

$$\begin{aligned}
 (a) \quad 610 + x_4 &= 450 + x_2 \Rightarrow x_1 - x_4 = 160 \\
 x_1 + 400 &= 640 + x_2 \Rightarrow x_1 - x_2 = 240 \\
 x_2 + 600 &= x_3 \Rightarrow -x_2 + x_3 = 600 \\
 x_3 &= 520 + x_4 \Rightarrow x_3 - x_4 = 520
 \end{aligned}$$

(b) (i) The augmented matrix on the LHS corresponds to the linear system in (a).

There is no leading entry for x_4 . Set $x_4 = t$, $t \in \mathbb{R}$. Back substitution then gives

$$x_3 = 520 + t$$

$$x_2 = -80 + t$$

$$x_1 = 160 + t$$

Hence the general solution is

$$\{(160+t, -80+t, 520+t, t) \mid t \in \mathbb{R}\}$$

$$(ii) \quad x_4 = 80.$$

(i) As an augmented matrix

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 \\ 0 & 2 & k & k \end{array} \right] \underset{R_3 - 2R_2}{\sim} \left[\begin{array}{ccc|c} 1 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & k-2 & k-4 \end{array} \right]$$

Unique solution provided there are three leading entries and thus $k \neq 2$. In this circumstance

$$x_3 = \frac{k-4}{k-2}.$$

$$(a) (i) BC = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 1 \\ 13 \end{bmatrix}$$

$$(ii) C^T B^T BC = (BC)^T BC = [5 \ 1 \ 13] \begin{bmatrix} 5 \\ 1 \\ 13 \end{bmatrix} = 25 + 1 + 169 = 195.$$

$$(iii) ABC = [1 \ 3 \ 1] \begin{bmatrix} 5 \\ 1 \\ 13 \end{bmatrix} = 5 + 3 + 13 = 21$$

Hence $(ABC)^{-1} = \frac{1}{21}$

(b) (i) For $A_{m \times n} B_{p \times q}$ to be well defined we require $n=p$

For $B_{p \times q} A_{m \times n}$ to be well defined we require $q=m$

For $A_{m \times n} B_{p \times q} - B_{p \times q} A_{m \times n}$ to be well defined, in addition we require

$$m=p, \ q=n$$

Thus

$$q=m=p=n$$

so both matrices must be square of the same size.

$$3(a) \text{(ii)} A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

(ii) The entry in row 1, column 1 of A^4 is the number of walks from vertex a back to itself in exactly 4 steps.

In exactly 4 steps, there are 3 possibilities:

$$(a) (a \rightarrow b \rightarrow c)$$

$$\text{or } (a \rightarrow b \rightarrow c)(a) \text{ or } (a)^4$$

Hence the entry will be 3.

$$b(i) \text{ Consider } \left[\begin{array}{ccc|ccc} 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 1 & 0 \\ 1 & -1 & -2 & 0 & 0 & 1 \end{array} \right] R_1 \leftrightarrow R_3$$

$$\left[\begin{array}{ccc|ccc} 1 & -1 & -2 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 2 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \end{array} \right] R_2 \leftrightarrow R_3 \sim \left[\begin{array}{ccc|ccc} 1 & -1 & -2 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{array} \right] R_1 \leftrightarrow R_3, R_2 - R_3$$

$$\left[\begin{array}{ccc|ccc} 1 & -1 & 0 & 0 & 2 & 1 \\ 0 & 1 & 0 & 2 & -1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{array} \right] R_1 + R_2 \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 2 & 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{array} \right]$$

$$\text{Hence } B^{-1} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$(iii) C^{-1} = \frac{1}{\alpha\delta - \beta\gamma} \begin{bmatrix} \delta - \beta & & \\ -\gamma & \alpha & \\ & & \end{bmatrix}, \tilde{C}^{-1} = \frac{1}{\gamma\delta - \beta\alpha} \begin{bmatrix} \beta - \delta & & \\ -\alpha & \gamma & \\ & & \end{bmatrix} = \frac{1}{\alpha\delta - \beta\gamma} \begin{bmatrix} -\beta & \delta \\ \alpha & -\gamma \end{bmatrix}$$

Hence the two columns of C^{-1} should be swapped.

