

Optimisation Techniques and Algorithms Lab Assignment 7

Aim:

1) Implement Particle Swarm Optimization with the following parameters:

- a) Population size: 50
- b) Maximum number of iterations: 500
- c) Cognitive coefficient (c1) (alpha): 2
- d) Social coefficient (c2)(beta): 2

Optimize any 5 test functions.

2) Compare the results of GA and PSO for any 5 test functions on the following parameters for 500 iterations:

- a) Mean function values for 20 runs
- b) Best function values for 20 runs
- c) Standard deviation values for 20 runs

Compare the iteration-wise mean function values plots for both the values.

Code:

Code 1:

% Define parameters

```
nParticles = 50;           % Number of particles
nDimensions = 2;           % Number of dimensions (change as needed)
maxIterations = 500;       % Maximum number of iterations
cognitiveCoeff = 2;        % Cognitive coefficient (c1)
socialCoeff = 2;           % Social coefficient (c2)
inertiaWeight = 0.5;       % Inertia weight (w)
minBound = -10;            % Lower bound of search space
maxBound = 10;             % Upper bound of search space
```

% Define the objective function

```
str = 'x1^2 + x2^2'; % Objective function as a string
syms x [1 nDimensions];
fitnessFunction = str2sym(str);
```

```
f = matlabFunction(fitnessFunction, 'vars', {x});
```

```
% Initialize particles' positions and velocities
```

```
positions = minBound + (maxBound - minBound) * rand(nParticles, nDimensions);
```

```
velocities = rand(nParticles, nDimensions);
```

```
% Evaluate initial fitness values
```

```
fitness = arrayfun(@(i) f(positions(i,:)), 1:nParticles, 'UniformOutput', false);
```

```
fitness = cell2mat(fitness);
```

```
% Initialize personal best positions and fitness
```

```
pBestPositions = positions;
```

```
pBestFitness = fitness;
```

```
% Find the initial global best
```

```
[globalBestFitness, globalBestIndex] = min(fitness);
```

```
gBestPosition = positions(globalBestIndex, :);
```

```
% Initialize array to store the best fitness values over iterations
```

```
bestFitnessOverTime = zeros(maxIterations, 1);
```

```
% PSO main loop
```

```
for iteration = 1:maxIterations
```

```
    % Update velocities
```

```
    r1 = rand(nParticles, nDimensions); % Random values for cognitive component
```

```
    r2 = rand(nParticles, nDimensions); % Random values for social component
```

```
    velocities = inertiaWeight * velocities + ...
```

```
        cognitiveCoeff * r1 .* (pBestPositions - positions) + ...
```

```
        socialCoeff * r2 .* (gBestPosition - positions);
```

```

% Update positions
positions = positions + velocities;

% Apply boundary conditions
positions = max(min(positions, maxBound), minBound);

% Evaluate new fitness values
fitness = arrayfun(@(i) f(positions(i,:)), 1:nParticles, 'UniformOutput', false);
fitness = cell2mat(fitness);

% Update personal bests
improved = fitness < pBestFitness;
pBestPositions(improved, :) = positions(improved, :);
pBestFitness(improved) = fitness(improved);

% Update global best
[currentGlobalBestFitness, globalBestIndex] = min(fitness);
if currentGlobalBestFitness < globalBestFitness
    globalBestFitness = currentGlobalBestFitness;
    gBestPosition = positions(globalBestIndex, :);
end

% Store the best fitness value for the current iteration
bestFitnessOverTime(iteration) = globalBestFitness;

% Display iteration information
fprintf('Iteration %d: Best Fitness = %.4f\n', iteration, globalBestFitness);
end

```

```

% Output final results

fprintf('Final Global Best Fitness: %.4f\n', globalBestFitness);
fprintf('Final Global Best Position: [%s]\n', num2str(gBestPosition, '%.4f '));

% Plot convergence graph
figure;
plot(1:maxIterations, bestFitnessOverTime, 'LineWidth', 2);
xlabel('Iteration');
ylabel('Best Fitness Value');
title('Convergence Graph of PSO');
grid on;

