

Image Warping

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Image Processing



- Quantization
 - Uniform Quantization
 - Random dither
 - Ordered dither
 - Floyd-Steinberg dither
- Pixel operations
 - Add random noise
 - Add luminance
 - Add contrast
 - Add saturation

- Filtering
 - Blur
 - Detect edges
- Warping
 - Scale
 - Rotate
 - Warp
- Combining
 - Composite
 - Morph

Image Processing



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Image Warping



- Move pixels of image
 - Mapping
 - Resampling



Source image



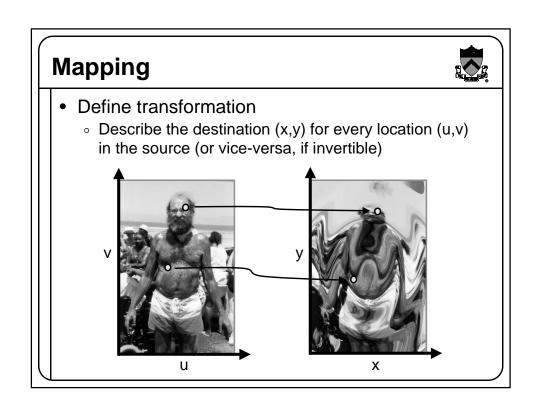
Warp

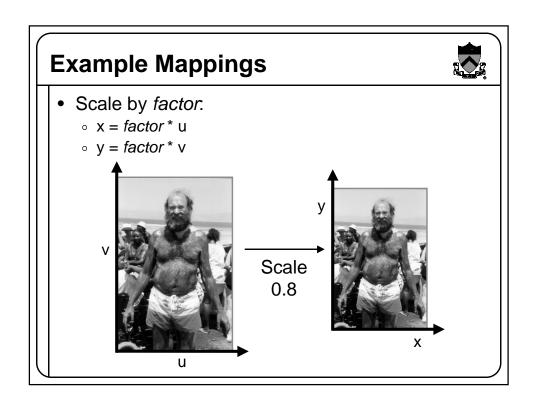
Destination image

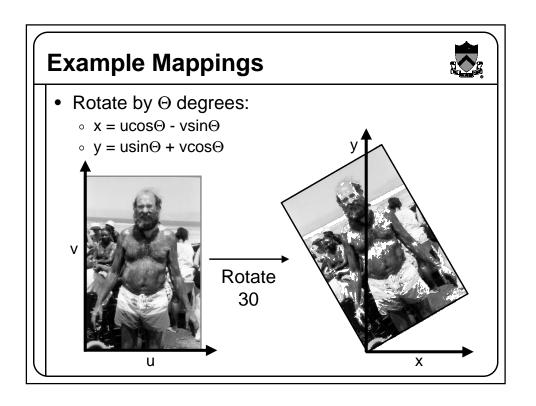
Overview

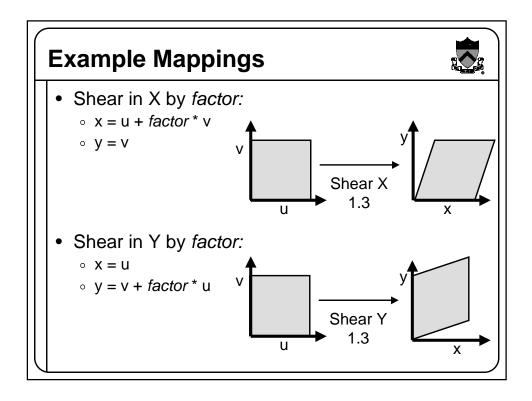


- Mapping
 - Forward
 - Reverse
- Resampling
 - Point sampling
 - Triangle filter
 - Gaussian filter









