# Learned index structures

Kraska, Beutel, Chi, Dean, Polyzotis

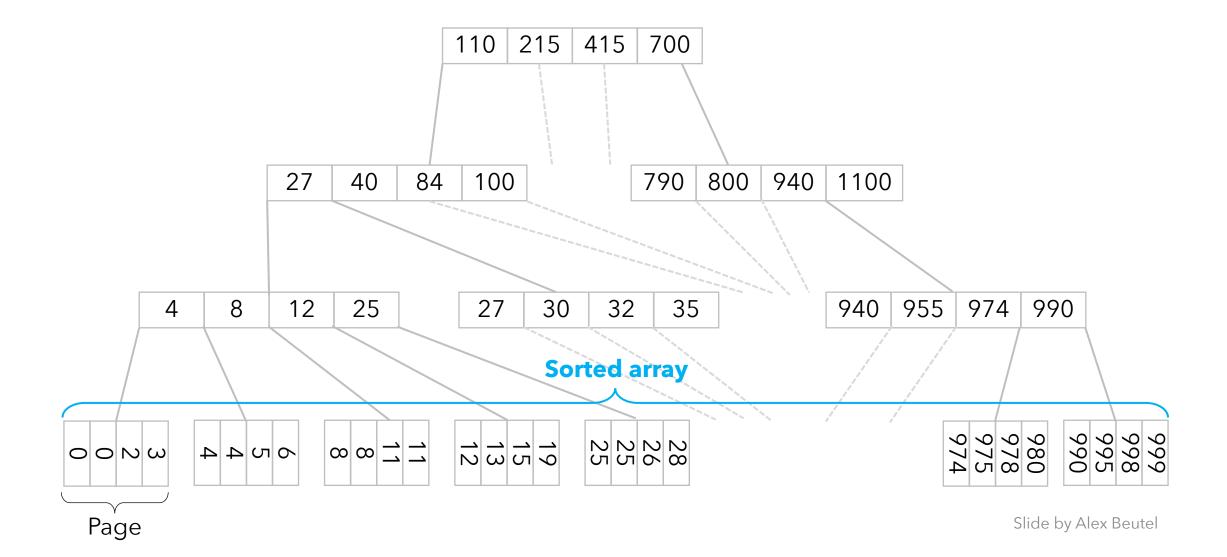
SIGMOD'18

## Outline

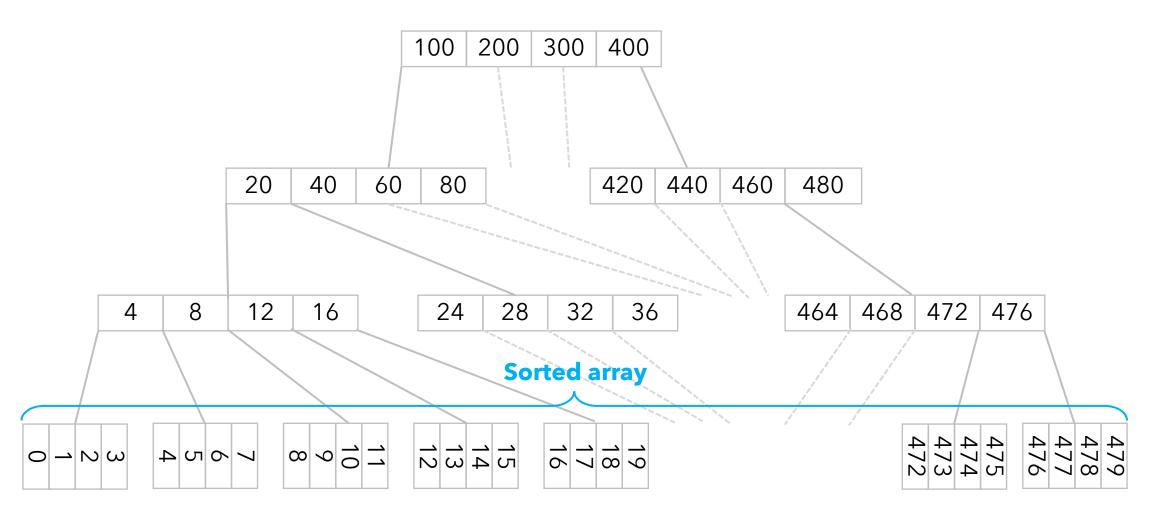
Goal: Use machine learning to augment

- 1. Range index structures (B-trees)
- 2. Existence index structures (Bloom filters)

