

CS - S12 COMPUTER VISION

# ANOMALY-DRIVEN VIDEO SUMMARIZATION FOR REAL-TIME SURVEILLANCE SYSTEMS

PROJECT PROPOSAL

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# OBJECTIVE

OUR PROJECT FOCUSES ON OPTIMIZING SURVEILLANCE VIDEO PROCESSING BY AUTOMATICALLY DETECTING AND SUMMARIZING ANOMALOUS EVENTS. THIS APPROACH REDUCES THE NEED FOR MANUAL VIDEO REVIEW, ENABLING QUICKER THREAT IDENTIFICATION AND EFFICIENT STORAGE MANAGEMENT.

# PROBLEM STATEMENT

SURVEILLANCE SYSTEMS GENERATE MASSIVE AMOUNTS OF FOOTAGE, MOSTLY STORED PASSIVELY, WHICH IS INEFFICIENT FOR MONITORING AND DIFFICULT TO ANALYZE IN REAL TIME. MANUAL REVIEW OF SUCH DATA IS LABOR-INTENSIVE, PRONE TO ERRORS, AND SLOW, PARTICULARLY WHEN SEARCHING FOR SPECIFIC ANOMALOUS EVENTS.

# PROJECT OVERVIEW

Our project, "Anomaly-Driven Video Summarization for Real-Time Surveillance Systems," aims to enhance the efficiency of surveillance monitoring by automatically detecting anomalies in video footage and summarizing relevant segments.

Our approach segments videos into smaller portions, extracts spatial and temporal features using deep learning models (C3D and 3D ResNet), and applies a modified loss function to improve anomaly localization.

Using datasets like UFC-Crime, UBNormal, and UBI-Flights, our model is trained to detect and prioritize significant footage, enabling quicker and more reliable monitoring and response.

Create a concise video summary by selecting keyframes from the top-ranked segments, providing a quick overview of anomalous activities.



# LITERATURE REVIEW

## MAIN PAPER SUMMARY

The paper, "**Real-world Anomaly Detection in Surveillance Videos**" by Waqas Sultani, Chen Chen, and Mubarak Shah, introduces an innovative approach for anomaly detection using weakly labeled data. The authors leverage a Multiple Instance Learning (MIL) framework where video-level labels (indicating whether an anomaly is present) are used without specific segment-level annotations. The model assigns high anomaly scores to segments with unusual behavior, aided by a ranking loss function with sparsity and temporal smoothness constraints, enhancing its ability to localize anomalies within the footage.

## MAIN PAPER SUMMARY

Our project addresses key gaps by focusing not only on detecting anomalies but also on summarizing them, enabling efficient video monitoring and retrieval. Additionally, our model incorporates a modified loss function and ranks segments based on factors like memorability and entropy, refining anomaly localization and improving overall detection precision in real-world surveillance environments, which require quick and accurate anomaly identification.

# PROPOSED SOLUTION

A stylized illustration of a woman's face from the chest up. She has dark hair and is wearing blue-tinted, futuristic-looking goggles with a grid pattern over the lenses. Her eyes are a vibrant blue. The background behind her is a dark purple with faint, glowing blue and white streaks.

Our solution automates anomaly detection in surveillance videos by segmenting footage, extracting spatial-temporal features using C3D and 3D ResNet, and applying a modified loss function for better anomaly localization. We rank segments by significance, using scoring metrics, to create a summary that highlights key events for efficient monitoring and threat identification.

## SOLUTION APPROACH



1

### SHOT SEGMENTATION

Divide videos into smaller temporal segments

2

### FEATURE EXTRACTION

Use advanced models like C3D (Convolutional 3D) and 3D ResNet to capture both spatial and temporal features

3

### LOSS FUNCTION

Enhance the ranking loss function by adding Temporal Smoothness and Sparsity Constraints

