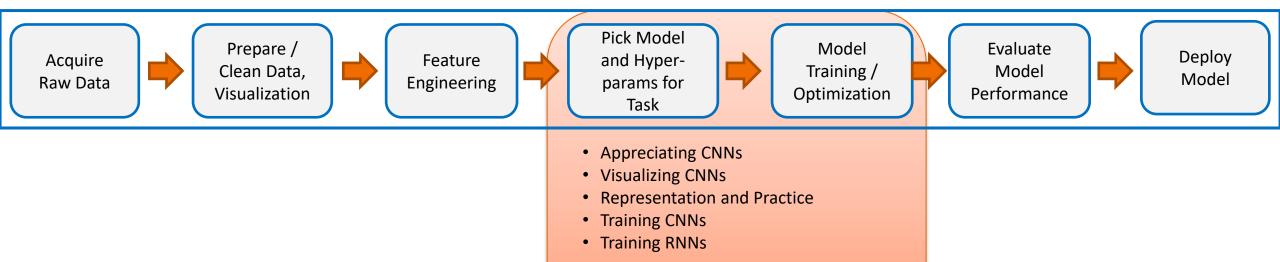


Today's Focus



Appreciation of Convolutional Neural Networks

Visualization, Interpretation



Recap: CNNs



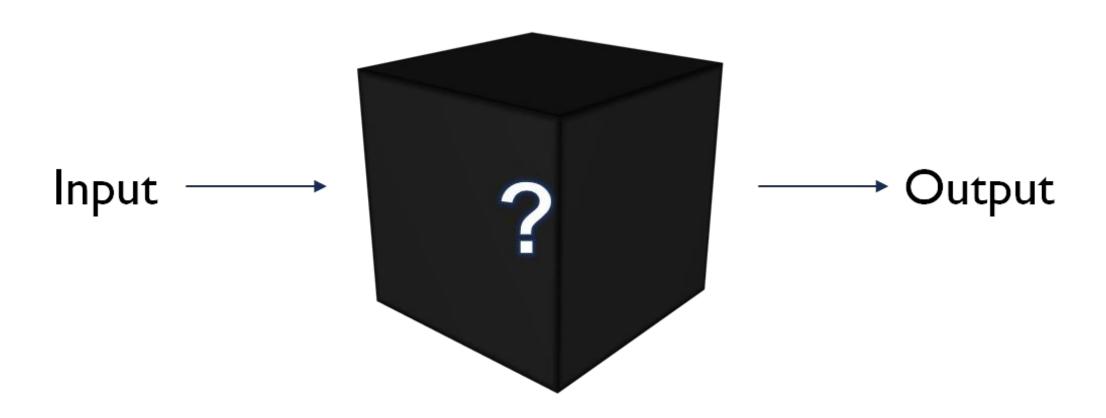
Recap: CNNs



Recap: CNNs



What goes on inside a convnet?



What is in this image?



epochs

Which part of the image explains the classification?

Input C2 Maxpool C3 C4 Maxpool C5 C6 C7 Maxpool C8 C9 C10 Maxpool C11 C12 C13 Maxpool D3 Monitoring

Output

Feature Inversion

Feature

training

Saliency

Cat

conv5

Dog



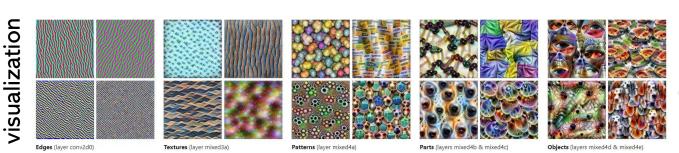
fc6



fc7

fc8

How much information is retained/discarded at each layer of a deep network?



What pattern does each convolutional filter search for?

How well is the CNN getting trained?



- Activation maximization
- Deep Dream
- Feature inversion
- Saliency visualization
- Statistical methods