## B-trees



# If data is all integers from 0 to 1 million?

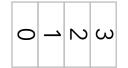


# If data is all integers from 0 to 1 million?

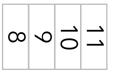
No need for B-tree

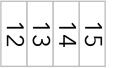
- O(1) look-up
- O(1) memory

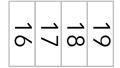








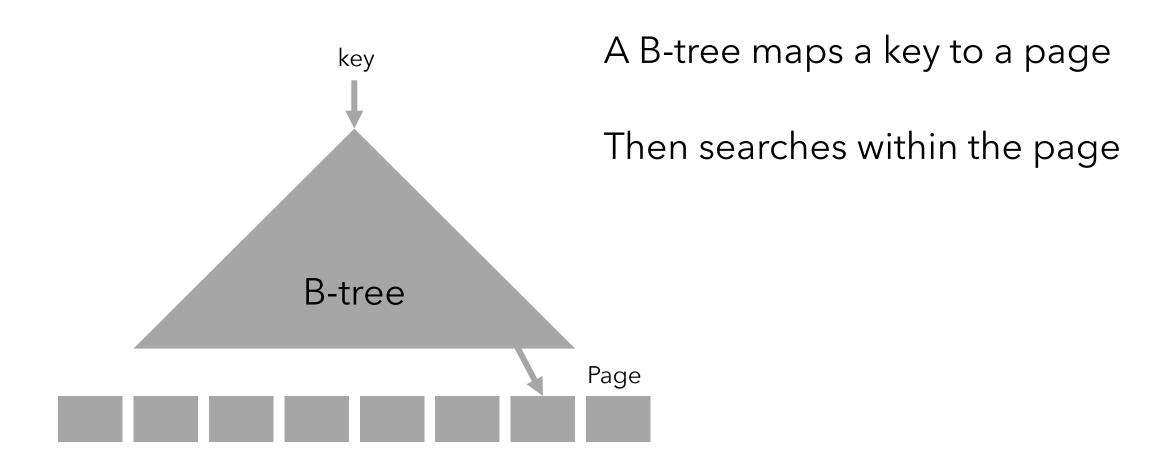




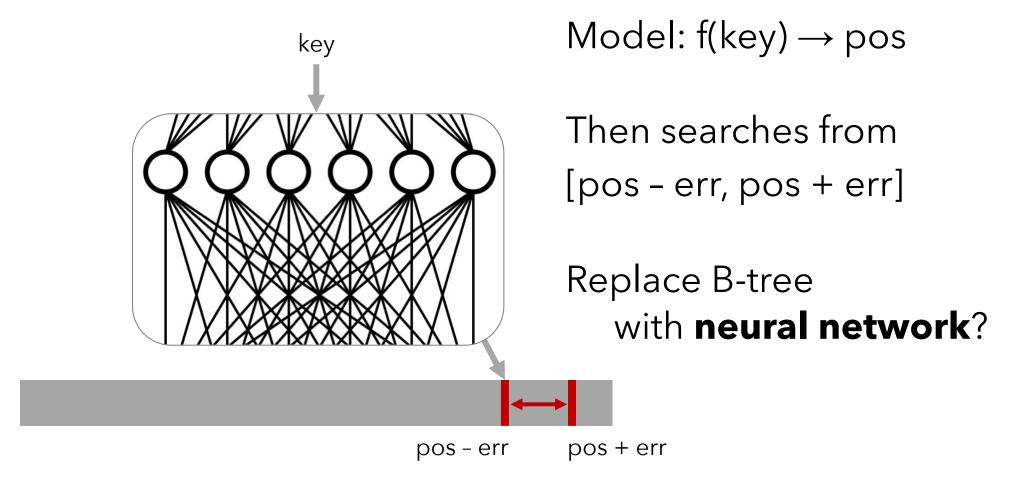




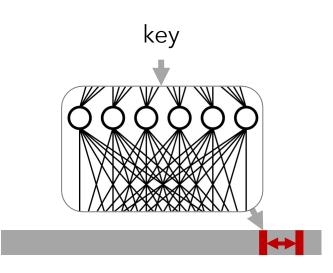
### B-trees



## First attempt



## First attempt



200M serve logs timestamp sorted

2-layer NN, 32-width fully-connected, ReLU *Tensorflow* 

B-trees lookup time: 300ns