4

### SCORING AND RANKING

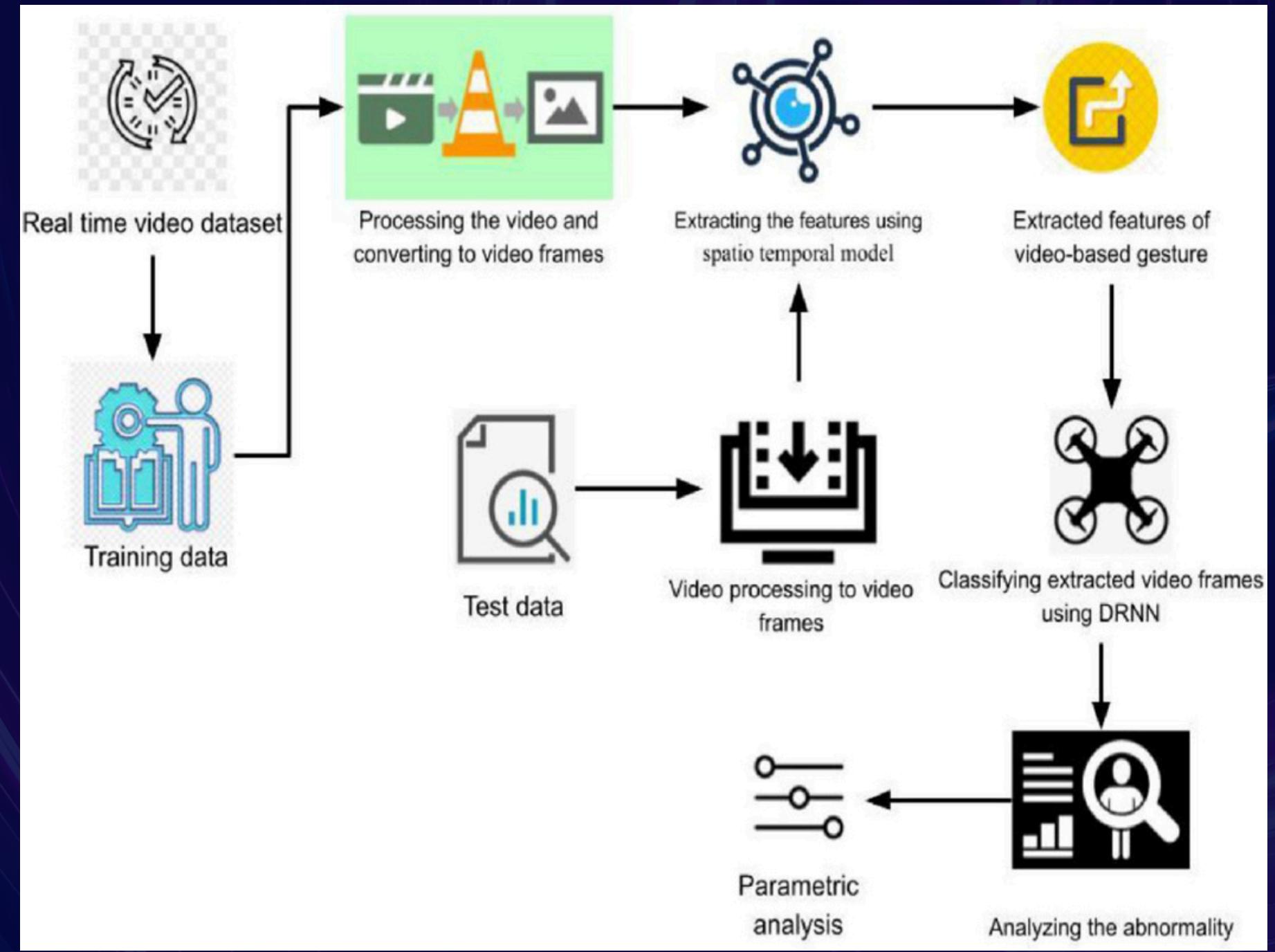
Score each segment based on memorability, entropy, and temporal dynamics.

5

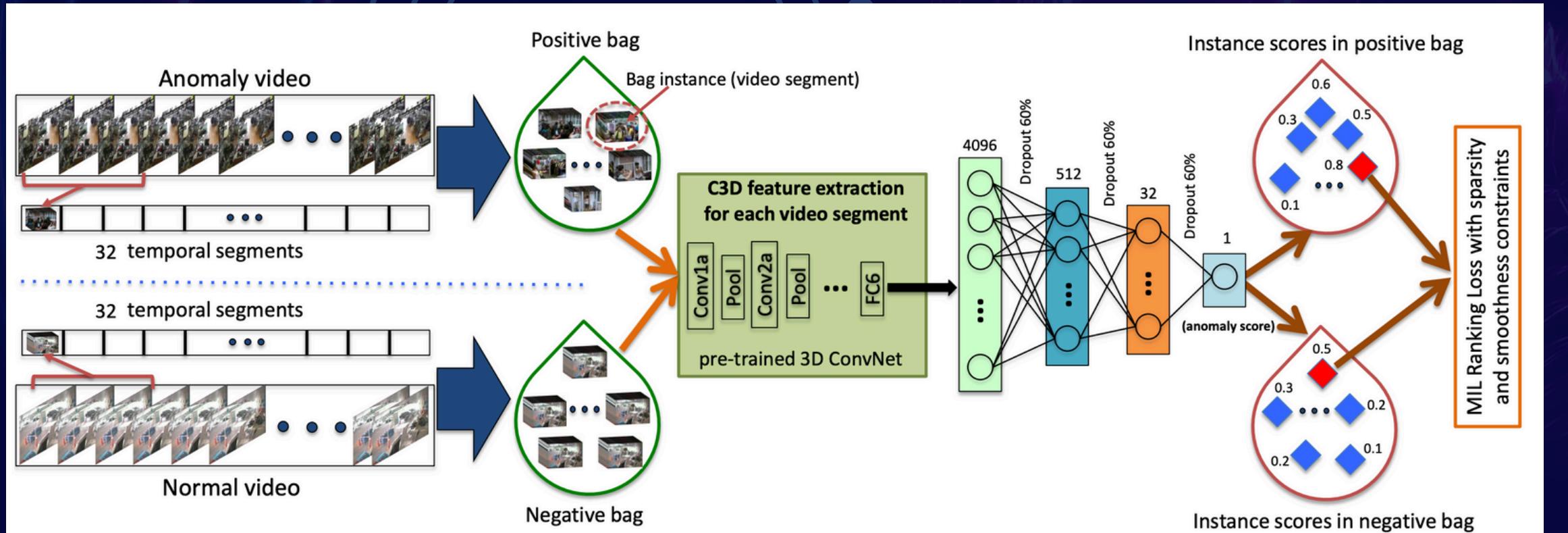
### VIDEO SUMMARIZATION

Generate a summary of the footage by selecting keyframes from the highest-ranked segments, ensuring efficient storage and faster retrieval.

