## Martingales



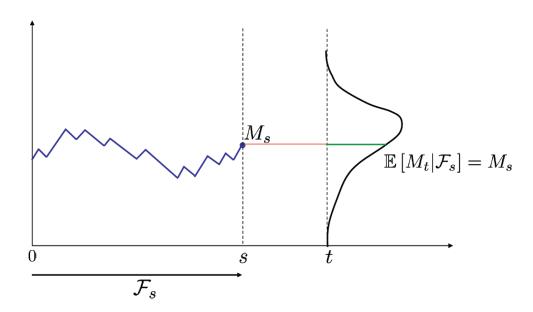
**Martingales** are a key concept in probability and in mathematical finance. The term 'martingale' may refer to very different ideas e.g. a stochastic process that has no drift. Essentially, this is the idea of a fair (random) game. We encounter Martingales through three distinct, but closely connected ideas:

- 1. Martingales as a class of stochastic process;
- 2. Exponential martingales, which are a specific and extremely useful example of a martingale;
- 3. Equivalent martingale measures, where we look for a probability measure  $\mathbb{Q}$  such that a given stochastic process S(t) is a martingale under  $\mathbb{Q}$  regardless of its nature under  $\mathbb{P}$ . The correspondence between the measures  $\mathbb{P}$  and  $\mathbb{Q}$  is done through a change of measure.

## Discrete Time Martingales

A discrete time stochastic process  $\{M_t: t=0,\ldots,T\}$  such that  $M_t$  is  $\mathcal{F}_t$ -measurable for  $\mathbb{T}=\{0,\ldots,T\}$  is a **martingale** if  $\mathbb{E}\,|M_t|<\infty$  and

$$\mathbb{E}\left[M_{t+1}|\mathcal{F}_t\right] = M_t \tag{1}$$



The first equation represents a standard integrability condition.

The second equation tells you that the expected value of M at time t+1 conditional on all the information available up to time t is the value of M at time t. In short, a Martingale is a **driftless process**.

If we take expectation on both sides of eqn. 1, then

$$\mathbb{E}\left[M_{t+1}\right] = \mathbb{E}\left[M_t\right]$$

This is due to the **Tower Property** of conditional expectations.

Martingales are a very nice mathematical object. They "get rid of the drift" and enable us to focus on what probabilists consider is the most interesting part: the statistical properties of purely random processes.

In addition, Doob and Meyer have developed a powerful theory centred around martingales.

## Continuous Time Martingales

Next, we generalize our definitions to continuous time: A continuous time stochastic process

$$\left\{ M_t : t \in \mathbb{R}^+ \right\}$$

such that  $M_t$  is  $\mathcal{F}_t$ -measurable for  $t \in \mathbb{R}^+$  is a **martingale** if

$$\mathbb{E}|M_t|<\infty$$

and

$$\mathbb{E}\left[M_t|\mathcal{F}_s\right] = M_s, \quad 0 \le s \le t.$$

**Lévy's Martingale Characterisation:** Let  $X_t$ , t > 0 be a stochastic process and let  $\mathcal{F}_t$  be the filtration generated by it.  $X_t$  is a Brownian motion iff the following conditions are satisfied:

- 1.  $X_0 = 0$  a.s.;
- 2. the sample paths  $t \mapsto X_t$  are continuous a.s.;
- 3.  $X_t$  is a martingale with respect to the filtration  $\mathcal{F}_t$ ;
- 4.  $|X_t|^2 t$  is a martingale with respect to the filtration  $\mathcal{F}_t$ .

The Lévy characterization can be contrasted with the classical definition of a Brownian motion as a stochastic process  $X_t$  satisfying:

1. 
$$X_0 = 0$$
 a.s.;

- 2. the sample paths  $t \mapsto X(t)$  are continuous a.s.;
- 3. **independent increments**: for  $t_1 < t_2 < t_3 < t_4$  the increments  $X_{t_4} X_{t_3}$ ,  $X_{t_2} X_{t_1}$  are independent;
- 4. normally distributed increments:  $X_t X_s \sim N(0, |t s|)$ .

Lévy's characterization neither mentions independent increments nor normally distributed increments.

Instead, Lévy introduces two easily verifiable martingale conditions.

## Itô Integrals and Martingales

Next, we explore the link between Itô integration and martingales.

