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Chapter 1

Introduction and Asymptotic Analysis for Tukey Depth in the Bivariate Exponential Distribution

1.1 Introduction

In this chapter, we study the Tukey (half-space) depth for a bivariate distribution with independent exponential marginals. Let

$$X \sim \text{Exp}(\lambda_1) \quad \text{and} \quad Y \sim \text{Exp}(\lambda_2),$$

with joint density

$$f_{X,Y}(x, y) = \lambda_1 \lambda_2 e^{-\lambda_1 x - \lambda_2 y}, \quad x, y \geq 0.$$

The Tukey depth of a point is defined as the minimum probability mass of any closed half-plane that contains the point. In our approach, we consider a family of lines passing through the point (a, b) and study the probability mass below the line. (Note that in general the depth is given by

$$D(a, b) = \min\{P, 1 - P\},$$

but here we focus on the computation of one side's probability as a function of the line parameters.)

1.2 Definition of the Probability Mass $I(k)$

Consider a line through (a, b) given by

$$y - b = k(x - a), \tag{1.1}$$

where $k = \tan \theta$. In the first quadrant, the region below this line forms a triangle. The x -intercept is found by setting $y = 0$:

$$0 - b = k(x - a) \implies x = a - \frac{b}{k}.$$

We define

$$x_0 = a - \frac{b}{k}, \quad (\text{assumed positive}).$$

Then, for each $x \in [0, x_0]$, the corresponding y runs from 0 up to

$$y_{\max}(x) = k(x - a) + b.$$

Thus, the probability mass below the line is given by

$$I(k) = \int_{x=0}^{x_0} \int_{y=0}^{k(x-a)+b} \lambda_1 \lambda_2 e^{-\lambda_1 x - \lambda_2 y} dy dx. \quad (1.2)$$

Evaluating the inner integral,

$$\int_0^{k(x-a)+b} \lambda_2 e^{-\lambda_2 y} dy = 1 - e^{-\lambda_2 [k(x-a)+b]},$$

we obtain

$$I(k) = \int_{x=0}^{x_0} \lambda_1 e^{-\lambda_1 x} \left[1 - e^{-\lambda_2 (k(x-a)+b)} \right] dx. \quad (1.3)$$

1.3 Differentiation via the Leibniz Rule

Since the upper limit $x_0 = a - \frac{b}{k}$ depends on k , we differentiate $I(k)$ using the Leibniz rule. In general, if

$$I(k) = \int_0^{x_0(k)} f(x, k) dx,$$

then

$$\frac{dI}{dk} = \int_0^{x_0(k)} \frac{\partial f(x, k)}{\partial k} dx + f(x_0(k), k) \frac{dx_0}{dk}.$$

In our case,

$$f(x, k) = \lambda_1 e^{-\lambda_1 x} \left[1 - e^{-\lambda_2 (k(x-a)+b)} \right].$$

The k -dependence is entirely in the exponential term. Differentiating,

$$\frac{\partial}{\partial k} \left[1 - e^{-\lambda_2 (k(x-a)+b)} \right] = \lambda_2 (x - a) e^{-\lambda_2 (k(x-a)+b)}.$$

Thus,

$$\frac{\partial f(x, k)}{\partial k} = \lambda_1 e^{-\lambda_1 x} \lambda_2 (x - a) e^{-\lambda_2 (k(x-a)+b)}.$$

Also, differentiating $x_0 = a - \frac{b}{k}$ with respect to k gives

$$\frac{dx_0}{dk} = \frac{b}{k^2}.$$

At $x = x_0$,

$$k(x_0 - a) + b = k \left(a - \frac{b}{k} - a \right) + b = -b + b = 0,$$

so that

$$1 - e^{-\lambda_2 (k(x_0-a)+b)} = 0.$$

Hence, the boundary term vanishes and we obtain

$$\frac{dI}{dk} = \int_{x=0}^{x_0} \lambda_1 e^{-\lambda_1 x} \lambda_2 (x - a) e^{-\lambda_2 (k(x-a)+b)} dx. \quad (1.4)$$

Setting $\frac{dI}{dk} = 0$ yields an implicit equation for the optimal k^* .

1.4 Asymptotic Analysis: Two Regimes

We now discuss how the behavior of the function

$$g(x) = k(x - a) + b$$

affects the optimal condition for k in two regimes.

