

Group

Segmentation:

The chunks that a program is divided into which are not necessarily all in the same size called segments or Segmentation.

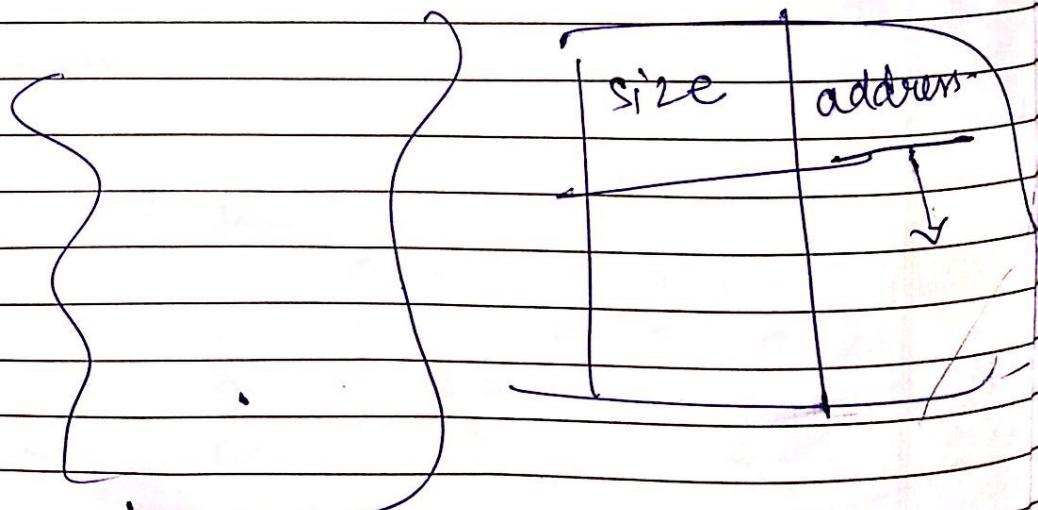
In Main Memory, we only store the segment table is used of process. This advantages: process is stored in table form which keeps the record of segment, its size and memory address.

Advantages:

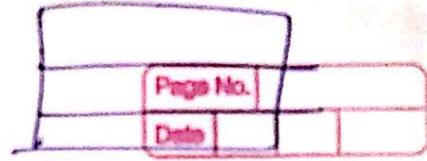
- Segmented table occupies less space.
- No internal fragmentation.

Disadvantages:

- Due to segments external fragmentation it results in a lot of memory waste.



team:
me
C 0000000000000000



Segmentation Paging

variable size

fixed size

External fragmentation

→ internal fragmentation

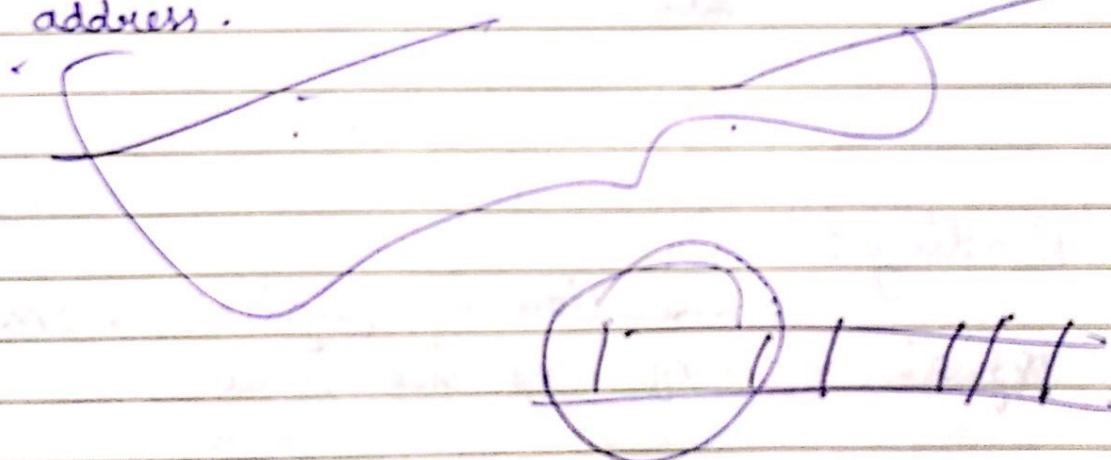
user specified address
is divided by CPU
into

Hardware decides
user specified
size.