Q. 4

4. (i) $\underline{u} \times \underline{v}$, let $\underline{u} = (u_1, u_2, u_3)$
 $\underline{v} = (v_1, v_2, v_3)$

$$\text{Ans } \underline{u} \times \underline{v} = \begin{vmatrix} i & j & k \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$$

(where $|A| = \det(A)$)

$$(ii) \underline{u} \cdot (\underline{u} \times \underline{v}) = \underline{u} \cdot \begin{vmatrix} i & j & k \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} \quad (\text{from (i)})$$

$$= \underline{u} \cdot \left(\begin{vmatrix} u_2 v_3 \\ v_2 v_3 \end{vmatrix} - \begin{vmatrix} u_1 v_3 \\ v_1 v_3 \end{vmatrix} + \begin{vmatrix} u_1 u_2 \\ v_1 v_2 \end{vmatrix} \right)$$

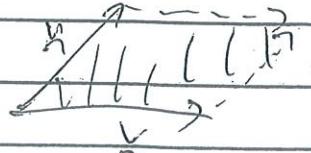
$$= u_1 \begin{vmatrix} u_2 v_3 \\ v_2 v_3 \end{vmatrix} - u_2 \begin{vmatrix} u_1 v_3 \\ v_1 v_3 \end{vmatrix} + u_3 \begin{vmatrix} u_1 u_2 \\ v_1 v_2 \end{vmatrix}$$

$$= \begin{vmatrix} u_1 & u_2 & u_3 \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = 0 \quad (\text{two identical rows } \Rightarrow \text{det} = 0)$$

\underline{u} and $(\underline{u} \times \underline{v})$

perpendicular w.r.t. the dot product.

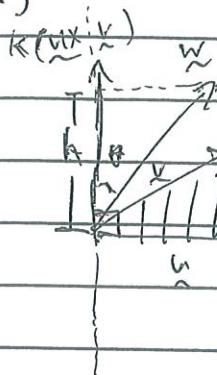
(iii) Area of parallelogram = $\|\underline{u} \times \underline{v}\|$



Q. 4

iii) $\underline{w} \cdot (\underline{u} \times \underline{v}) = \|\underline{w}\| \|\underline{u} \times \underline{v}\| \cos \theta.$

(cont.)



Volume = height \times area

but $\frac{h}{\|\underline{w}\|} = \cos \theta$ (see diagram)

$$\Rightarrow h = \|\underline{w}\| \cos \theta$$

(and Area = $\|\underline{u} \times \underline{v}\|$ ~~$\|\underline{u} \times \underline{v}\|$~~)

$$Wz \quad \underline{w} \cdot (\underline{u} \times \underline{v}) = \|\underline{w}\| \cos \theta \quad \|\underline{u} \times \underline{v}\|$$

$$= h \times \text{Area}$$

$$= \text{Volume.}$$

. i.e. Volume of parallelepiped = $|\underline{w} \cdot (\underline{u} \times \underline{v})|$
Spanned by $\underline{u}, \underline{v}, \underline{w}$

b) Area of $\Delta = \frac{1}{2}$ Area of parallelogram

$$= \frac{1}{2} \|\underline{u} \times \underline{v}\|$$

$$= \frac{1}{2} \|(1-0, 2-0, 0-0) \times (1-0, 2-0, 3-0)\|$$

$$= \frac{1}{2} \left| \det \begin{bmatrix} 1 & 2 & 0 \\ 1 & 2 & 0 \\ 1 & 2 & 3 \end{bmatrix} \right| = \frac{1}{2} \|(6-0, -(3-0), (2-2))\|$$

$$= \frac{1}{2} \sqrt{6^2 + 9 + 0} = \frac{1}{2} \sqrt{36+9} = \frac{1}{2} \sqrt{45}$$

Q. 4 & 5

$$4.) \text{ (contd)} = \frac{1}{2} \sqrt{9} \sqrt{6} = \frac{3}{2} \sqrt{5}$$

$i.e. A \text{ is } \frac{3}{2} \sqrt{5}$

$$5. \text{ a) } \left\{ a(1, 1, 0, -1) + b(2, 0, 2, 0) + c(0, 2, -2, -2) \mid a, b, c \in \mathbb{R} \right.$$