```

Code 2:

```

clc;
clear;

% Parameters
MaxIter = 100; % Total iterations
str = 'x1^2 + x2^2 + x3^2'; % Fitness function
D = 3; % Number of dimensions
Npop = 50; % Population size
CR = 0.6; % Crossover rate
MR = 0.05; % Mutation rate
n = 20; % Number of runs
LB = [-10, -10, -10]; % Lower bounds for each dimension
UB = [10, 10, 10]; % Upper bounds for each dimension

% Create symbolic variables and the fitness function
syms x [1 D];
fitnessFunction = str2sym(str);

```

```
f = matlabFunction(fitnessFunction, 'vars', {x});
```

```
% Initialize storage for fitness values
```

```
GA_bestFitness = zeros(MaxIter, n);
```

```
GA_meanFitness = zeros(MaxIter, 1);
```

```
GA_stddevFitness = zeros(MaxIter, 1);
```

```
PSO_bestFitness = zeros(MaxIter, n);
```

```
PSO_meanFitness = zeros(MaxIter, 1);
```

```
PSO_stddevFitness = zeros(MaxIter, 1);
```

```
% GA Algorithm
```

```
for run = 1:n
```

```
    % Initialize population
```

```
    X = LB + rand(Npop, D) .* (UB - LB);
```

```
    % Fitness evaluation
```

```
    fitness = zeros(Npop, 1);
```

```
    for i = 1:Npop
```

```
        fitness(i) = f(X(i, :));
```

```
    end
```

```
    for it = 1:MaxIter
```

```
        X_new = X; % Copy population for new individuals
```

```
        for i = 1:Npop
```

```
            % Selection of r1
```

```
            r1 = randi(Npop);
```

```
            while r1 == i
```

```
                r1 = randi(Npop);
```

```

end

% Crossover
if rand < CR
    crossoverPoint = floor(D / 2); % Single-point crossover at midpoint
    X_new(i, 1:crossoverPoint) = X(i, 1:crossoverPoint);
    X_new(i, crossoverPoint+1:end) = X(r1, crossoverPoint+1:end);
end

% Mutation
if rand < MR
    mutationPoint = randi(D);
    X_new(i, mutationPoint) = LB(mutationPoint) + rand * (UB(mutationPoint) -
LB(mutationPoint));
end

% Fitness evaluation
fitness_new = f(X_new(i, :));
if fitness_new < fitness(i)
    X(i, :) = X_new(i, :);
    fitness(i) = fitness_new;
end
end

% Sort population by fitness
[sortedFitness, ~] = sort(fitness, 'ascend');

% Track best fitness for this iteration
GA_bestFitness(it, run) = sortedFitness(1);
end
end

```

```
% Compute GA statistics
```

```
GA_meanFitness = mean(GA_bestFitness, 2);
```

```
GA_stddevFitness = std(GA_bestFitness, 0, 2);
```

```
% PSO Algorithm
```

```
for run = 1:n
```

```
    [bestFitnessOverTime] = particleSwarmOptimization(f, Npop, MaxIter, D, LB, UB);
```

```
    PSO_bestFitness(:, run) = bestFitnessOverTime;
```

```
end
```

```
% Compute PSO statistics
```

```
PSO_meanFitness = mean(PSO_bestFitness, 2);
```

```
PSO_stddevFitness = std(PSO_bestFitness, 0, 2);
```

```
% Plot the results
```

```
figure;
```

```
plot(1:MaxIter, GA_meanFitness, 'r', 'LineWidth', 2);
```

```
hold on;
```

```
plot(1:MaxIter, PSO_meanFitness, 'b', 'LineWidth', 2);
```

```
xlabel('Iteration');
```

```
ylabel('Mean Fitness Value');
```

```
title('Mean Fitness Value Over Iterations');
```

```
legend('GA', 'PSO');
```

```
grid on;
```

```
figure;
```

```
plot(1:MaxIter, min(GA_bestFitness, [], 2), 'r', 'LineWidth', 2);
```

```
hold on;
```

```
plot(1:MaxIter, min(PSO_bestFitness, [], 2), 'b', 'LineWidth', 2);
```

```

xlabel('Iteration');
ylabel('Best Fitness Value');
title('Best Fitness Value Over Iterations');
legend('GA', 'PSO');
grid on;

figure;
plot(1:MaxIter, GA_stddevFitness, 'r', 'LineWidth', 2);
hold on;
plot(1:MaxIter, PSO_stddevFitness, 'b', 'LineWidth', 2);
xlabel('Iteration');
ylabel('Standard Deviation of Fitness Value');
title('Standard Deviation of Fitness Value Over Iterations');
legend('GA', 'PSO');
grid on;