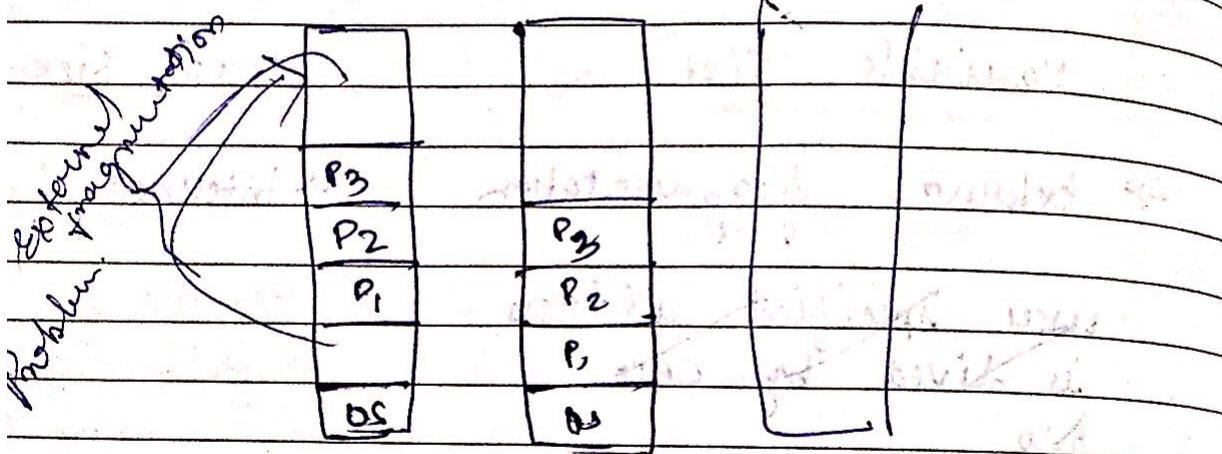
→ Hardware decides
the size

size and memory
address.

→ Base address of
each page.



External Fragmentation



Binding :

Compile

Load

Binding :

translation of physical memory to logical memory or vice versa

- compile
- load
- execution.

ch-4

Switch On / OFF

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→ Garbage Collection:

* Memory Management:

→ Issue that prompt this →

① Allocation

② Swapping, Fragmentation & Compaction

→ Garbage Collection:

The area released by a process is usually not accounted for immediately by the process - it's garbage. compaction or garbage collection is responsibility of the OS.

→ Protection:

Checking for illegal access of data from another process memory area.

* Binding :

Address binding of instruction and data to memory address can happen at three different stages.

→ Compile Time :

If memory location known at ~~pub~~,
absolute code can be generated; must
recompile code if starting location
changes

→ Load Time :

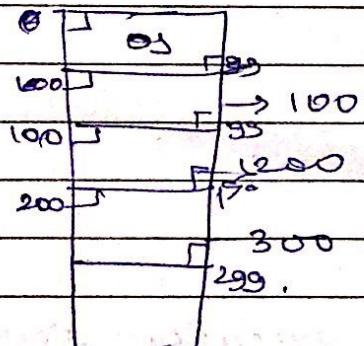
Must generate relocatable code if
memory location is ~~not~~ known at
compile time.

→ Execution time :