$= \text{Span } \{(1, 1, 0, -1), (2, 0, 2, 0), (0, 2, -2, -2)\}$

(clearly)

$$\begin{bmatrix} 1 & 2 & 0 \\ 1 & 0 & 2 \\ 0 & 2 & -2 \\ -1 & 0 & -2 \end{bmatrix} \xrightarrow{R_4 + R_2} \begin{bmatrix} 1 & 2 & 0 \\ 1 & 0 & 2 \\ 0 & 2 & -2 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 - R_1} \begin{bmatrix} 1 & 2 & 0 \\ 0 & -2 & 2 \\ 0 & 2 & -2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 0 \\ 0 & -2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{rank} = 2, \text{ first \& second columns are lin. indep, third column depends on first and second columns.}$$

$$\Rightarrow \text{basis} = \{(1, 1, 0, -1), (2, 0, 2, 0)\}$$

and dimension = 2

\mathbf{u} , and \mathbf{v} are

$$b.) \text{ Suppose general vectors. Suppose } n \text{ general vectors, in } \mathbb{R}^3:$$

$$\mathbf{v} = (v_1, v_2, v_3) \in \mathbb{R}^3, \quad \mathbf{u} = (u_1, u_2, u_3) \in \mathbb{R}^3$$

belong in S . That is $v_1 + 2v_2 + v_3 = 0$,

$$v_1 - v_2 + v_3 = 0 \quad | \quad ①$$

$$u_1 + 2u_2 + u_3 = 0 \quad | \quad ②$$

$$\text{and } u_1 - u_2 + u_3 = 0. \quad | \quad ③$$

so that $\mathbf{u}, \mathbf{v} \in S$.

Q. 5

$$u + v = (u_1, u_2, u_3) + (v_1, v_2, v_3)$$

$$= (u_1 + v_1, u_2 + v_2, u_3 + v_3)$$

But since $u, v \in S$.

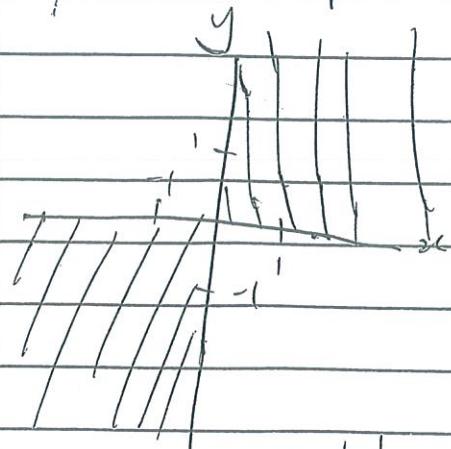
$$\begin{aligned} &\Rightarrow (u_1 + v_1) + 2(u_2 + v_2) + (u_3 + v_3) \\ &= (u_1 + 2u_2 + u_3) + (v_1 + 2v_2 + v_3) \\ &\geq 0 + 0 = 0 \quad (\text{from } \textcircled{1}) \end{aligned}$$

$$\begin{aligned} \text{and } &(u_1 + v_1) - (u_2 + v_2) + (u_3 + v_3) \\ &= (u_1 - u_2 + u_3) + (v_1 - v_2 + v_3) \\ &\geq 0 + 0 = 0 \quad (\text{from } \textcircled{2}) \end{aligned}$$

$\therefore (u + v) \in S$.

$\therefore S$ is c.u.v.a.

c) $\{(x, y) \mid x, y \geq 0\} \cup \{(x, y) \mid x, y \leq 0\} = R$



Take $(1, 0) \in R$ ($1, 0 \geq 0$)

and $(0, -1) \in R$ ($0, -1 \leq 0$)

$$(1, 0) + (0, -1) = (1, -1)$$

$1 \geq 0$ but $-1 \not\geq 0$

similarly $-1 \leq 0$ but $+1 \not\leq 0$

$\therefore (1, -1) \notin R$ \therefore Not. c.u.v.a.

Q. 4

$$\underline{u} = (u_1, u_2, u_3) \quad \underline{v} = (v_1, v_2, v_3)$$

$$\text{i}) \quad \underline{u} \times \underline{v} = \begin{vmatrix} i & j & k \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$$

$$\begin{aligned} \text{ii}) \quad \underline{u} \cdot (\underline{u} \times \underline{v}) &= \underline{u} \cdot \left(\begin{vmatrix} i & j & k \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} \right) \\ &= \underline{u} \cdot \left(\begin{vmatrix} u_2 u_3 & i \\ v_2 v_3 & i \end{vmatrix} - \begin{vmatrix} u_1 u_3 & j \\ v_1 v_3 & j \end{vmatrix} + \begin{vmatrix} u_1 u_2 & k \\ v_1 v_2 & k \end{vmatrix} \right) \\ &= (u_1, u_2, u_3) \cdot (u_2 v_3 - u_3 v_2, -u_1 v_3 + u_3 v_1, u_1 v_2 - u_2 v_1) \\ &= u_1 u_2 v_3 - u_1 u_3 v_2 - u_2 u_3 v_3 + u_2 u_3 v_1 + u_3 u_1 v_2 - u_3 u_2 v_1 \\ &= 0 \end{aligned}$$

