



# Graphs

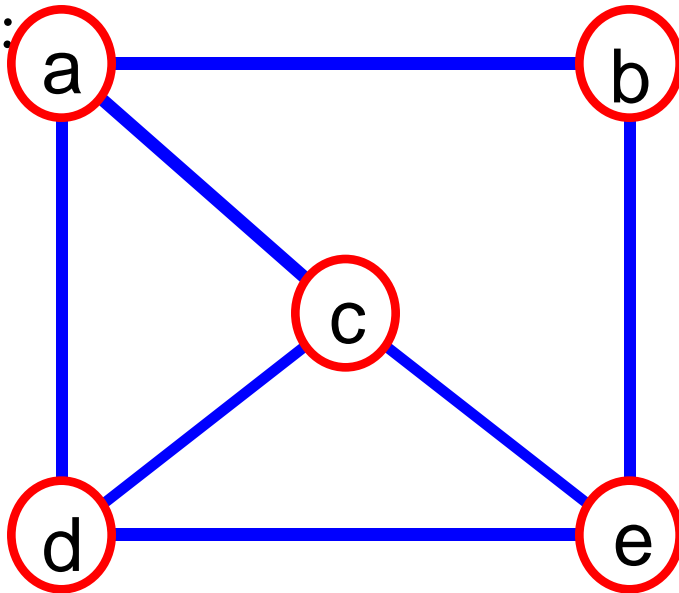
# What is a Graph?

- A graph  $G = (V, E)$  is composed of:

$V$ : set of **vertices**

$E$ : set of **edges** connecting the **vertices** in  $V$

- An **edge**  $e = (u, v)$  is a pair of **vertices**
- Example:

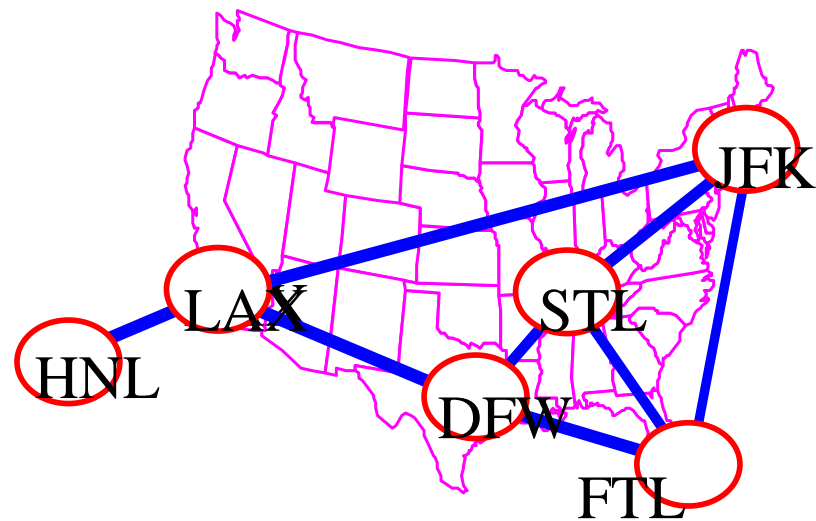
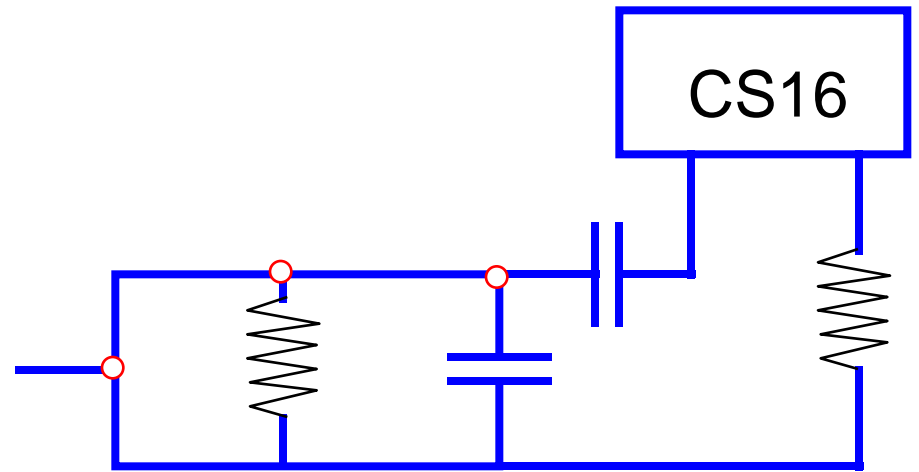


$V = \{a, b, c, d, e\}$

$E = \{(a, b), (a, c), (a, d), (b, e), (c, d), (c, e), (d, e)\}$

# Applications

- electronic circuits
- **networks** (roads, flights, communications)