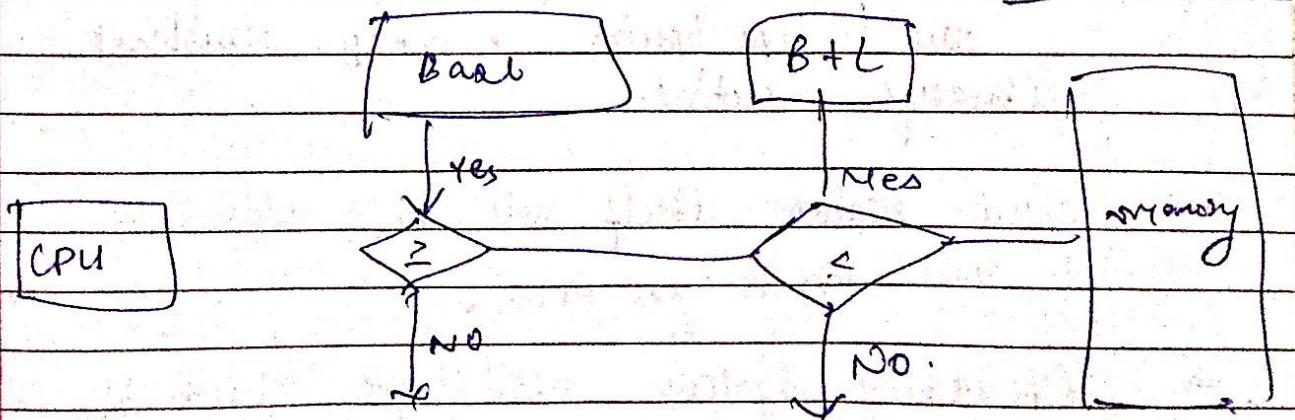
Binding delayed until run time
if the process can be moved during its
execution from one memory segment to
another. Need hardware support for
address maps.

* Memory Management Unit

- Hardware device that maps virtual to physical address.
- In MMU scheme, the value in the relocation register is added to every address generated by a user process at the time it is sent to memory.
- The user program deals with logical address, it can never see its physical address.



$$100 + 199 = 299$$



* Dynamic Loading :

- Routine is not loaded until it is called.
- Better memory space utilization; unused routine is never loaded.
- useful when large amount of codes are needed to handle infrequent occurring cases.
- NO special support from the operating system is required implemented through program design.

* Dynamic Linking :

- linking postponed until execution time.
- Small piece of code, stub, used to locate the appropriate memory-resident library routine.
- Stub replace itself with the address of the routine, and execute the routine.
- Operating system needed to check if routine is in process memory address.

→ Dynamic linking is particularly useful for libraries.

→ Memory allocation technique

- first fit → 40

- Best fit → 10

- Worst fit → 40

- Next fit → allocated at 1st available slot

Technique used to solve External fragmentation.

	→	external fragmentation	P ₃	40
30			P ₂	
20				20
10			P ₁	10
05				05

Per 5 KB

* Context switching :

It occurs when a computer's CPU switches from one process to a different process.

It allows for one CPU to handle numerous processes without the need for

additional processor.

A context switch is the mechanism to store and restore the data state or context of a CPU in process Control Block so that a process execution can be resumed from the same point at a later time.

Any operating system that allows for multi tasking relies heavily on the use of context switching to allow different processes to run at the same time.

- ⇒ Typically, there are three situations that a context switch is necessary
 - Multi-tasking : when the CPU needs to switch process in and out of memory, so that more than one process can be running.
 - Kernel / switch : when switching between user mode to kernel mode, it may be used.
 - Interrupts : when the CPU is interrupted to return data from a disk read.

⇒ The steps in the full process switch are :

- ① Save the content of the processor, including program counter and other registers.

- ② Update the process control block of the process that is currently in the running state. This includes changing the state of process to one to other states (ready, blocked, suspend, exit). Other relevant fields must also be updated, including the reason for leaving the running state and accounting information.
- ③ Move the PCB of the process to appropriate queue (Ready; Blocked on event i; Ready (suspend))
- ④ Select another process for execution
- ⑤ Update the PCB of the process selected. This includes changing the state of the process to Running.
- ⑥ Update Memory management data structures. This may be required, depending on how address translation is managed.

* Universal Serial Bus

→ Classification:

- ① Human Interaction device class
- ② Communication device class
- ③ Printer device class
- ④ Mass storage device class

→ Modes of communication:

- ① Interrupt
- ② Bulk transfer
- ③ High Synchronous
- ④

→ Three tier Architecture:

* **Address Binding:** It is the process of mapping the program's logical or virtual addresses to corresponding physical or main memory address.

(OR)

A given logical address is mapped by MMU to a physical address.