$\therefore \underline{u}$ is perpendicular to $\underline{u} \times \underline{v}$

$$\begin{aligned} \text{iii}) \quad \underline{u} \times \underline{w} &\quad | \underline{w} \cdot (\underline{u} \times \underline{v})| \\ &\quad = \cancel{\|\underline{w}\| \|\underline{u} \times \underline{v}\| |\cos \theta_1|} \\ &\quad \text{volume} = (\text{height}) \times (\text{base}) \\ &\quad = (\text{height}) \times \|\underline{u} \times \underline{v}\| \end{aligned}$$

$$\theta_1 + \theta_2 = \pi/2 \quad \text{and height} = \|\underline{w}\| \sin \theta_2$$

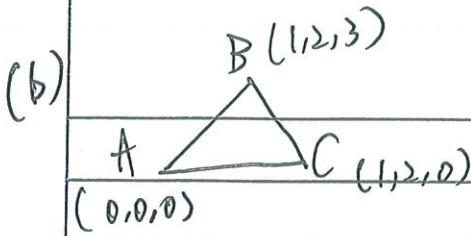
$$\therefore |\cos \theta_1| = \sin \theta_2 \quad \text{assume } \sin \theta_2 \geq 0$$

$$\begin{aligned} \therefore \text{volume} &= (\text{height}) \times \|\underline{u} \times \underline{v}\| \\ &= \|\underline{w}\| \|\underline{u} \times \underline{v}\| \sin \theta_2 \\ &= \|\underline{w}\| \|\underline{u} \times \underline{v}\| |\cos \theta_1| \end{aligned}$$

since θ_1 is the angle between $\underline{u} \times \underline{v}$ and \underline{w}

$$\text{we have volume} = |\underline{w} \cdot (\underline{u} \times \underline{v})|$$

Q. 4



$$\vec{AB} = (1, 2, 3)$$

$$\vec{AC} = (1, 2, 0)$$

$$\vec{AB} \times \vec{AC} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & 3 \\ 1 & 2 & 0 \end{vmatrix} = \begin{vmatrix} 2 & 3 \\ 2 & 0 \end{vmatrix} \hat{i} - \begin{vmatrix} 1 & 3 \\ 1 & 0 \end{vmatrix} \hat{j} + \begin{vmatrix} 1 & 2 \\ 1 & 2 \end{vmatrix} \hat{k}$$

$$= (-6, 3, 0)$$

$$\text{Area of the triangle} = \frac{1}{2} \|\vec{AB} \times \vec{AC}\|$$

$$= \frac{1}{2} \sqrt{(-6)^2 + 3^2 + 0^2}$$

$$= \frac{1}{2} \sqrt{36+9}$$

$$= \frac{1}{2} \sqrt{45} = \frac{3}{2} \sqrt{5}$$

Q. 5

(a) Let $S = \{a(1, 1, 0, -1) + b(2, 0, 2, 0) + c(0, 2, -2, 2) : a, b, c \in \mathbb{R}\}$

$$\therefore S = \text{Span} \{(1, 1, 0, -1), (2, 0, 2, 0), (0, 2, -2, 2)\}$$

represent the ~~set of~~ 3 vectors in matrix form to compute the rank

$$\left[\begin{array}{cccc} 1 & 2 & 0 \\ 1 & 0 & 2 \\ 0 & 0 & 2 \\ -1 & 0 & -2 \end{array} \right] \xrightarrow{R_2 \leftrightarrow R_1} \sim \left[\begin{array}{cccc} 1 & 2 & 0 \\ 0 & -2 & 2 \\ 0 & 2 & -2 \\ 0 & 2 & -2 \end{array} \right] \xrightarrow{R_3 + R_2} \sim \left[\begin{array}{cccc} 1 & 2 & 0 \\ 0 & -2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

\therefore only 1st & 2nd column have leading entry in RE form.