```

% PSO function

```

function [bestFitnessOverTime] = particleSwarmOptimization(fitnessFunction, nParticles,
maxIterations, nDimensions, LB, UB)

```

% PSO Parameters

```

cognitiveCoeff = 2; % Cognitive coefficient

```

```

socialCoeff = 2; % Social coefficient

```

```

inertiaWeight = 0.5; % Inertia weight

```

% Initialize positions and velocities

```

positions = LB + (UB - LB) .* rand(nParticles, nDimensions);

```

```

velocities = rand(nParticles, nDimensions);

```

% Evaluate initial fitness values

```

fitness = arrayfun(@(i) fitnessFunction(positions(i,:)), 1:nParticles, 'UniformOutput',
false);

```



```

fitness = cell2mat(fitness);

% Initialize personal bests
pBestPositions = positions;
pBestFitness = fitness;

% Find the initial global best
[globalBestFitness, globalBestIndex] = min(fitness);
gBestPosition = positions(globalBestIndex, :);

% Initialize array to store best fitness values over iterations
bestFitnessOverTime = zeros(maxIterations, 1);

% PSO main loop
for iteration = 1:maxIterations
    % Update velocities
    r1 = rand(nParticles, nDimensions); % Random values for cognitive component
    r2 = rand(nParticles, nDimensions); % Random values for social component

    velocities = inertiaWeight * velocities + ...
        cognitiveCoeff * r1 .* (pBestPositions - positions) + ...
        socialCoeff * r2 .* (gBestPosition - positions);

    % Update positions
    positions = positions + velocities;

    % Apply boundary conditions
    positions = max(min(positions, UB), LB);

    % Evaluate new fitness values

```

```

    fitness = arrayfun(@(i) fitnessFunction(positions(i,:)), 1:nParticles, 'UniformOutput',
false);
    fitness = cell2mat(fitness);

    % Update personal bests
    improved = fitness < pBestFitness;
    pBestPositions(improved, :) = positions(improved, :);
    pBestFitness(improved) = fitness(improved);

    % Update global best
    [currentGlobalBestFitness, globalBestIndex] = min(fitness);
    if currentGlobalBestFitness < globalBestFitness
        globalBestFitness = currentGlobalBestFitness;
        gBestPosition = positions(globalBestIndex, :);
    end

    % Store the best fitness value for the current iteration
    bestFitnessOverTime(iteration) = globalBestFitness;
end
end

```

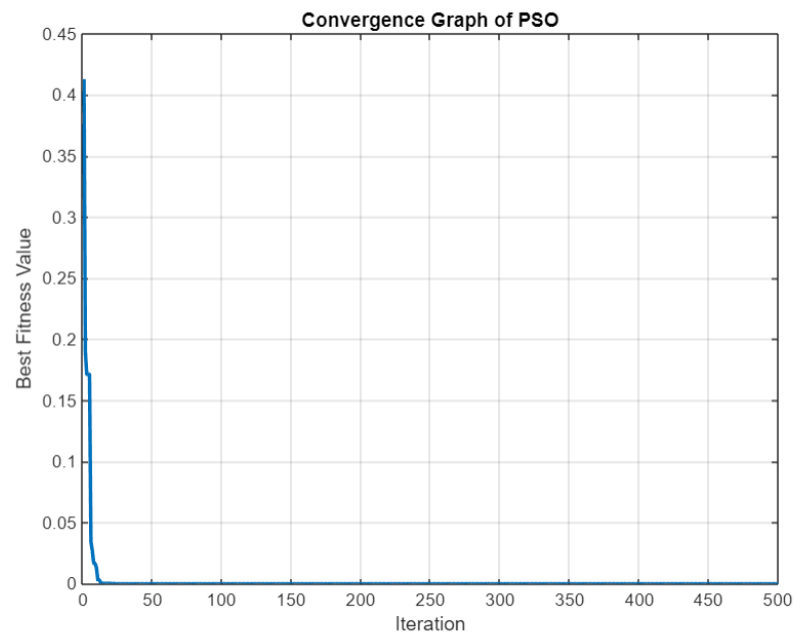
Output:

Function 1: Sphere function

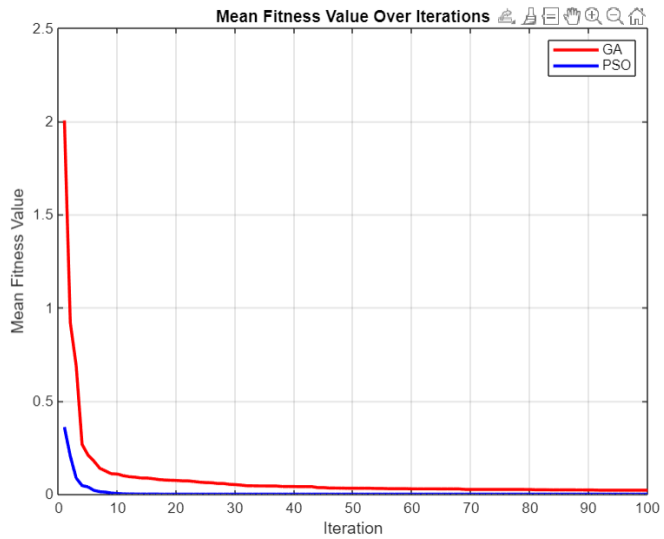
Dimensions=2

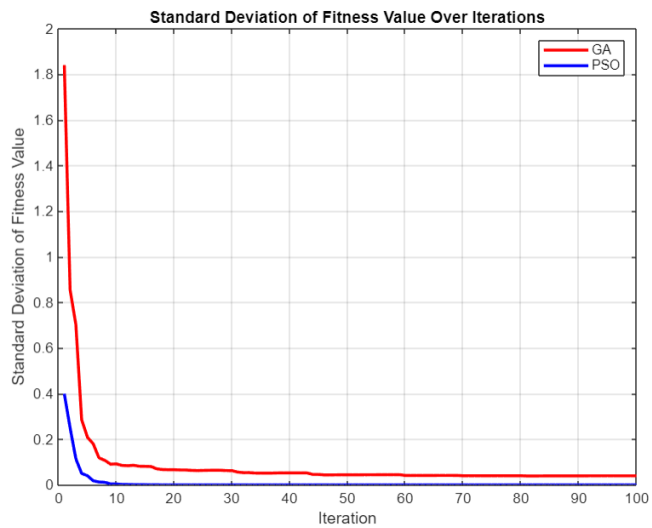
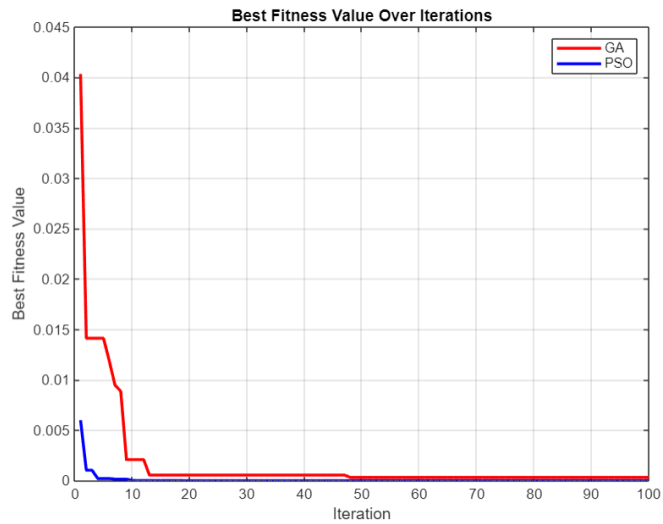
$F = x_1^2 + x_2^2$