How do we study what happens inside convnets

LOOK INSIDE CONVNETS



ACTIVATION MAXIMIZATION



filter 1

Activation Maximization

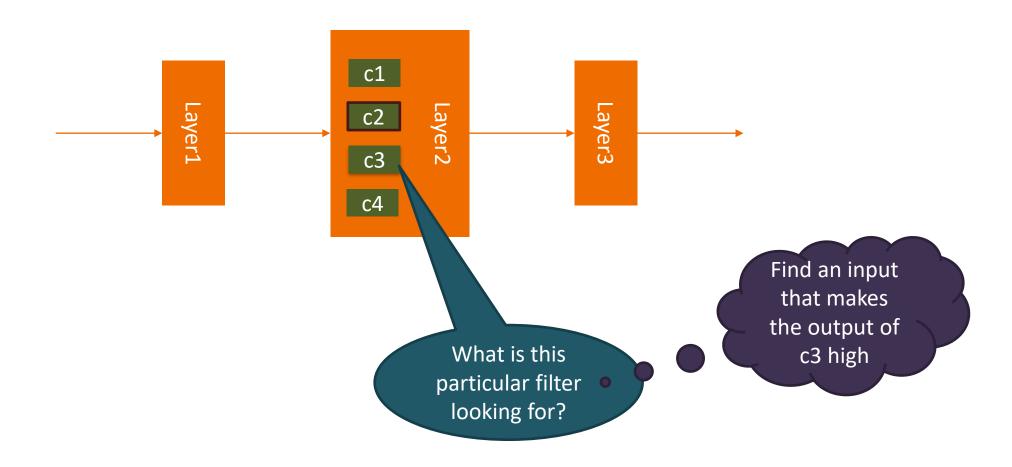
- Visualize filters of a conv net
- What patterns is a filter looking for in an input image?