\therefore Basis for S is

$$\{(1, 1, 0, -1), (2, 0, 2, 0)\}$$

and it has dimension = 2

(b) we set $v_1 = (x_1, y_1, z_1) \in S$, ~~$x_1, y_1, z_1 \in \mathbb{R}$~~

$$x_1 + 2y_1 + z_1 = 0 \quad x_2 - y_1 + z_1 = 0$$

$v_2 = (x_2, y_2, z_2) \in S$, ~~$x_2, y_2, z_2 \in \mathbb{R}$~~

$$x_2 + 2y_2 + z_2 = 0 \quad x_2 - y_2 + z_2 = 0$$

$$\underline{v_1 + v_2} = (x_1 + x_2, y_1 + y_2, z_1 + z_2)$$

$$= (x_1 + x_2, y_1 + y_2, z_1 + z_2)$$

$$(x_1 + x_2) + 2(y_1 + y_2) + z_1 + z_2 = (x_1 + 2y_1 + z_1) + (x_2 + 2y_2 + z_2) \\ = 0 + 0 = 0$$

$$(x_1 + x_2) - (y_1 + y_2) + (z_1 + z_2) = (x_1 - y_1 + z_1) + (x_2 - y_2 + z_2) \\ = 0 + 0$$

$$\therefore \underline{v_1 + v_2} \in S$$

\therefore the set is closed under vector addition

Q. 5

Denote the subset as S

(c) Let $\underline{v}_1 = (5, 4)$ $5, 4 \geq 0$

$\therefore \underline{v}_1 \in \text{Subspace } S$

$\underline{v}_2 = (-3, -5)$ $-3, -5 \leq 0$

$\therefore \underline{v}_2 \in S$

$\underline{v}_1 + \underline{v}_2 = (2, -1)$ $2 \geq 0$ $-1 < 0$

$\therefore \underline{v}_1 + \underline{v}_2 \notin S$

\therefore the counterexample exists.

\therefore the subset is not closed under vector addition

(a) dim (row space of A)

= number of leading entries of RE form of A
= 3

(b) dim (solution space of A)

= number of columns with no leading entries of A in RE form

$$= 2$$

(c) Column space of A

$$= \text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix} \right\}$$

(d) We see

$$[a_1 \ a_2 \ a_3 \ b_1] \sim \left[\begin{array}{cccc} 1 & 0 & 0 & 7 \\ 0 & 2 & 0 & -2 \\ 0 & 0 & 3 & -1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

It follows that

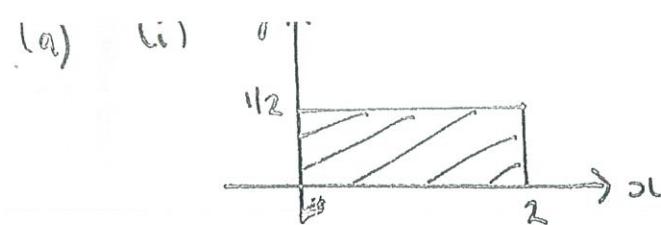
$$7a_1 - a_2 - \frac{1}{3}a_3 = b_1$$

$$(e) \text{ We have } [A|b_1] = \left[\begin{array}{ccccc|c} 1 & 0 & -2 & 0 & 0 & 7 \\ 0 & 2 & 1 & 0 & 1 & -2 \\ 0 & 0 & 3 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

With the unknowns denoted x_1, \dots, x_5 , there is no leading entry for x_5 nor x_3 . We set $x_5 = t, x_3 = s, t, s \in \mathbb{R}$.

Back substitution gives $3x_4 = -1 \Rightarrow x_4 = -\frac{1}{3}s$,
 $2x_2 + x_3 = -s - t - 2 \Rightarrow x_2 = -\frac{1}{2}s - \frac{1}{2}t - 1$, $x_1 = 2s + 7$. Hence the solution set is $\{(2s+7, -\frac{1}{2}s - \frac{1}{2}t - 1, s, -\frac{1}{3}s, t) \mid t, s \in \mathbb{R}\}$

(f) The linear system corresponding to the augmented matrix $[A|b_2]$ is inconsistent. Hence b_2 cannot be expressed as a linear combination of the columns of A



(ii) We read off that

$$T \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \quad T \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1/2 \end{bmatrix}$$

((iii)) Because the area of the image is unchanged, and the order of the areas is unchanged.