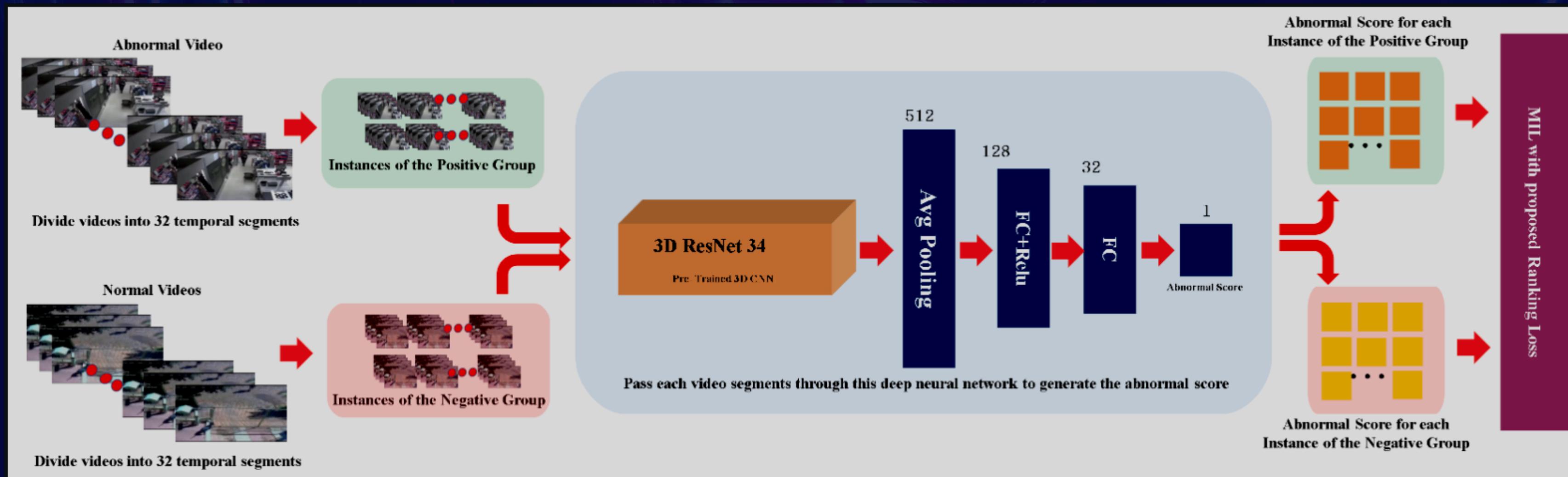
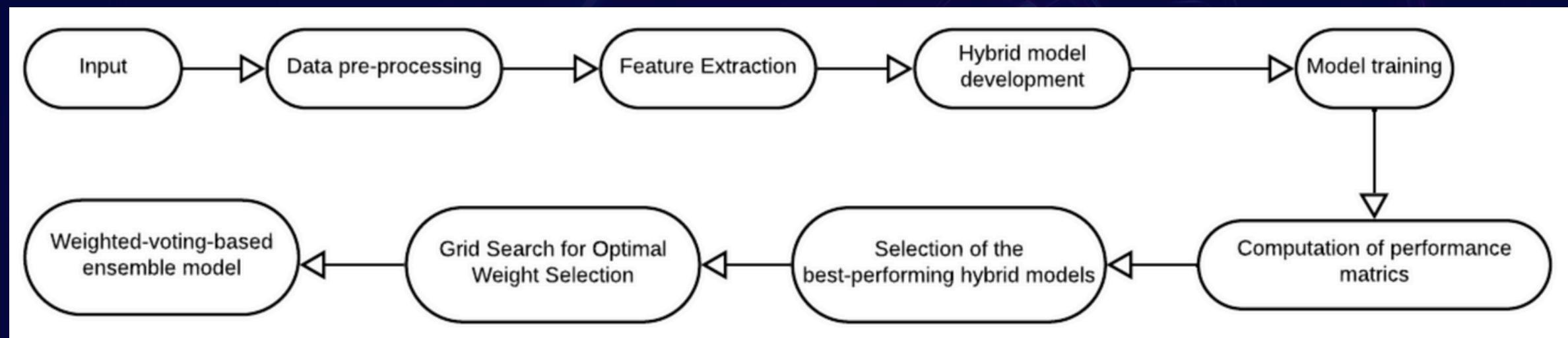
# ANOMALY DETECTION APPROACH