# Terminology

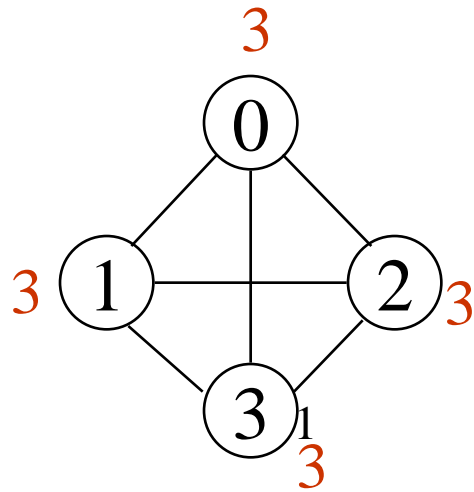
## Adjacent and Incident

- If  $(v_0, v_1)$  is an edge in an undirected graph,
  - $v_0$  and  $v_1$  are **adjacent (w.r.t.vertices)**
  - The edge  $(v_0, v_1)$  is **incident** on vertices  $v_0$  and  $v_1$  (w.r.t.edges)
- If  $\langle v_0, v_1 \rangle$  is an edge in a directed graph
  - $v_0$  is **adjacent to**  $v_1$ , and  $v_1$  is **adjacent from**  $v_0$
  - The edge  $\langle v_0, v_1 \rangle$  is incident on  $v_0$  and  $v_1$

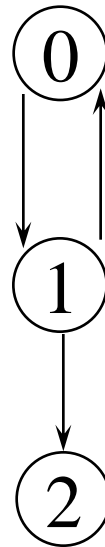
# *Degree of a Vertex*

- The **degree** of a vertex is the number of edges incident to that vertex
- For directed graph,
  - the **in-degree** of a vertex  $v$  is the number of edges that have  $v$  as the head
  - the **out-degree** of a vertex  $v$  is the number of edges that have  $v$  as the tail

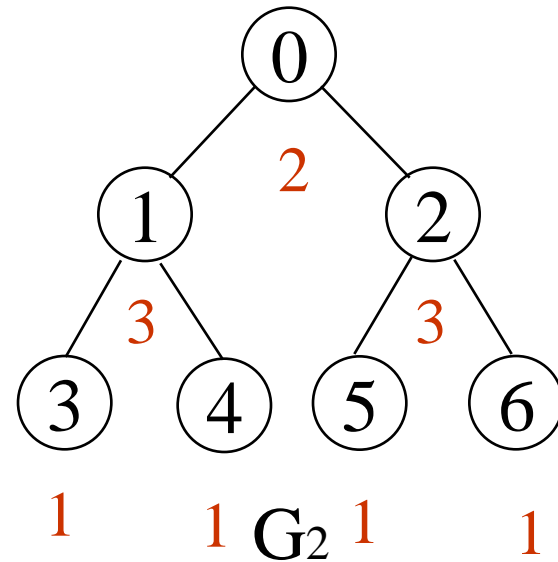
# Examples



directed graph  
in-degree  
out-degree



$G_3$



in: 1, out: 1

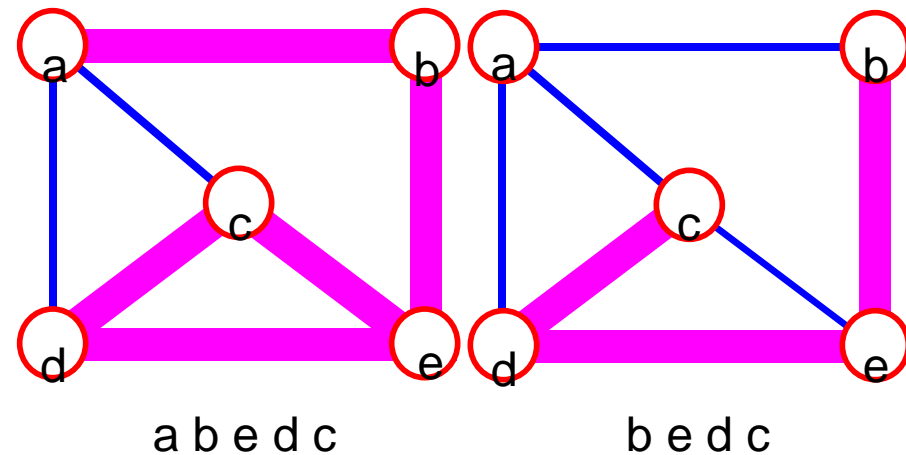
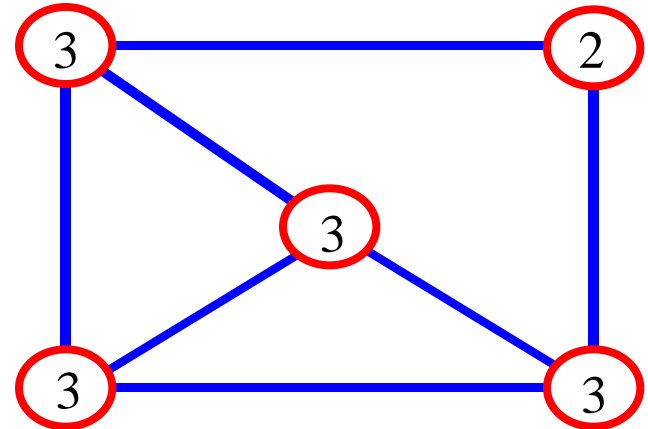
in: 1, out: 2