(b) (i) Reflection in the line $y=x$.

$$(ii) S_1 \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x-y \\ y \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

and hence

$$A_{S_1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

We recognise this as the standard matrix for a shear by -1 units in the x -direction.

(iii) T_1 applied 5 times is a rotation by π anti-clockwise. The corresponding standard matrix is

$$\begin{bmatrix} \cos \pi & -\sin \pi \\ \sin \pi & \cos \pi \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}.$$

$$(a) (i) \underline{w}_1 = \frac{1}{\sqrt{3}}(1,1,1) \quad \underline{w}_2 = \frac{1}{\sqrt{2}}(0,1,-1)$$

$$\text{With } \underline{x} = (1,1,1)$$

$$\underline{w}_1 \cdot \underline{x} = \frac{1}{\sqrt{3}} 3 \quad \underline{w}_1 \cdot \underline{w}_2 = 0$$

Hence

$$T(1,1,1) = (1,1,1)$$

$$\begin{aligned} (ii) \quad (1,1,1) \times (0,1,-1) &= \begin{vmatrix} i & j & k \\ 1 & 1 & 1 \\ 0 & 1 & -1 \end{vmatrix} \\ &= i \begin{vmatrix} 1 & 1 \\ 0 & -1 \end{vmatrix} - j \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} + k \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} \\ &= -2i + j + k \end{aligned}$$

Geometrically, T is an orthogonal projection onto the plane spanned by \underline{w}_1 and \underline{w}_2 . All vectors perpendicular to this plane will map to 0 and thus give the kernel. The direction perpendicular to the plane is $\underline{w}_1 \times \underline{w}_2$ and so $\ker T$ is equal to its span.

$$(b) (i) \quad T(1,0,0) = \frac{1}{3}(1,1,1)$$

$$T(0,1,0) = \frac{1}{3}(1,1,1) + \frac{1}{2}(0,1,-1) = \frac{1}{6}(2,5,-1)$$

$$T(0,0,1) = \frac{1}{3}(1,1,1) - \frac{1}{2}(0,1,-1) = \frac{1}{6}(2,-1,5)$$

Putting these vectors down the columns of a matrix in order gives A_T

(ii) Since $A_T \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ the vector $(-2,1,1)$ belongs to the solution set of A_T .

9. (a) Because there are 3 vectors, each an element of \mathbb{R}^3 , and the 3 vectors are linearly independent.

$$(b) \begin{bmatrix} \underline{x} \\ \underline{c}_1 \\ \underline{c}_2 \\ \underline{c}_3 \end{bmatrix}_B = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} \Rightarrow \underline{x} = 2\underline{c}_1 + \underline{c}_2 + \underline{c}_3 \\ = (2, 0, -2) + (1, 0, 1) + (0, 1, 0) \\ = (3, 1, -1)$$

$$(c) P_{S,C} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & 1 & 0 \end{bmatrix}, \quad P_{C,S} = P_{S,C}^{-1}$$

Consider

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} R_2 \cap R_1$$

$$\sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\frac{1}{2}R_2} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \cap R_2}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{bmatrix} 1/2 & 0 & -1/2 \\ 1/2 & 0 & 1/2 \\ 0 & 1 & 0 \end{bmatrix}} \text{Hence } P_{C,S} = \begin{bmatrix} 1/2 & 0 & -1/2 \\ 1/2 & 0 & 1/2 \\ 0 & 1 & 0 \end{bmatrix}$$

$$(d) \begin{bmatrix} \underline{x} \\ \underline{c}_1 \\ \underline{c}_2 \end{bmatrix}_B = \frac{1}{2} \begin{bmatrix} -1 & 1 & 0 \\ 1 & 0 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\text{Hence } \underline{x} = \frac{1}{2} \underline{c}_1 + \frac{1}{2} \underline{c}_2.$$

(e) From (d) we read off from the first column in $P_{B,B}$ that

$$\begin{bmatrix} \underline{b}_1 \\ \underline{b}_2 \end{bmatrix}_B = \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \quad \text{Hence} \quad \underline{b}_1 = -\frac{1}{2} \underline{c}_1 + \frac{1}{2} \underline{c}_2 \\ = -\frac{1}{2} (1, 0, -1) + \frac{1}{2} (1, 0, 1) \\ = (0, 0, 1).$$

