0점잡기 테스트

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| #include <Servo.h>    Servo servo2;  Servo servo3;  Servo servo4;  int angle = 0; // servo position in degrees  void setup()  {  Serial.begin(9600);  servo2.attach(2);  servo3.attach(3);  servo4.attach(4);  }  void loop()  {    Serial.print("start");  //초기자세  servo2.write(90);  servo3.write(30);  servo4.write(90);  //return;  Servo servo = servo3;  //scan from 0 to 180 degrees  for(angle = 0; angle < 90; angle++)  { servo2.write(70+angle);  servo3.write(angle);  servo4.write(100+angle);  delay(15);  }  /\*  Servo servo = servo4;  //scan from 0 to 180 degrees  for(angle = 0; angle < 180; angle++)  {  Serial.print(angle);  //servo.write(angle);  //servo2.write(angle);  servo3.write(angle);  servo4.write(angle);  delay(15);  }  // now scan back from 180 to 0 degrees  for(angle = 180; angle > 0; angle--)  {  Serial.print(angle);  //servo2.write(angle);  servo3.write(angle);  //servo4.write(angle);  delay(15);  } \*/  } |