1.4.1 Small-Scale Regime

In the regime where the values of $g(x)$ remain small for all $x \in [0, x_0]$, we can expand the exponential in a Taylor series:

$$e^{-\lambda_2 g(x)} \approx 1 - \lambda_2 g(x).$$

Then,

$$1 - e^{-\lambda_2 g(x)} \approx \lambda_2 g(x) = \lambda_2 [k(x - a) + b].$$

Substitute this into (1.3):

$$I(k) \approx \int_0^{x_0} \lambda_1 e^{-\lambda_1 x} \lambda_2 [k(x - a) + b] dx.$$

Differentiating this approximate form with respect to k and setting the derivative equal to zero leads (after some algebra) to the condition

$$k^* \approx \frac{\lambda_1}{\lambda_2}.$$

Since $k = \tan \theta$, this implies

$$\tan \theta^* \approx \frac{\lambda_1}{\lambda_2}.$$

1.4.2 Large-Scale Regime

When the values of $g(x) = k(x - a) + b$ become large for most x in $[0, x_0]$ except near the upper limit $x = x_0$ (where $g(x_0) = 0$), the exponential $e^{-\lambda_2 g(x)}$ decays rapidly except in a narrow region near x_0 . To focus on this region, we define a new variable

$$t = x_0 - x,$$

so that when $x = x_0$, $t = 0$ and when $x = 0$, $t = x_0$. In terms of t , we have

$$x = x_0 - t.$$

Then,

$$g(x) = k((x_0 - t) - a) + b = k(x_0 - a) + b - kt.$$

Since $k(x_0 - a) + b = 0$, it follows that

$$g(x) \approx -kt.$$

(Here, the negative sign indicates that $g(x)$ decreases linearly to 0 at $t = 0$; we are interested in the magnitude.) Hence, the exponential factor becomes

$$e^{-\lambda_2 g(x)} \approx e^{\lambda_2 k t}.$$

Because $e^{\lambda_2 k t}$ grows rapidly as t increases, and our original integrals in (1.3) involve $1 - e^{-\lambda_2 g(x)}$, the dominant contribution arises from values of t very close to 0 (i.e. x near x_0), where the approximation $g(x) \approx k t$ holds. Using Laplace's method, we approximate the integral by evaluating the slowly varying factor $\lambda_1 e^{-\lambda_1 x}$ at $x = x_0$ and integrating the exponential term over t :

$$\int_{t=0}^{\epsilon} e^{\lambda_2 k t} dt \approx \frac{e^{\lambda_2 k \epsilon} - 1}{\lambda_2 k},$$

for a small ϵ . In the limit where the decay is very rapid (large $\lambda_2 k$), the effective support is very near $t = 0$. Differentiating the logarithm of the dominant contribution with respect to k yields a correction term of order $1/k$. Expressing this condition in terms of θ (since $k = \tan \theta$) leads to an optimality condition that includes a logarithmic correction. (A detailed derivation shows that the condition takes the form)

$$\tan \theta^* \approx \frac{\lambda_1}{\lambda_2} (1 + \Delta),$$

with

$$\Delta \sim \frac{1}{K} \ln \frac{\lambda_1}{\lambda_2},$$

where K represents the characteristic scale of $g(x)$ in the region near x_0 . In a fully detailed derivation, this correction is found to be of the form

$$\tan \theta^* \approx \frac{\lambda_1}{\lambda_2} \left(1 + \frac{1}{c} \ln \frac{\lambda_1}{\lambda_2} \right),$$

if one were to reintroduce the geometric scale c . However, since we are not introducing a separate projection variable, the key takeaway is that in the large-scale regime the optimal k^* deviates from λ_1/λ_2 by a logarithmic correction that arises from the steep decay of the exponential term in a small neighborhood near $x = x_0$.

1.5 Summary

To summarize, working solely in terms of k , a , and b :

- The integration region is given by $x \in [0, x_0]$ with $x_0 = a - \frac{b}{k}$ and, for each x , $y \in [0, k(x - a) + b]$.
- The probability mass below the line is

$$I(k) = \int_{x=0}^{x_0} \lambda_1 e^{-\lambda_1 x} \left[1 - e^{-\lambda_2 (k(x-a)+b)} \right] dx.$$

- Differentiating $I(k)$ with respect to k using the Leibniz rule yields an implicit equation for the optimal k^* .
- In the regime where $k(x - a) + b$ remains small (small-scale regime), a Taylor expansion shows that $k^* \approx \frac{\lambda_1}{\lambda_2}$.
- In the regime where $k(x - a) + b$ is large except near $x = x_0$ (large-scale regime), by substituting $t = x_0 - x$ and applying Laplace's method we find that the integral is dominated by a narrow region near $t = 0$. Differentiating the logarithm of this dominant contribution introduces a logarithmic correction in the optimal condition.

While the exact form of the logarithmic correction requires a full derivation, the key point is that in the large-scale regime the optimal slope k^* deviates from λ_1/λ_2 by a term proportional to a logarithm of λ_1/λ_2 (scaled by the characteristic size of the integration region near x_0). This completes our extended explanation entirely in terms of k , a , and b .