(a) In the formula

$$u_1 v_1 + u_2 v_2 + u_3 v_3$$

we substitute

$$u_3 = (u_1 - u_2)$$

$$v_3 = (v_1 - v_2)$$

This gives

$$u_1 v_1 + u_2 v_2 + (u_1 - u_2)(v_1 - v_2)$$

$$= u_1 v_1 + u_2 v_2 + u_1 v_1 - u_1 v_2 - u_2 v_1 + u_2 v_2$$

$$= 2u_1 v_1 - u_1 v_2 - u_2 v_1 + 2u_2 v_2.$$

which agrees with
the expanded
form of

$$[u_1, u_2] \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix} [v_1, v_2]$$

(b) From the construction of $\langle (u_1, u_2), (v_1, v_2) \rangle$
we have

$$\langle (u_1, u_2), (u_1, u_2) \rangle = u_1^2 + u_2^2 + u_3^2 \quad \text{with}$$

$$u_3 = u_1 - u_2$$

Hence $\langle (u_1, u_2), (u_1, u_2) \rangle \geq 0$

and $\langle (u_1, u_2), (u_1, u_2) \rangle = 0$ when $u_1 = u_2 = u_3 = 0$

Since $u_3 = u_1 - u_2$ this can be reduced to
 $u_1 = u_2 = 0$.

(c) Let the sought vector be (x, y) . We have

$$\langle (1, 1), (x, y) \rangle = 2x - y - x + 2y = (x+y).$$

Hence for $\langle (1, 1), (x, y) \rangle = 0$, require $x = -y = t \in \mathbb{R}$

so $(x, y) = (t, -t)$. For normalisation

$$\langle (t, -t), (t, -t) \rangle = 2t^2 + t^2 + t^2 + 2t^2 = 6t^2 \Rightarrow t = \frac{1}{\sqrt{6}}$$

Hence $(x, y) = \frac{1}{\sqrt{6}} (1, -1)$.

$$\therefore (a) \text{ Define } A = \begin{bmatrix} 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$$

The unknowns $\begin{bmatrix} a \\ b \end{bmatrix}$ in the line of best fit satisfy

$$A^T A \begin{bmatrix} a \\ b \end{bmatrix} = A^T \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$$

$$\text{Now } A^T A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix} = \begin{bmatrix} 3 & 9 \\ 9 & 29 \end{bmatrix}$$

$$A^T \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 16 \end{bmatrix}$$

Thus

$$\begin{bmatrix} 3 & 9 \\ 9 & 29 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 5 \\ 16 \end{bmatrix}$$

$$\text{linear system } \left[\begin{array}{cc|c} 3 & 9 & 5 \\ 9 & 29 & 16 \end{array} \right]_{R_2-3R_1} \sim \left[\begin{array}{cc|c} 3 & 9 & 5 \\ 0 & 2 & 1 \end{array} \right]$$

$$\Rightarrow b = \frac{1}{2}$$

$$3a + 9 \cdot \frac{1}{2} = 5 \Rightarrow a = \frac{1}{6}$$

Thus the line of best fit is $Y = \frac{1}{6} + \frac{1}{2}X$

(b) Substituting $X = 6$ gives $Y = 3\frac{1}{6}$

To the nearest integer, 3 kg are predicted as the weight loss.

L. (a) (i) Let the two vectors be denoted \underline{b}_1 and \underline{b}_2 . By inspection

$$\underline{b}_1 \cdot \underline{b}_1 = 1, \quad \underline{b}_2 \cdot \underline{b}_2 = 1, \quad \underline{b}_1 \cdot \underline{b}_2 = 0$$

Hence \mathcal{B} is an orthonormal set.

$$\begin{aligned} \text{(ii)} \quad A &= \frac{1}{2} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \\ &= \frac{1}{2} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 2 & 2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} \end{aligned}$$

(iii) Since \mathcal{B} is an orthonormal set, $A^{-1} = A^T$, we have

$$A Q = Q D$$

This is the matrix form of the eigenvalue equation and tells us that

$\lambda = 1$ is an eigenvalue, normalised eigenvector $\frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$\lambda = 2$ is an eigenvalue, normalised eigenvector $\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

(i) The lines $y = -x$, and $y = x$.

(ii) The line $y = -x$ is left unchanged, implying eigenvalue $\lambda = 1$.

The line $y = x$ is flipped, implying eigenvalue $\lambda = -1$.