Filters get more complicated towards the last layers

We need to find an image that maximizes the activation of a filter

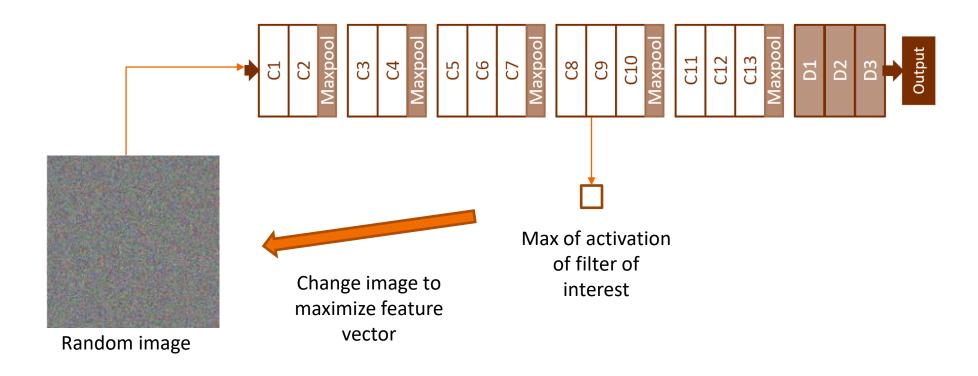


Activation maximization





Activation maximization method

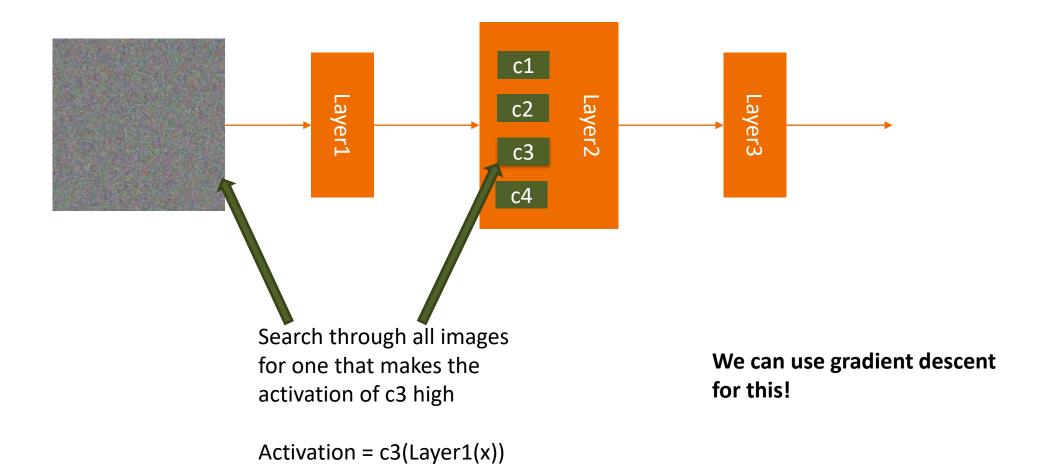


•
$$x^* = \underset{x}{argmax} h(x) + \lambda R$$

where R is a regularization function



Activation maximization

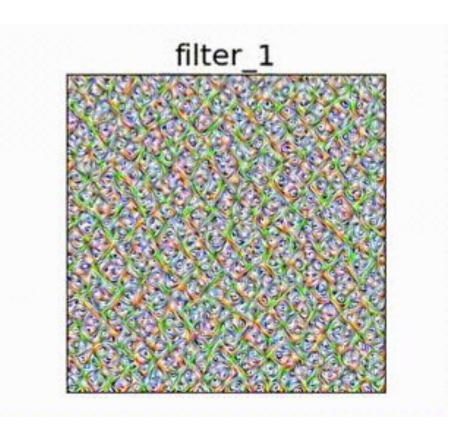


NSE talent



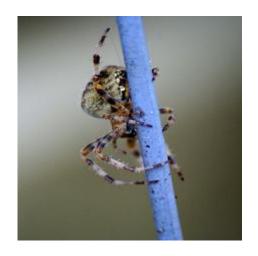
Convolutional Neural Network Filter Visualization

- Optimize the input image with respect to output of the specific convolution operation
- Used a pre-trained VGG16
- Visualizations of layers start with basic color and direction filters at lower levels
- Complexity of the filters also increase in the final layers

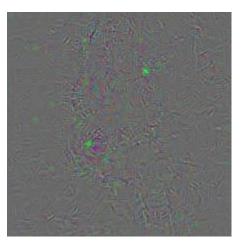




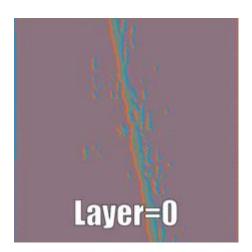
Understanding VGG net w.r.t an input



Input Image



Gradients generated with vanilla back propagation from Input



Visualize activations of Filter 0 in the first 30 layers of VGG16 net for given input



Visualize activations of the first 30 filters in layer 29 for given input



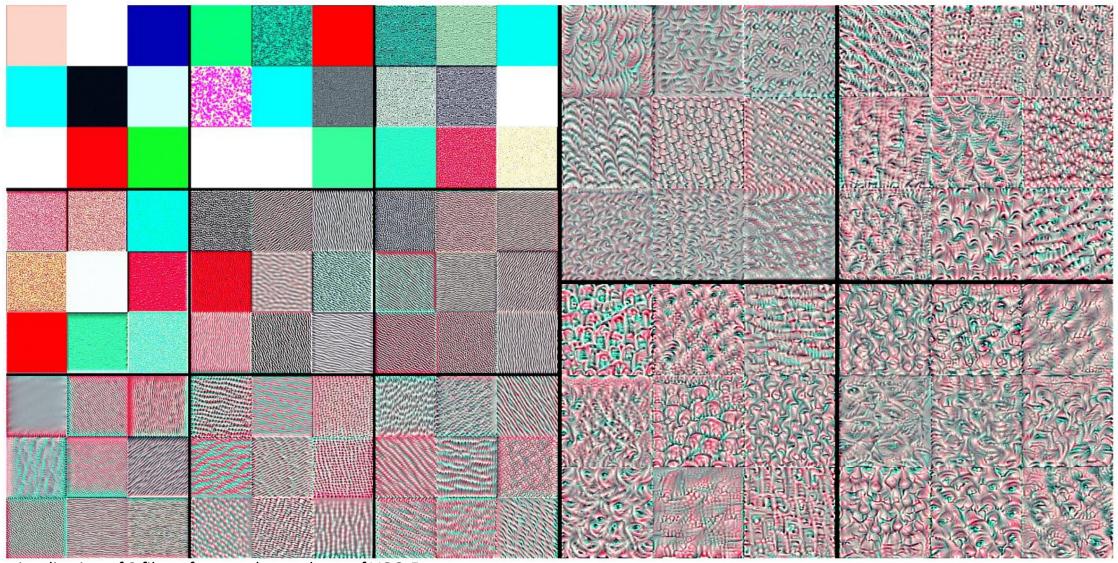
Filter hierarchy of object recognition network



Image source: <u>Feature Visualization (distill.pub)</u>
Feature visualization of GoogleNet layers