* **Internal Fragmentation:** It occurs when the memory is divided into fixed size blocks, whenever a process request for the memory, the fixed size block is allocated to the process. In case, if the memory assigned to the process is somewhat larger than the memory requested, then the difference between assigned and request memory is known as IF.

* **External Fragmentation:** It occurs when there is a sufficient amount of space in the memory to satisfy the memory request of a process. But the process's memory request cannot be satisfied as the memory available is in a non-contiguous manner. Either you apply first-fit or best fit memory allocation strategy it will cause EF.

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when a process is loaded and removed from the memory the free space creates the hole in the memory space, and there are many such holes in the memory space.

Compaction may be the solution.

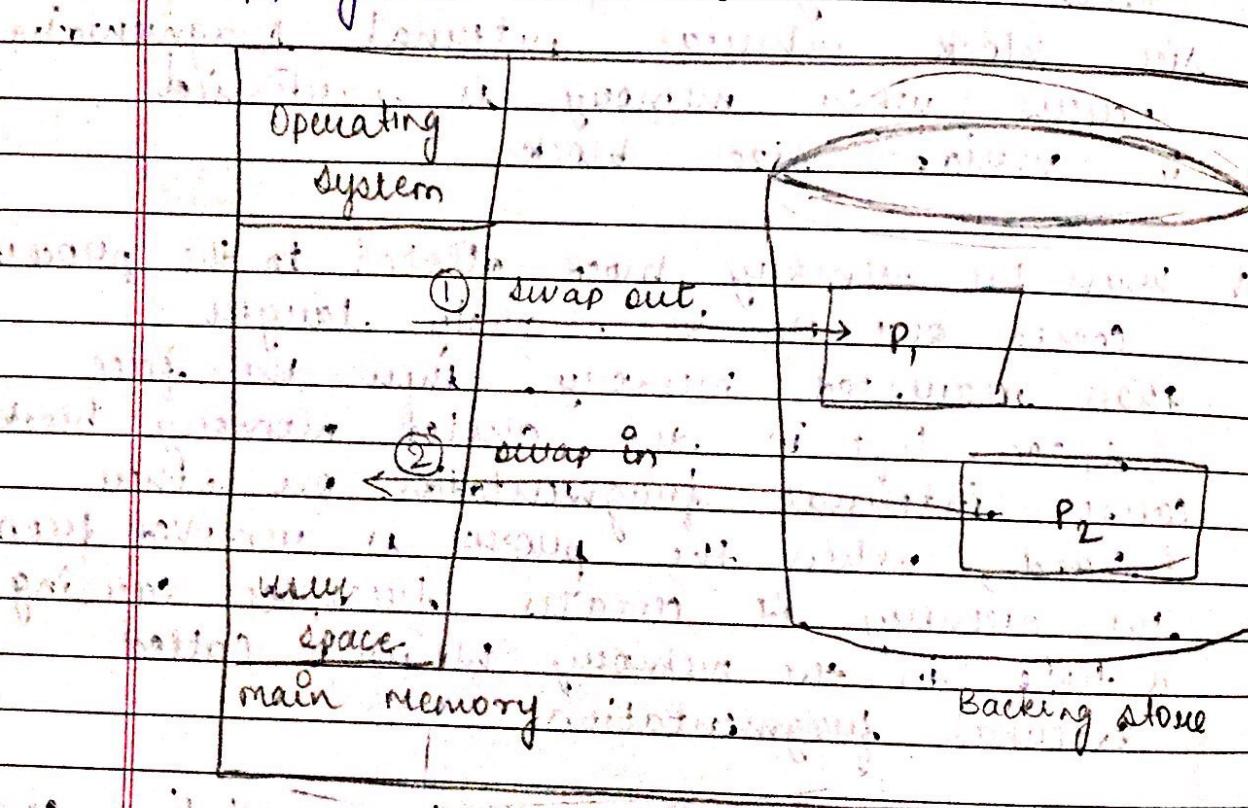
Compaction algorithm shuffles all memory contents to one side and free one large block of memory. But Compaction algorithm