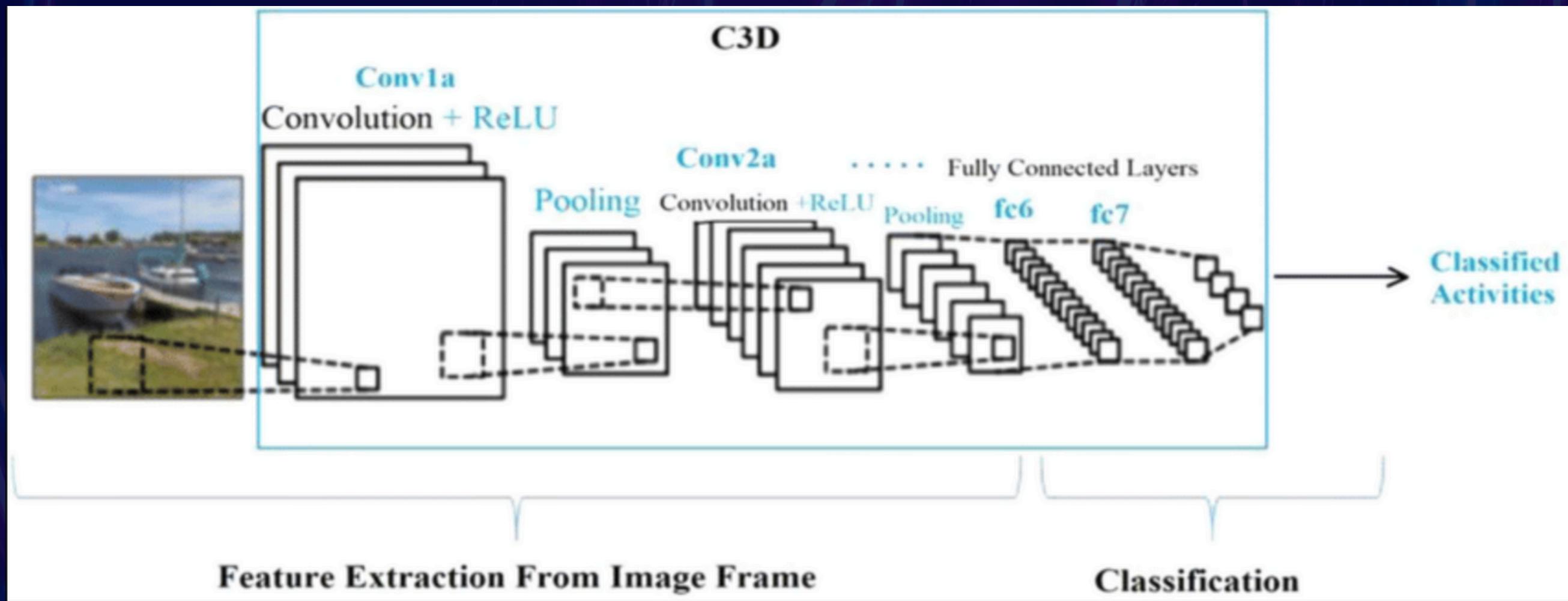
# DETECTION EXAMPLES



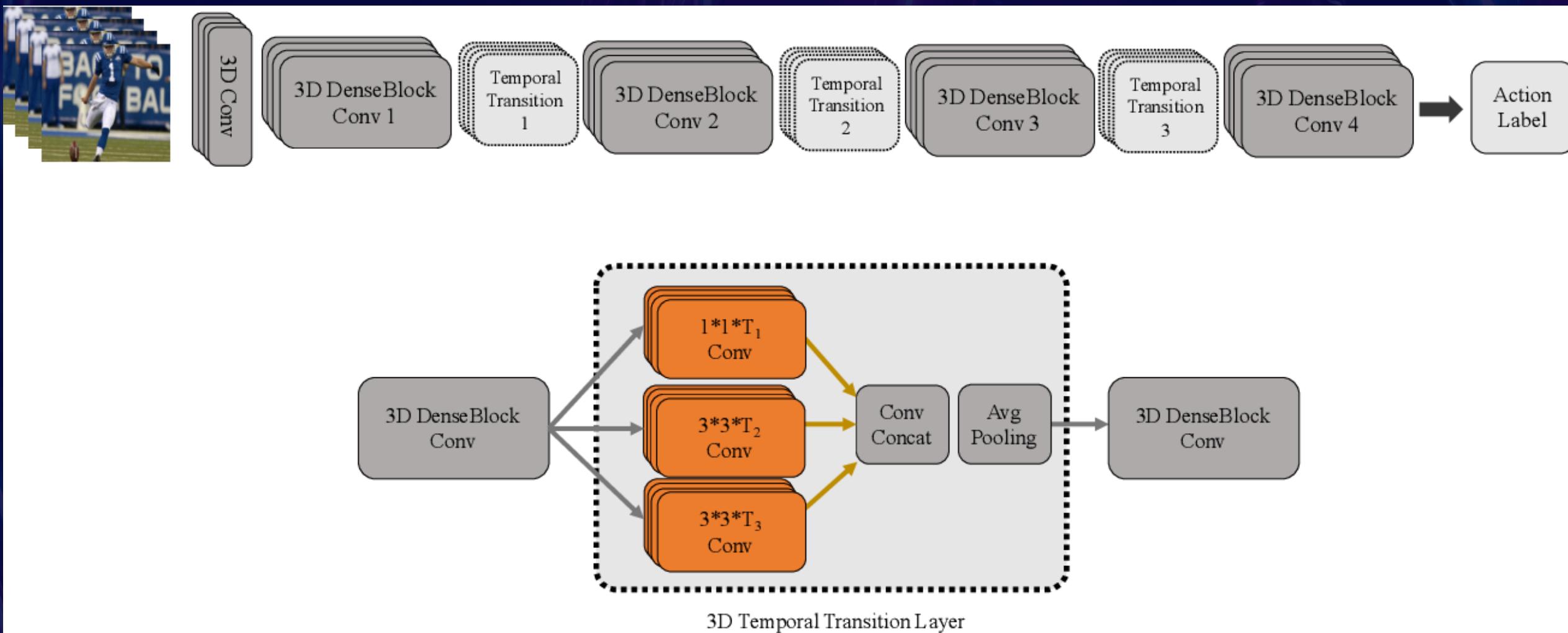