Code 1:



Code 2:



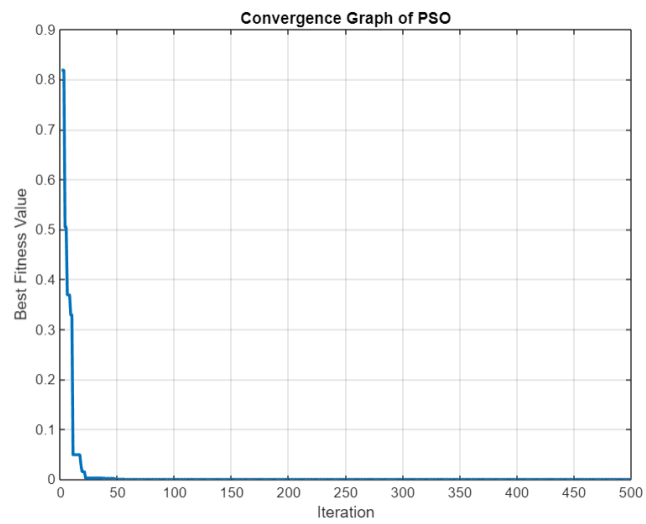


Function 2: Rosenbrock

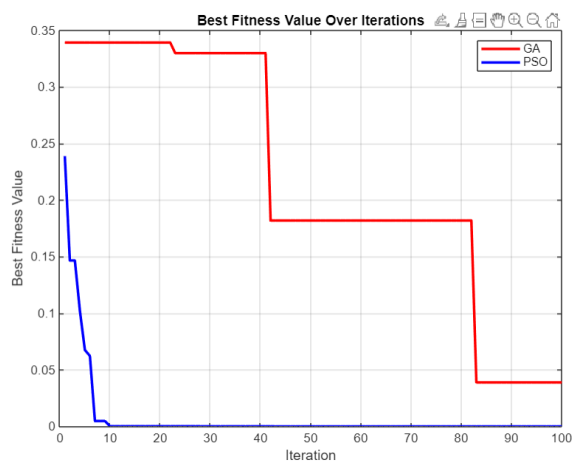
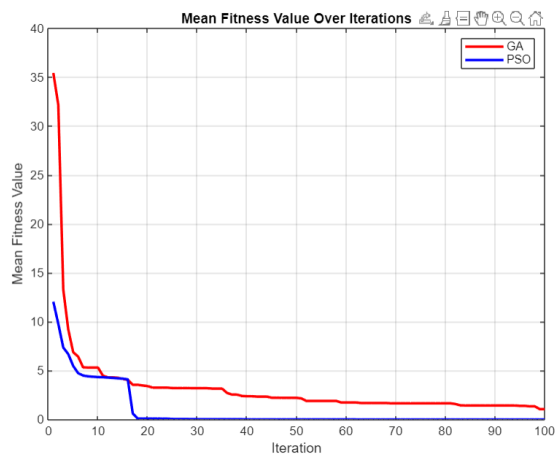
Dimensions=2

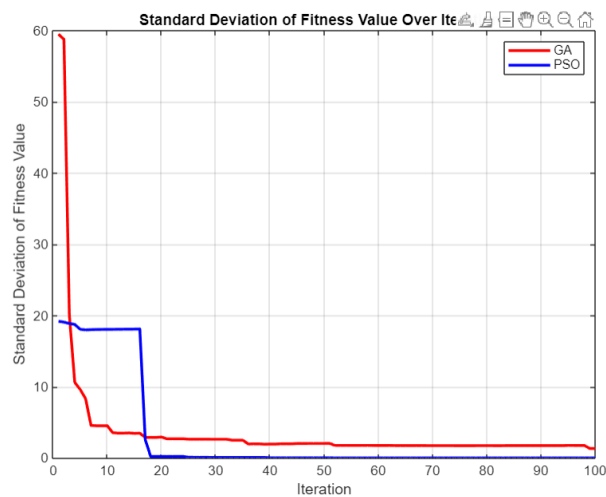
$$F = 100 \cdot (x_2^2 - x_1^2)^2 + (1 - x_1)^2$$