Consider the stochastic process  $Y(t) = X^2(t)$ . By Itô, we have

$$X^{2}(T) = T + \int_{0}^{T} 2X(t)dX(t)$$

Taking the expectation, we get

$$\mathbb{E}[X^{2}(T)] = T + \mathbb{E}\left[\int_{0}^{T} 2X(t)dX(t)\right]$$

Now, the quadratic variation property of Brownian motions implies that

$$\mathbb{E}[X^2(T)] = T$$

and hence

$$\mathbb{E}\left[\int_0^T 2X(t)dX(t)\right] = 0$$

Therefore, the Itô integral

$$\int_0^T 2X(t)dX(t)$$

is a martingale.

In fact, this property is shared by all Itô integrals.

#### The Itô integral is a martingale

Let  $g(t, X_t)$  be a function on [0, T] and satisfying the technical condition. Then the Itô integral

$$\int_0^T g(t, X_t) dX_t$$

is a martingale.

So, Itô integrals are martingales.

But does the converse hold? Can we represent any martingale as an Itô integral?

The answer is yes!

Martingale Representation Theorem: If  $M_t$  is a martingale, then there exists a function  $g(t, X_t)$  satisfying the technical condition such that

$$M_T = M_0 + \int_0^T g(t, X_t) dX_t$$

**Example** Using only Itô and the fact that Itô integrals are martingales, we will show that

$$\mathbb{E}\left[X^2(T)\right] = T.$$

Consider the function  $F(t, X_t) = X_T^2$ , then by Itô's lemma,

$$X_T^2 = X_0^2 + \frac{1}{2} \int_0^T 2dt + \int_0^T 2X_t dX_t$$
$$= \int_0^T dt + 2 \int_0^T X_t dX_t$$

since  $X_0 = 0$ 

Taking the expectation,

$$\mathbb{E}\left[X_T^2\right] = \mathbb{E}\left[\int_0^T dt\right] + 2\mathbb{E}\left[\int_0^T X_t dX_t\right]$$

Now,

$$\int_0^T X_t dX_t$$

is an Itô integral and as a result  $\mathbb{E}\left[\int_0^T X_t dX_t\right] = \mathbf{0}$ 

Moreover,

$$\mathbb{E}\left[\int_0^T dt\right] = \mathbb{E}\left[T\right] = T$$

We can conclude that

$$\mathbb{E}\left[X^2(T)\right] = T$$

As an aside, we can usually exchange the order of integration between the time integral and the expectation so that

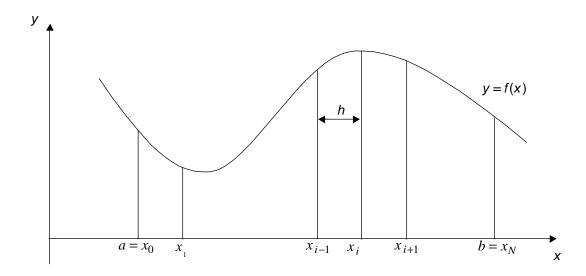
$$\mathbb{E}\left[\int_0^T f(X_t)dt\right] = \int_0^T \mathbb{E}\left[f(X_t)\right]dt$$

This is due to an analysis result known as Fubini's Theorem.

## Itô Integral

Recall the usual Riemann definition of a definite integral

$$\int_{a}^{b} f(x) dx$$



which represents the area under the curve between x=a and x=b, where the curve is the graph of f(x) plotted against x.

Assuming f is a "well behaved" function on [a, b], there are many different ways (which all lead to the same value for the definite integral).

Start by partitioning [a,b] into N intervals with end points  $x_0 = a < x_1 < x_2 < \dots < x_{N-1} < x_N = b$ , where the length of an interval  $dx = x_i - x_{i+1}$  tends to zero as  $N \to \infty$ . So there are N intervals and N+1 points  $x_i$ .

Discretising x gives

$$x_i = a + idx$$

Now consider the definite integral

$$\int_0^T f(t) dt.$$

With Riemann integration there are a number of ways we can approximate this:

1. left hand rectangle rule;

$$\int_{0}^{T} f(t) dt = \lim_{N \to \infty} \sum_{i=0}^{N-1} f(t_{i}) (t_{i+1} - t_{i})$$

2. right hand rectangle rule;

$$\int_{0}^{T} f(t) dt = \lim_{N \to \infty} \sum_{i=0}^{N-1} f(t_{i+1}) (t_{i+1} - t_{i})$$

3. trapezium rule;

$$\int_{0}^{T} f(t) dt = \lim_{N \to \infty} \sum_{i=0}^{N-1} \frac{1}{2} (f(t_{i}) + f(t_{i+1})) (t_{i+1} - t_{i})$$

#### 4. midpoint rule

$$\int_{0}^{T} f(t) dt = \lim_{N \to \infty} \sum_{i=0}^{N-1} f(\frac{1}{2}(t_{i} + t_{i+1})) (t_{i+1} - t_{i})$$

In the limit  $N \to \infty$ , f(t) we get the same value for each definition of the definite integral, provided the function is integrable.