# OVERALL PROCESS



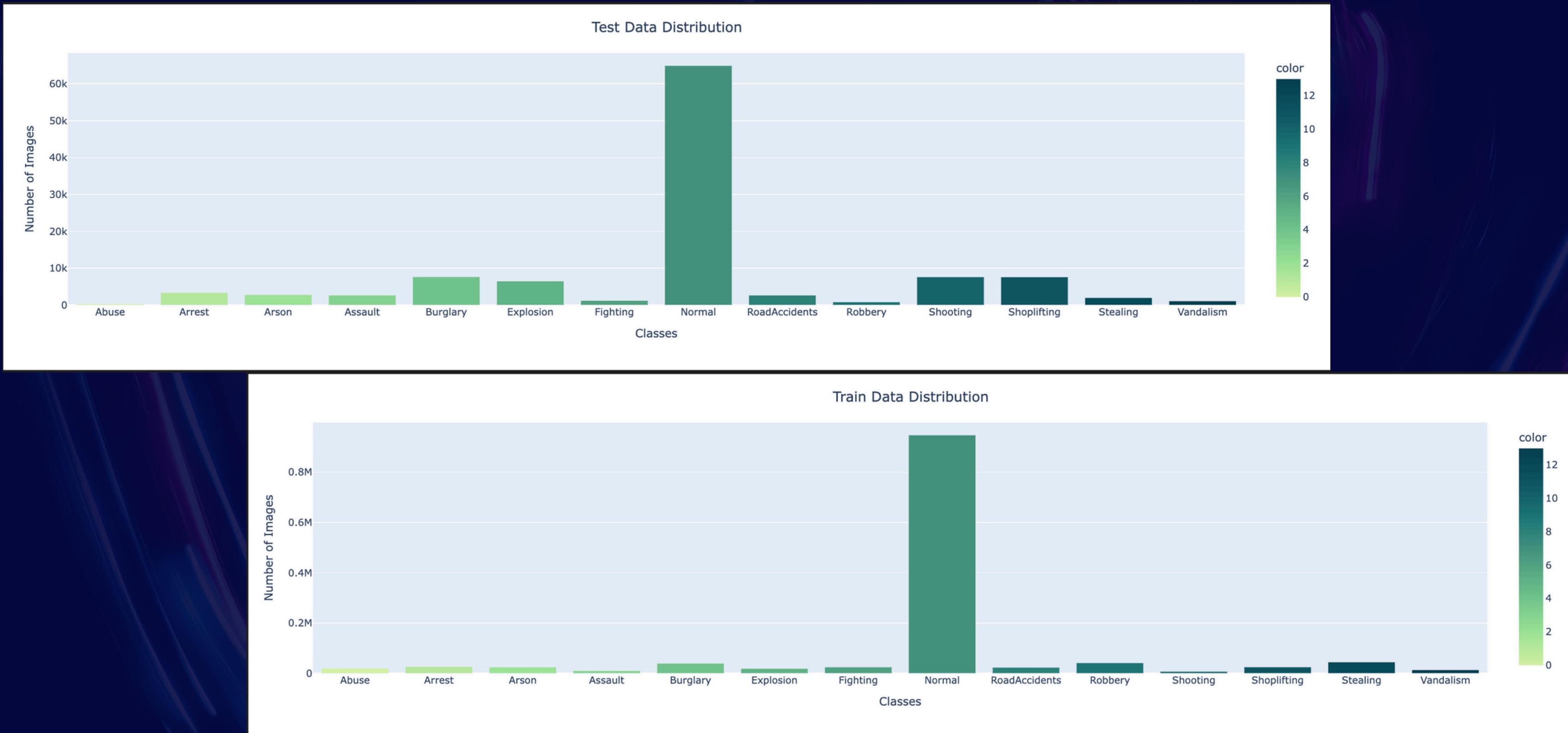
# C3D FEATURE EXTRACTION