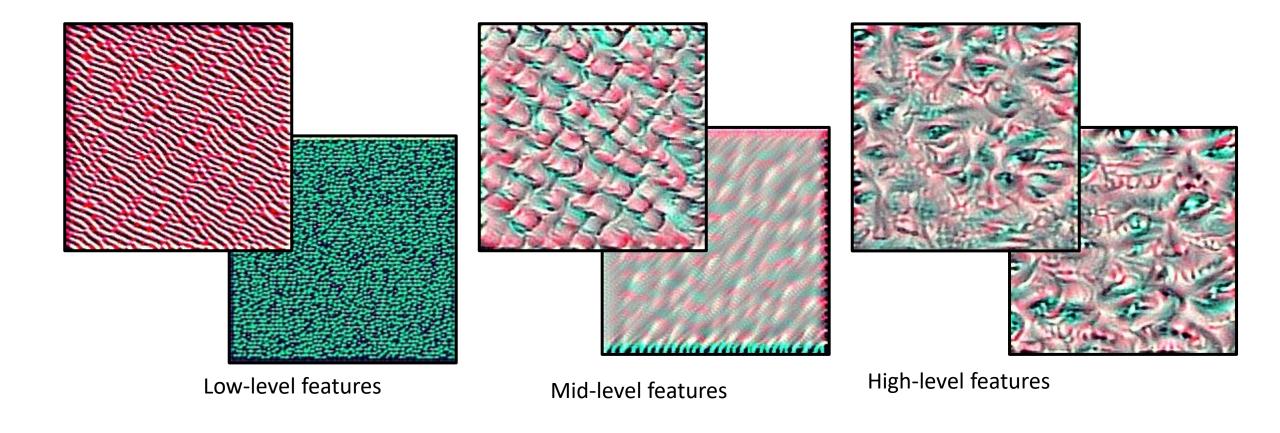


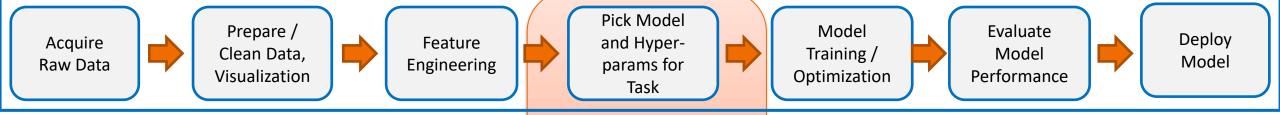
Filter hierarchy of face networks

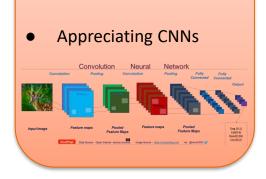




Filter hierarchy for face networks







Insight into CNNs

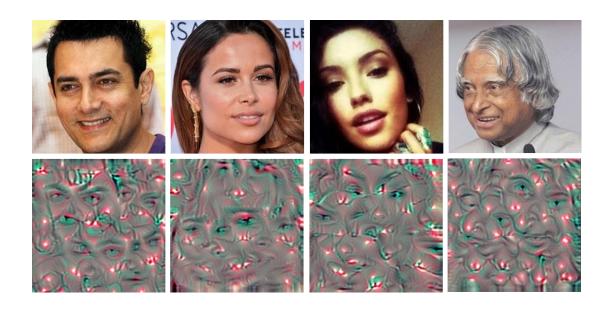


What do they learn?



Class visualization

Visualize the output neurons instead of a specific conv filter



Maximize the **output** of a class neuron



Turtle



Pelican



Tarantula



Chains



Better Visualizations





Deep dream: AI Creativity?

How does a convnet interpret an image?

