

Vivado HLS Design Flow Lab

Introduction

This lab provides a basic introduction to high-level synthesis using the Vivado HLS tool flow. You will use Vivado HLS in GUI mode to create a project. You will simulate, synthesize, and implement the provided design.

Objectives

After completing this lab, you will be able to:

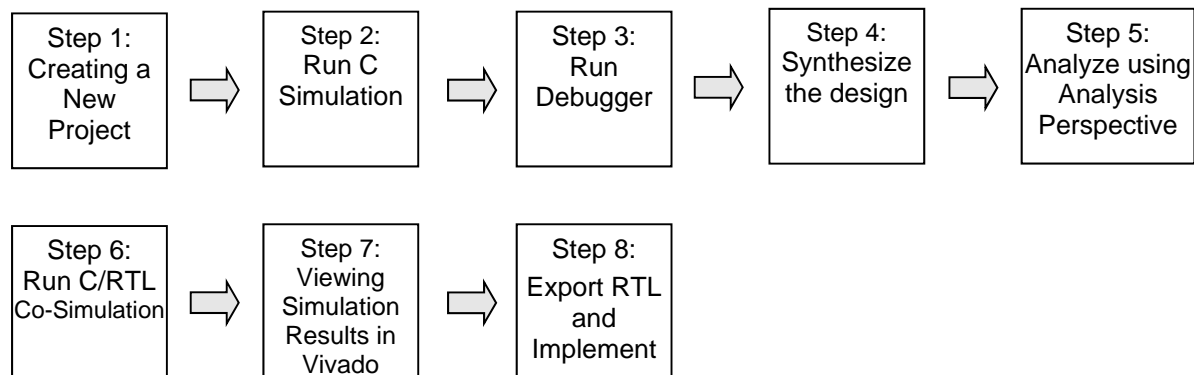
- Create a new project using Vivado HLS GUI
- Simulate a design
- Synthesize a design
- Implement a design
- Perform design analysis using the Analysis capability of Vivado HLS
- Analyze simulator output using Vivado and XSim simulator

Procedure

This lab is separated into steps that consist of general overview statements that provide information on the detailed instructions that follow. Follow these detailed instructions to progress through the lab.

This lab comprises 8 primary steps: You will create a new project in Vivado HLS, run simulation, run debug, synthesize the design, open an analysis perspective, run RTL co-simulation, view simulation results using Vivado and XSim, and export and implement the design in Vivado HLS.

General Flow for this Lab



Create a New Project

Step 1

1-1. Create a new project in Vivado HLS targeting Zynq xc7z020clg484-1 (ZedBoard) or xc7z010clg400-1 (Zybo).

1-1-1. Launch Vivado HLS: Select **Start > All Programs > Xilinx Design Tools > Vivado 2016.4 > Vivado HLS > Vivado HLS 2016.4**

A Getting Started GUI will appear.

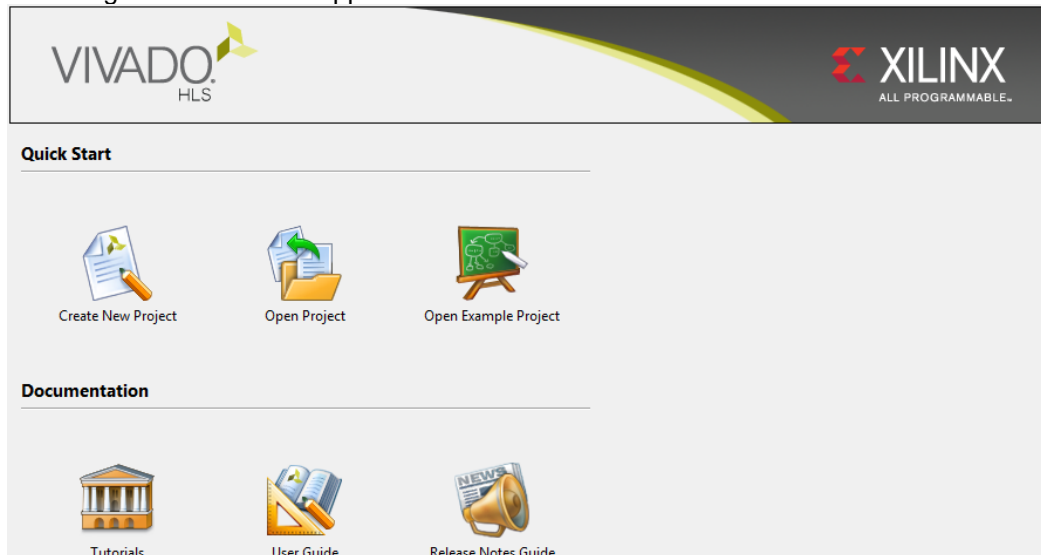


Figure 1. Getting Started view of Vivado-HLS

1-1-2. In the Getting Started GUI, click on **Create New Project**. The **New Vivado HLS Project** wizard opens.

1-1-3. Click the **Browse...** button of the Location field and browse to **c:\xup\hls\labs\lab1** and then click **OK**.

1-1-4. For Project Name, type **matrixmul.prj**

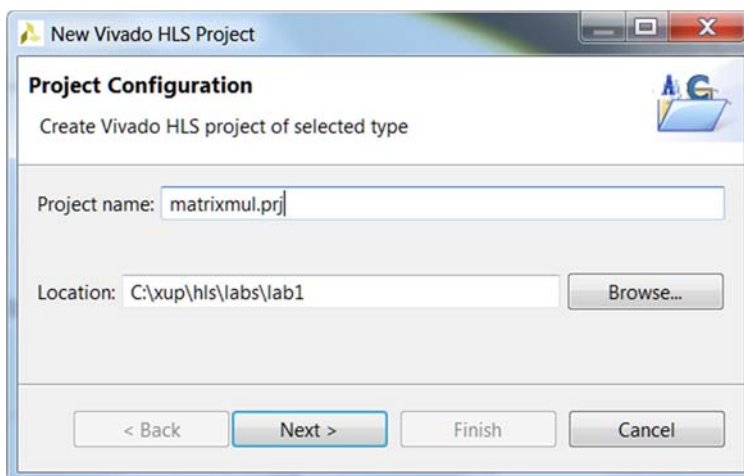


Figure 2. New Vivado HLS Project wizard

1-1-5. Click **Next**.

1-1-6. In the *Add/Remove Files* window, type **matrixmul** as the Top Function name (the provided source file contains the function, to be synthesized, called matrixmul).

1-1-7. Click the **Add Files...** button, select *matrixmul.cpp* file from the **c:\xup\hls\labs\lab1** folder, and then click **Open**.

1-1-8. Click **Next**.

1-1-9. In the *Add/Remove Files* for the testbench, click the **Add Files...** button, select *matrixmul_test.cpp* file from the **c:\xup\hls\labs\lab1** folder and click **Open**.

1-1-10. Select the *matrixmul_test.cpp* in the files list window and click the **Edit CFLAG...** button, type **-DHW_COSIM**, and click **OK**. (This defines a custom flag that will be used later.)

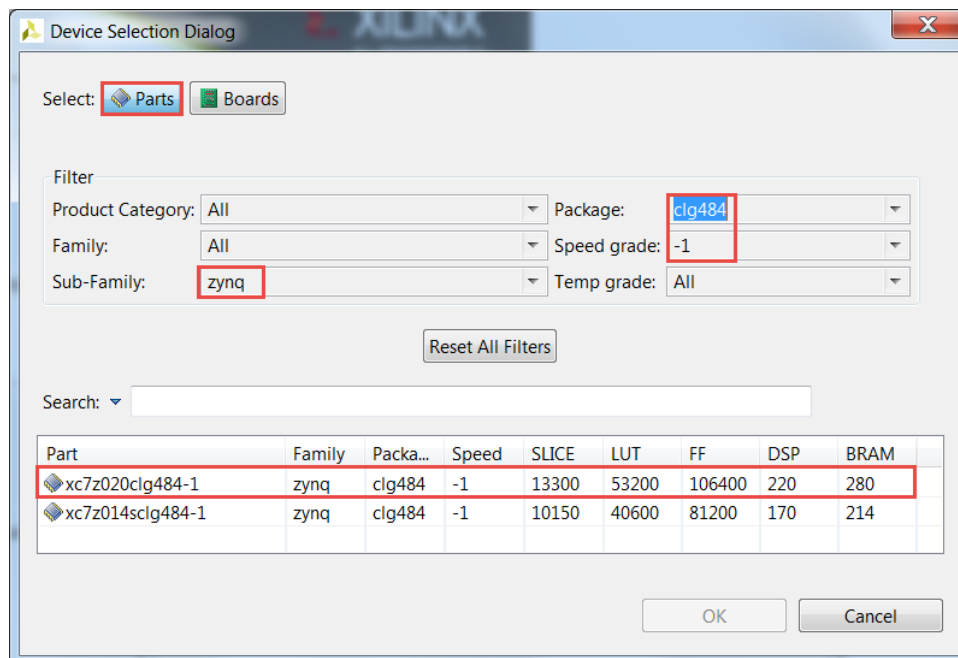
1-1-11. Click **Next**.

1-1-12. In the *Solution Configuration* page, leave Solution Name field as **solution1** and set the clock period as **10** (for ZedBoard) or **8** (for Zybo). Leave Uncertainty field blank it will take 1.25 as the default value for ZedBoard and 1 for Zybo.

Click the ... button in the *Part Selection* section.

