## optimation in Deep Learning > In Deep Learning with the help of low function, the performance of the model evaluated. to this low is used to train the network so that it performs Better . But from wall stage ! > Essentially, we try to minimize the loss function of Lower low means the model performs better ex the process of minimizing any mathematical in called optimization. -> optimens are algorithms used to change the feature of newtral network such as weight and learning that so that the loss is the duced in private to The 1 Goal of an optimized is to minimize the objective boutfunction who is about the land the book of + presente Prescence of Local minima reduces the model performance Need for optimization et to minimize the loss value (Training error) i potrackours

-> To select appropriate weight values and other associated

model parameters. He will all the parameters to

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## Types of optimization 1. Gradient descent with some coefficient seen it moves towards bower weight and apolites, the values of coefficient and repeat until the local min is reach SHOT MARKET THE KNOWN COL Disadvan loges -> Expensive to calculate a gradient if the size of the del is huge alot suitable Ast non-convex function 2. stochastic Gradient Descent: 10 162 100 land 1000000 10 Instead of taking the whole duty set for each iteration nandomly select batches of the data Select the initial parameter w and learning data -> Randomly shuffle the delta and each iteration to reach (Alterially a 10+ balt The approximate minimum. one panie r i a lay than GD but the fort 6 + since only few batcher are

Drs advantage 1

## 3. Stochastic Gradient descent with Momentum: => since SGD is a noisy path we are going for sGD with momentum ey momentum helps in fast convergence of the loss function) and opdate the weight weight previous opdate by adding the fraction of the previous opdate to the current update will make the process a bit factor. 4. Mini batch opadient descent is used for calculating the los function of It takes only fewer iterations so failed than 500 it is smoother than SGD + it has good balance blw speed and accuracy 5. Adagrad Adaptive gradient descent => it was different harning nature for each iteration I the change i'm the learning nate depends upon the difference in the parameter unit training.