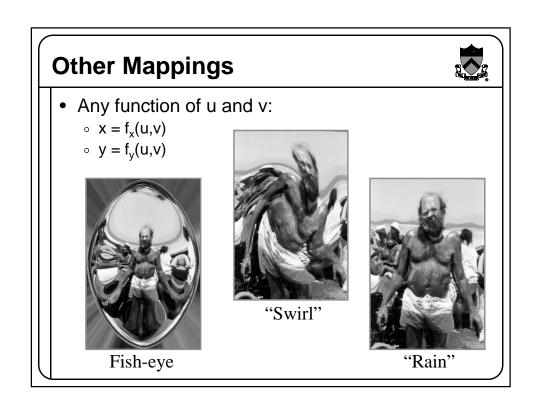
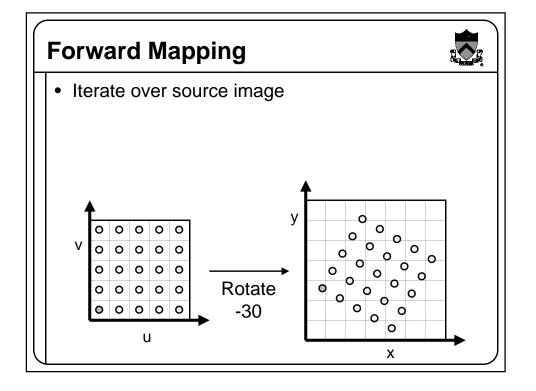
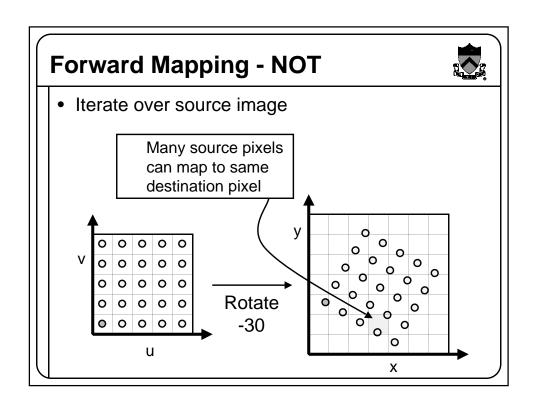


Image Warping Implementation I • Forward mapping: for (int u = 0; u < umax; u++) { for (int v = 0; v < vmax; v++) { float x = f_x(u,v); float y = f_y(u,v); dst(x,y) = src(u,v); } } Source image Destination image





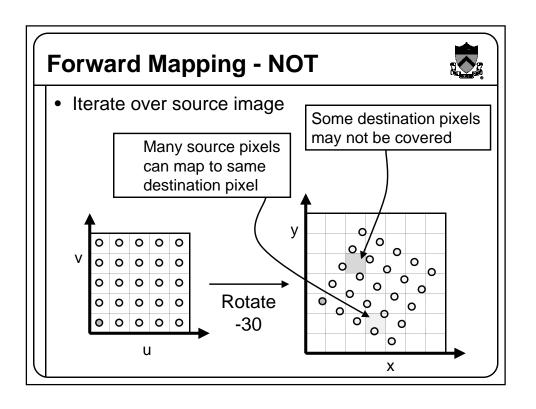
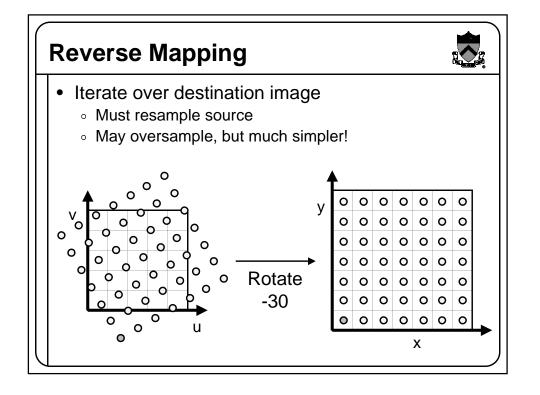
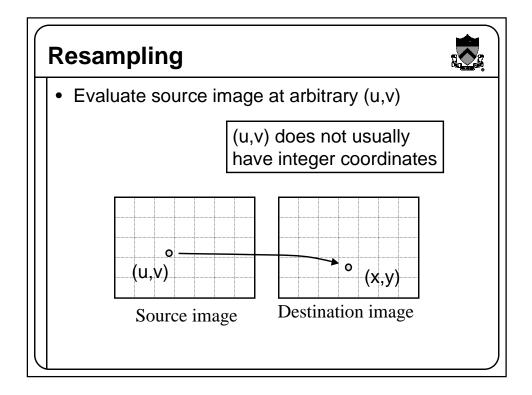


Image Warping Implementation II • Reverse mapping: for (int x = 0; x < xmax; x++) { for (int y = 0; y < ymax; y++) { float u = f_x⁻¹(x,y); float v = f_y⁻¹(x,y); dst(x,y) = src(u,v); } } // Complementation II • Reverse mapping: for (int x = 0; x < xmax; x++) { for (int y = 0; y < ymax; y++) { float u = f_x⁻¹(x,y); dst(x,y); dst(x,y) = src(u,v); } }