Model lookup time: 80,000ns

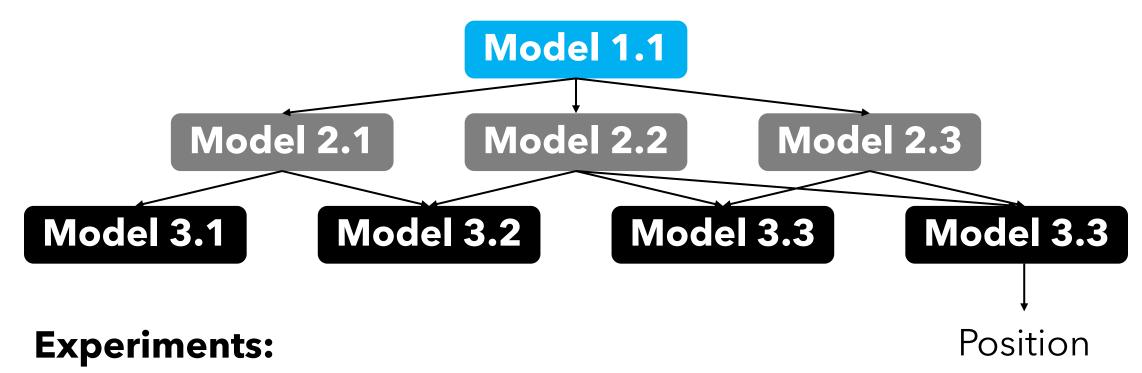
## First attempt: key issues

1 Tensorflow designed for big models
Big overhead on small models

2 B-Trees "overfit" the data...
but NNs designed for generalization

3 B-trees are cache- and operation-efficient

# Revised approach: Hierarchy of experts



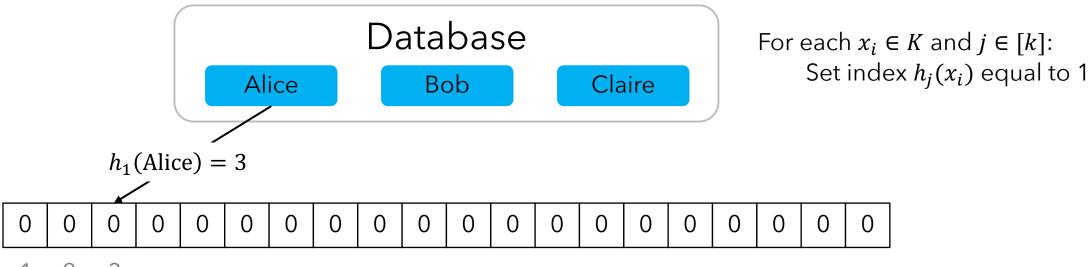
- Up to 70% speed optimization
- Order-of-magnitude memory savings

## Outline

Goal: Use machine learning to augment

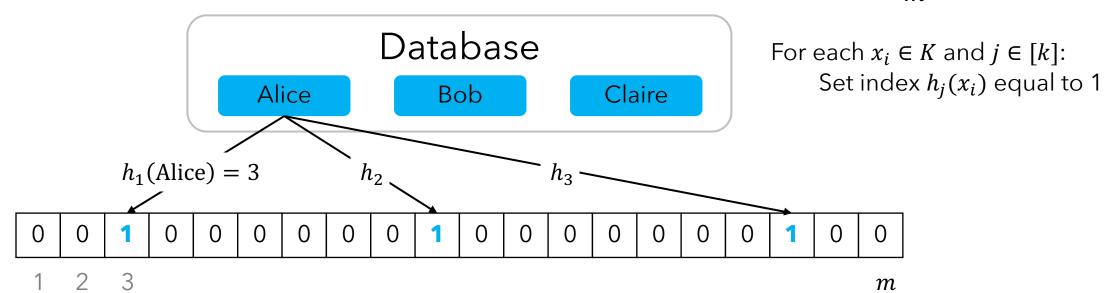
- 1. Range index structures (B-trees)
- 2. Existence index structures (Bloom filters)