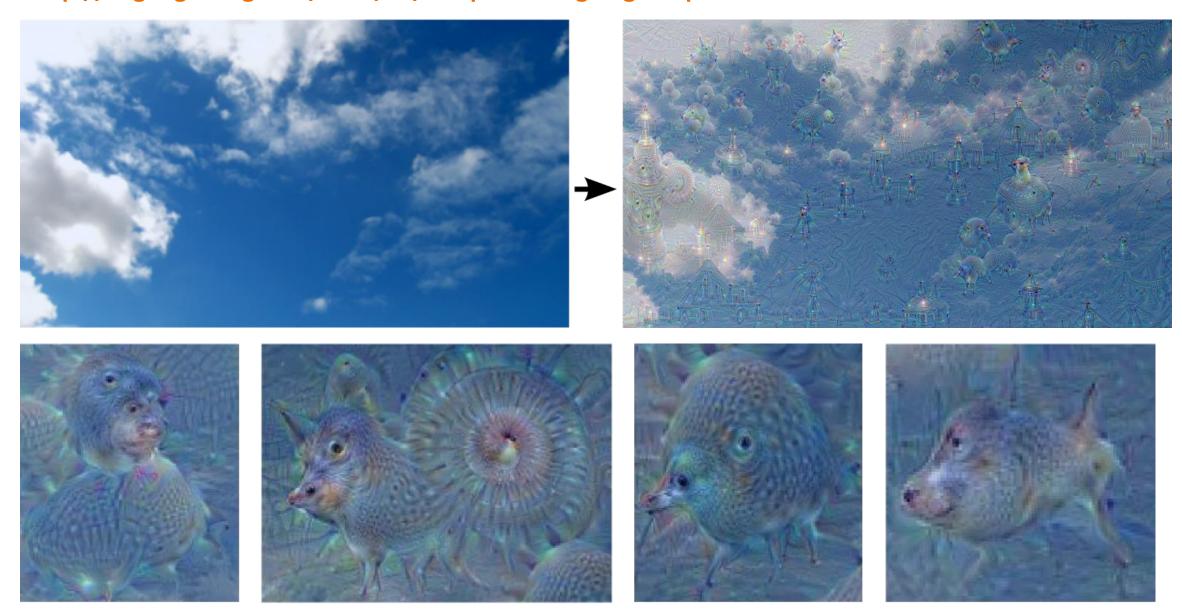






Interpreting a cloudy sky

http://ai.googleblog.com/2015/06/inceptionism-going-deeper-into-neural.html



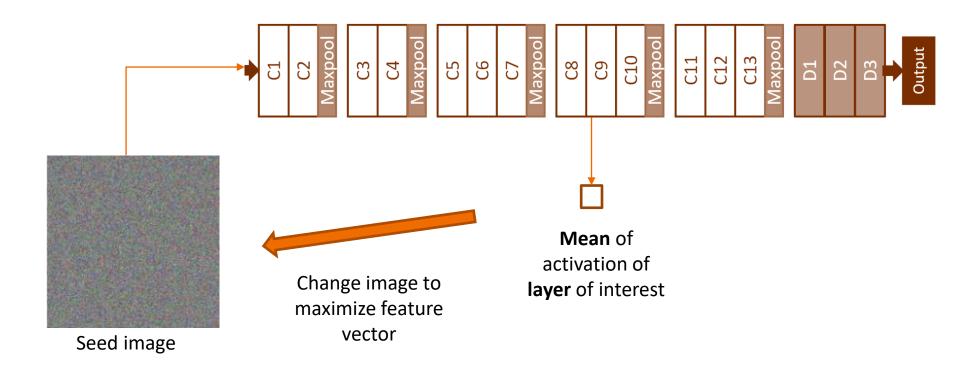


Procedure

- Start with a natural image instead of a blank image
- Pick a layer we want to visualize
- Instead of choosing a filter, the loss function is the mean of the entire layer (This makes the model 'choose' what it sees)



Deep Dream method



•
$$x^* = \underset{x}{argmax} h(x) + \lambda R$$

where R is a regularization function



Deep dream: AI Creativity?



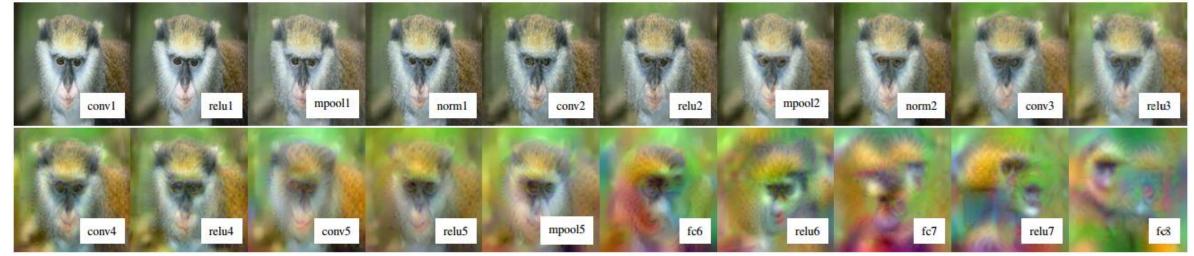
https://deepdreamgenerator.com/; https://en.wikipedia.org/wiki/DeepDream



Feature Inversion

- Invert a feature representation back to image space
- What information is retained or discarded down the layers?