1-1-13. In the *Device Selection Dialog* page, select *Parts* Specify field, and select the following filters to select the **xc7z020clg484-1 (ZedBoard)** or **xc7z010clg400-1 (Zybo)** part, and click **OK**:

- o Family: **Zynq**
- o Sub-Family: **Zynq**
- o Package: **clg484** (for ZedBoard) or **clg400** (for Zybo)
- o Speed Grade: **-1**



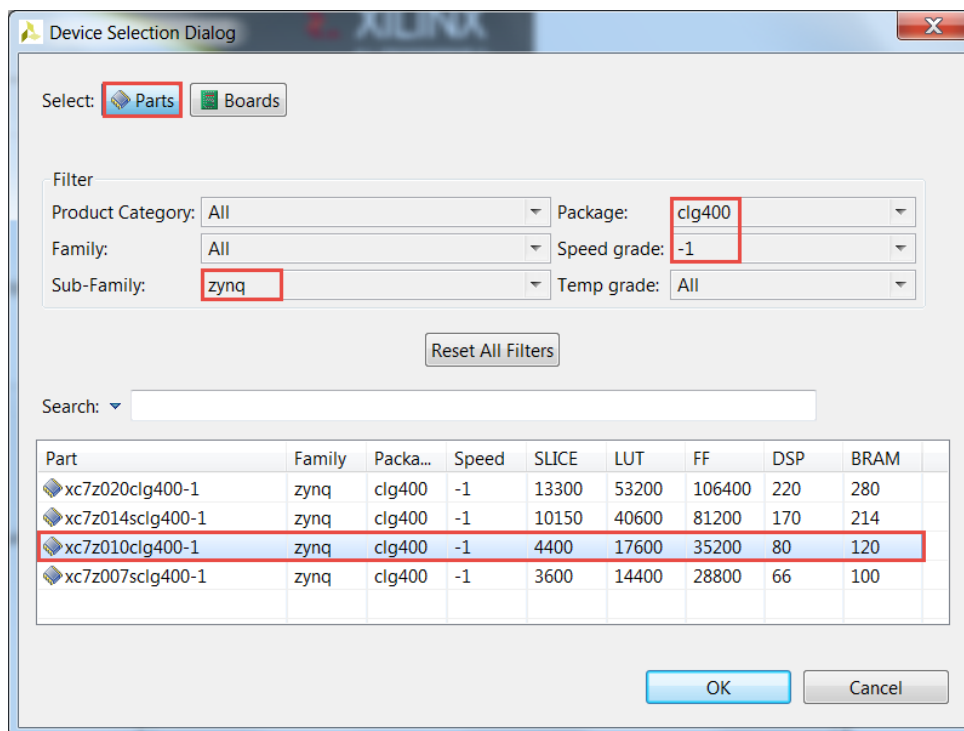


Figure 3. Using Parts Specify option in Part Selection Dialog

You can also select the *Boards* specify option (only for ZedBoard) and select one of the listed board if the desired target board is listed.

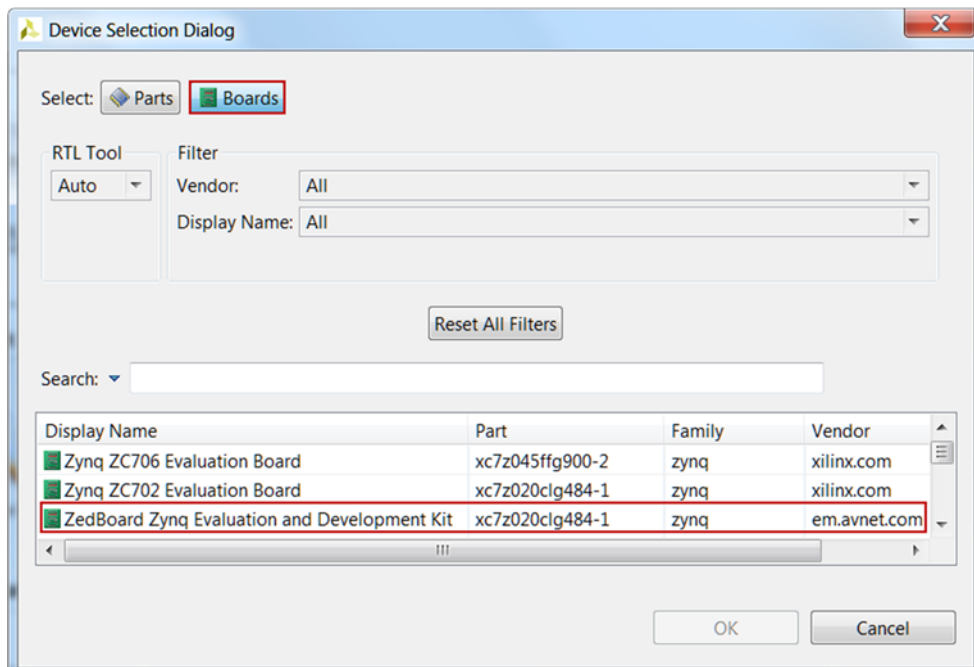


Figure 4. Using Boards Specify option in Part Selection Dialog

1-1-14. Click **Finish**.

You will see the created project in the Explorer view. Expand various sub-folders to see the entries under each sub-folder.

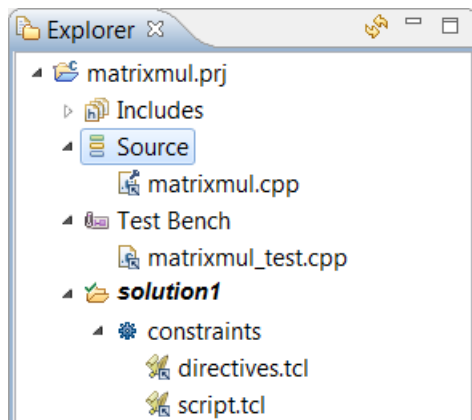


Figure 5. Explorer Window

1-1-15. Double-click on the **matrixmul.cpp** under the source folder to open its content in the information pane.

```

67#include "matrixmul.h"
68
69void matrixmul(
70    mat_a_t a[MAT_A_ROWS][MAT_A_COLS],
71    mat_b_t b[MAT_B_ROWS][MAT_B_COLS],
72    result_t res[MAT_A_ROWS][MAT_B_COLS])
73{
74    // Iterate over the rows of the A matrix
75    Row: for(int i = 0; i < MAT_A_ROWS; i++) {
76        // Iterate over the columns of the B matrix
77        Col: for(int j = 0; j < MAT_B_COLS; j++) {
78            // Do the inner product of a row of A and col of B
79            res[i][j] = 0;
80            Product: for(int k = 0; k < MAT_B_ROWS; k++) {
81                res[i][j] += a[i][k] * b[k][j];
82            }
83        }
84    }
85}

```


Figure 6. The Design under consideration

It can be seen that the design is a matrix multiplication implementation, consisting of three nested loops. The *Product* loop is the inner most loop performing the actual Matrix elements product and sum. The *Col* loop is the outer-loop which feeds the next column element data with the passed row element data to the Product loop. Finally, *Row* is the outer-most loop. The `res[i][j]=0` (line 79) resets the result every time a new row element is passed and new column element is used.

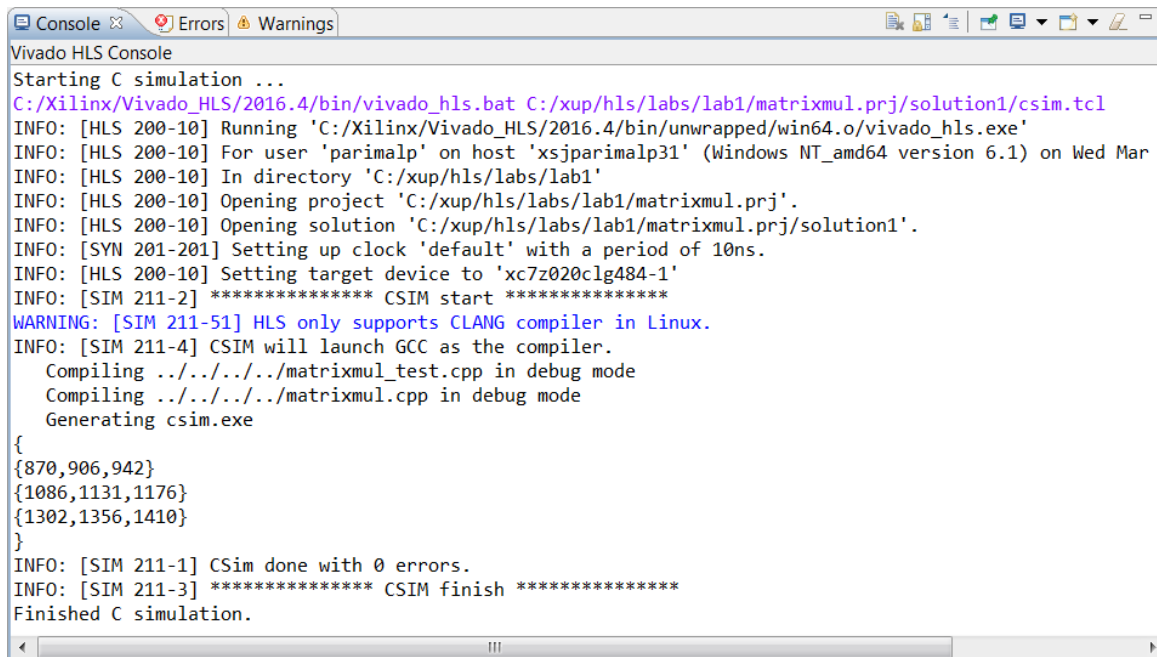
Run C Simulation

Step 2

2-1. Run C simulation to view the expected output.

2-1-1. Select **Project > Run C Simulation** or click on  from the tools bar buttons, and Click **OK** in the *C Simulation Dialog* window.