- Database is a set  $K \subseteq U$
- Goal: DS allowing us to quickly determine if any  $x \in U$  is in K
  - Use hash functions  $h_1, h_2, \dots, h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$

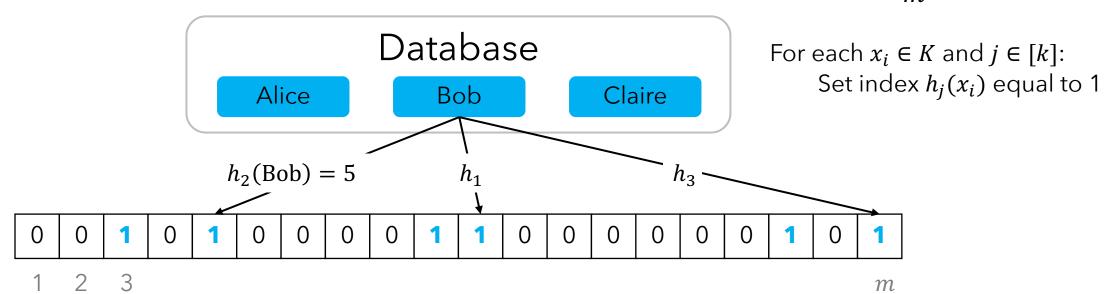


m

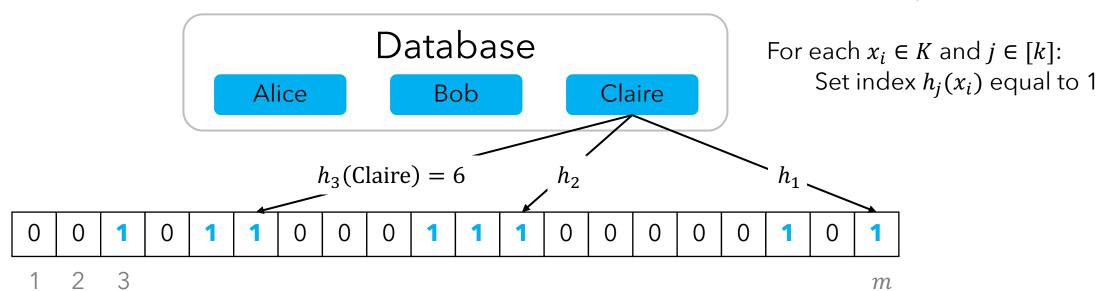
- Database is a set  $K \subseteq U$
- Goal: DS allowing us to quickly determine if any  $x \in U$  is in K
  - Use hash functions  $h_1, h_2, \dots, h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$



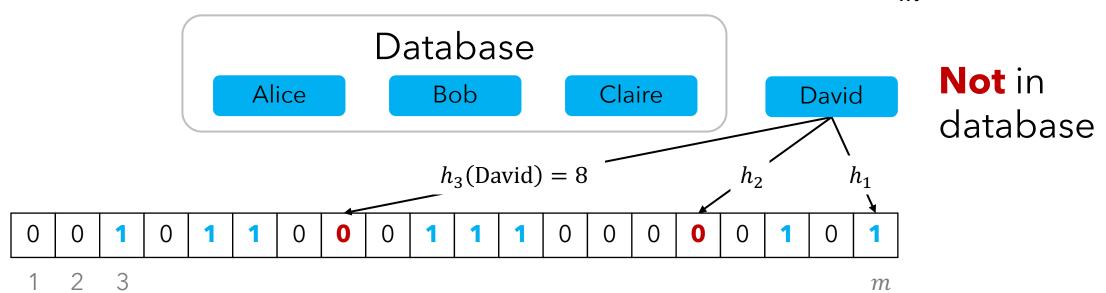
- Database is a set  $K \subseteq U$
- Goal: DS allowing us to quickly determine if any  $x \in U$  is in K
  - Use hash functions  $h_1, h_2, \dots, h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$