in: 1, out: 0

$G_2$

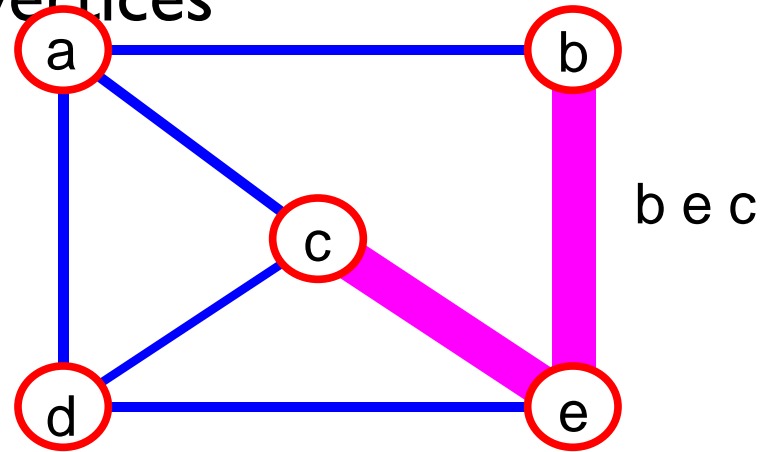
# Path

- **path**: sequence of vertices  $v_1, v_2, \dots, v_k$  such that consecutive vertices  $v_i$  and  $v_{i+1}$  are adjacent.



# More Terminology

- **simple path:** no repeated vertices

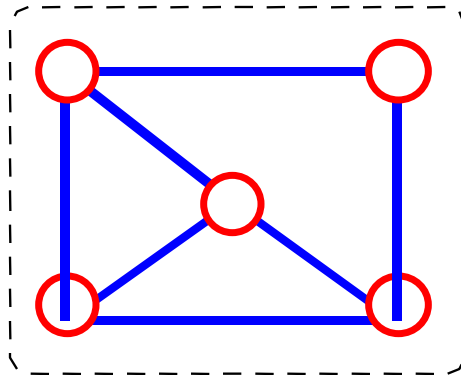


- **cycle:** simple path, except that the last vertex is the same as the first vertex

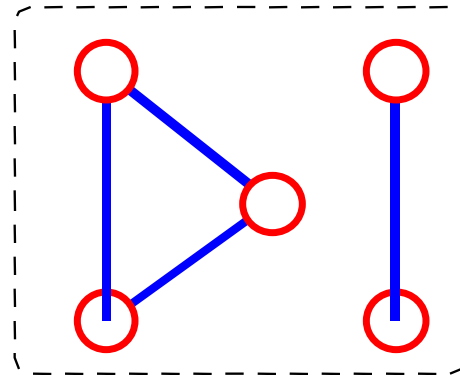


# Even More Terminology

- **connected graph**: any two vertices are connected by some path



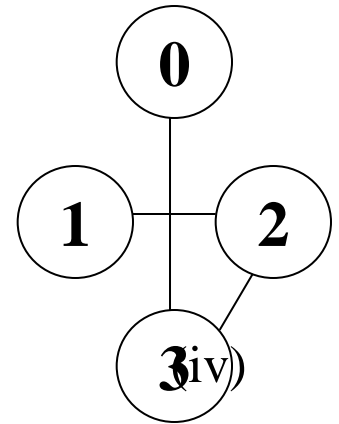
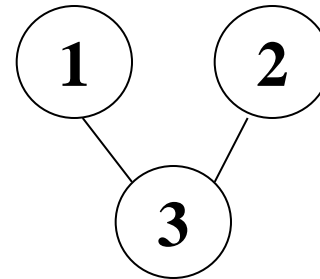
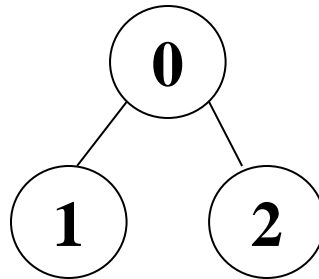
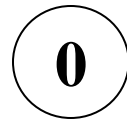
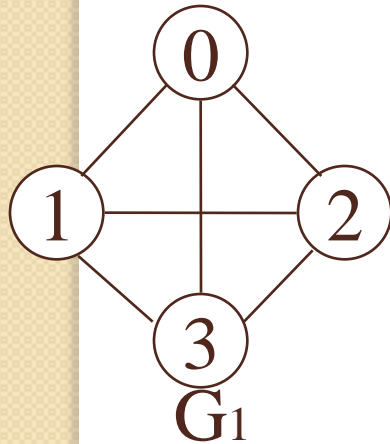
connected



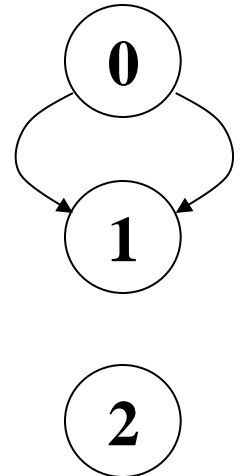
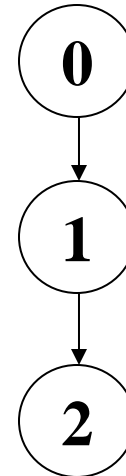
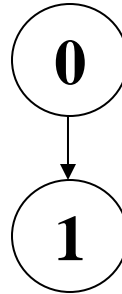
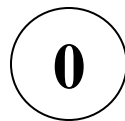
not connected

- **subgraph**: subset of vertices and edges forming a graph

# Subgraphs Examples



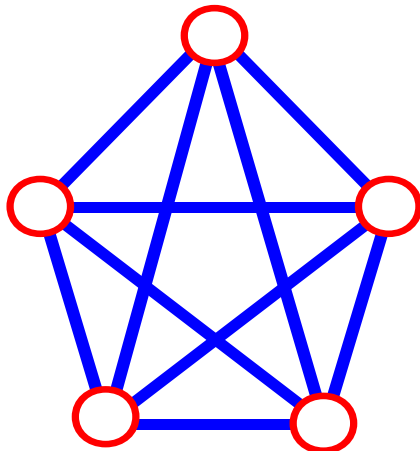
(a) Some of the subgraph of  $G_1$



(b) Some of the subgraph of  $G_3$

# Connectivity

- Let  $n = \text{\#vertices}$ , and  $m = \text{\#edges}$
- **A complete graph**: one in which all pairs of vertices are adjacent
- *How many total edges in a complete graph?*
  - Each of the  $n$  vertices is incident to  $n-1$  edges, however, we would have counted each edge twice! Therefore, intuitively,  $m = n(n-1)/2$ .
- Therefore, if a graph is not complete,  $m < n(n-1)/2$



$$n = 5$$

$$m = (5 * 4) / 2 = 10$$

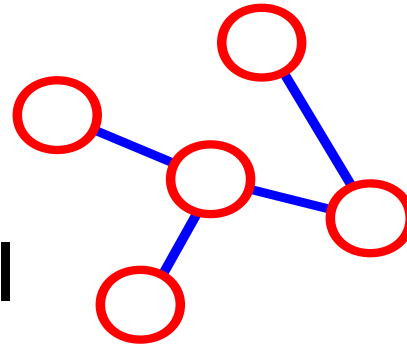
# More Connectivity

**n** = #vertices

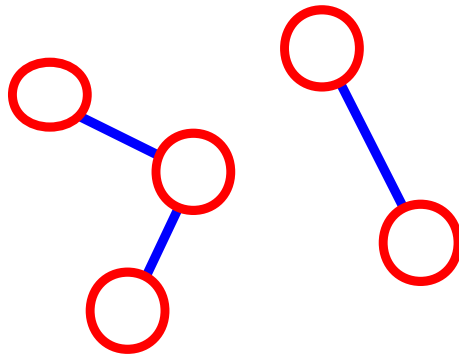
**m** = #edges

- For a tree **m** = **n** - 1

If **m** < **n** - 1, G is  
not connected



**n** = 5  
**m** = 4



**n** = 5  
**m** = 3

# Directed vs. Undirected Graph

- An **undirected graph** is one in which the pair of vertices in a edge is unordered,  $(v_0, v_1) = (v_1, v_0)$
- A **directed graph** is one in which each edge is a directed pair of vertices,  $\langle v_0, v_1 \rangle \neq \langle v_1, v_0 \rangle$   

**tail**  
\_\_\_\_\_

→

**head**

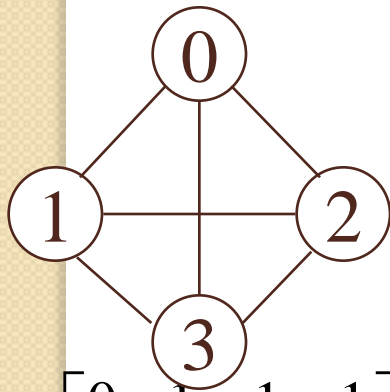
# Graph Representations

- Adjacency Matrix
- Adjacency Lists

# Adjacency Matrix

- Let  $G=(V,E)$  be a graph with  $n$  vertices.
- The **adjacency matrix** of  $G$  is a two-dimensional  $n$  by  $n$  array, say `adj_mat`
- If the edge  $(v_i, v_j)$  is in  $E(G)$ , `adj_mat[i][j]=1`
- If there is no such edge in  $E(G)$ , `adj_mat[i][j]=0`
- The adjacency matrix for an undirected graph is symmetric; the adjacency matrix for a digraph need not be symmetric

# Examples for Adjacency Matrix



$$\begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

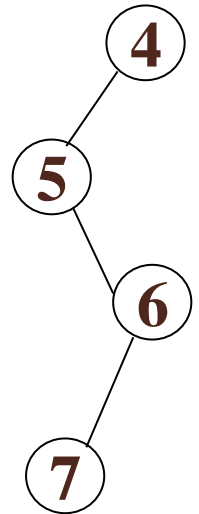
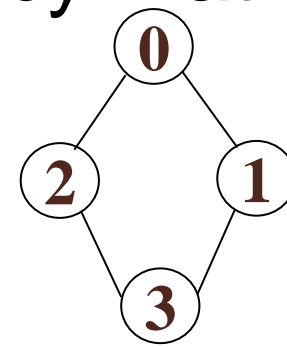
$G_1$



$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$G_2$

symmetric



$$\begin{bmatrix} 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

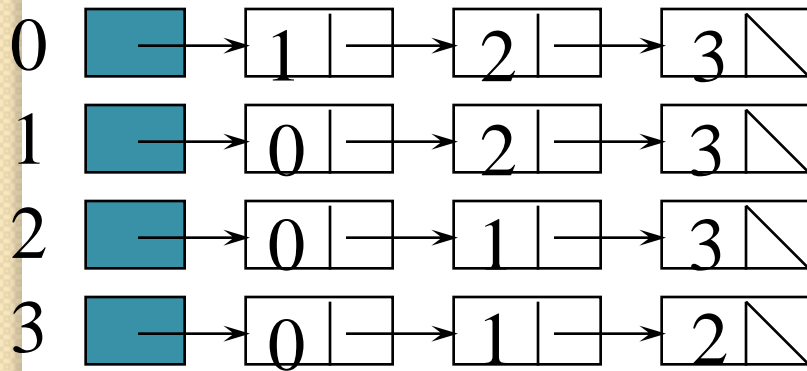
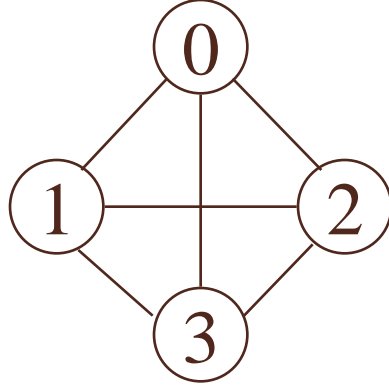
$G_4$



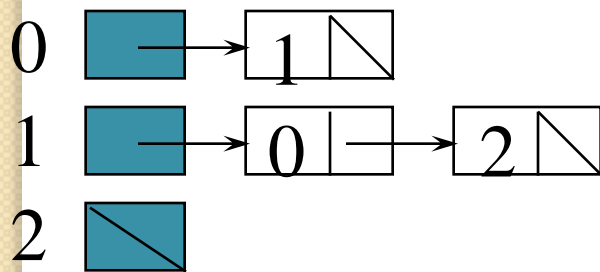
# Adjacency Lists (data structures)

Each row in adjacency matrix is represented as an adjacency list.

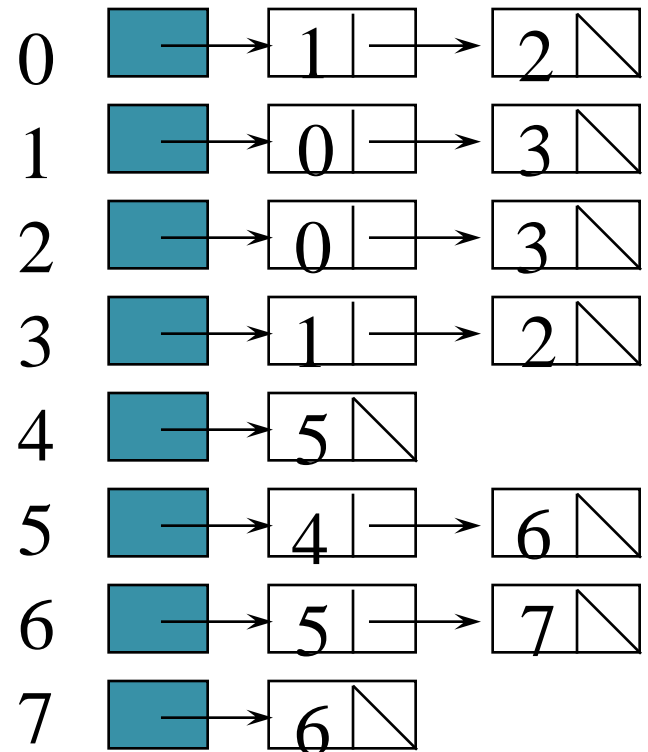
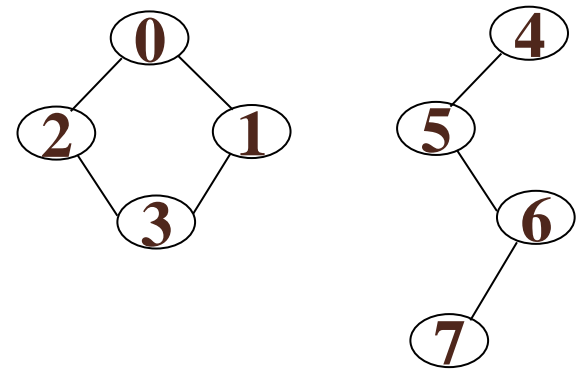
```
#define MAX_VERTICES 50
typedef struct node *node_pointer;
typedef struct node {
    int vertex;
    struct node *link;
};
node_pointer graph[MAX_VERTICES];
```



$G_1$



$G_3$



$G_4$

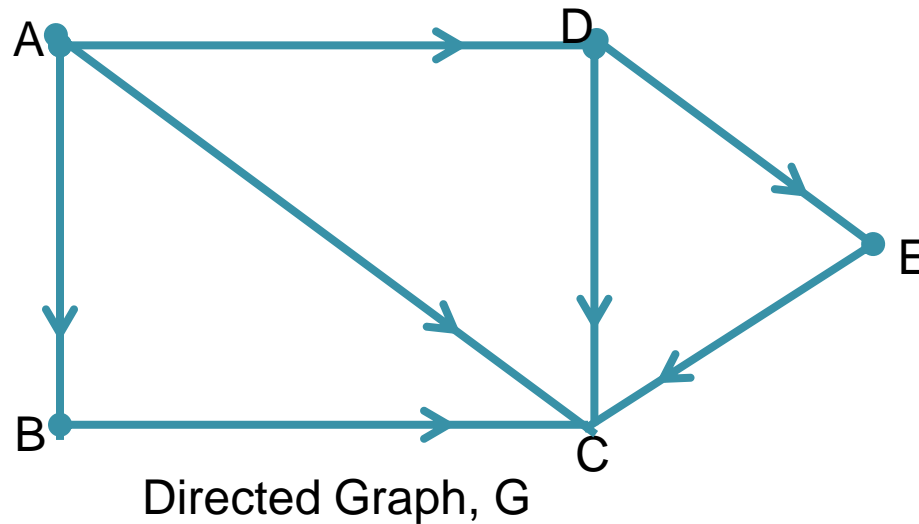
An undirected graph with  $n$  vertices and  $e$  edges  $\implies$   $n$  head nodes and  $2e$  list nodes



# Linked Representation of Graph

**S. Graceline Jasmine, SCSE, VIT**

# Drawbacks of sequential representation of G in memory



Sparse matrix  
Great deal  
of space will  
be wasted

Adjacency List

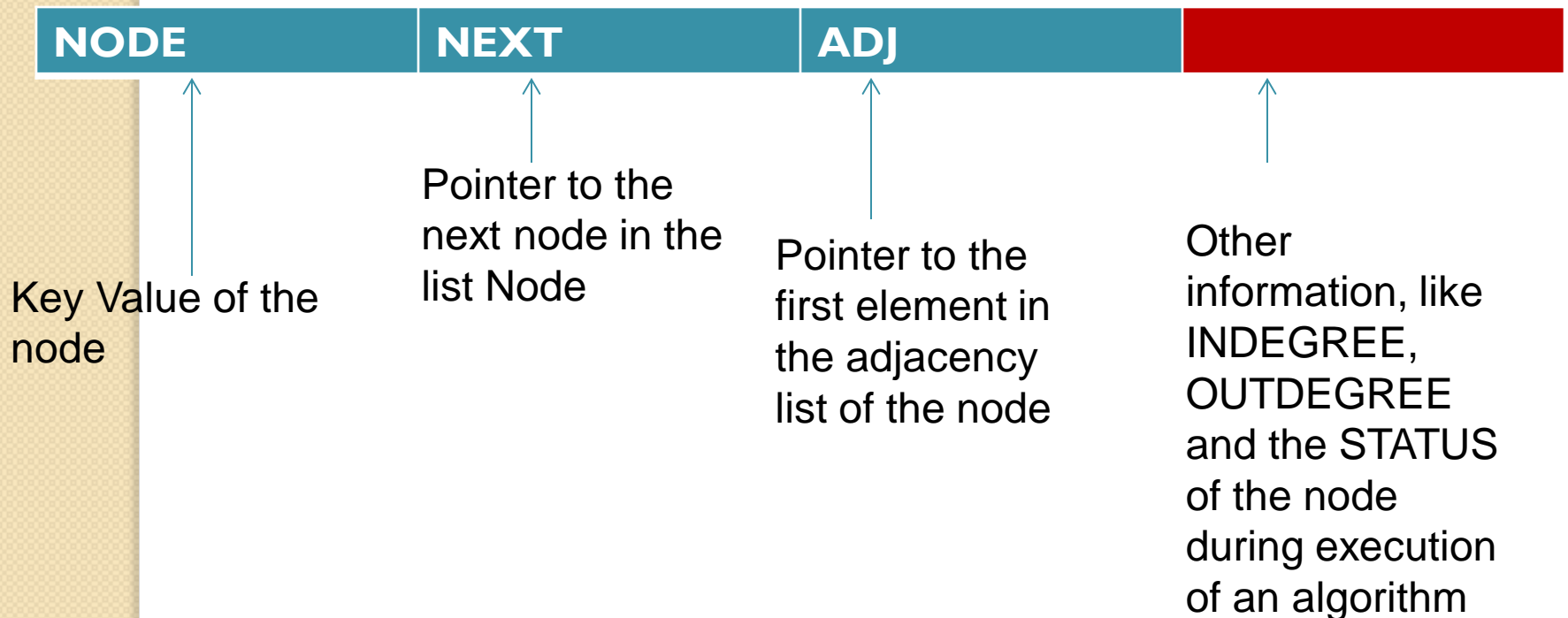
Nod e	Adjacency List
A	B, C, D
B	C
C	
D	C, E
E	C