* Key Difference between IF & EF

- 1) The basic reason behind the occurrence of internal and external fragmentation is that internal fragmentation occurs when memory is partitioned into fixed size block whereas external fragmentation occurs when memory is partitioned in variable size block.
- 2) When the memory block allotted to the process comes out to be slightly larger than requested memory, then the free space left in the allotted memory block cause internal fragmentation. On other hand, when the process is removed from the memory it creates freespace causing a hole in the memory which is called external fragmentation.
- 3) The problem of Internal fragmentation can be solved by partitioning the memory into variable size block and assign the best fit block to the requesting process. However, the solution for external fragmentation is compaction, but it is expensive to implement, so the process must be allowed to acquire

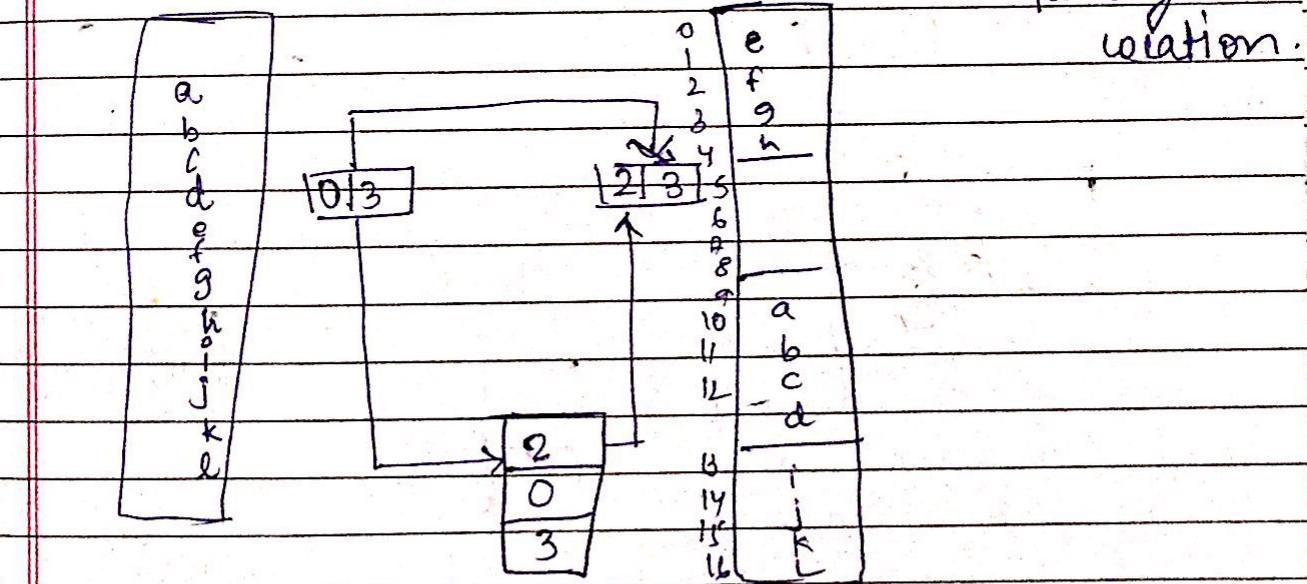
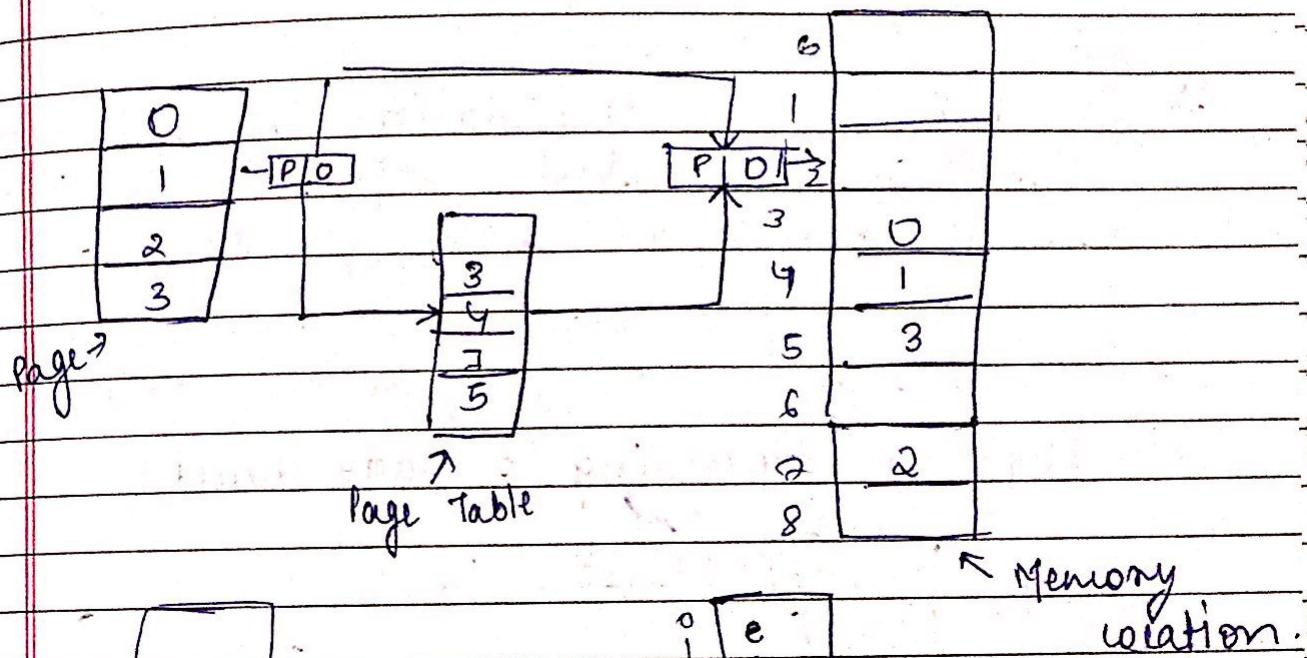
* physical memory is non-contiguous manner, to achieve the technique of paging and segmentation is introduced.