2-1-2. The files will be compiled and you will see the output in the Console window.



```

Vivado HLS Console
Starting C simulation ...
C:/Xilinx/Vivado_HLS/2016.4/bin/vivado_hls.bat C:/xup/hls/labs/lab1/matrixmul.prj/solution1/csim.tcl
INFO: [HLS 200-10] Running 'C:/Xilinx/Vivado_HLS/2016.4/bin/unwrapped/win64.o/vivado_hls.exe'
INFO: [HLS 200-10] For user 'parimalp' on host 'xsjparimalp31' (Windows NT_amd64 version 6.1) on Wed Mar
INFO: [HLS 200-10] In directory 'C:/xup/hls/labs/lab1'
INFO: [HLS 200-10] Opening project 'C:/xup/hls/labs/lab1/matrixmul.prj'.
INFO: [HLS 200-10] Opening solution 'C:/xup/hls/labs/lab1/matrixmul.prj/solution1'.
INFO: [SYN 201-201] Setting up clock 'default' with a period of 10ns.
INFO: [HLS 200-10] Setting target device to 'xc7z020clg484-1'
INFO: [SIM 211-2] ***** CSIM start *****
WARNING: [SIM 211-51] HLS only supports CLANG compiler in Linux.
INFO: [SIM 211-4] CSIM will launch GCC as the compiler.
    Compiling ../../../../matrixmul_test.cpp in debug mode
    Compiling ../../../../matrixmul.cpp in debug mode
    Generating csim.exe
{
{870,906,942}
{1086,1131,1176}
{1302,1356,1410}
}
INFO: [SIM 211-1] CSim done with 0 errors.
INFO: [SIM 211-3] ***** CSIM finish *****
Finished C simulation.
  
```

Figure 7. Program output

2-1-3. Double-click on **matrixmul_test.cpp** under **testbench** folder in the Explorer to see the content.


You should see two input matrices initialized with some values and then the code that executes the algorithm. If **HW_COSIM** is defined (as was done during the project set-up) then the **matrixmul** function is called and compares the output of the computed result with the one returned from the called function, and prints *Test passed* if the results match.

If **HW_COSIM** had not been defined then it will simply output the computed result and not call the **matrixmul** function.

Run Debugger

Step 3

3-1. Run the application in debugger mode and understand the behavior of the program.

3-1-1. Select **Project > Run C Simulation** or click on  from the tools bar buttons. Select the *Launch Debugger* option and click **OK**.

The application will be compiled with **-g** option to include the debugging information, the compiled application will be invoked, and the debug perspective will be opened automatically.

3-1-2. The Debug perspective will show the **matrixmul_test.cpp** in the source view, **argc** and **argv** variables defined in the Variables view, Outline view showing the objects which are in the current scope, thread created and the program suspended at the **main()** function entry point.

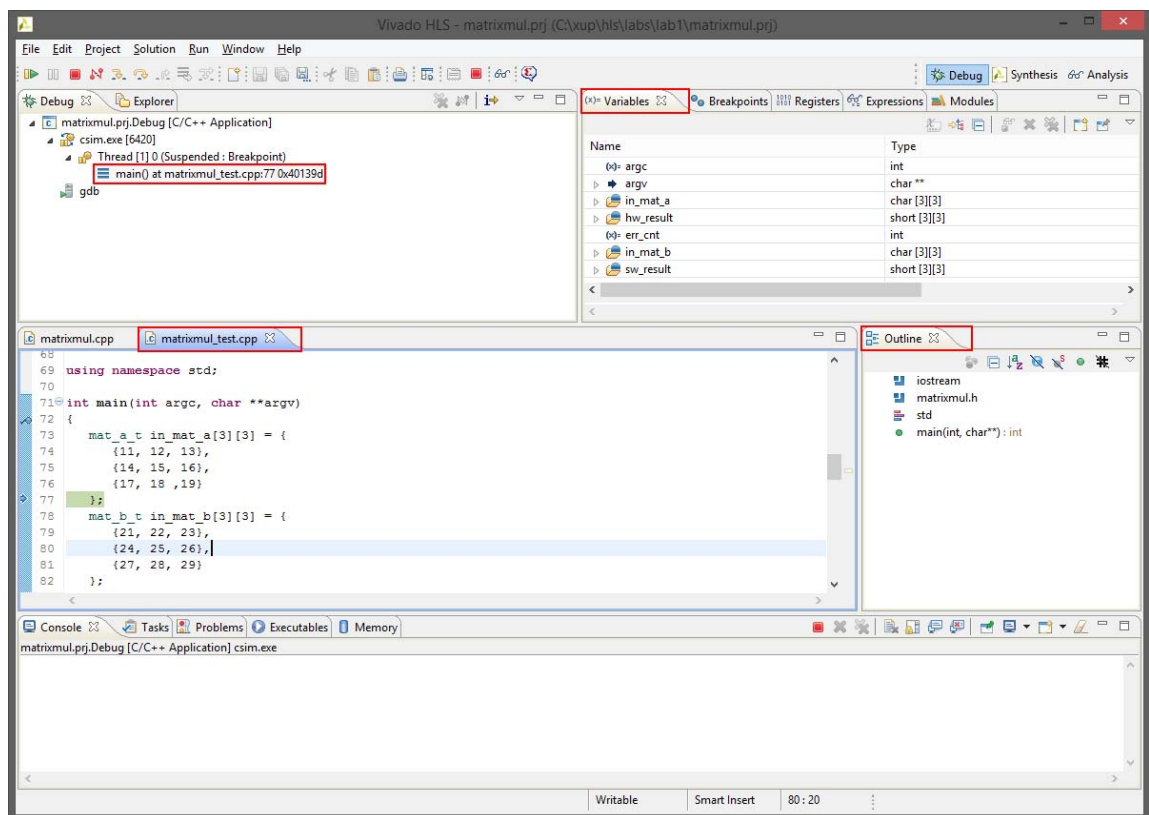



Figure 8. A Debug perspective

- 3-1-3.** Scroll-down in the source view, and double-click in the blue margin at line 105 where it is about to output "{" in the output console window. This will set a break-point at line 105. .

The breakpoint is marked with a blue circle, and a tick

```
104 // Print result matrix
105 cout << "{" << endl;
```

- 3-1-4.** Similarly, set a breakpoint at line 101 on the matrixmul() function

- 3-1-5.** Using the **Step Over (F6)** button () several times, observe the execution progress, and observe the variable values updating, as well as computed software result.

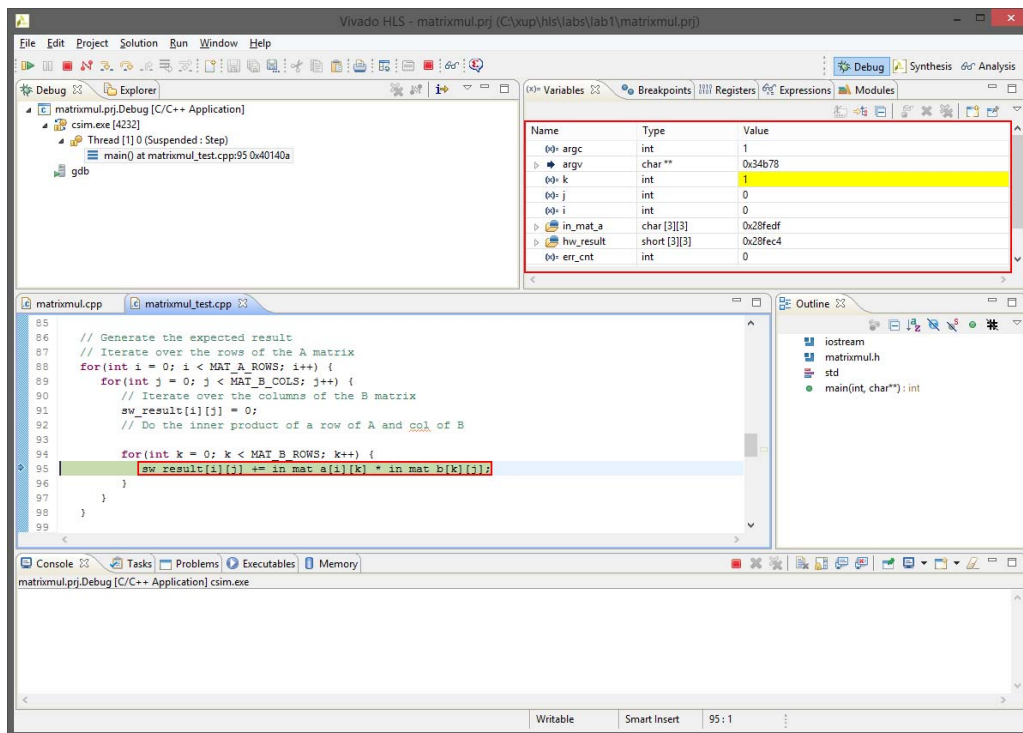



Figure 9. Debugger's intermediate output view

3-1-6. Now click the **Resume** () button or **F8** to complete the software computation and stop at line 101.

3-1-7. Observe the following computed software result in the variables view.

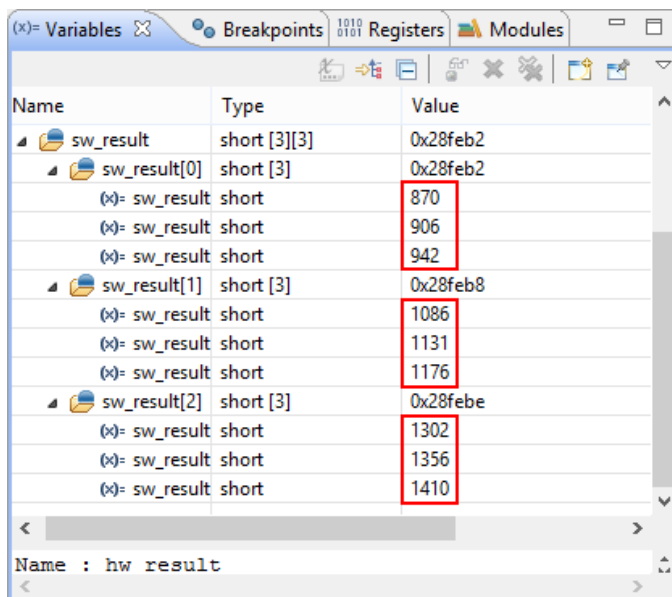

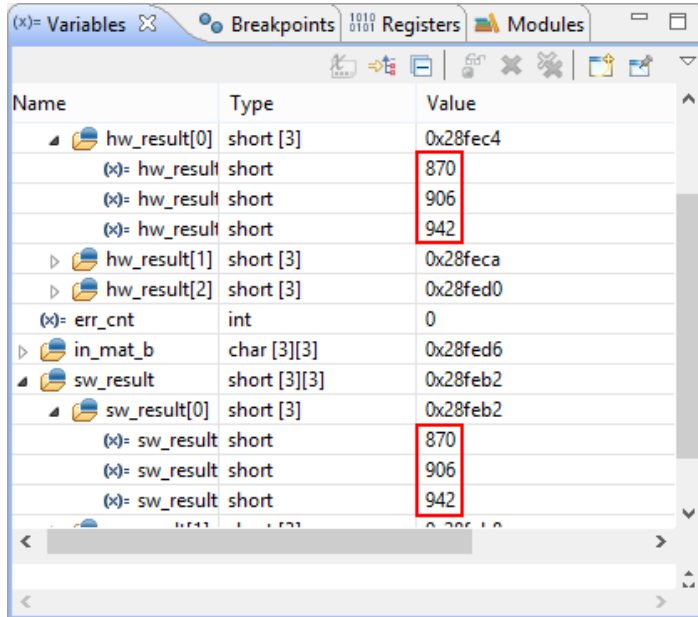


Figure 10. Software computed result

3-1-8. Click on the **Step Into (F5)** button () to traverse into the matrixmul module, the one that we will synthesize, and observe that the execution is paused on line 75 of the module.

