

Example Exercise 2-7

1. To create a class, use the keyword `class`, and create a class named *Droid*, with a property named *myName*. Next using the class *Droid*, create an object named *p1*, and print the value of *myName*:

```
Week 1 Assignemnt > lab.py > ...
1  class Droid:
2      myName = 'R2D22'
3  p1 = Droid()
4  print(p1.myName)
5

PROBLEMS  OUTPUT  DEBUG CONSOLE  TERMINAL  PORTS  COMMENTS

PS C:\Users\mcmur\Desktop\sdn> & C:/Users/mcmur/AppData/Local/Microsoft/WindowsAp
R2D22
PS C:\Users\mcmur\Desktop\sdn> []
```

2. Example Exercise Create a class named *Droid*, use the `__init__()` function to assign values for name and age:

```
example2.py X
Week 1 Assignemnt > example2.py > Droid > __init__
1  class Droid:
2      def __init__(self,name,age):
3          self.name = name
4          self.age = age
5  p1 = Droid('R2D2', 5)
6
7  print(p1.name+"s age is "+ str(p1.age))

PROBLEMS  OUTPUT  DEBUG CONSOLE  TERMINAL  PORTS  COMMENTS

PS C:\Users\mcmur\Desktop\sdn> & C:/Users/mcmur/AppData/Local/Microsoft/WindowsApps
R2D2's age is 5
PS C:\Users\mcmur\Desktop\sdn>
```

3. Example Exercise

```
example3.py X
Week 1 Assignemnt > example3.py > ...
1  class Person:
2
3      def __init__(self, first_name, last_name, age):
4
5          self.first_name = first_name
6          self.last_name = last_name
7          self.age = age
8
9  class Candidate(Person):
10
11      def __init__(self, first_name, last_name, age, qualification):
12
13          Person.__init__(self, first_name, last_name, age)
14          self.qualification = qualification
15
16  candidate1 = Candidate('Vishal', 'Verma', 30, 'Masters')
17  candidate2 = Candidate('Vandana', 'Verma', 25, 'Bachelors')
18
19  print("candidate1 is an instance of {}".format(type(candidate1)))
20  print("candidate2 is an instance of {}".format(type(candidate2)))
21
22  print("{}'s qualification is {}".format(candidate1.first_name, candidate1.qualification))
23  print("{}'s qualification is {}".format(candidate2.first_name, candidate2.qualification))
24
25

PROBLEMS  OUTPUT  DEBUG CONSOLE  TERMINAL  PORTS  COMMENTS
PS C:\Users\mcmur\Desktop\sdn> & C:/Users/mcmur/AppData/Local/Microsoft/WindowsApps/python3.11.exe "c:/Users/mcmur/Desktop/sdn/Week 1 Assignemnt/example3.py"
candidate1 is an instance of <class '__main__.Candidate'>
candidate2 is an instance of <class '__main__.Candidate'>
Vishal's qualification is Masters
Vandana's qualification is Bachelors
PS C:\Users\mcmur\Desktop\sdn>
```

