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using System;
using System.Collections.Generic;
using System.ComponentModel;
using System.Data;
using System.Drawing;
using System.Net.Mail;
using System.Text;
using System.Windows.Forms;
using Emgu.CV;
using Emgu.CV.Structure;
using Emgu.CV.CvEnum;
using System.Diagnostics;
using System.Media;
namespace Drowsy_Driver_Detection_System
{
    public partial class Webcam : Form
    {
        #region Variables
        private Capture capWebCam;
        private HaarCascade haar, haar_eye;
        private HaarCascade _faces;
        private HaarCascade _eyes;
        int xMax;
        int yMax;
        Stopwatch stpWatch, stpWatch2;
        #endregion
        int eye_counter = 0;
        int speed_counter = 0;

        public Webcam()
        {
            InitializeComponent();
            _faces = new HaarCascade("haarcascade_frontalface_alt_tree.xml");
            _eyes = new HaarCascade("haarcascade_eye.xml");
            stpWatch = new Stopwatch();
            stpWatch2 = new Stopwatch();
        }

        private void Webcam_Load(object sender, EventArgs e)
        {
            capWebCam = new Capture(0);
            //capWebCam = new Capture("1.3gp");
            haar = new HaarCascade("haarcascade_frontalface_alt_tree.xml");
            haar_eye = new HaarCascade("parojosG.xml");
            // haar_eye = new HaarCascade("haarcascade_eye.xml");
            timer1.Start();
        }

        private void timer1_Tick(object sender, EventArgs e)
        {
            using (Image<Bgr, Byte> nextFrame = capWebCam.QueryFrame())
            {
                // label2.Visible = false;
                if (nextFrame != null)

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{
    Image<Gray, Byte> grayframe = nextFrame.Convert<Gray, Byte>();

    var faces = grayframe.DetectHaarCascade(haar, 1.4, 4,
HAAR_DETECTION_TYPE.FIND_BIGGEST_OBJECT, new Size(nextFrame.Width / 8,
nextFrame.Height / 8))[0];
    if (faces == null || faces.Length <= 0)
    {
        if (stpWatch.IsRunning)
        {
            //check if the face has not been detected for 10 secs
            if (stpWatch.Elapsed.Seconds >= 5)
            {
                Console.Beep(1000, 1000);
                System.Media.SystemSounds.Question.Play();
                #region Extra Sounds
                /*
                 * System.Media.SystemSounds.Beep.Play();
                 System.Media.SystemSounds.Asterisk.Play();
                 System.Media.SystemSounds.Exclamation.Play();
                 System.Media.SystemSounds.Question.Play();
                 System.Media.SystemSounds.Hand.Play();
                 * */
                #endregion
                //MessageBox.Show("driver is drowsy!");
                // label2.Visible = true;

                stpWatch.Reset();
                stpWatch.Stop();
            }
        }
        else
        {
            stpWatch.Start();
        }
    }
    foreach (var face in faces)
    {
        try
        {
            nextFrame.Draw(face.rect, new Bgr(555, double.MaxValue,
250), 1);

            //if the person is attentive stop the stopwatch

            if (stpWatch.IsRunning)
            {
                stpWatch.Reset();
                stpWatch.Stop();
            }
            grayframe.ROI = face.rect;
            //var eyes = grayframe.DetectHaarCascade(haar_eye, 1.4, 4,
HAAR_DETECTION_TYPE.DO_CANNY_PRUNING, new Size(nextFrame.Width / 8, nextFrame.Height
/ 8))[0];
            var eyes = grayframe.DetectHaarCascade(haar_eye, 1.15, 4 ,
HAAR_DETECTION_TYPE.DO_CANNY_PRUNING, new Size(20, 20))[0];
            // MCvAvgComp[][] leftEyesDetected =
grayFrame.DetectHaarCascade(_eyes, 1.15, 0,
Emgu.CV.CvEnum.HAAR_DETECTION_TYPE.DO_CANNY_PRUNING, new Size(20, 20));

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foreach (var eye in eyes)
{

    //grayframe.ROI = Rectangle.Empty;
    Rectangle rect = new Rectangle(eye.rect.X + face.rect.X,
eye.rect.Y + face.rect.Y, eye.rect.Width, eye.rect.Height);
    nextFrame.Draw(rect, new Bgr(Color.AliceBlue), 1);
    Gray cannyThreshold = new Gray(50);
    Gray cannyThresholdLinking = new Gray(10);
    grayframe.ROI = rect;
    grayframe = grayframe.ThresholdBinary(new Gray(40), new
Gray(250)); //CHANGE ACCORDING TO YOUR NEED
    imageBox1.Image = grayframe;

    int count = 0;
    for (int i = 0; i < grayframe.Rows; i++)
    {
        for (int j = 0; j < grayframe.Cols; j++)
        {
            if (grayframe.Data[i, j, 0] == 0)
                count++;
            label1.Text = string.Format("{0} black pixels",
count);

        }
    }

    //count = 20;

    //Change this value according to ur camera & environment
    brightness

    if (count <= 100)
    {
        eye_counter++;
    }
    else
        eye_counter = 0;
    if (eye_counter >= 5) // NO. of Consecutive Frames
    {
        if (stpWatch2.IsRunning)
        {
            //check if the face has not been detected for 10
secs

            if (stpWatch2.Elapsed.Seconds >= 5)
            {
                Console.Beep(5000, 1000);
                System.Media.SystemSounds.Question.Play();
                //SoundPlayer simpleSound = new
SoundPlayer(@"C:\voice.wav");

                //simpleSound.Play();
                #region Extra Sounds
                /*
                * System.Media.SystemSounds.Beep.Play();
                System.Media.SystemSounds.Asterisk.Play();
                System.Media.SystemSounds.Exclamation.Play();

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        System.Media.SystemSounds.Question.Play();
        System.Media.SystemSounds.Hand.Play();
        * */

        #endregion
        //MessageBox.Show("driver is drowsy!");

        stpWatch2.Reset();
        stpWatch2.Stop();

        SmtpClient smtpserver = new SmtpClient();
        MailMessage mail = new MailMessage();
        smtpserver.Credentials = new
System.Net.NetworkCredential("togale4@gmail.com", "tej@12345");
        smtpserver.Port = 587;
        smtpserver.EnableSsl = true;
        smtpserver.Host = "smtp.gmail.com";
        mail = new MailMessage();
        mail.From = new
MailAddress("togale4@gmail.com");

        mail.To.Add("pranetakasbe@gmail.com");
        mail.Subject = "Warning";
        mail.Body = " Details: driver drowsy detected
" ;

        smtpserver.Send(mail);

    }
}
else
{
    stpWatch2.Start();
}
}
}
//Image<Gray, Byte> cannyEdges = grayframe.Canny(new
Gray(150), new Gray(60));
//imageBox2.Image = cannyEdges;
//CircleF[] circles = cannyEdges.HoughCircles(
//
//    cannyThreshold,
//    cannyThresholdLinking,
//    1.0, //Resolution of the accumulator
used to detect centers of the circles
//
//    15.0, //min distance
//    5, //min radius
//    10 //max radius
//)[0]; //Get the circles from the first
channel

//for (int i = 0; i < circles.Length; i++)
//{
//    circles[i].Center = new PointF(rect.X +
circles[i].Center.X, rect.Y + circles[i].Center.Y);
//    nextFrame.Draw(circles[i], new
Bgr(Color.DarkOliveGreen), 1);
//}

}

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        }  
        catch (Exception ee)  
        { }  
    }  
    webcamBox.Image = nextFrame;  
}  
  
}  
  
}  
  
}  
  
}
```