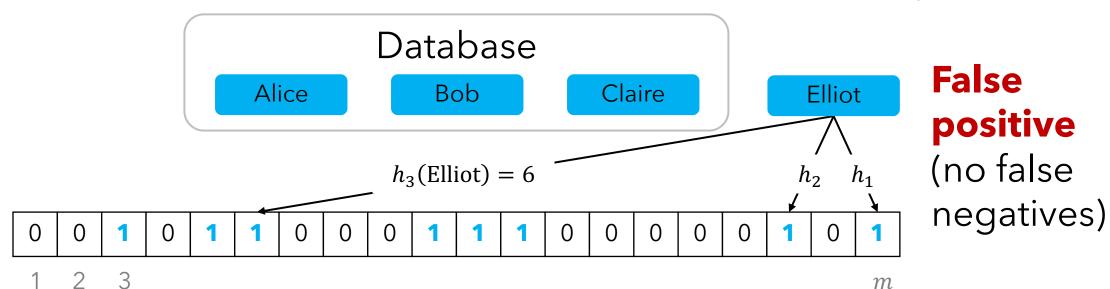
- Database is a set  $K \subseteq U$
- Goal: DS allowing us to quickly determine if any  $x \in U$  is in K
  - Use hash functions  $h_1, h_2, \dots, h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$



- Database is a set  $K \subseteq U$
- Goal: DS allowing us to quickly determine if any  $x \in U$  is in K
  - Use hash functions  $h_1, h_2, \dots, h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$



- Database is a set  $K \subseteq U$
- Goal: DS allowing us to quickly determine if any  $x \in U$  is in K
  - Use hash functions  $h_1, h_2, \dots, h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$



## Learned Bloom filters

#### Idea 1: Replace Bloom filter with a classifier?

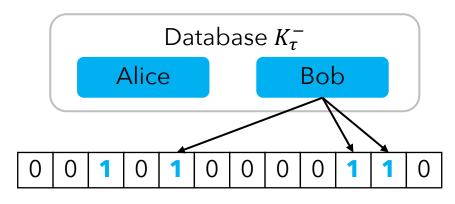
- Train ML model  $f: U \to [0,1]$  with threshold  $\tau$  so (hopefully)  $f(x) \ge \tau \iff x \in K$
- Training set: (x, 1) for some  $x \in S$ , (x, 0) for some  $x \notin S$

**Key issue:** May be false negatives  $(f(x) < \tau \text{ for some } x \in K)$ 

## Learned Bloom filters

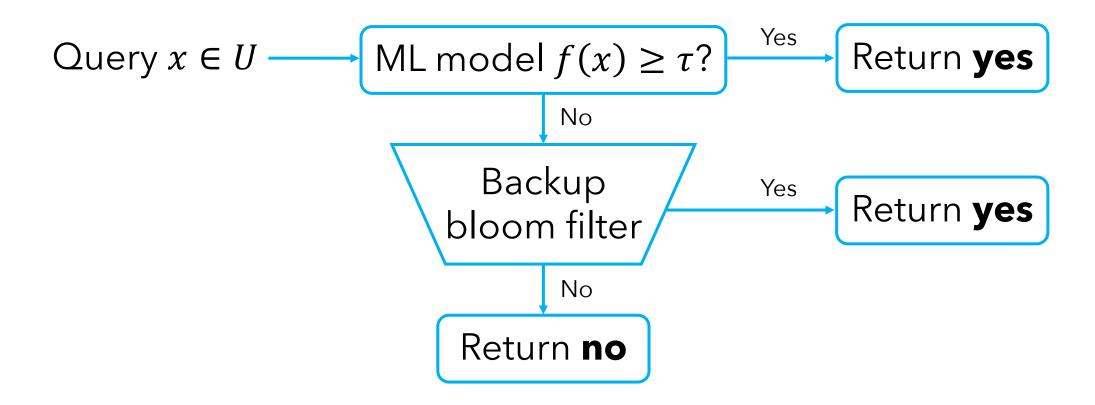
#### Idea 2:

- Train ML model  $f: U \to [0,1]$  with threshold  $\tau$  so (hopefully)  $f(x) \ge \tau \quad \Leftrightarrow \quad x \in K$
- Training set: (x, 1) for some  $x \in S$ , (x, 0) for some  $x \notin S$
- Construct backup Bloom filter:
  - Bloom filter for set  $K_{\tau}^- = \{x \in K : f(x) < \tau\}$