Now consider the stochastic integral of the form

$$\int_0^T f(t, X) dX = \int_0^T f(t, X(t)) dX(t)$$

where X(t) is a Brownian motion. We can define this integral as

$$\lim_{N\to\infty}\sum_{i=0}^{N-1}f\left(t_{i},X_{i}\right)\left(X_{i+1}-X_{i}\right),$$

where  $X_i = X(t_i)$ , or as

$$\lim_{N \to \infty} \sum_{i=0}^{N-1} f(t_{i+1}, X_{i+1}) (X_{i+1} - X_i),$$

or as

$$\lim_{N \to \infty} \sum_{i=0}^{N-1} f\left(t_{i+\frac{1}{2}}, X_{i+\frac{1}{2}}\right) \left(X_{i+1} - X_i\right),\,$$

where  $t_{i+\frac{1}{2}}=\frac{1}{2}(t_i+t_{i+1})$  and  $X_{i+\frac{1}{2}}=X\left(t_{i+\frac{1}{2}}\right)$  or in many other ways. So clearly drawing parallels with the above Riemann form.

**Very Important:** In the case of a stochastic variable dX(t) the value of the stochastic integral **does** depend on which definition we choose.

In the case of a stochastic integral, the definition

$$I = \lim_{N \to \infty} \sum_{i=0}^{N-1} f(t_i, X_i) (X_{i+1} - X_i),$$

is special. This definition results in the Itô Integral.

non-predictive

It is special because it is **non-anticipatory**; given that we are at time  $t_i$  we know  $X_i = X(t_i)$  and therefore we know  $f(t_i, X_i)$ . The only uncertainty is in the  $X_{i+1} - X_i$  term.

Compare this to a definition such as

$$\lim_{\text{predict} \stackrel{N-1}{\mapsto} \infty} \sum_{i=0}^{N-1} f(t_{i+1}, X_{i+1}) \left(X_{i+1} - X_i\right), \quad \left(\int \text{tratonovich}\right)$$

which is **anticipatory**; given that at time  $t_i$  we know  $X_i$  but are uncertain about the future value of  $X_{i+1}$ . Thus we are uncertain about *both* the value of

$$f\left(t_{i+1},X_{i+1}\right)$$

and the value of  $(X_{i+1} - X_i)$  — there exists uncertainty in both of these quantities. That is, evaluation of this integral requires us to <u>anticipate</u> the future value of  $X_{i+1}$  so that we may evaluate  $f(t_{i+1}, X_{i+1})$ .

The main thing to note about Itô integrals is that I is a random variable (unlike the deterministic case). Additionally, since I is essentially the limit of a sum of normal random variables, then by the CLT I is also normally distributed, and can be characterized by its mean and variance.

**Example**: Show that Itô's lemma implies that

$$3\int_0^T X^2 dX = X(T)^3 - X(0)^3 - 3\int_0^T X(t) dt.$$

Show that the result also can be found by writing the integral

$$3\int_{0}^{T} X^{2} dX = \lim_{N \to \infty} 3\sum_{i=0}^{N-1} X_{i}^{2} (X_{i+1} - X_{i})$$

Hint: use  $3b^2(a-b) = a^3 - b^3 - 3b(a-b)^2 - (a-b)^3$ .

The Itô integral here is defined as

$$\int_{0}^{T} 3X^{2}(t) dX(t) = \lim_{N \to \infty} \sum_{i=0}^{N-1} 3X_{i}^{2}(X_{i+1} - X_{i})$$

Now note the hint:

$$3b^{2}(a-b) = a^{3} - b^{3} - 3b(a-b)^{2} - (a-b)^{3}$$

hence

$$\equiv 3X_i^2 (X_{i+1} - X_i)$$
  
=  $X_{i+1}^3 - X_i^3 - 3X_i (X_{i+1} - X_i)^2 - (X_{i+1} - X_i)^3$ ,

so that

$$\sum_{i=0}^{N-1} 3X_i^2 (X_{i+1} - X_i) =$$

$$\sum_{i=0}^{N-1} X_{i+1}^3 - \sum_{i=0}^{N-1} X_i^3 - \sum_{i=0}^{N-1} 3X_i (X_{i+1} - X_i)^2 - \sum_{i=0}^{N-1} (X_{i+1} - X_i)^3$$