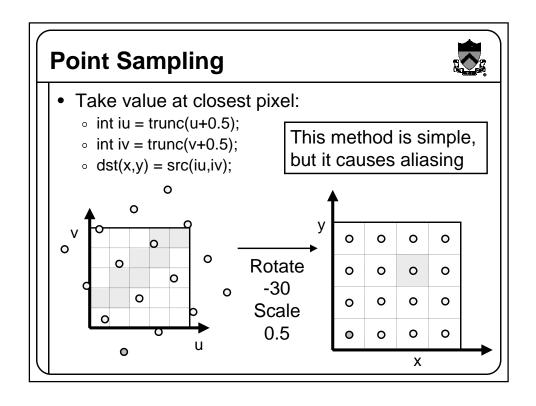


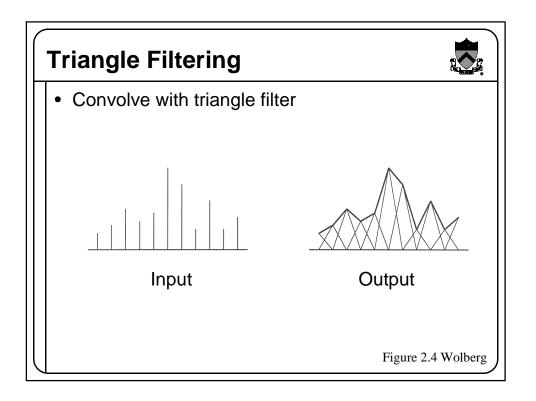


Overview



- Mapping
 - Forward
 - Reverse
- » Resampling
 - Point sampling
 - Triangle filter
 - Gaussian filter

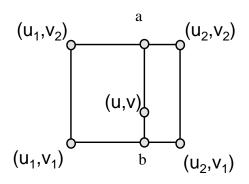




Triangle Filtering



- · Bilinearly interpolate four closest pixels
 - a = linear interpolation of $src(u_1, v_2)$ and $src(u_2, v_2)$
 - b = linear interpolation of $src(u_1,v_1)$ and $src(u_2,v_1)$
 - dst(x,y) = linear interpolation of "a" and "b"



Gaussian Filtering



· Convolve with Gaussian filter



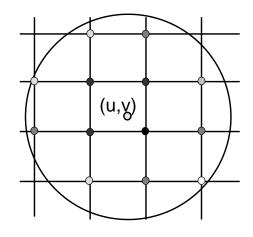
Width of Gaussian kernel affects bluriness

Figure 2.4 Wolberg





- Compute weighted sum of pixel neighborhood:
 - Weights are normalized values of Gaussian function



Filtering Methods Comparison



- Trade-offs
 - Aliasing versus blurring
 - Computation speed



Point



Bilinear



Gaussian

Image Warping Implementation



• Reverse mapping:

```
for (int x = 0; x < xmax; x++) {
  for (int y = 0; y < ymax; y++) {
    float u = f<sub>x</sub><sup>-1</sup>(x,y);
    float v = f<sub>y</sub><sup>-1</sup>(x,y);
    dst(x,y) = resample_src(u,v,w);
  }
}
```

Source image

Destination image

0

(x,y)

Image Warping Implementation



Reverse mapping:

```
for (int x = 0; x < xmax; x++) {
  for (int y = 0; y < ymax; y++) {
    float u = f<sub>x</sub><sup>-1</sup>(x,y);
    float v = f<sub>y</sub><sup>-1</sup>(x,y);
    dst(x,y) = resample_src(u,v,w);
  }
}
```

Source image

Destination image

Example: Scale



Example: Rotate



• Rotate (src, dst, theta):

for (int x = 0; x < xmax; x++) {
 for (int y = 0; y < ymax; y++) {
 float u = x*cos(-Θ) - y*sin(-Θ);
 float u = x*sin(-Θ) + y*cos(-Θ);
 dst(x,y) = resample_src(u,v,w);
 }
}

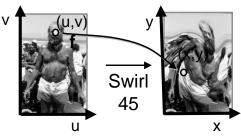
x = ucosΘ - vsinΘ
y = usinΘ + vcosΘ

Example: Fun



• Swirl (src, dst, theta):

```
for (int x = 0; x < xmax; x++) {
  for (int y = 0; y < ymax; y++) {
    float u = rot(dist(x,xcenter)*theta);
    float v = rot(dist(y,ycenter)*theta);
    dst(x,y) = resample_src(u,v,w);
  }
}</pre>
```



Summary



- Mapping
 - Forward
 - Reverse

Resampling

- Point sampling
- Triangle filter
- Gaussian filter

Reverse mapping is simpler to implement

Different filters trade-off speed and aliasing/blurring

Fun and creative warps are easy to implement!

Next Time



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