* Swapping: moving the unneeded part.



A process can be swapped temporarily out of memory to a backing store, and then brought back into memory for continuous execution.

* Paging



PTBR : Page Table Base Register

PTLR : Page Table Length Register

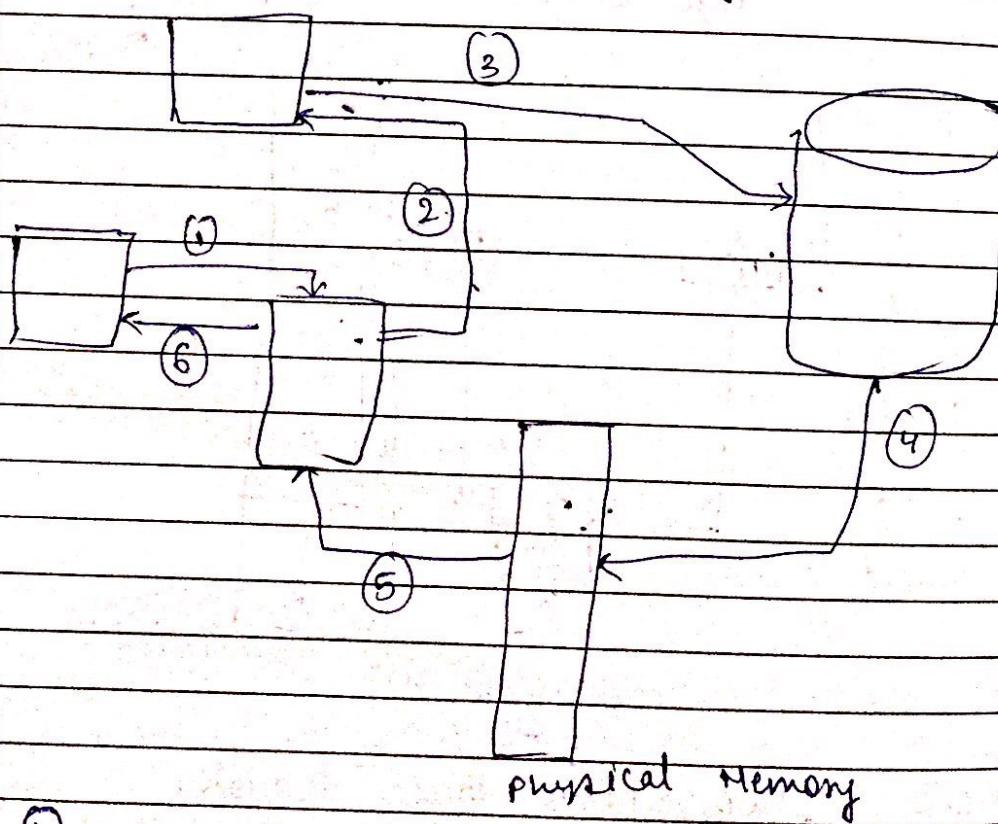
ASID : Address Space Identifier

TLB : Transaction Loop Buffer.

* Short note on Paging & buddy System. *

→ During address translation, if valid-invalid bit is page table entry is 0 then it is known as page fault.

→ Steps in handling a page fault



①

②

③ Page is on backing store

④ Bring in missing page

⑤

⑥ restart instruction

* Advantage of Demand Paging

→ Bringing a page into memory only when needed

- less I/O needed
- less memory needed
- faster response
- more users.

→ Page is needed \Rightarrow reference to it

- invalid reference \rightarrow abort
- not in memory \rightarrow bring to memory

* Basic Page Replacement

- ① find the location of the desired page on disk
- ② find a free frame:
- ③ read the desired page, update
- ④ restart the instruction.

Algorithm

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* first In first Out

(1)

1 2 3 4 1 2 5 1 2 3 4 5

1	1	1	4	4	4	5			5	5