4. Example Exercise

```
example4.py X
Week 1 Assignment > example4.py > Droid > turn
1 from math import sin, cos, radians
2
3 class Droid:
4     # Create a class
5     def __init__(self, name, pos):
6         # The class takes a name as a parameter
7         self.name = name
8         self.pos = pos # Position as list of coordinates [x, y]
9         self.head = radians(0) # Angle
10
11     def turn(self, rotation):
12         # Rotate left or right
13         if rotation == 'R': # Rotate right
14             self.head -= radians(90) # Turn 90 right
15         elif rotation == 'L': # Rotate left
16             self.head += radians(90) # Turn 90 left
17
18     def move(self, step):
19         # Step forward or backward
20         if step == 'F': # Move forward by 1 step
21             self.pos[0] = self.pos[0] + round(cos(self.head))
22             self.pos[1] = self.pos[1] + round(sin(self.head))
23         elif step == 'B': # Move backward
24             self.pos[0] = self.pos[0] + round(cos(self.head - radians(180)))
25             self.pos[1] = self.pos[1] + round(sin(self.head - radians(180)))
26
27     def current_pos(self):
28         # Return the current position
29         return self.pos
30
31 def main():
32     r2d2 = Droid('r2d2', [0, 0]) # Creating a Droid named 'r2d2'
33     marvin = Droid('marvin', [1, 1]) # Creating a Droid named 'marvin'
34     c3po = Droid('c3po', [3, 1]) # Creating a Droid named 'c3po'
35
36     r2d2.move('F')
37     r2d2.move('B')
38     r2d2.turn('R')
39     r2d2.move('F')
40     r2d2.turn('L')
41     r2d2.move('B')
42
43     print(r2d2.current_pos())
44     print(marvin.current_pos())
45
46 # Call the function main()
47 if __name__ == '__main__':
48     main()
Python X
PS C:\Users\mcmur\Desktop\sdn> & C:\Users\mcmur\AppData\Local\Microsoft\WindowsApps\python3.11.exe "c:/Users/mcmur/Desktop/sdn/week 1 Assignment/example4.py"
[-1, -1]
[1, 1]
PS C:\Users\mcmur\Desktop\sdn>

example4.py X example4-2.py X
Week 1 Assignment > example4-2.py > Droid > turn
1 from math import sin, cos, radians
2
3 class Droid:
4     # Create a class
5     def __init__(self, name, pos):
6         # The class takes a name as a parameter
7         self.name = name
8         self.pos = pos # Position as list of coordinates [x, y]
9         self.head = radians(0) # Angle
10
11     def turn(self, rotation):
12         # Rotate left or right
13         if rotation == 'R': # Rotate right
14             self.head -= radians(90) # Turn 90 right
15         elif rotation == 'L': # Rotate left
16             self.head += radians(90) # Turn 90 left
17
18     def move(self, step):
19         # Step forward or backward
20         if step == 'F': # Move forward by 1 step
21             self.pos[0] = self.pos[0] + round(cos(self.head))
22             self.pos[1] = self.pos[1] + round(sin(self.head))
23         elif step == 'B': # Move backward
24             self.pos[0] = self.pos[0] + round(cos(self.head - radians(180)))
25             self.pos[1] = self.pos[1] + round(sin(self.head - radians(180)))
26
27     def current_pos(self):
28         # Return the current position
29         return self.pos
30
31 class Marvin(Droid):
32     def __init__(self):
33         self.eyes = 2
34         self.arms = 2
35         self.legs = 2
36         Droid.__init__(self, 'marvin1', [2, 3]) # Inheriting from parent class
37
38 def main():
39     r2d2 = Droid('r2d2', [0, 0]) # Creating an object with name argument as 'r2d2'
40     marvin = Droid('marvin', [1, 1])
41     marvin1 = Marvin()
42     print(marvin1.current_pos())
43     marvin1.turn('R')
44     marvin1.move('F')
45     print(marvin1.current_pos())
46     print(marvin1.legs)
47     print(r2d2.current_pos())
48
49 # Call the function main()
50 if __name__ == '__main__':
51     main()
Python X
PS C:\Users\mcmur\Desktop\sdn> & C:\Users\mcmur\AppData\Local\Microsoft\WindowsApps\python3.11.exe "c:/Users/mcmur/Desktop/sdn/week 1 Assignment/example4-2.py"
[2, 3]
[2, 2]
2
[0, 0]
PS C:\Users\mcmur\Desktop\sdn>
```

Exercise-3.1: Printing your machine's name and IPv4 address

The screenshot shows a VS Code editor with a file named `localMachineInfo.py`. The script uses the `socket` module to retrieve the local machine's hostname and IP address. The terminal output shows the script being executed from a command prompt, resulting in the following information:

```
PS C:\Users\mcmur\Desktop\sdn> & C:\Users\mcmur\AppData\Local\Microsoft\WindowsApps\python3.11.exe c:\Users\mcmur\Desktop\sdn\localMachineInfo.py
Host name: MCMURDOGTX
IP address: 172.19.122.104
PS C:\Users\mcmur\Desktop\sdn>
```

Below the terminal, a separate window titled "Command Prompt" displays detailed network configuration information:

```
Link-local IPv6 Address . . . . . : fe80::6a9e:aa36:df0c:c163%17(Preferred)
IPv4 Address. . . . . : 172.19.122.104(Preferred)
Subnet Mask . . . . . : 255.255.254.0
Lease Obtained. . . . . : 26 February 2025 09:01:56
Lease Expires . . . . . : 26 February 2025 11:14:59
Default Gateway . . . . . : 172.19.122.1
DHCP Server . . . . . : 10.221.166.10
DHCPv6 IAID . . . . . : 167128213
DHCPv6 Client DUID. . . . . : 00-01-00-01-2E-27-89-40-FC-34-97-4B-6A-99
DNS Servers . . . . . : 138.25.16.8
```