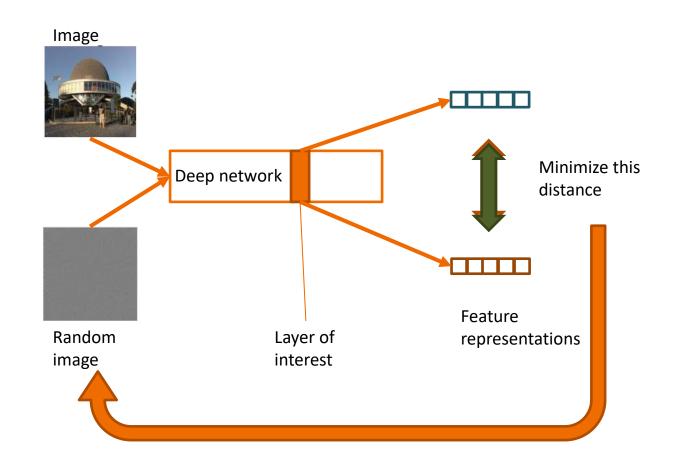




Method

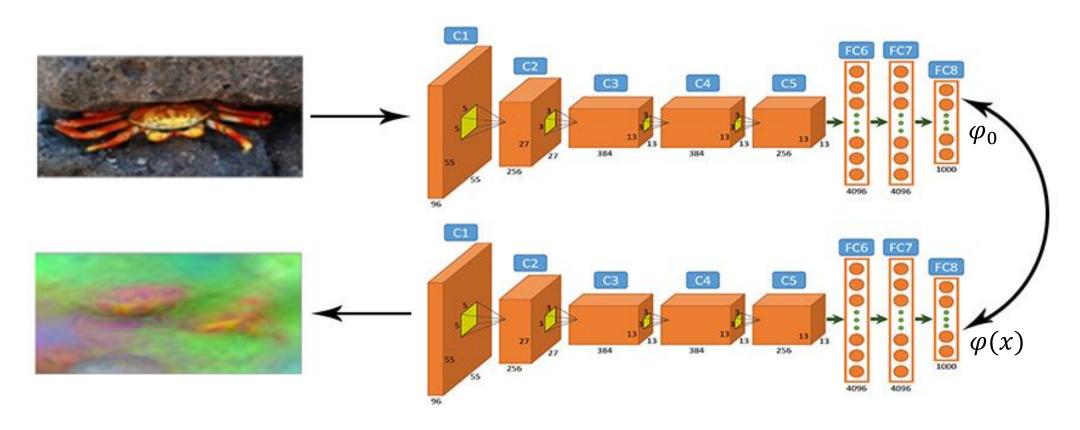
$$\mathbf{x}^* = \operatorname*{argmin}_{\mathbf{x} \in \mathbb{R}^{H \times W \times C}} \ell(\Phi(\mathbf{x}), \Phi_0) + \lambda \mathcal{R}(\mathbf{x})$$

Where $\ell(l)$ is a distance function between two feature representations and $\mathcal{R}(l)$ is a regularization function.





Inverting Specific Representation



$$x^* = \underset{x \in R}{\operatorname{argmin}} L(\varphi(x), \varphi_0) + \lambda R(x)$$

Aravindh Mahendran and Andrea Vedaldi, Understanding Deep Image Representations by Inverting Them, CVPR'15



Inverting at different stages

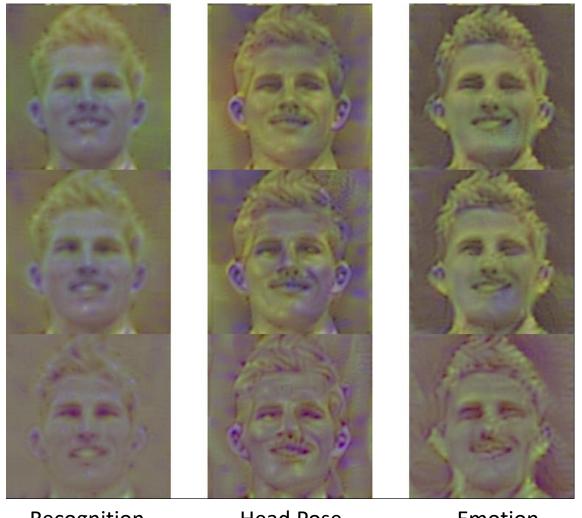
 As we go down the layers, unnecessary information is discarded, and only discriminatory information remains





Inverting faces

 Convnets trained for different tasks find different kinds of information useful to keep



Recognition

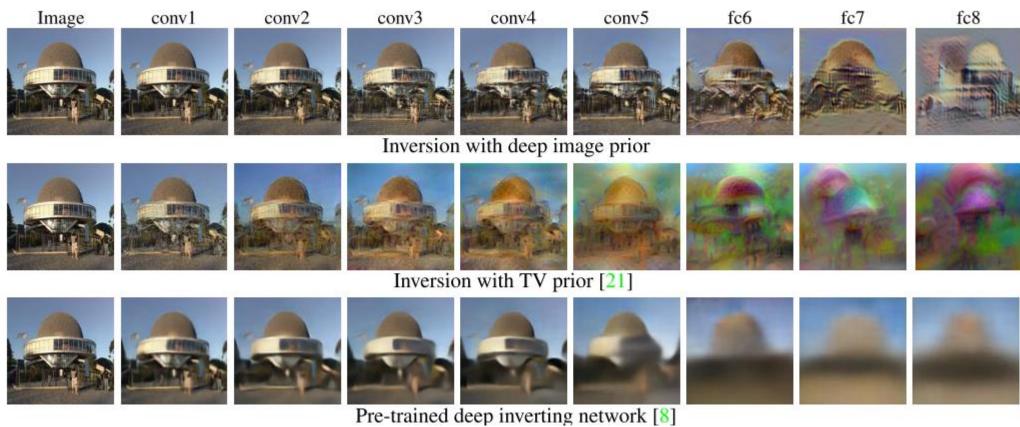
Head Pose

Emotion



Regularization matters!

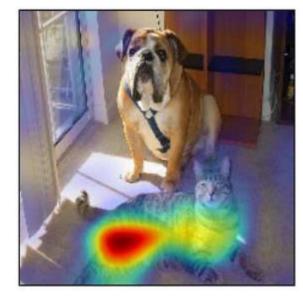
• The visualizations are very sensitive to regularization



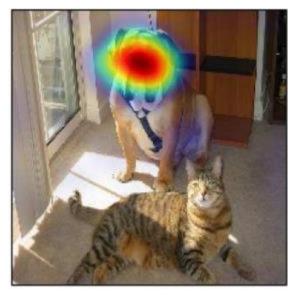


Saliency Visualization

Which part of an input image is important?



Class is 'cat'



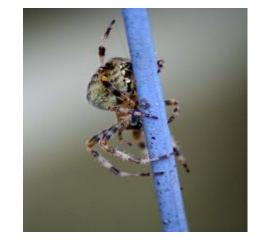
Class is 'dog'

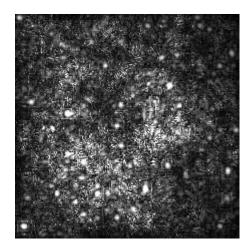


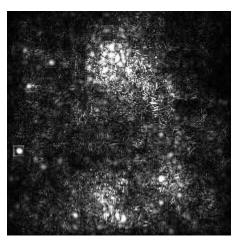
Visualize magnitude of gradients

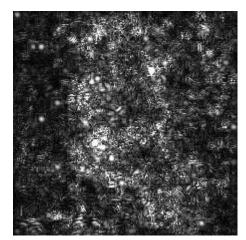










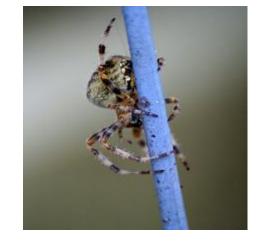


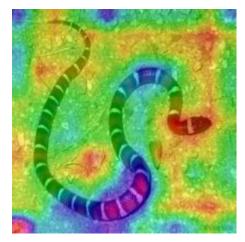


Class activation mapping (Grad-CAM)











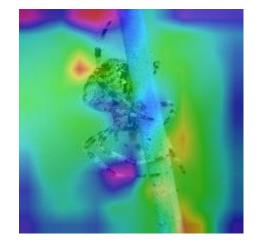


Image source: utkuozbulak/pytorch-cnn-visualizations: Pytorch implementation of convolutional neural network visualization techniques (github.com)



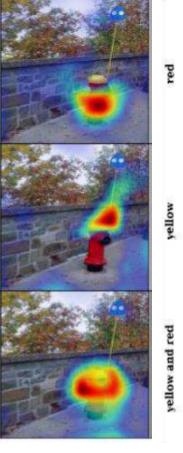
Grad-CAM: How

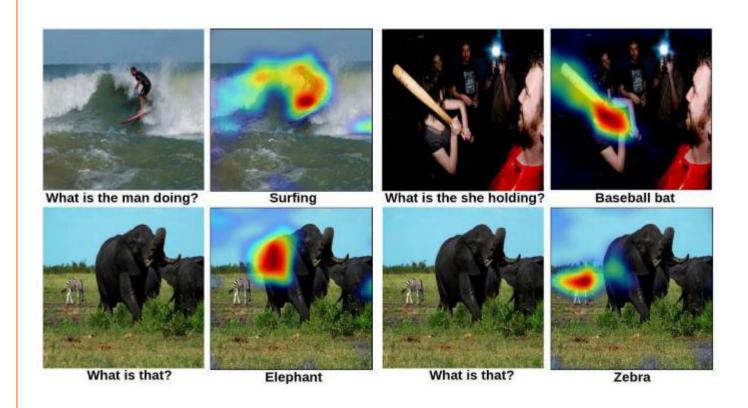
- Two basic Ideas (partly known earlier are combined)
- CAM: Class Activation Maps
 - Limitation to certain type of architectures
- Role of Gradients
 - e.g., Gradient of score of the class wrt to activation from a layer
 - We are interested in feature maps that have positive impact on the class of interest (negative ones correspond to BG or some other class)



GradCAM in Visual Question Answering









Grad-CAM in image captioning



A group of people flying kites on a beach

A man is sitting at a table with a pizza

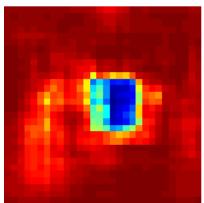




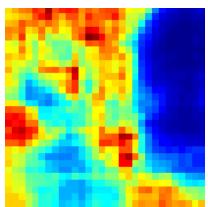
Another: Occlusion map

 Systematically occlude parts of the image and record the drop in classification confidence

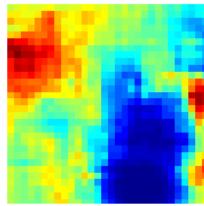






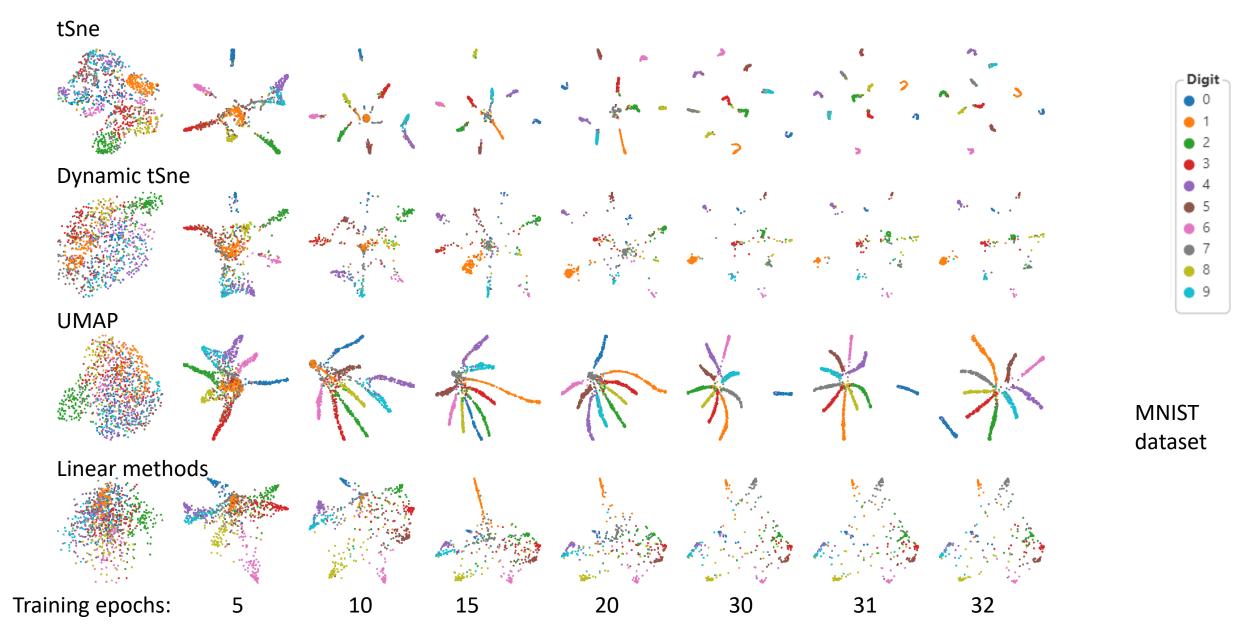








At output: Monitor training dynamics 2D embedding





Summary

- Visualizing different aspects of CNNs
- Interpreting for better understanding
- Better explanations
- Better design/refinements

Thanks!!

Questions?