2	2	2	2	1	1	1			3	3
3	3	3	3	2	2	2			2	4

2

Page default = 9.

(2)

1 2 3 1 4 3 2 3 4 1 3 2 5

1	2	3	1	4	3	2	3	4	1
1	1	1	1	4				4	
2	2	2	2	2	3			1	
3	3	3	3	3	3			3	
4	4	4	5						
			1	1					
			2	2					

4

Page Default : 7

(3)

-	1	2	3	4	1	2	5	1	2
.	-	2	2	2	.	-	2	-	1
.	-	3	3	.	.	.	3	3	2
.	-	4	4	4	4
5	1	2	3	4	5	1	2	3	4

4

5	4	4
1	1	5
2	2	2
3	3	3

[Problem of FIFO]
Belady
Anomaly.

Page fault: 10

(4)

1	1	2	3	1	4	3	2	3
4	1	2	2	.	2	.	.	.
1	.	3	.	3	.	4	.	.
3	.	.	3	.	4	.	.	.
4	1	3	2	3	2	5	5	2
1	2	4	1	3	4	3	2	4
3	4	5	2	3	5	4	3	4
5	2	3	4	5	3	4	2	3
4	3	5	4	2	1	3	5	1

Page fault : 5.

70120304230321201701

0	0	+1	2	0	3	0	4	2	3	0	3
-2	7	7	-2	1	-2	2	-4	0	0	0	7
-0	0	0	-3	3	3	-3	-3	3	3	3	
-1	1	1	1	-0	0	2	-2	2	2	2	

2 1 2 0 1 2 0 1

0						0					
1						1					
2						7					

7	0	1	2	0	3	0	4	2	3
-2	7	7	2	0	2	-2	4	4	-4
0	0	-0		3	3	-3	2	2	

0	3	2	1	2	0	1	2	0	1
-2			1	1			-1	0	0
3		-3	2				2	-2	1

Page Default

15 - 3.

10 - 4

09 - 5

Optimal Page Replacement

7	0	1	2	0	3	0	4	2	3	0
7	7	2	2		2		2			2
0	0	0			0		4			0
1	1				3		3			3

3	2	(1)	2	0	1	3	0	1
			2		2		2	
		0			2		0	
		1			3		4	

7	0	1	2	0	3	0	4
7	7	7	2		3		3
0	0	0	0		0		0
1		1	1		1		4

2	3	0	3	2	1

2	0	1	2	0	1

Page fault : 8