Code 1:



Code 2:



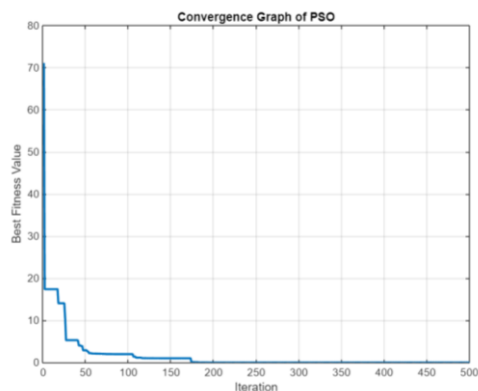


Function 3: Rastrigin Function

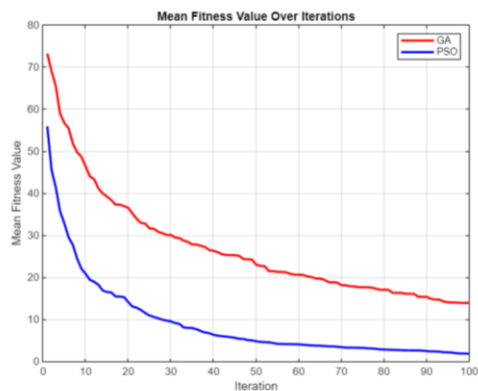
Dimensions:5

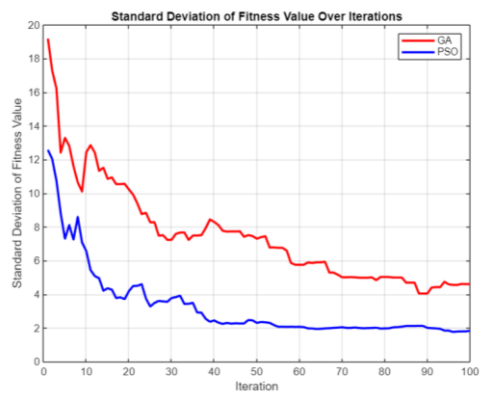
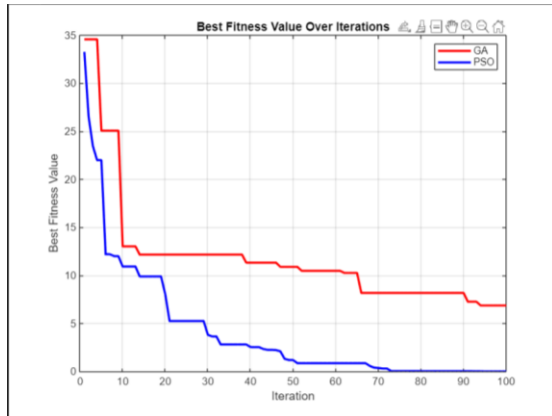
$$F = 10 \times 5 + (x_1^2 - 10 \times \cos(2\pi x_1)) + (x_2^2 - 10 \times \cos(2\pi x_2)) + (x_3^2 - 10 \times \cos(2\pi x_3)) + (x_4^2 - 10 \times \cos(2\pi x_4)) + (x_5^2 - 10 \times \cos(2\pi x_5))$$

Code 1:



Code 2:



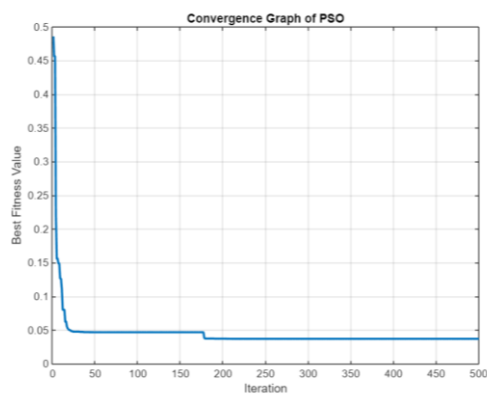


Function 4: Griewank Function:

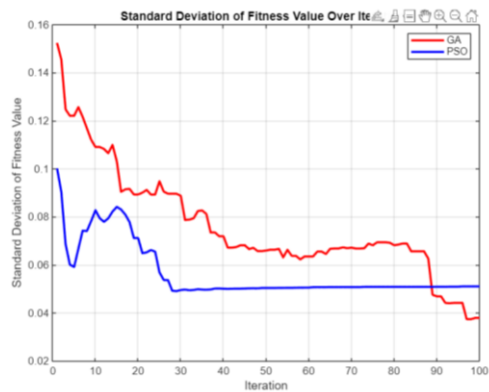
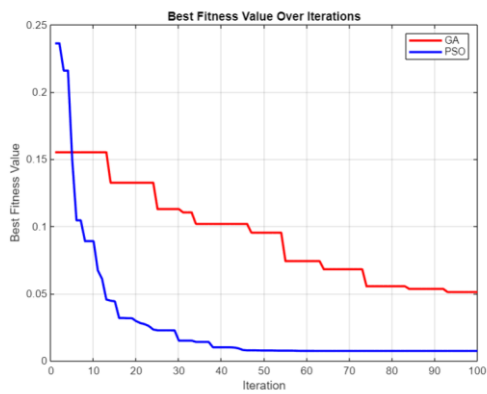
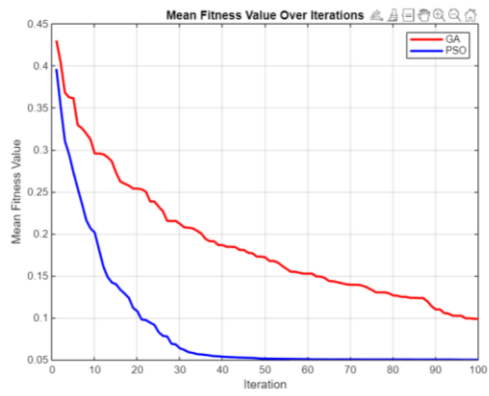
Dimensions: 5

$$F = 1 + \frac{(x_1^2 + x_2^2 + x_3^2 + x_4^2 + x_5^2)}{4000} - \cos(x_1) \cdot \cos\left(\frac{x_2}{\sqrt{2}}\right) \cdot \cos\left(\frac{x_3}{\sqrt{3}}\right) \cdot \cos\left(\frac{x_4}{\sqrt{4}}\right) \cdot \cos\left(\frac{x_5}{\sqrt{5}}\right)$$

Code 1:



Code 2:

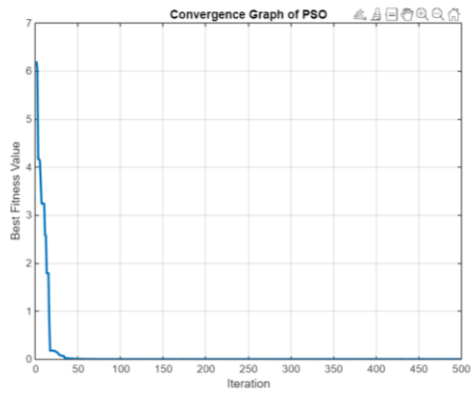


Function 5: Ackley Function:

Dimensions: 5

$$F = -20 \cdot \exp(-0.2 \cdot \sqrt{(\frac{x_1^2 + x_2^2 + x_3^2 + x_4^2 + x_5^2}{5})}) - \exp((\cos(2\pi \cdot x_1) + \cos(2\pi \cdot x_2) + \cos(2\pi \cdot x_3) + \cos(2\pi \cdot x_4) + \cos(2\pi \cdot x_5))/5) + 20 + \exp(1)$$

Code 1:



Code 2:

