view_frames Result Recorded at time: 366.164 odom Broadcaster: /odometer1 Broadcaster: /odom_link_broadcaster Average rate: 100.671 Hz Average rate: 10.684 Hz Most recent transform: 366.157 (0.007 sec old) Most recent transform: 366.200 (-0.036 sec old) Buffer length: 1.490 sec Buffer length: 1.404 sec fake_odom base_link Broadcaster: /robot_state_publisher Broadcaster: /odometer2 Average rate: 10000.000 Hz Average rate: 100.671 Hz Most recent transform: 0.000 (366.164 sec old) Most recent transform: 366.157 (0.007 sec old) Buffer length: 0.000 sec Buffer length: 1.490 sec body_link fake base link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 44.188 Hz Average rate: 44.188 Hz Most recent transform: 0.000 (366.164 sec old) Most recent transform: 0.000 (366.164 sec old) Most recent transform: 366.148 (0.016 sec old) Most recent transform: 366.148 (0.016 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 1.471 sec Buffer length: 1.471 sec left_wheel right_wheel base_scan caster