Now the first two expressions above give

$$\sum_{i=0}^{N-1} X_{i+1}^3 - \sum_{i=0}^{N-1} X_i^3 = X_N^3 - X_0^3$$
$$= X(T)^3 - X(0)^3.$$

In the limit  $N \to \infty$ , i.e.  $dt \to 0$ ,  $(X_{i+1} - X_i)^2 \to dt$ , so

$$\lim_{N \to \infty} \sum_{i=0}^{N-1} 3X_i (X_{i+1} - X_i)^2 = \int_0^T 3X(t) dt$$

Finally  $(X_{i+1}-X_i)^3=(X_{i+1}-X_i)^2\cdot (X_{i+1}-X_i)$  which when  $N\to\infty$  behaves like  $dX^2dX\sim O\left(dt^{3/2}\right)\longrightarrow 0$ .

Hence putting together gives

$$X(T)^3 - X(0)^3 - \int_0^T 3X(t) dt$$

which is consistent with Itô's lemma.

The other important property that the Itô integral has is that it is a martingale. We know that

$$X_{i+1} - X_i$$

is a martingale; i.e. in the context

$$\mathbb{E}\left[X_{i+1}-X_i\right]=\mathbf{0}.$$

Since

$$\mathbb{E}\left[\sum_{i=0}^{N-1} f(t_i, X_i) (X_{i+1} - X_i)\right] = \sum_{i=0}^{N-1} f(t_i, X_i) \mathbb{E}\left[X_{i+1} - X_i\right] = 0$$

Thus

$$\mathbb{E}\left[\int_{0}^{T} f\left(t, X\left(t\right)\right) dX\left(t\right)\right] = 0.$$

This is, essentially a consequence of the Itô integral being non-anticipatory, as discussed earlier. No other stochastic integral has this property.

**Exercise** We know from Itô's lemma that

$$4\int_{0}^{T} X^{3}(t) dX(t) = X^{4}(T) - X^{4}(0) - 6\int_{0}^{T} X^{2}(t) dt$$

Show from the definition of the Itô integral that the result can also be found by initially writing the integral

$$4\int_{0}^{T} X^{3} dX = \lim_{N \to \infty} 4\sum_{i=0}^{N-1} X_{i}^{3} (X_{i+1} - X_{i})$$

**Hint**: use  $4b^3(a-b) = a^4 - b^4 - 4b(a-b)^3 - 6b^2(a-b)^2 - (a-b)^4$ .

# Proving that a Continuous Time Stochastic Process is a Martingale

Consider a stochastic process Y(t) solving the following SDE:

$$dY(t) = f(Y_t, t)dt + g(Y_t, t)dX(t), Y(0) = Y_0$$

How can we tell whether Y(t) is a martingale?

The answer has to do with the fact that Itô integrals are martingales.

Y(t) is a martingale if and only if it satisfies the martingale condition

$$\mathbb{E}\left[Y_t|\mathcal{F}_s\right] = Y_s, \quad 0 \le s \le t$$

Let's start by integrating the SDE between s and t to get an exact form for Y(t):

$$Y(t) = Y(s) + \int_s^t f(Y_u, u) du + \int_s^t g(Y_u, u) dX(u)$$

Taking the expectation conditional on the filtration at time s, we get

$$\mathbb{E}\left[Y_t|\mathcal{F}_s\right] = \mathbb{E}\left[Y(s) + \int_s^t f(Y_u, u)du + \int_s^t g(Y_u, u)dX(u)|\mathcal{F}_s\right]$$
$$= Y(s) + \mathbb{E}\left[\int_s^t f(Y_u, u)du|\mathcal{F}_s\right]$$

where the last line follows from the fact that a Itô integral is a martingale, :.

$$\mathbb{E}\left[\int_{s}^{t}g(Y_{u},u)dX(u)|\mathcal{F}_{s}\right]=\int_{s}^{s}g(Y_{u},u)dX(u)=0.$$
 So,  $Y(t)$  is a martingale iff 
$$\lim_{t\to\infty}\int_{s}^{t}f(u)du|\mathcal{F}_{s}=0 \quad \text{for } f(u)dx(u)=0.$$

This condition is satisfied only if  $f(Y_t, t) = 0$  for all t. Returning to our SDE, we conclude that Y(t) is a martingale iff it is of the form

$$dY(t) = g(Y_t, t)dX(t), Y(0) = Y_0$$

## Exponential Martingales

Let's start with a motivating example. No dependence on

where f(t) and g(t) are two time-dependent functions and X(t) is a standard Brownian motion.

