Diffraction sets fundamental limits on the resolution of imaging systems, described by the Rayleigh criterion:

$$\theta_{\min} = 1.22 \frac{\lambda}{D} \tag{15}$$

where D is the diameter of the aperture.

## 3.4.2 Diffraction and Structured Light

Structured light can be tailored to manipulate diffraction patterns for specific applications, such as beam shaping, optical trapping, and microscopy.

# 3.5 Diffraction and Structured Light Beams

Structured light beams can be engineered to exploit diffraction effects to enhance specific applications:

### 3.5.1 Beam Shaping

Diffraction patterns can be controlled to create complex beam shapes, such as Airy beams or Bessel beams, which have unique propagation characteristics.

#### 3.5.2 Optical Trapping

The diffraction patterns of structured beams can create optical traps for manipulating microscopic particles. By adjusting the beam parameters, precise control over particle movement can be achieved.

#### 3.5.3 Applications in Imaging

Diffraction limits resolution, but by utilizing structured light, such as super-resolution techniques, it is possible to surpass traditional diffraction limits, leading to enhanced imaging capabilities.

# 4 Fourier Optics

## 4.1 Introduction

Fourier optics provides a framework for understanding how light waves can be manipulated using lenses and other optical components. It describes how spatial frequencies within a light field can be altered and analyzed, forming the basis for advanced imaging and beam shaping techniques.

## 4.2 Mathematical Framework

### 4.2.1 Fourier Transform of a Light Field

The Fourier transform is a mathematical tool that converts a spatial domain signal into a frequency domain signal:

$$\mathcal{F}\{E(x,y)\} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E(x,y)e^{-i2\pi(ux+vy)} dx dy$$
 (16)

where:

- E(x,y) is the light field.
- u and v are spatial frequencies.

**Inverse Fourier Transform** The inverse transform reconstructs the spatial domain from the frequency domain:

$$E(x,y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \mathcal{F}\{E(u,v)\}e^{i2\pi(ux+vy)} du dv$$
 (17)

## 4.3 Fourier Transform and Diffraction

Fourier optics reveals that the far-field diffraction pattern of an object is the Fourier transform of the object's aperture function. This relationship is central to understanding optical systems:

#### 4.3.1 Fraunhofer Diffraction and Fourier Transform

In the Fraunhofer (far-field) regime, the diffraction pattern E(u, v) is the Fourier transform of the aperture function A(x, y):

$$E(u,v) = \mathcal{F}\{A(x,y)\}\tag{18}$$

The distribution of spatial frequencies u and v in the diffraction pattern determines the resolution and detail of the image.

## 4.3.2 Example: Circular Aperture and Airy Pattern

For a circular aperture, the Fourier transform leads to the Airy disk pattern, which describes the intensity distribution of a point source in the focal plane of a lens.

$$E(u,v) = 2J_1(ka\sqrt{u^2 + v^2})/(ka\sqrt{u^2 + v^2})$$
(19)

where  $J_1$  is the Bessel function of the first kind.

# 5 Lasers

### 5.1 Introduction to Lasers

Lasers (Light Amplification by Stimulated Emission of Radiation) are devices that emit light through a process of optical amplification based on the stimulated emission of electromagnetic radiation. They are a critical component in the field of optics and have revolutionized many applications across science, industry, medicine, and communication.

# 5.2 Basic Theory of Lasers

The operation of a laser is based on three primary processes:

- 1. **Absorption:** Atoms or molecules in a medium absorb energy from an external source, moving electrons to a higher energy level.
- 2. **Spontaneous Emission:** An electron in an excited state can return to a lower energy state, emitting a photon randomly.
- 3. **Stimulated Emission:** If an electron in an excited state encounters a photon with energy equal to the energy difference between the excited state and a lower state, it can be induced to drop to the lower state, releasing a photon that is coherent with the incoming photon.

The fundamental requirement for laser operation is achieving a population inversion, where more electrons are in the excited state than in the lower energy states, allowing stimulated emission to dominate.

# 5.3 Mathematical Representation

#### **Rate Equations**

The rate equations describe the dynamics of population inversion and photon density in a laser medium. Let  $N_1$  and  $N_2$  be the population densities of the lower and upper energy levels, respectively, and  $\Phi$  the photon density.

#### 1. Population Inversion:

$$\Delta N = N_2 - N_1 \tag{20}$$

### 2. Rate of Change of Population:

$$\frac{dN_2}{dt} = -\frac{N_2}{\tau} - B_{21}N_2\Phi + B_{12}N_1\Phi \tag{21}$$

$$\frac{dN_1}{dt} = \frac{N_2}{\tau} + B_{21}N_2\Phi - B_{12}N_1\Phi \tag{22}$$

Where  $\tau$  is the spontaneous emission lifetime, and  $B_{21}$  and  $B_{12}$  are the Einstein coefficients for stimulated emission and absorption, respectively.

#### Gain and Threshold Condition

For laser action to occur, the gain must exceed losses in the system. The gain g is defined as:

$$g = \sigma(N_2 - N_1) \tag{23}$$

Where  $\sigma$  is the stimulated emission cross-section. The threshold condition for laser oscillation is given by:

$$g \ge \frac{\alpha}{L} + \frac{1}{2L} \ln \left( \frac{1}{R_1 R_2} \right) \tag{24}$$

Where  $\alpha$  is the loss coefficient, L is the length of the gain medium, and  $R_1$  and  $R_2$  are the reflectivities of the mirrors.

# 5.4 Types of Lasers

- (a) **Solid-State Lasers:** Utilize a solid gain medium, such as Nd:YAG (neodymium-doped yttrium aluminum garnet).
- (b) Gas Lasers: Use a gas as the gain medium, such as CO<sub>2</sub> or helium-neon lasers.
- (c) **Semiconductor Lasers:** Include laser diodes, commonly used in consumer electronics and telecommunications.
- (d) **Fiber Lasers:** Employ optical fibers doped with rare-earth elements like erbium or ytterbium.
- (e) **Dye Lasers:** Utilize organic dyes in liquid form as the gain medium, offering tunability across a range of wavelengths.

# 5.5 Applications of Lasers

- Communication: Fiber optic communication systems rely on laser diodes for data transmission over long distances with minimal loss.
- Medicine: Lasers are used in various medical procedures, including eye surgery, dermatology, and oncology, for precise and minimally invasive treatments.
- Industry: Lasers are employed in cutting, welding, engraving, and additive manufacturing due to their precision and control.

- Research: Lasers enable high-resolution spectroscopy, microscopy, and studies in quantum mechanics and atomic physics.
- Imaging and Displays: Lasers are used in holography, projectors, and advanced imaging techniques.

# 6 Conclusion

The study of structured light waves offers insights into the wave nature of light and its capabilities. By harnessing interference, diffraction, and Fourier optics, we can manipulate light beams in novel ways, paving the way for advances in communications, imaging, and beyond.

Structured light waves present exciting opportunities and challenges in both theoretical and applied physics. As technology advances, the applications of these beams will continue to expand, highlighting the importance of understanding their propagation and manipulation.