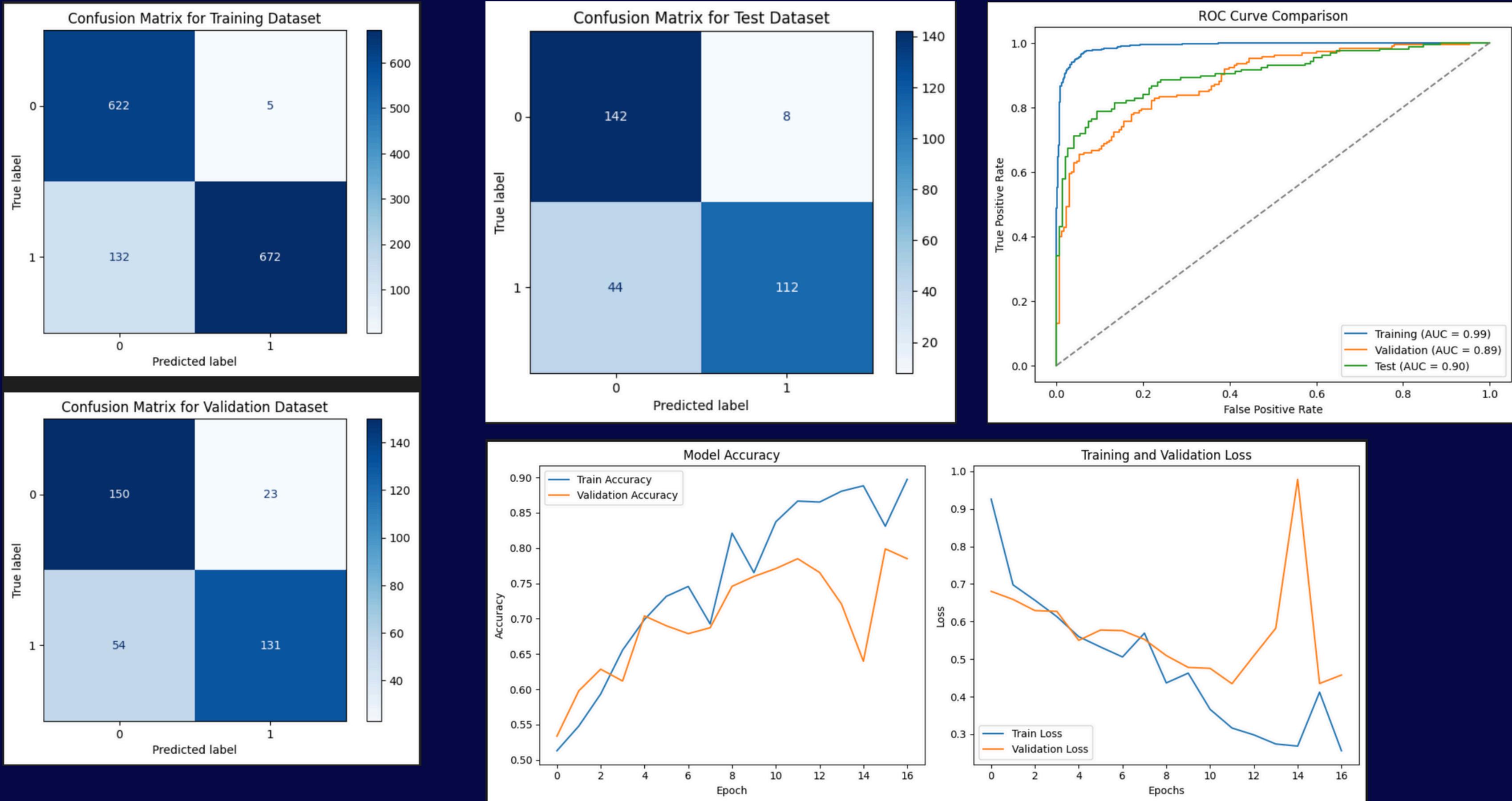
# 3D RESNET



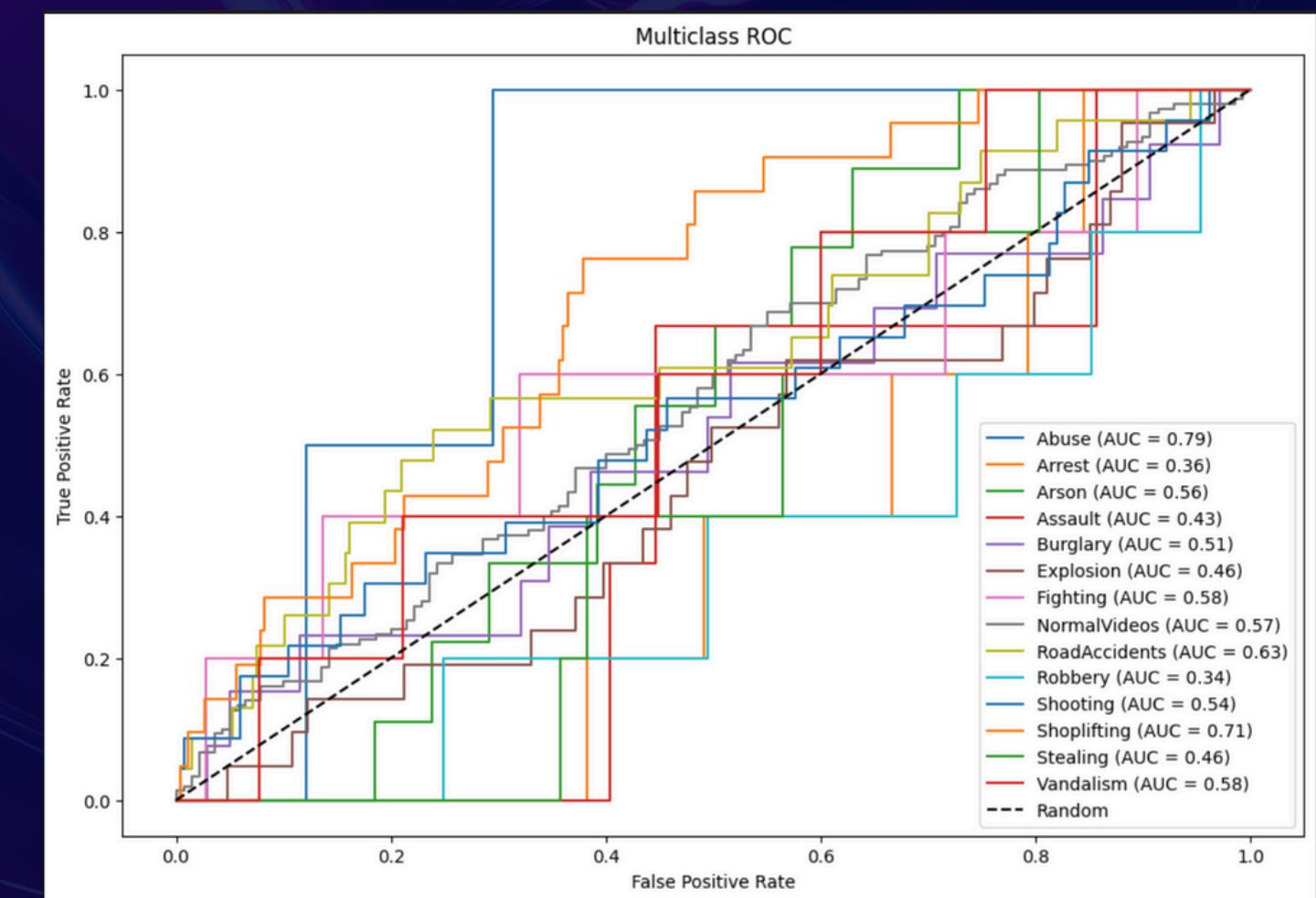