Exercise-3.2: Retrieving a remote machine's IP address

The screenshot shows a VS Code editor with a file named `remoteMachineInfo.py`. The script uses the `socket` module to retrieve the IP addresses of two remote hosts: `www.python.org` and `www.uts.edu.au`. The terminal output shows the script being executed from a command prompt, resulting in the following information:

```
PS C:\Users\mcmur\Desktop\sdn> python.exe .\remoteMachineInfo.py
Remote host name: www.python.org
IP address: 151.101.0.223
Remote host name: www.uts.edu.au
IP address: 23.40.52.5
PS C:\Users\mcmur\Desktop\sdn>
```

Exercise-3.3: Converting an IPv4 address to different formats

Create and save python script as `ip4AddressConversion.py`

```

ip4AddressConversion.py X
Week 1 Assignemnt > ip4AddressConversion.py > ...
1 import socket
2 from binascii import hexlify
3
4 def convert_ip4_address():
5     for ip_addr in ['127.0.0.1', '192.168.0.1']:
6         packed_ip_addr = socket.inet_aton(ip_addr)
7         unpacked_ip_addr = socket.inet_ntoa(packed_ip_addr)
8         print("IP Address: %s => Packed: %s, Unpacked: %s" %(ip_addr, hexlify(packed_ip_addr), unpacked_ip_addr))
9 if __name__ == '__main__':
10     convert_ip4_address()

```

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```

PS C:\Users\mcmur\Desktop> & C:/Users/mcmur/AppData/Local/Microsoft/WindowsApps/python3.11.exe "c:/Users/mcmur/Desktop/sdn/Week 1 Assignemnt/ip4AddressConversion.py"
IP Address: 127.0.0.1 => Packed: b'7f000001', Unpacked: 127.0.0.1
IP Address: 192.168.0.1 => Packed: b'c0a80001', Unpacked: 192.168.0.1
PS C:\Users\mcmur\Desktop>

```

binascii converts between binary data and various ASCII-encoded binary representations, enabling tasks like hexadecimal encoding and checksum calculations. It bridges the gap between raw binary data and text-based formats.

Exercise-3.4: Finding a service name, given the port and protocol

```

findingServiceName.py X
Week 1 Assignemnt > findingServiceName.py > ...
1 import socket
2
3 def find_service_name():
4     protocolname = 'tcp'
5     for port in [80, 25]:
6         print("Port: %s => service name: %s" %(port, socket.getservbyport(port, protocolname)))
7     print("Port: %s => service name: %s" %(53, socket.getservbyport(53, 'udp')))
8
9 if __name__ == '__main__':
10     find_service_name()

```

PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL PORTS COMMENTS

```

PS C:\Users\mcmur\Desktop> & C:/Users/mcmur/AppData/Local/Microsoft/WindowsApps/python3.11.exe "c:/Users/mcmur/Desktop/sdn/Week 1 Assignemnt/FindingServiceName.py"
Port: 80 => service name: http
Port: 25 => service name: smtp
Port: 53 => service name: domain
PS C:\Users\mcmur\Desktop>

```

Modify the code to complete the table:

Port	Protocol Name
21	FTP
22	SSH
110	Pop3