Ideally *much smaller* than Bloom filter for *K* 

## Learned Bloom filters



## Setting au

- D is a distribution over  $U \setminus K$
- FPR<sub>B</sub> = false positive rate of backup Bloom filter Next class: how to set Bloom filter size to control  $FPR_B$
- False positive rate of learned Bloom filter:

$$\operatorname{FPR}_O = \mathbb{P}_{x \sim D} [f(x) > \tau] + \mathbb{P}_{x \sim D} [f(x) \leq \tau] \cdot \operatorname{FPR}_B$$
Return **yes** Send to backup Bloom filter

- If want  $FPR_O \leq \epsilon$ :
  - Choose  $\tau$  s.t.  $\mathbb{P}_{x \sim D}[f(x) > \tau] \leq \frac{\epsilon}{2}$
  - $FPR_B \leq \frac{\epsilon}{2}$

## Experiments

**Keys:** 1.7M URLs from a Google dataset

Non-keys: Random URLs and phishing URLs

Goal: 1% FPR

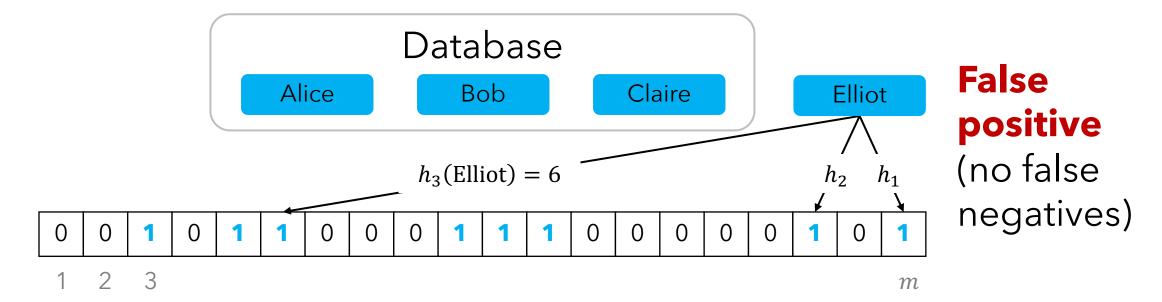
- Normal Bloom filter: 2.04MB
- Learned Bloom filter:
  - ML model (RNN) requires 0.0259MB
  - Backup Bloom filter requires 1.31MB

36% improvement

## Outline

- Goal: Use machine learning to augment
  - 1. Range index structures (B-trees)
  - 2. Existence index structures (Bloom filters)
    - i. Approach
    - ii. Theoretical guarantees/insights

- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, ..., h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$



- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, ..., h_k: U \rightarrow [m]$ 
  - Map  $x \in U$  to a random number in [m], independently and uniformly
- $\rho$  = fraction of bits set to 1
- For any  $y \notin K$ ,

```
\mathbb{P}[y \text{ yields a false positive } | \rho = q]
= \mathbb{P}[h_i(y) = 1, \forall i \in [m] | \rho = q]
= \mathbb{P}[h_1(y) = 1 | \rho] \cdots \mathbb{P}[h_k(y) = 1 | \rho = q]
= q^k
```

- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, ..., h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$
- $\rho$  = fraction of bits set to 1

$$\mathbb{E}[\rho] = \mathbb{E}\left[\frac{1}{m}\sum_{i=1}^{m}\mathbf{1}_{\{i^{\text{th}}\text{ bit set to 1}\}}\right] = \frac{1}{m}\sum_{i=1}^{m}\mathbb{P}[i^{\text{th}}\text{ bit set to 1}]$$

- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, ..., h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$
- $\rho$  = fraction of bits set to 1

$$\mathbb{E}[\rho] = \mathbb{E}\left[\frac{1}{m}\sum_{i=1}^{m}\mathbf{1}_{\{i^{\text{th}}\text{ bit set to 1}\}}\right] = \frac{1}{m}\sum_{i=1}^{m}\mathbb{P}[i^{\text{th}}\text{ bit set to 1}]$$
$$= \frac{1}{m}\sum_{i=1}^{m}(1 - \mathbb{P}[i^{\text{th}}\text{ bit set to 0}])$$

- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, ..., h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$
- $\rho$  = fraction of bits set to 1

$$\mathbb{E}[\rho] = \frac{1}{m} \sum_{i=1}^{m} \left( 1 - \mathbb{P}[i^{\text{th}} \text{ bit set to } 0] \right)$$

$$\mathbb{P}\left[i^{\text{th}} \text{ bit set to } 0\right] = \mathbb{P}\left[h_j(x) \neq i, \forall x \in K, \forall j \in [k]\right]$$

- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, ..., h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$
- $\rho$  = fraction of bits set to 1

$$\mathbb{E}[\rho] = \frac{1}{m} \sum_{i=1}^{m} \left( 1 - \mathbb{P}[i^{\text{th}} \text{ bit set to 0}] \right)$$

$$\mathbb{P}[i^{\text{th}} \text{ bit set to 0}] = \mathbb{P}\left[h_{j}(x) \neq i, \forall x \in K, \forall j \in [k]\right]$$

$$\mathbb{P}[h_{j}(x) \neq i] = 1 - \mathbb{P}[h_{j}(x) = i] = 1 - \frac{1}{m}$$

- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, ..., h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$
- $\rho$  = fraction of bits set to 1

$$\mathbb{E}[\rho] = \frac{1}{m} \sum_{i=1}^{m} \left( 1 - \mathbb{P}[i^{\text{th}} \text{ bit set to 0}] \right) = \frac{1}{m} \sum_{i=1}^{m} \left( 1 - \left( 1 - \frac{1}{m} \right)^{|K|k} \right)$$

$$\mathbb{P}[i^{\text{th}} \text{ bit set to 0}] = \mathbb{P}\left[ h_j(x) \neq i, \forall x \in K, \forall j \in [k] \right]$$

$$= \left( 1 - \frac{1}{m} \right)^{|K|k}$$

- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, \dots, h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$
- $\rho$  = fraction of bits set to 1

$$\mathbb{E}[\rho] = \frac{1}{m} \sum_{i=1}^{m} \left( 1 - \mathbb{P}[i^{\text{th}} \text{ bit set to } 0] \right) = \frac{1}{m} \sum_{i=1}^{m} \left( 1 - \left( 1 - \frac{1}{m} \right)^{|K|k} \right)$$

$$\approx 1 - \exp\left( -\frac{|K|k}{m} \right)$$

• With high probability,  $\rho \approx \mathbb{E}[\rho]$  (Chernoff bound)

- Database is a set  $K \subseteq U$
- Hash functions  $h_1, h_2, ..., h_k: U \to [m]; \mathbb{P}[h_i(x) = j] = \frac{1}{m}$
- For any  $y \notin K$ ,

$$\mathbb{P}[y \text{ yields a false positive}] \approx \mathbb{E}[\rho]^k \approx \left(1 - \exp\left(-\frac{|K|k}{m}\right)\right)^k$$

• If  $m \approx |K| \log \frac{1}{\epsilon}$  and  $k = \log \frac{1}{\epsilon'}$ .  $\mathbb{P}[y \text{ yields a false positive}] \approx \epsilon$ 

## Differences between FPRs

**Bloom filter: for any**  $y \notin K$ ,  $\mathbb{P}[y \text{ yields a false positive}] \leq \epsilon$ 

#### **Learned Bloom filter:**

- D is a distribution over  $U \setminus K$
- $FPR_B$  = false positive rate of backup Bloom filter
- False positive rate of learned Bloom filter:

$$FPR_{O} = \mathbb{P}_{y \sim D}[f(y) > \tau] + \mathbb{P}_{y \sim D}[f(y) \leq \tau] \cdot FPR_{B}$$
Return **yes** Send to backup Bloom filter

• FPR<sub>O</sub> is with respect to a random draw of  $y \sim D$ 

## Differences between FPRs

Bloom filter: for any y

**Robust** to distribution shift

tive  $\leq \epsilon$ 

**Learned Bloom filter:** ← Not robust to distribution shift

- D is a distribution over  $U \setminus K$
- FPR<sub>B</sub> = false positive rate of backup Bloom filter
- False positive rate of learned Bloom filter:

$$\operatorname{FPR}_{O} = \mathbb{P}_{y \sim D} [f(y) > \tau] + \mathbb{P}_{y \sim D} [f(y) \leq \tau] \cdot \operatorname{FPR}_{B}$$
Return **yes** Send to backup Bloom filter

• FPR<sub>0</sub> is with respect to a **random draw** of  $y \sim D$