Define a new process  $Z(t) = e^{Y(t)}$ .

How should we choose f(t) if we want the process Z(t) to be a martingale?

Consider the process  $Z(t) = e^{Y(t)}$ . Applying Itô to the function we obtain:

$$dZ(t) = \frac{dZ}{dY}dY(t) + \frac{1}{2}\frac{d^{2}Z}{dY^{2}}dY^{2}(t)$$

$$= \frac{dZ}{dY}(f(t)dt + g(t)dX(t)) + \frac{1}{2}\frac{d^{2}Z}{dY^{2}}g^{2}(t)dt$$

$$= e^{Y(t)}\left(f(t) + \frac{1}{2}g^{2}(t)\right)dt + e^{Y(t)}g(t)dX(t)$$

$$= Z(t)\left[\left(f(t) + \frac{1}{2}g^{2}(t)\right)dt + g(t)dX(t)\right]$$

Z(t) is a martingale if and only if it is a driftless process.

Therefore for Z(t) to be a martingale we must have

$$f(t) + \frac{1}{2}g^2(t) = 0$$

This is only possible if

$$f(t) = -\frac{1}{2}g^2(t)$$

Going back to the process Y(t), we must have

$$dY(t) = -\frac{1}{2}g^2(t)dt + g(t)dX(t), \qquad Y(0) = Y_0$$

implying that

$$Y(T) = Y_0 - \frac{1}{2} \int_0^T g^2(t) dt + \int_0^T g(t) dX(t)$$

Hence, in terms of Z(t):

$$dZ(t) = Z(t)g(t)dX(t).$$

Using the earlier relationship, we can write  $Z(T) = e^{Y(T)}$ .

Let's simplify this Z(T) =

$$\exp\left\{Y_0 - \frac{1}{2} \int_0^T g^2(t) dt + \int_0^T g(t) dX(t)\right\}$$

to give

$$Z(T) = Z_0 \exp \left\{ -\frac{1}{2} \int_0^T g^2(t) dt + \int_0^T g(t) dX(t) \right\}$$

Because the stochastic process Z(t) is the exponential of another process (namely Y(t)) and because it is a martingale, we call Z(t) an **exponential** martingale.

We have actually just stumbled upon a much more general and very important result.

## Key Condition (Novikov Condition)

A trading strategy  $(\phi, \psi) = \{(\phi_t, \psi_t); t \in [0, ..., T]\}$  is a previsible process in that  $\phi_t \in \mathcal{F}_{t-}$ .

A stochastic process  $Y_t$  satisfies the *Novikov condition* if

$$\mathbb{E}\left[\exp\left(\frac{1}{2}\int_0^T \gamma_s^2 ds\right)\right] < \infty$$

where is a  $\gamma_t$  previsible process.

### Key Fact

Given a process  $\gamma_t$  satisfying the Novikov condition, then the process  $M_t^{\gamma}$  defined as we can define the probability measure  $\mathbb Q$  on  $(\Omega, \mathcal F)$  equivalent to  $\mathbb P$  through the Radon Nikodým derivative

$$M_t^{\gamma} = \exp\left(-\int_0^t \gamma_s dX_s - \frac{1}{2}\int_0^t \gamma_s^2 ds\right), \quad t \in [0, T]$$

is a martingale.

In our earlier example  $\gamma_t = -g(t)$ ;  $M_t^{\gamma} = Z(t)$ .

## Key Fact (Girsanov's Theorem)

Given a process  $\mathscr{Y}_t$  satisfying the Novikov condition, we can define the probability measure  $\mathbb{Q}$  on  $(\Omega, \mathcal{F})$  equivalent to  $\mathbb{P}$  through the Radon Nikodým derivative

$$\frac{d\mathbb{Q}}{d\mathbb{P}} = \exp\left(-\int_0^t \gamma_s dX_s - \frac{1}{2} \int_0^t \gamma_s^2 ds\right), \quad t \in [0, T]$$

In this case, the process  $X_t^{\mathbb{Q}}$  defined as

$$X_t^{\mathbb{Q}} = X_t^{\mathbb{P}} + \int_0^t \gamma_s dX_s$$

as is a standard Brownian motion on  $(\Omega, \mathcal{F}, \mathbb{Q})$ .