3-1-9. Using the **Step Over (F6)** several times, observe the computed results. Once satisfied, you can use the **Step Return (F7)** button to return from the function.

3-1-10. The program execution will suspend at line 105 as we had set a breakpoint. Observe the software and hardware (function) computed results in the Variables view.



Name	Type	Value
hw_result[0]	short [3]	0x28fec4
(x)= hw_result	short	870
(x)= hw_result	short	906
(x)= hw_result	short	942
hw_result[1]	short [3]	0x28feca
hw_result[2]	short [3]	0x28fed0
err_cnt	int	0
in_mat_b	char [3][3]	0x28fed6
sw_result	short [3][3]	0x28feb2
sw_result[0]	short [3]	0x28feb2
(x)= sw_result	short	870
(x)= sw_result	short	906
(x)= sw_result	short	942

Figure 11. Computed results

3-1-11. Set a breakpoint on line 134 (return err_cnt;), and click on the **Resume** button.

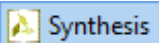
The execution will continue until the breakpoint is encountered. The console window will show the results as seen earlier (**Figure 7**).

3-1-12. Press the **Resume** button or **Terminate** button to finish the debugging session.

Synthesize the Design

Step 4

4-1. Switch to Synthesis view and synthesize the design with the defaults. View the synthesis results and answer the question listed in the detailed section of this step.

4-1-1. Switch to the Synthesis view by clicking  on the tools bar.

4-1-2. Select **Solution > Run C Synthesis > Active Solution** or click on the  button to start the synthesis process.

4-1-3. When synthesis is completed, the Synthesis Results will be displayed along with the Outline pane. Using the Outline pane, one can navigate to any part of the report with a simple click.

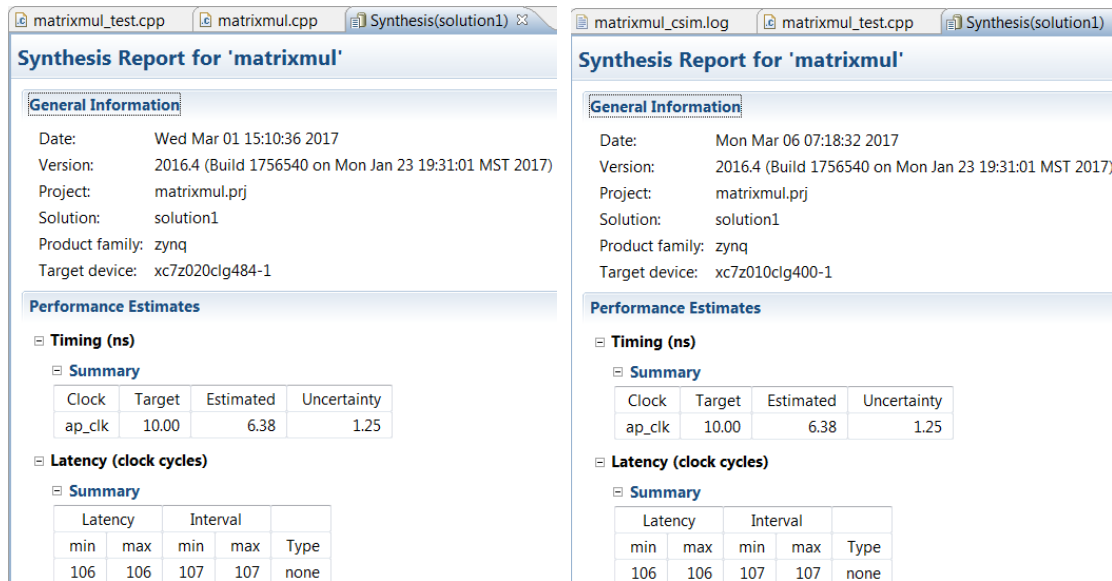


Figure 12. Report view after synthesis is completed

- 4-1-4. If you expand **solution1** in Explorer, several generated files including report files will become accessible.

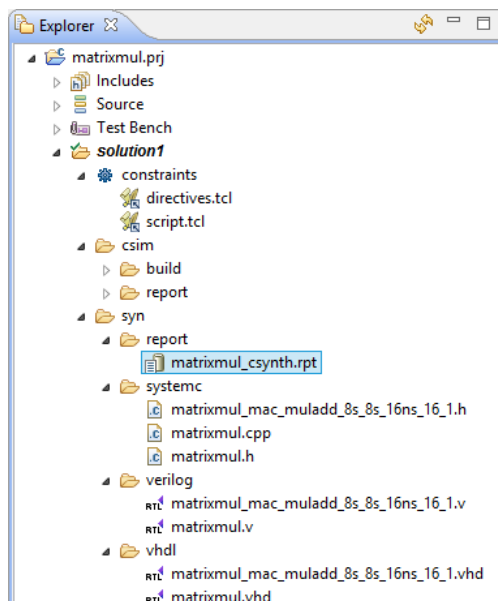


Figure 13. Explorer view after the synthesis process

Note that when the syn folder under the Solution1 folder is expanded in the Explorer view, it will show report, systemC, verilog, and vhd sub-folders under which report files, and generated source (vhd, verilog, header, and cpp) files. By double-clicking any of these entries will open the corresponding file in the information pane.

Also note that if the target design has hierarchical functions, reports corresponding to lower-level functions are also created.

- 4-1-5. The Synthesis Report shows the performance and resource estimates as well as estimated latency in the design.

4-1-6. Using scroll bar on the right, scroll down into the report and answer the following question.

Question 1

Estimated clock period: _____

Worst case latency: _____

Number of DSP48E used: _____

Number of FFs used: _____

Number of LUTs used: _____

4-1-7. The report also shows the top-level interface signals generated by the tools.

Interface					
Summary					
RTL Ports	Dir	Bits	Protocol	Source Object	C Type
ap_clk	in	1	ap_ctrl_hs	matrixmul	return value
ap_rst	in	1	ap_ctrl_hs	matrixmul	return value
ap_start	in	1	ap_ctrl_hs	matrixmul	return value
ap_done	out	1	ap_ctrl_hs	matrixmul	return value
ap_idle	out	1	ap_ctrl_hs	matrixmul	return value
ap_ready	out	1	ap_ctrl_hs	matrixmul	return value
a_address0	out	4	ap_memory	a	array
a_ce0	out	1	ap_memory	a	array
a_q0	in	8	ap_memory	a	array
b_address0	out	4	ap_memory	b	array
b_ce0	out	1	ap_memory	b	array
b_q0	in	8	ap_memory	b	array
res_address0	out	4	ap_memory	res	array
res_ce0	out	1	ap_memory	res	array
res_we0	out	1	ap_memory	res	array
res_d0	out	16	ap_memory	res	array

Figure 14. Generated interface signals

You can see ap_clk, ap_rst and ap_idle and ap_ready control signals are automatically added to the design by default. These signals are used as handshaking signals to indicate when the design is ready to begin the next computation command (ap_ready), when the next computation is started (ap_start), and when the computation is completed (ap_done). Other signals are generated based on the input and output signals in the design and their default or specified interfaces.

Analyze using Analysis Perspective

Step 5

5-1. Switch to the Analysis Perspective and understand the design behavior.

5-1-1. Select **Solution > Open Analysis Perspective** or click on ( Debug  Synthesis  Analysis) to open the analysis viewer.

The Analysis perspective consists of 5 panes as shown below. Note that the module and loops hierarchies are displayed unexpanded by default.

The Module Hierarchy pane shows both the performance and area information for the entire design and can be used to navigate through the hierarchy. The Performance Profile pane is visible and shows the performance details for this level of hierarchy. The information in these two panes is similar to the information reviewed earlier in the synthesis report.

The Performance view is also shown in the right-hand side pane. This view shows how the operations in this particular block are scheduled into clock cycles.

