A robot moves in a plane starting from the original point (0,0). The robot can move toward LEFT and RIGHT with one step, Record robot movement in a file and calculate the total distance.

```
#include <iostream>
#include<fstream>
#include<windows.h>
using namespace std;
ofstream fout;
ifstream fin;
int main()
  system("Color F4");
  char ch,ch1;
  int pos;
  int m=0;
  do{
  cout<<"\nSelect Robot movement"<<endl;</pre>
  cout<<"'L' for left\n'R' for right\n'C' Check Movement\n'N' for Stop"<<endl;
  cin>>ch;
  switch(ch)
  case 'L':
    fout.open("d:/cpp/move.txt",ios::app);
    fout<<"LEFT"<<endl;
    fout.close();
    cout<<"Move 1eft"<<endl;
    break;
  case 'R':
    m+=1;
    fout.open("d:/cpp/move.txt",ios::app);
    fout<<"RIGHT"<<endl;
    fout.close();
    cout<<"Move right"<<endl;
    break;
  case 'C':
    cout<<"Enter Position'0' for start '1' for Left '2' For Right"<<endl;
    cin>>pos;
    if(pos==0)
      fin.open("d:/cpp/move.txt");
      fin.seekg(0,ios::beg);
      fin.tellg();
      while(!fin.eof())
```

```
ch1=fin.get();
    cout<<ch1;
    fin.clear();
    fin.close();
  }
  if(pos==1)
    fin.open("d:/cpp/move.txt");
    fin.seekg(5,ios::beg);
    fin.tellg();
    while(!fin.eof())
    ch1=fin.get();
    cout<<ch1;
    fin.clear();
    fin.close();
  if(pos==2)
    string line;
    fin.open("d:/cpp/move.txt");
    fin.seekg(0,ios::beg);
    fin.tellg();
    while (getline(fin, line ))
      if (line == "RIGHT")
         while(!fin.eof())
         ch1=fin.get();
         cout<<ch1;
         }
      }
    }
    fin.clear();
    fin.close();
  }
  break;
case 'N':
  cout<<"Total Movement:"<<m<<endl;
  break;
}
}while(ch!='N');
fout.open("d:/cpp/move.txt",ios::app);
```

```
fout<<"Total Movement:"<<m<<endl;
 fout.close();
 return 0;
}
Output Screen:
 D:\SEMESTERS\Semester-July-2020\C++\Examples\RobotEx\bin\Debug\RobotEx.exe
Select Robot movement
'L' for left
'R' for right
'C' Check Movement
'N' for Stop
Move 1eft
Select Robot movement
'L' for left
'R' for right
'C' Check Movement
'N' for Stop
Move right
Select Robot movement
'L' for left
'R' for right
'C' Check Movement
'N' for Stop
Total Movement:2
Process returned 0 (0x0) execution time : 7.232 s
Press any key to continue.
```