view_frames Result Recorded at time: 1438343238.103 map Broadcaster: /amcl Average rate: 10.262 Hz Most recent transform: 1438343238.957 (-0.855 sec old) Buffer length: 4.677 sec odom Broadcaster: /segway_rmp_node Average rate: 100.161 Hz Most recent transform: 1438343238.115 (-0.013 sec old) Buffer length: 4.852 sec base_footprint Broadcaster: /robot_state_publisher Average rate: 5.217 Hz Most recent transform: 1438343238.542 (-0.439 sec old) Buffer length: 4.600 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 5.217 Hz Average rate: 4.000 Hz Most recent transform: 1438343238.011 (0.092 sec old) | Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) \ Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.542 (-0.439 sec old) Buffer length: 4.600 sec Buffer length: 4.500 sec l_wheel_link r_wheel_link waist link b_wheel_base_link f_wheel_base_link nav_hokuyo_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 4.000 Hz Average rate: 5.217 Hz Average rate: 4.000 Hz Average rate: 4.000 Hz Average rate: 4.000 Hz Average rate: 4.000 Hz Most recent transform: 1438343238.542 (-0.439 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Buffer length: 4.500 sec Buffer length: 4.600 sec f_wheel_link b_wheel_link neck_pan_link l_shoulder_scapula_link r_shoulder_scapula_link nav_hokuyo_laser_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 4.000 Hz Average rate: 4.000 Hz Average rate: 4.000 Hz Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Buffer length: 4.500 sec Buffer length: 4.500 sec Buffer length: 4.500 sec neck_tilt_link l_shoulder_flection_link r_shoulder_flection_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: $4.000 \, \text{Hz}$ Average rate: 4.000 Hz Average rate: 4.000 Hz Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Buffer length: 4.500 sec Buffer length: 4.500 sec Buffer length: 4.500 sec eyes_tilt_link l_shoulder_abduction_link r_shoulder_abduction_link Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Broadcaster: /robot_state_publisher Average rate: 5.217 Hz Average rate: 4.000 Hz Average rate: 4.000 Hz Most recent transform: 1438343238.542 (-0.439 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Buffer length: 4.600 sec Buffer length: 4.500 sec Buffer length: 4.500 sec eyes_center_link l_shoulder_rotation_link r_shoulder_rotation_link Broadcaster: /robot_state_publisher Average rate: 4.000 Hz Average rate: 5.217 Hz Average rate: 4.000 Hz Most recent transform: 1438343238.011 (0.092 sec old) | Most recent transform: 1438343238.011 (0.092 sec old) | Most recent transform: 1438343238.011 (0.092 sec old) | Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.542 (-0.439 sec old) Buffer length: 4.500 sec Buffer length: 4.500 sec Buffer length: 4.600 sec Buffer length: 4.500 sec Buffer length: 4.500 sec Buffer length: 4.500 sec Buffer length: 4.500 sec l_eye_version_link r_eye_version_link version_link l_elbow_flection_link r_elbow_flection_link eyes_center_vision_link vergence_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 4.000 Hz Average rate: 4.000 Hz Average rate: 4.000 Hz Average rate: 4.000 Hz Most recent transform: 1438343238.011 (0.092 sec old) Buffer length: 4.500 sec Buffer length: 4.500 sec Buffer length: 4.500 sec Buffer length: 4.500 sec l_eye_vergence_link r_eye_vergence_link r_forearm_pronation_link l_forearm_pronation_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 5.217 Hz Average rate: 5.217 Hz Average rate: 4.000 Hz Average rate: 4.000 Hz Most recent transform: 1438343238.542 (-0.439 sec old) Most recent transform: 1438343238.011 (0.092 sec old) Most recent transform: 1438343238.542 (-0.439 sec old) Most 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transform: 1438343238.542 (-0.439 sec old) Most recent transform: 1438343238.542 (-0.439 sec old) Buffer length: 4.600 sec Buffer length: 4.600 sec l_palm_link r_palm_link