- The left-hand column lists the resources
- The top row lists the control states (c0 to c5) in the design. Control states are the internal states used by High-Level Synthesis to schedule operations into clock cycles. There is a close correlation between the control states and the final states in the RTL Finite State Machine(FSM) but there is no one-to-one mapping

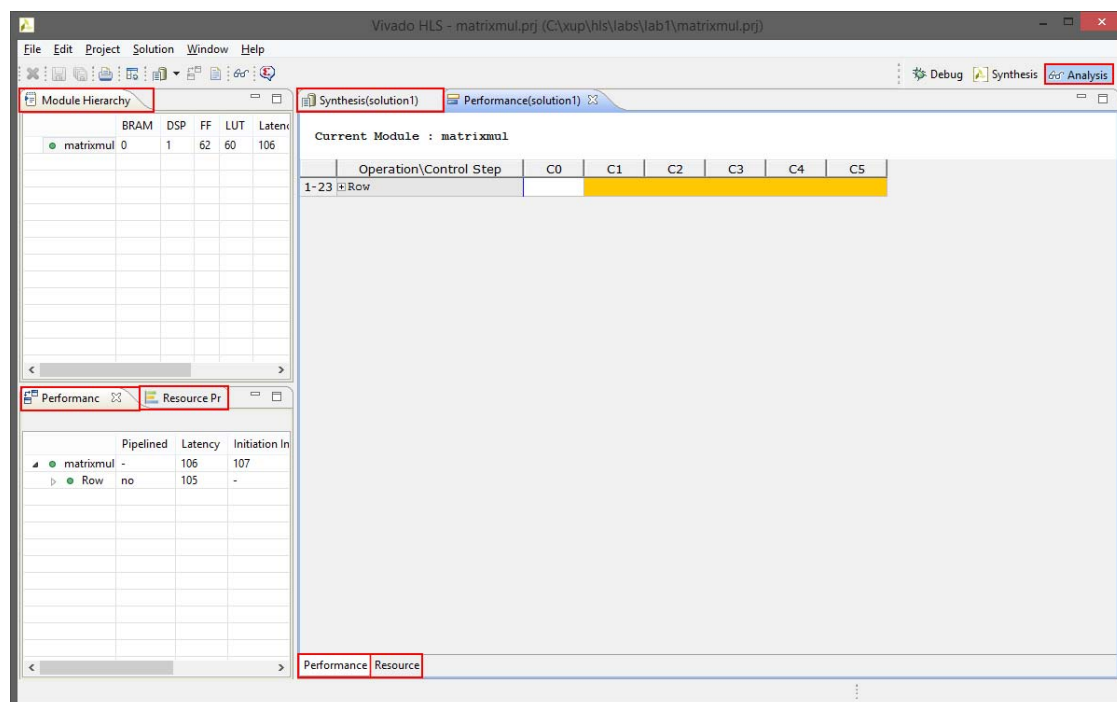


Figure 15. Analysis perspective

- 5-1-2.** Click on '+' of loop **Row** to expand, and then similarly click on sub-loops **Col** and **Product** to fully expand the loop hierarchy.

Current Module : matrixmul

	Operation\Control S...	C0	C1	C2	C3	C4	C5
1	Row						
2	i(phi mux)						
3	tmp 7(-)						
4	exitcond2(icmp)						
5	i 1(+)						
6	Col						
7	j(phi mux)						
8	tmp 8(+)						
9	exitcond1(icmp)						
10	j 1(+)						
11	Product						
12	res load(phi...						
13	k(phi mux)						
14	node 40(write)						
15	tmp 9(+)						
16	tmp 10(-)						
17	tmp 11(+)						
18	exitcond(icmp)						
19	k 1(+)						
20	a load(read)						
21	b load(read)						
22	tmp 2(*)						
23	tmp 3(+)						

Figure 16. Performance matrix showing top-level Row operation

From this we can see that in the first state (C1) of the Row the loop exit condition is checked and there is an add operation performed. This addition is likely the counter to count the loop iterations, and we can confirm this.

The operations resulting from the loops are colored yellow, the standard operations are colored purple, and sub-blocks will be colored green (in our case we don't have any lower-level functions).

- 5-1-3.** Select the purple block for the adder in state C1, right-click and select *Goto Source*.

The source code pane will be opened, highlighting line 75 where the *Row* loop index is being tested and incremented. In the next state (C2) it starts to execute the *Col* loop.

Current Module : matrixmul

Operation\Control S...	C0	C1	C2	C3	C4	C5
1 Row						
2 i(phi mux)						
3 tmp 7 (-)						
4 exitcond2(icmp)						
5 i 1(+)						
6 Col						
7 j(phi mux)						
8 tmp 8(+)						
9 exitcond1(icmp)						
10 j 1(+)						
11 Product						
12 res load(phi...						
13 k(phi mux)						
14 node 40(write)						
15 tmp 9(+)						
16 tmp 10(-)						
17 tmp 11(+)						
18 exitcond(icmp)						
19 k 1(+)						
20 a load(read)						
21 b load(read)						
22 tmp 2(*)						
23 tmp 3(+)						

Performance Resource

Properties Warnings C Source

File: C:\xup\hls\labs\lab1\matrixmul.cpp

```

73 {
74 // Iterate over the rows of the A matrix
75 Row: for(int i = 0; i < MAT_A_ROWS; i++) {
76 // Iterate over the columns of the B matrix
77 Col: for(int j = 0; j < MAT_B_COLS; j++) {
78 // Do the inner product of a row of A and col of B
79 res[i][j] = 0;
80 Product: for(int k = 0; k < MAT_B_ROWS; k++) {
81 res[i][j] += a[i][k] * b[k][j];
82 }
83 }
84 }

```

Figure 17. Cross probing into the source file

- 5-1-4. Click on the C2-8 purple cell in the **Col** loop to see the source code highlighting (line 79) update.
- 5-1-5. Expand the *Performance Profile* hierarchy and note iteration latencies, Trip counts, and overall latencies for each of the nested loops.

	Pipelined	Latency	Initiation Interval	Iteration Latency	Trip count
matrixmul	-	106	107	-	-
Row	no	105	-	35	3
Col	no	33	-	11	3
Product	no	9	-	3	3

Figure 18. The Performance Profile output

The number of iterations can also be noted by holding the mouse over the loop in the Performance view (a dialog box shows the loop statistics).

11	Product			
12	res load(phi...			
13	k(phi mux)			
14	node 40(write)			
15	tmp 9(+)			
16	tmp 10(-)			
17	tmp 11(+)			
18	exitcond(icmp)			
19	k 1(+)			
20	a load(read)			
21	b load(read)			

Property	Value
Pipelined:	no
Latency:	9
Initiation Interval:	-
Iteration Latency:	3
Trip count:	3

Figure 19. Loop information

Note that the initiation interval does not have a number as this loop is not pipelined.

- 5-1-6.** Click next to the *matrixmul* entry in the **Module Hierarchy** and observe that the entry is not expanded, since there are no lower-level functions defined in the design.
- 5-1-7.** Select the **Resource Profile** tab and observe various resources and where they have been used. You can expand Expressions and Registers sections to see how the resources are being used by which operations.

	BRAM	DSP	FF	LUT	Bits P0	Bits P1
matrixmul	0	0	61	51		
I/O Ports(3)					32	
Instances(0)	0	0	0	0		
Memories(0)	0		0	0	0	
Expressions(11)	0	0	0	28	37	34
Registers(13)			61		64	
Channels(0)	0		0	0	0	
Multiplexers(5)	0		0	23	23	

Figure 20. The Resource Profile tab view

- 5-1-8.** In the *Performance Matrix* tab, select the **Resource** tab (at the bottom of the page), and expand **Expressions**, **I/O Ports**, and **Memory Ports** entries to view the type of operations, resources used, and in which state they are being used.

Current Module : matrixmul

	Resource\Control Step	C0	C1	C2	C3	C4	C5
1	I/O Ports						
2	a(p0)				read		
3	b(p0)				read		
4	res(p0)				write		
5	Memory Ports						
6	b(p0)				read		
7	a(p0)				read		
8	res(p0)				write		
9	Expressions						
10	i 1 fu 149		+				
11	i phi fu 79		phi_mux				
12	tmp 7 fu 137		-				
13	exitcond2 fu 143		icmp				
14	j 1 fu 175			+			
15	tmp 8 fu 159			+			
16	j phi fu 90			phi_mux			
17	exitcond1 fu 169			icmp			
18	tmp 11 fu 213				+		
19	tmp 9 fu 185				+		
20	k 1 fu 229				+		
21	k phi fu 114				phi_mux		
22	res load phi f...				phi_mux		
23	tmp 10 fu 207				-		
24	exitcond fu 223				icmp		
25	grp fu 241						+

Performance Resource

Figure 21. The Resource tab

5-1-9. Click on the **Synthesis** tool bar button to switch back to the Synthesis view.

Run C/RTL Co-simulation

Step 6

6-1. Run the C/RTL Co-simulation with the default settings of VHDL. Verify that the simulation passes.

6-1-1. Select **Solution > Run C/RTL Cosimulation** or if you are in the synthesis view, click on the ☒ toolbar button to open the dialog box so the desired simulations can be selected and run.

A C/RTL Co-simulation Dialog box will open.

6-1-2. Make sure the **VHDL** option is selected.

This allows the simulation to be performed using VHDL. To perform the verification using Verilog, you can select Verilog and choose the simulator from the drop-down menu or let the tools use the first simulator that appears in the PATH variable.

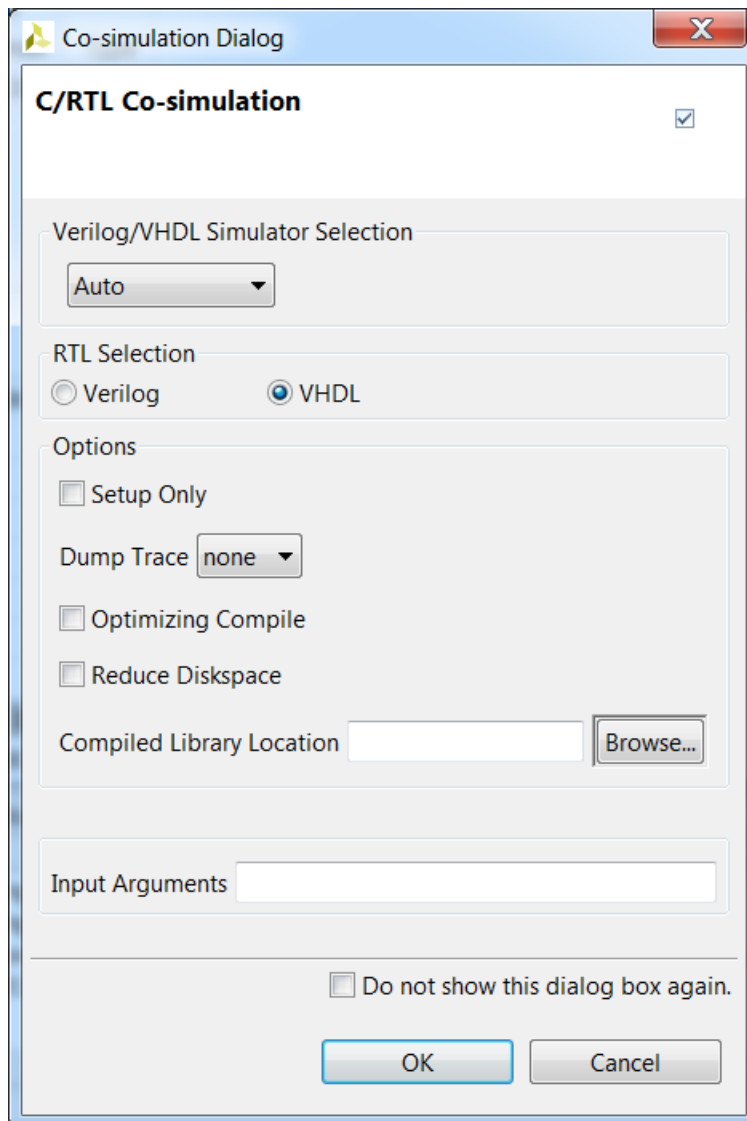


Figure 22. A C/RTL Co-simulation Dialog

6-1-3. Click **OK** to run the VHDL simulation.

The C/RTL Co-simulation will run, generating and compiling several files, and then simulating the design. It goes through three stages.

- First, the VHDL test bench is executed to generate input stimuli for the RTL design
- Second, an RTL test bench with newly generated input stimuli is created and the RTL simulation is then performed
- Finally, the output from the RTL is re-applied to the VHDL test bench to check the results

In the console window you can see the progress and also a message that the test is passed. This eliminates writing a separate testbench for the synthesized design.

```

Starting C/RTL cosimulation ...
C:/Xilinx/Vivado_HLS/2016.4/bin/vivado_hls.bat C:/xup/hls/labs/lab1/matrixmul.prj/solution1/cosim.tcl
INFO: [HLS 200-10] Running 'C:/Xilinx/Vivado_HLS/2016.4/bin/unwrapped/win64.o/vivado_hls.exe'
INFO: [HLS 200-10] For user 'parimalp' on host 'xsjparimalp31' (Windows NT_amd64 version 6.1) on Wed
INFO: [HLS 200-10] In directory 'C:/xup/hls/labs/lab1'
INFO: [HLS 200-10] Opening project 'C:/xup/hls/labs/lab1/matrixmul.prj'.
INFO: [HLS 200-10] Opening solution 'C:/xup/hls/labs/lab1/matrixmul.prj/solution1'.
INFO: [SYN 201-201] Setting up clock 'default' with a period of 10ns.
INFO: [HLS 200-10] Setting target device to 'xc7z020clg484-1'
INFO: [COSIM 212-47] Using XSIM for RTL simulation.
INFO: [COSIM 212-14] Instrumenting C test bench ...
    Build using "C:/Xilinx/Vivado_HLS/2016.4/msys/bin/g++.exe"
    Compiling apatb_matrixmul.cpp
    Compiling matrixmul.cpp_pre.cpp.tb.cpp
    Compiling matrixmul_test.cpp_pre.cpp.tb.cpp
    Generating cosim.tv.exe
INFO: [COSIM 212-302] Starting C TB testing ...
{
{870,906,942}
{1086,1131,1176}
{1302,1356,1410}
}
Test passed.

***** xsim v2016.4 (64-bit)
***** SW Build 1756540 on Mon Jan 23 19:11:23 MST 2017
***** IP Build 1755317 on Mon Jan 23 20:30:07 MST 2017
** Copyright 1986-2016 Xilinx, Inc. All Rights Reserved.

source xsim.dir/matrixmul/xsim_script.tcl
# xsim {matrixmul} -autoloadwcfg -tclbatch {matrixmul.tcl}
Vivado Simulator 2016.4
Time resolution is 1 ps
source matrixmul.tcl
## run all
Note: simulation done!
Time: 1245 ns Iteration: 1 Process: /apatb_matrixmul_top/generate_sim_done_proc
Failure: NORMAL EXIT (note: failure is to force the simulator to stop)
Time: 1245 ns Iteration: 1 Process: /apatb_matrixmul_top/generate_sim_done_proc
$finish called at time : 1245 ns
## quit
INFO: [Common 17-206] Exiting xsim at Wed Mar 01 15:30:23 2017...
INFO: [COSIM 212-316] Starting C post checking ...
{
{870,906,942}
{1086,1131,1176}
{1302,1356,1410}
}
Test passed.
INFO: [COSIM 212-1000] *** C/RTL co-simulation finished: PASS ***
Finished C/RTL cosimulation.

```

Figure 23. Console view showing simulation progress

- 6-1-4.** Once the simulation verification is completed, the simulation report tab will open showing the results. The report indicates if the simulation passed or failed. In addition, the report indicates the measured latency and interval.

Since we have selected only VHDL, the result shows the latencies and interval (initiation) which indicates after how many clock cycles later the next input can be provided. Since the design is not pipelined, it will be latency+1 clock cycles.

Cosimulation Report for 'matrixmul'							
Result							
RTL	Status	Latency			Interval		
		min	avg	max	min	avg	max
VHDL	Pass	106	106	106	0	0	0
Verilog	NA	NA	NA	NA	NA	NA	NA

(a) ZedBoard

Cosimulation Report for 'matrixmul'							
Result							
RTL	Status	Latency			Interval		
		min	avg	max	min	avg	max
VHDL	Pass	106	106	106	0	0	0
Verilog	NA	NA	NA	NA	NA	NA	NA

(b) ZYBO

Figure 24. Co-simulation results

Viewing Simulation Results in Vivado

Step 7

7-1. Run Verilog simulation with Dump Trace option selected.

7-1-1. Select **Solution > Run C/RTL Co-simulation** or click on the ☒ button in the Synthesis view to open the dialog box so the desired simulations can be run.

7-1-2. Click on the **Verilog** RTL Selection option, leaving Verilog/VHDL Simulator Section option to *Auto*.

Optionally, you can click on the drop-down button and select the desired simulator from the available list of XSim, ISim, ModelSim, and Riviera.

7-1-3. Select *All* for the *Dump Trace* option and click **OK**.

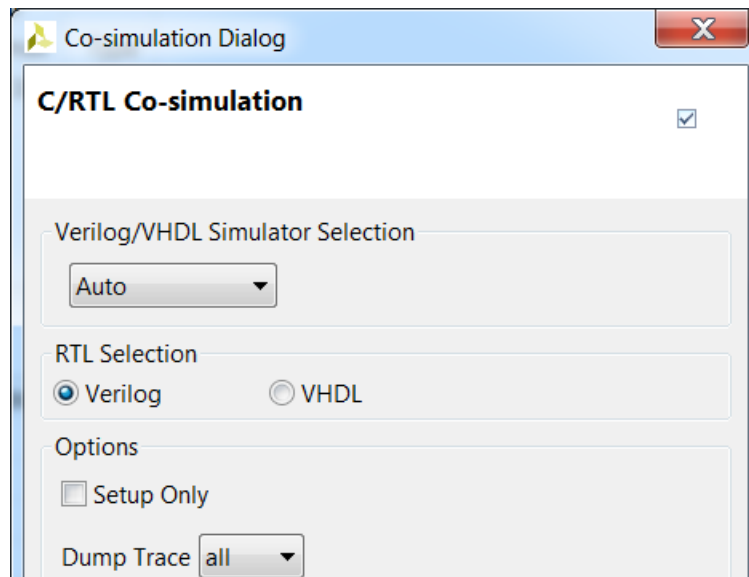


Figure 25. Setting up for Verilog simulation and dump trace

When RTL verification completes the co-simulation report automatically opens showing the Verilog simulation has passed (and the measured latency and interval). In addition, because the Dump Trace option was used and Verilog was selected, two trace files entries can be seen in the Verilog simulation directory

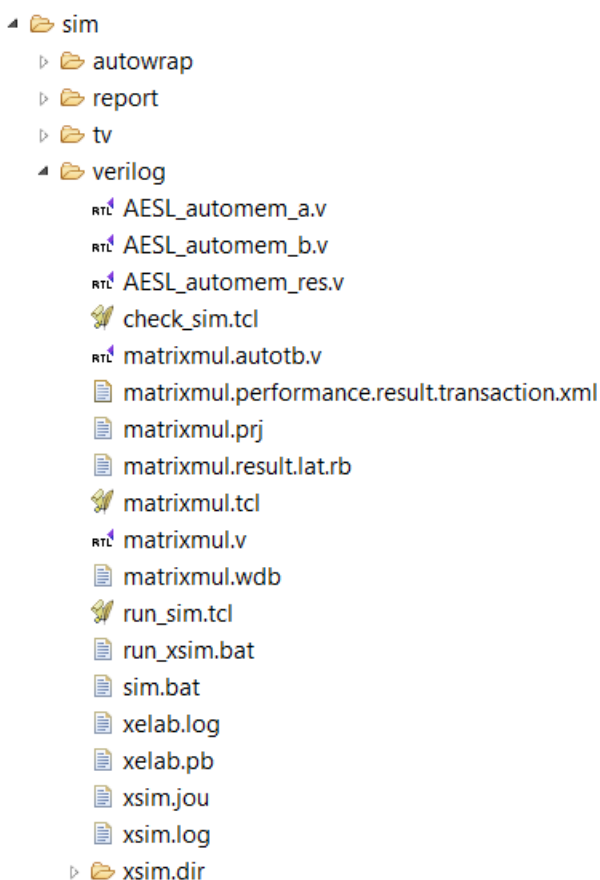


Figure 26. Explorer view after the Verilog RTL co-simulation run

The Co-simulation report shows the test was passed for Verilog along with latency and Interval results.

Cosimulation Report for 'matrixmul'

Result							
RTL	Status	Latency			Interval		
		min	avg	max	min	avg	max
VHDL	NA	106	106	106	0	0	0
Verilog	Pass	106	106	106	0	0	0

(a) ZedBoard


Cosimulation Report for 'matrixmul'

Result							
RTL	Status	Latency			Interval		
		min	avg	max	min	avg	max
VHDL	Pass	133	133	133	0	0	0
Verilog	Pass	133	133	133	0	0	0

(b) ZYBO

Figure 27. Cosimulation report

7-2. Analyze the dumped traces.