```

findingServiceName.py X findingServiceName2.py X
Week 1 Assignemnt > findingServiceName2.py > ...
1 import socket
2
3 def find_service_name():
4     protocolname = 'tcp'
5     for port in [21, 22, 110]:
6         print("Port: %s => service name: %s" %(port, socket.getservbyport(port, protocolname)))
7
8 if __name__ == '__main__':
9     find_service_name()

```

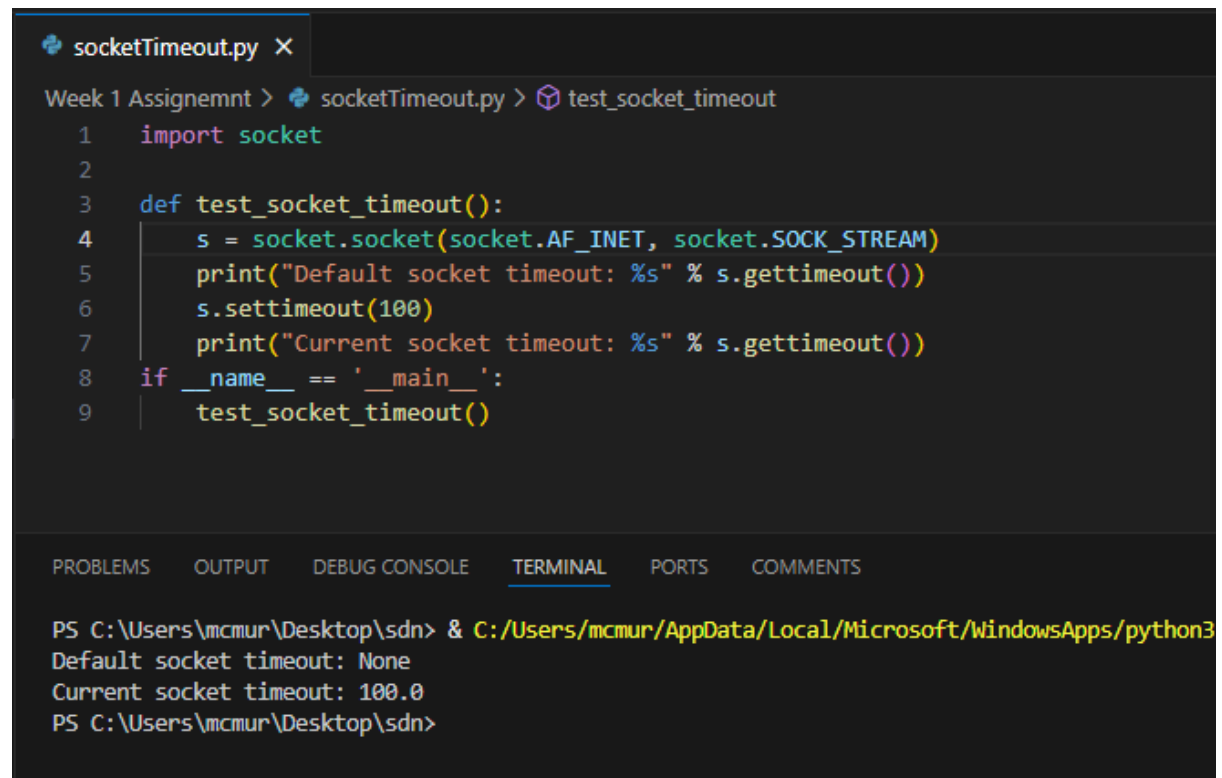
PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL PORTS COMMENTS

```

PS C:\Users\mcmur\Desktop> & C:/Users/mcmur/AppData/Local/Microsoft/WindowsApps/python3.11.exe "c:/Users/mcmur/Desktop/sdn/findingServiceName2.py"
Port: 21 => service name: ftp
Port: 22 => service name: ssh
Port: 110 => service name: pop3
PS C:\Users\mcmur\Desktop>

```

Exercise-3.5: Setting and getting the default socket timeout



The screenshot shows a code editor with a file named `socketTimeout.py`. The code defines a function `test_socket_timeout()` that creates a socket, prints its default timeout, sets it to 100, and prints the new timeout. The script is executed from a terminal window, showing the output of the function.

```
socketTimeout.py X
Week 1 Assignemnt > socketTimeout.py > test_socket_timeout
1 import socket
2
3 def test_socket_timeout():
4     s = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
5     print("Default socket timeout: %s" % s.gettimeout())
6     s.settimeout(100)
7     print("Current socket timeout: %s" % s.gettimeout())
8 if __name__ == '__main__':
9     test_socket_timeout()

PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL PORTS COMMENTS

PS C:\Users\mcmur\Desktop\sdn> & C:/Users/mcmur/AppData/Local/Microsoft/WindowsApps/python3
Default socket timeout: None
Current socket timeout: 100.0
PS C:\Users\mcmur\Desktop\sdn>
```

what is the role of socket timeout in real applications?

A socket timeout in network programming sets a time limit for operations like connecting, sending, or receiving data. If the operation exceeds this limit, it is aborted, preventing the program from hanging indefinitely.