NAME

CUTEST_cchprods_threaded - CUTEst tool to form the matrix-vector products of a vector with each of the Hessian matrices of the constraint functions.

SYNOPSIS

CALL CUTEST_cchprods_threaded(status, n, m, goth, X, Y, VECTOR, lchp, CHP_val, CHP_ind, CHP ptr, thread)

For real rather than double precision arguments, instead

CALL CUTEST_cchprods_threaded_s(...)

and for quadruple precision arguments, when available,

CALL CUTEST_cchprods_threaded_q(...)

DESCRIPTION

The CUTEST_cchprods_threaded subroutine forms the product of a vector with each of the Hessian matrix of the constraint functions c(x) corresponding to the problem decoded from a SIF file by the script *sifdecoder* at the point x = X.

The problem under consideration is to minimize or maximize an objective function f(x) over all $x \in \mathbb{R}^n$ subject to general equations $c_i(x) = 0$, $(i \in 1, ..., m_E)$, general inequalities $c_i^l \le c_i(x) \le c_i^u$. $(i \in m_E + 1, ..., m)$, and simple bounds $x^l \le x \le x^u$. The objective function is group-partially separable and all constraint functions are partially separable.

ARGUMENTS

The arguments of CUTEST_cchprods_threaded are as follows:

status [out] - integer

the outputr status: 0 for a successful call, 1 for an array allocation/deallocation error, 2 for an array bound error, 3 for an evaluation error,

n [in] - integer

the number of variables for the problem,

m [in] - integer

the total number of general constraints,

goth [in] - logical

a logical variable which specifies whether the second derivatives of the groups and elements, and the indexing information held in

CHP_ind and CHP_ptr (see below) have already been set (goth = .TRUE.) or if this information should be computed (goth = .FALSE.),

X [in] - real/double precision

when goth = .FALSE., the Hessians will be evaluated at X. Otherwise X is not used.

VECTOR [in] - real/double precision

an array which gives the vector whose product with the constraint Hessians is required,

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Ichp [in] - integer

a variable that specifies the declared lengths of CHP_val and CHP_ind. The precise length required may be found by calling *CUTEST_cdimchp* prior to *CUTEST_cchprods_threaded*,

CHP_val [out] - real/double precision

an array that gives the values of the nonzeros in the result obtained by multiplying the constraint Hessians by VECTOR. The values for the i-th constraint are stored in CHP_val(CHP_ptr(i):CHP_val(i+1)-1),

CHP_ind [inout] - integer

an array that gives the indices of the nonzeros in the result obtained by multiplying the constraint Hessians by VECTOR. The indices for the i-th constraint are stored in CHP_ind(CHP_ptr(i):CHP_ptr(i+1)-1), and match the values stored in CHP_val,

CHP ptr [inout] - integer

an array of length m+1 that gives pointers to the starting positions in CHP_ind and CHP_val for the nonzeros for the product with each Hessian. CHP_ptr(m+1)-1 gives the total space required by CHP_ind and CHP_val.

thread [out] - integer

thread chosen for the evaluation; threads are numbered from 1 to the value threads set when calling CUTEST_csetup_threaded.

NOTE

goth should be set to .TRUE. only when a previous call to CUTEST_cchprods_threaded, with goth = .FALSE., at the current point has been made. Otherwise, it should be set .FALSE.

AUTHORS

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SEE ALSO

CUTEst: a Constrained and Unconstrained Testing Environment with safe threads for mathematical optimization,

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CUTEr (and SifDec): A Constrained and Unconstrained Testing Environment, revisited,

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ACM TOMS, 29:4, pp.373-394, 2003.

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