7-2-1. Click on the () button to open the wave viewer.

This will start Vivado 2016.4 and open the wave viewer.

7-2-2. In the waveform window, expand the Design Top Signals as needed.

7-2-3. Click on the full zoom tool button () to see the entire simulation of one iteration.

7-2-4. Select `a_address0` in the waveform window, right-click and select **Radix > Unsigned Decimal**. Similarly, do the same for `b_address0` and `res_address0` signals.

7-2-5. Similarly, set the `a_q0`, `b_q0`, and `res_d0` radix to **Signed Decimal**.

You should see the output similar to shown below.

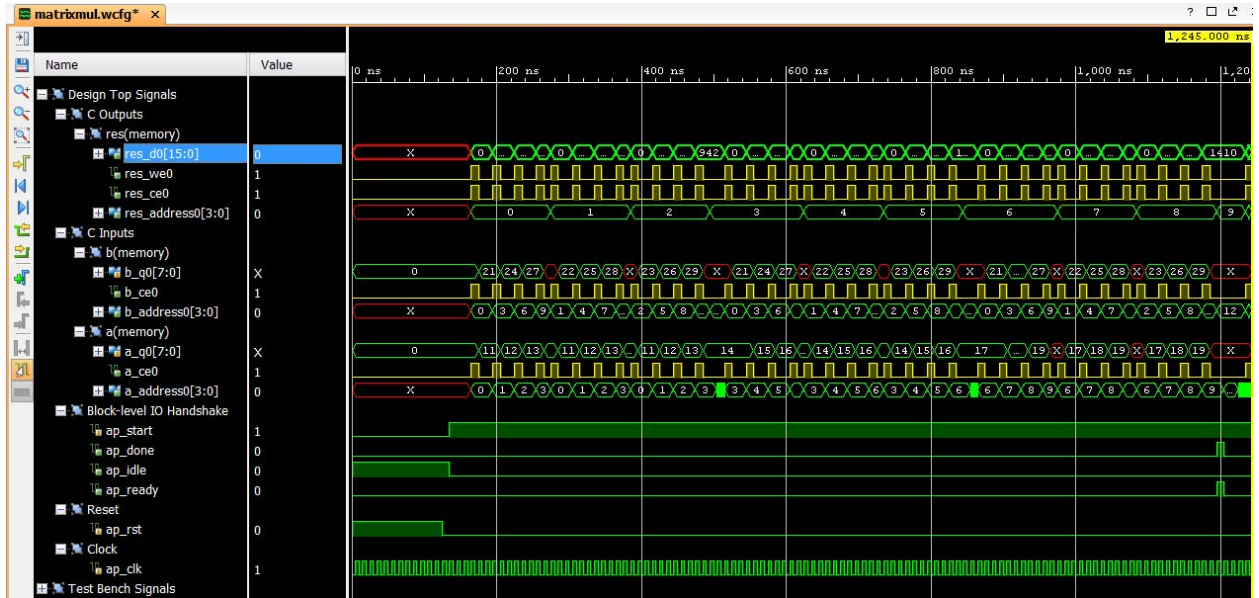


Figure 28. Full waveform showing iteration worth simulation

Note that as soon as `ap_start` is asserted, `ap_idle` has been de-asserted indicating that the design is in computation mode. The `ap_idle` signal remains de-asserted until `ap_done` is asserted, indicating completion of the process. This indicates 106 clock cycles latency.

7-2-6. Using the Zoom In button, view area of ~120 ns and ~550 ns.

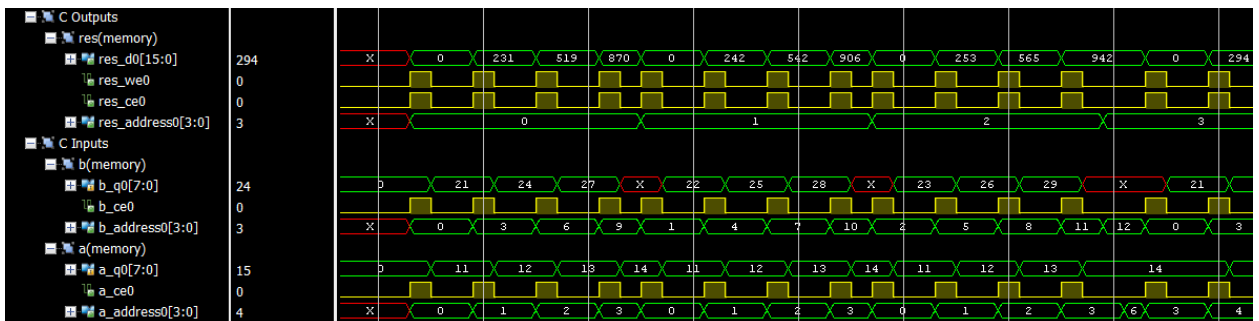


Figure 29. Zoomed view

Observe that the design expects element data by providing `a_address0`, `a_ce0`, `b_address0`, `b_ce0` signals and outputs result using `res_d0`, `res_we0`, and `res_ce0`.

7-2-7. View various part of the simulation and try to understand how the design works.

7-2-8. When done, close Vivado by selecting **File > Exit**. Click **OK** if prompted, and then **Discard** to close the program without saving.

Export RTL and Implement

Step 8

8-1. In Vivado HLS, export the design, selecting VHDL as a language, and run the implementation by selecting Evaluate option.

8-1-1. In Vivado-HLS, select **Solution > Export RTL** or click on the  button to open the dialog box so the desired implementation can be run.

An Export RTL Dialog box will open.

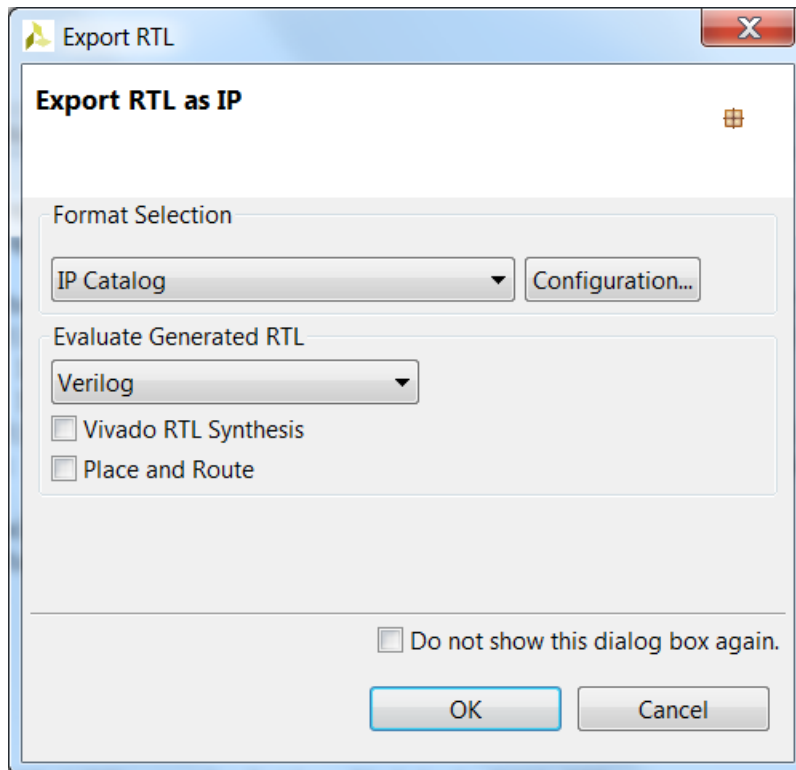


Figure 30. A Export RTL Dialog box

With default settings (shown above), the IP packaging process will run and create a package for the Vivado IP Catalog. Another option available from the Format Selection drop-down menu, is to create System Generator for DSP.

8-1-2. Click on the drop-down menu of the **Evaluate Generated RTL** field and select **VHDL**.

8-1-3. Click on the *Vivado RTL Synthesis* and *Place and Route* check boxes to run the implementation tool.

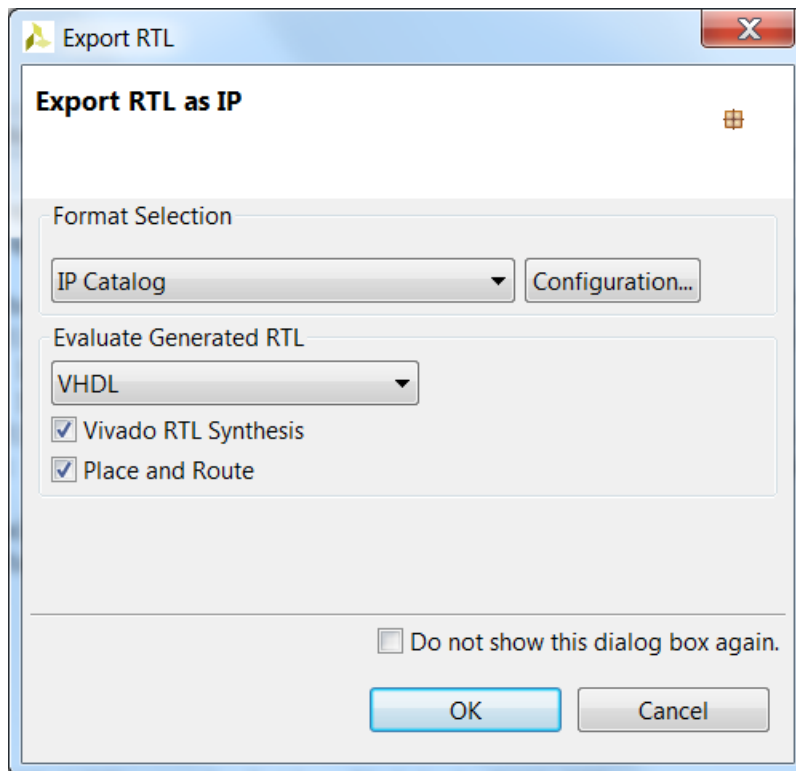


Figure 31. Selecting Evaluate options

8-1-4. Click **OK** and the implementation run will begin.