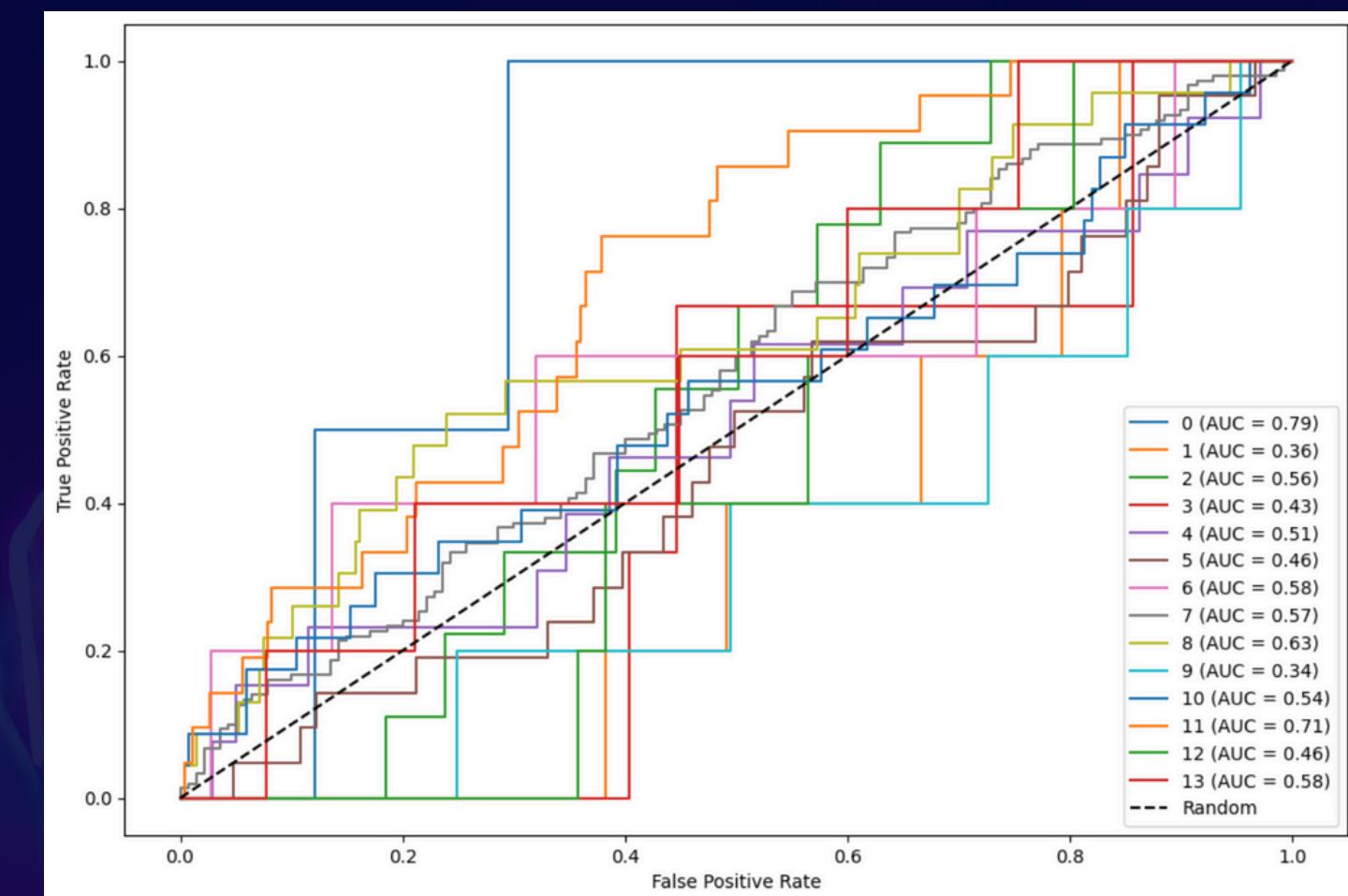
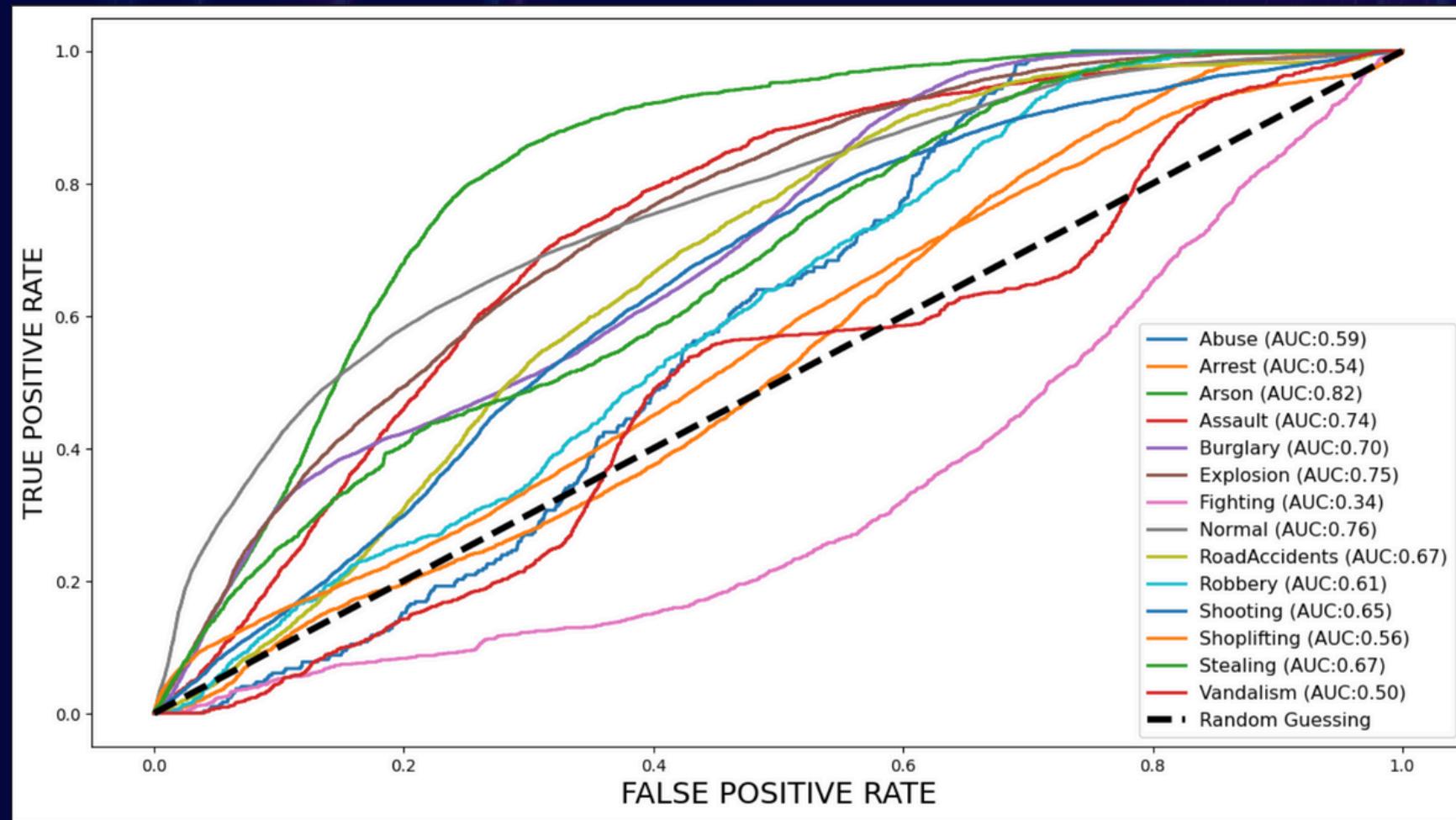
# TEST AND TRAIN RESLTS



# TEST, TRAIN AND VALIDATION RESLTS



# RESULTS AND COMPARISONS



**THANK YOU**