

### Final Transition Scheme (Including Different $c$ Scenarios):

Given a line through  $(a, b)$  described by

$$y - b = k(x - a),$$

with  $k = \tan \theta$ , the probability that an exponential vector  $(X, Y)$  (with density  $\lambda_1 \lambda_2 e^{-\lambda_1 x - \lambda_2 y}$ ) lies below the line in the first quadrant is

$$I(k) = \int_{x=x_0}^{\infty} \lambda_1 e^{-\lambda_1 x} \left[ 1 - e^{-\lambda_2 (k(x-a)+b)} \right] dx, \quad \text{where } x_0 = \max \left\{ 0, a - \frac{b}{k} \right\}.$$

Replacing  $k$  with  $\tan \theta$ , we rewrite the line as

$$x \cos \theta + y \sin \theta = a \cos \theta + b \sin \theta,$$

and define the threshold

$$c = a \cos \theta + b \sin \theta.$$

Expressing the point in polar coordinates via  $a = r \cos \phi$  and  $b = r \sin \phi$  gives

$$c = r \cos(\theta - \phi).$$

For intermediate values of  $c$  (neither asymptotically small nor large), the optimal separation direction is obtained by solving the implicit equation

$$\frac{d}{d\theta} I(\theta) = 0,$$

where

$$I(\theta) = \int_{x=\max\{0, a - \frac{b}{\tan \theta}\}}^{\infty} \lambda_1 e^{-\lambda_1 x} \left[ 1 - e^{-\lambda_2 (\tan \theta (x-a) + b)} \right] dx.$$

This integral formulation, with the lower limit depending on  $\theta$  via the  $\max$  operator, fully characterizes the behavior of the separation probability for intermediate  $c$ , linking the geometric parameter  $c = r \cos(\theta - \phi)$  with the slope parameter  $k = \tan \theta$ ; the resulting equation must be solved (typically numerically) to determine the optimal angle  $\theta^*$  (and hence the optimal  $k^* = \tan \theta^*$ ).

### Different $c$ Scenarios:

For **small**  $c$  (i.e., when the threshold is close to the origin), the approximation

$$\max\{0, a - b / \tan \theta\} \approx 0$$

simplifies the integral, leading to

$$k^* \approx \frac{\lambda_1}{\lambda_2} = \tan \theta^*.$$

For **large**  $c$  (i.e., when the threshold is far from the origin), the probability integral is dominated by the exponential decay, and we can apply the approximation

$$I(k) \approx \log \left( \frac{c}{a} \right),$$

resulting in the asymptotic behavior

$$k^* \approx \frac{a}{b} = \tan \phi.$$

This logarithmic correction comes from the fact that, for large values of  $c$ , the integrand tends to approach the boundary of the domain, and thus the result becomes proportional to  $\log(c)$ .

For **intermediate**  $c$ , the situation is more complex, and no direct analytical simplifications hold. In this case, the optimization must be conducted numerically using

$$\frac{d}{d\theta} \int_{x=\max\{0, a-b/\tan\theta\}}^{\infty} \lambda_1 e^{-\lambda_1 x} \left[ 1 - e^{-\lambda_2 (\tan\theta(x-a)+b)} \right] dx = 0.$$