You can observe the progress in the Vivado HLS Console window. It goes through several phases:

- Exporting RTL as an IP in the IP-XACT format
- RTL evaluation, since we selected Evaluate option
 - Goes through Synthesis
 - Goes through Placement and Routing

```

Starting export RTL ...
C:/Xilinx/Vivado_HLS/2016.4/bin/vivado_hls.bat C:/xup/hls/labs/lab1/matrixmul.prj/solution1/export.tcl
INFO: [HLS 200-10] Running 'C:/Xilinx/Vivado_HLS/2016.4/bin/unwrapped/win64.o/vivado_hls.exe'
INFO: [HLS 200-10] For user 'parimalp' on host 'xsjparimalp31' (Windows NT_amd64 version 6.1) on Wed Mar 01 16:26:42 2017
INFO: [HLS 200-10] In directory 'C:/xup/hls/labs/lab1'
INFO: [HLS 200-10] Opening project 'C:/xup/hls/labs/lab1/matrixmul.prj'.
INFO: [HLS 200-10] Opening solution 'C:/xup/hls/labs/lab1/matrixmul.prj/solution1'.
INFO: [SYN 201-201] Setting up clock 'default' with a period of 10ns.
INFO: [HLS 200-10] Setting target device to 'xc7z020clg484-1'
INFO: [IMPL 213-8] Exporting RTL as an IP in IP-XACT.

***** Vivado v2016.4 (64-bit)
**** SW Build 1756540 on Mon Jan 23 19:11:23 MST 2017
**** IP Build 1755317 on Mon Jan 23 20:30:07 MST 2017
** Copyright 1986-2016 Xilinx, Inc. All Rights Reserved.

source matrixmul.tcl -notrace
Command: synth_design -top matrixmul -part xc7z020clg484-1 -no_iobuf -mode out_of_context
Starting synth_design
Attempting to get a license for feature 'Synthesis' and/or device 'xc7z020'
INFO: [Common 17-349] Got license for feature 'Synthesis' and/or device 'xc7z020'
INFO: Launching helper process for spawning children vivado processes
INFO: Helper process launched with PID 11992
-----|-----
Starting RTL Elaboration : Time (s): cpu = 00:00:05 ; elapsed = 00:00:07 . Memory (MB): peak = 305.219 ; gain = 94.785
-----|-----
INFO: [Synth 8-638] synthesizing module 'matrixmul' [C:/xup/hls/labs/lab1/matrixmul.prj/solution1/impl/vhdl/matrixmul.v]
INFO: [Synth 8-5534] Detected attribute (* fsm encoding = "none" *) [C:/xup/hls/labs/lab1/matrixmul.prj/solution1/impl/

Implementation tool: Xilinx Vivado v.2016.4
Project:                matrixmul.prj
Solution:               solution1
Device target:          xc7z020clg484-1
Report date:            Wed Mar 01 16:26:42 -0800 2017

#=== Post-Implementation Resource usage ===
SLICE:                  9
LUT:                    31
FF:                     27
DSP:                    1
BRAM:                   0
SRL:                    0
#=== Final timing ===
CP required:            10.000
CP achieved post-synthesis:    3.019
CP achieved post-implemetation:  3.703
Timing met
INFO: [Common 17-206] Exiting Vivado at Wed Mar 01 16:26:42 2017...
Finished export RTL.

```

Figure 32. Console view

When the run is completed the implementation report will be displayed in the information pane.

Export Report for 'matrixmul'**General Information**

Report date: Wed Mar 01 16:26:41 -C
 Project: matrixmul.prj
 Solution: solution1
 Device target: xc7z020clg484-1
 Implementation tool: Xilinx Vivado v.2016.4

Resource Usage

	VHDL
SLICE	9
LUT	31
FF	27
DSP	1
BRAM	0
SRL	0

Final Timing

	VHDL
CP required	10.000
CP achieved post-synthesis	3.019
CP achieved post-implementation	3.703

Timing met

(a) ZedBoard**Export Report for 'matrixmul'****General Information**

Report date: Mon Mar 06 07:46:46 -0
 Project: matrixmul.prj
 Solution: solution1
 Device target: xc7z010clg400-1
 Implementation tool: Xilinx Vivado v.2016.4

Resource Usage

	VHDL
SLICE	9
LUT	30
FF	27
DSP	1
BRAM	0
SRL	0

Final Timing

	VHDL
CP required	10.000
CP achieved post-synthesis	3.019
CP achieved post-implementation	3.704

Timing met

(b) ZYBO

Figure 33. Implementation results in Vivado HLS (Zedboard and Zybo)

Observe that the timing constraint was met, the achieved period (3.703 [ZedBoard], 3.704 [Zybo] ns), and the type and amount of resources used.

- 8-1-5.** Collapse the Explorer view and observe that impl folder is created under which ip, report, Verilog, and vhdh sub-folders are created.

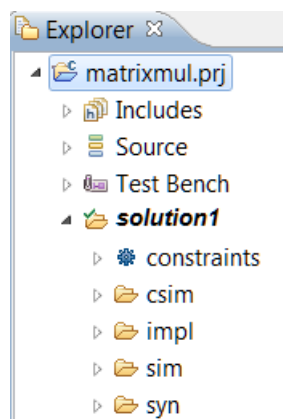


Figure 34. Explorer view after the RTL Export run

- 8-1-6.** Expand the Verilog and vhdl sub-folders and observe that the Verilog sub-folder only has the rtl file whereas the vhdl sub-folder has several files and sub-folders as the synthesis and implementation runs were made for it.

It includes project.xpr file (the Vivado project file), matrixmul.xdc file (timing constraint file), project.runs folder (which includes synth_1 and impl_1 sub-folders created by the synthesis and implementation runs) among others.

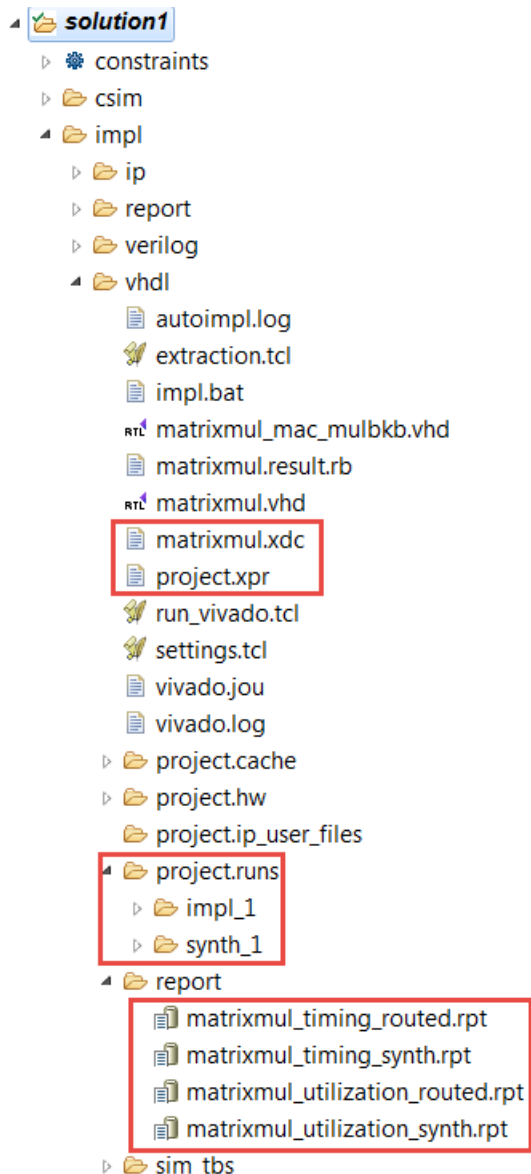


Figure 35. The implementation directory

- 8-1-7.** Expand the ip folder and observe the IP packaged as a zip file (xilinx_com_hls_matrixmul_1_0.zip), ready for adding to the Vivado IP catalog.

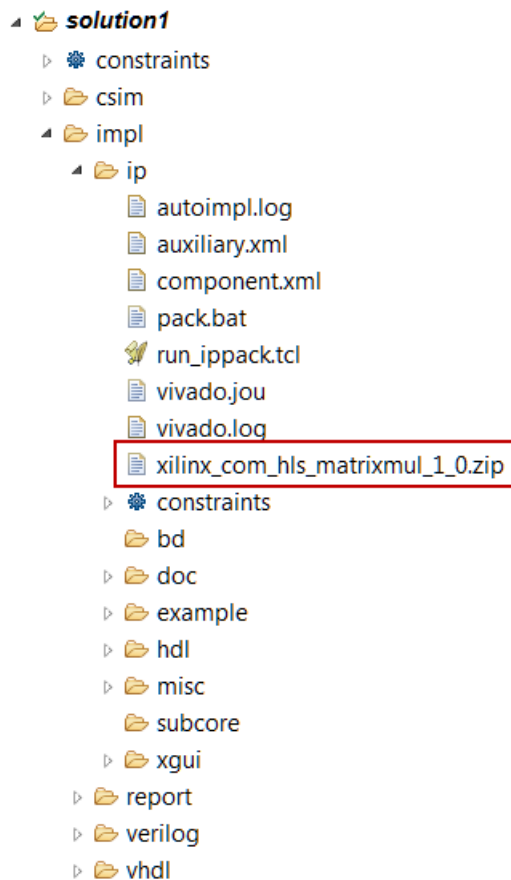


Figure 36. The ip folder content

8-1-8. Close Vivado HLS by selecting **File > Exit**.

Conclusion

In this lab, you completed the major steps of the high-level synthesis design flow using Vivado HLS. You created a project, adding source files, synthesized the design, simulated the design, and implemented the design. You also learned how to use the Analysis capability to understand the scheduling and binding.

Answers

1. Answer the following questions:

Estimated clock period:	<u>6.38 ns</u>
Worst case latency:	<u>106 clock cycles</u>
Number of DSP48E used:	<u>1</u>
Number of FFs used:	<u>61</u>
Number of LUTs used:	<u>52</u>