Adjacency Matrix

	A	B	C	D	E
A	0	1	1	1	0
B	0	0	1	0	0
C	0	0	0	0	0
D	0	0	1	0	1
E	0	0	1	0	0

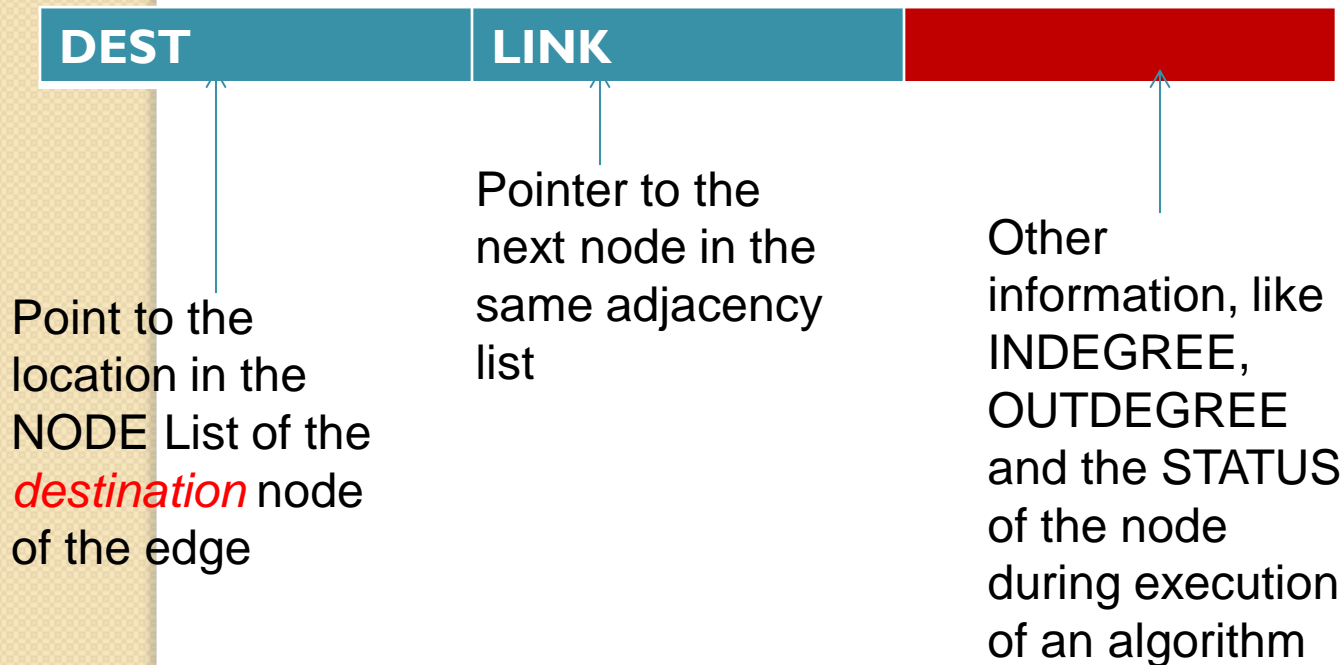
# Linked Representation

## NODE LIST

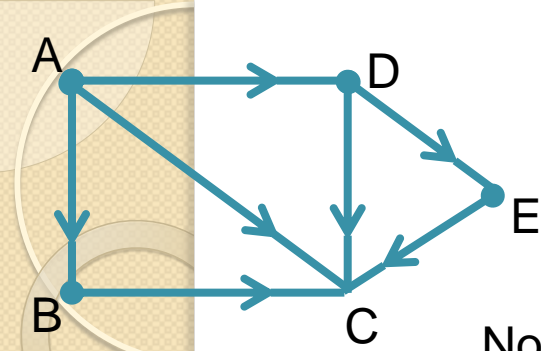


# Linked Representation

## EDGE LIST



# Schematic Diagram of the linked representation of G in memory

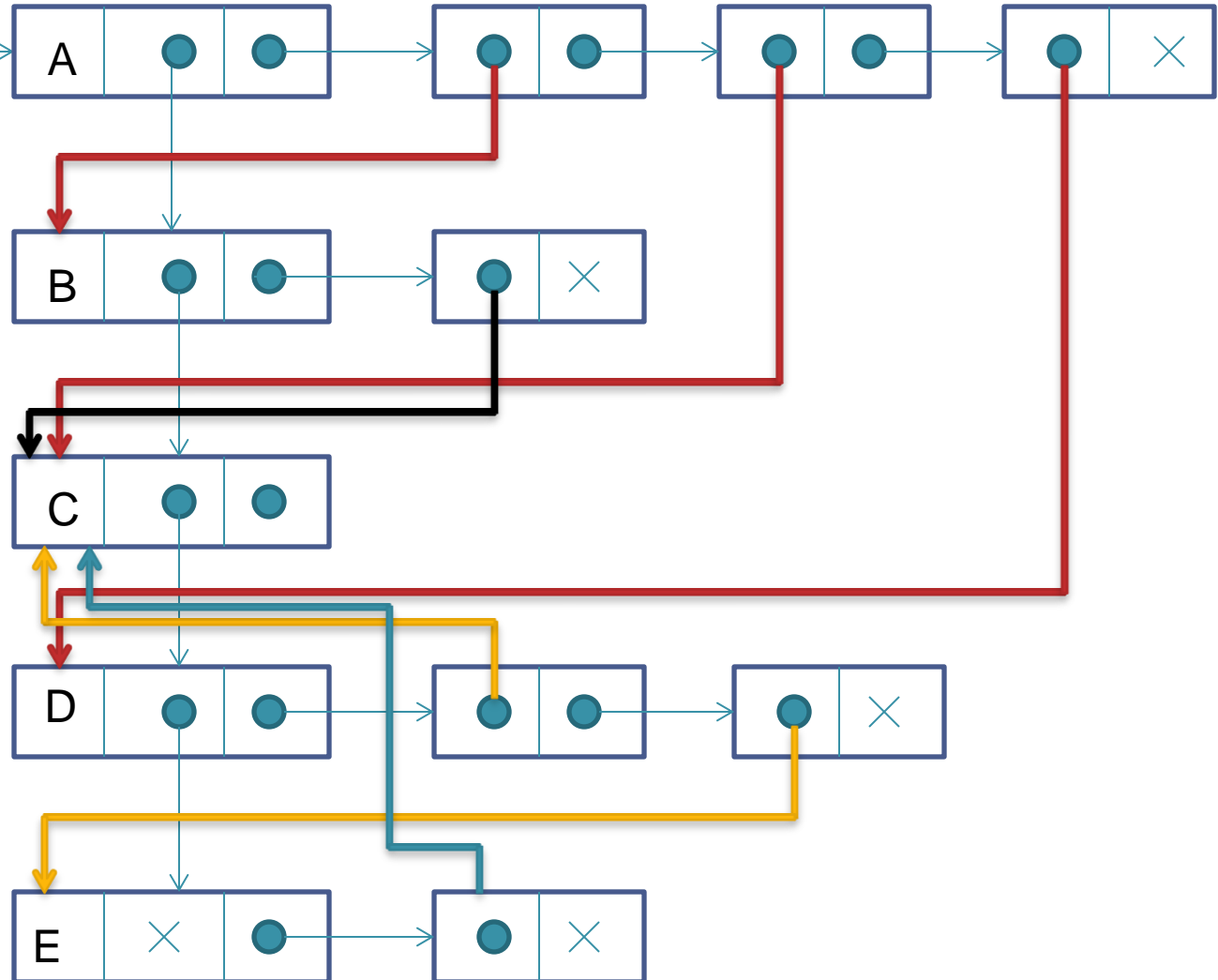


START



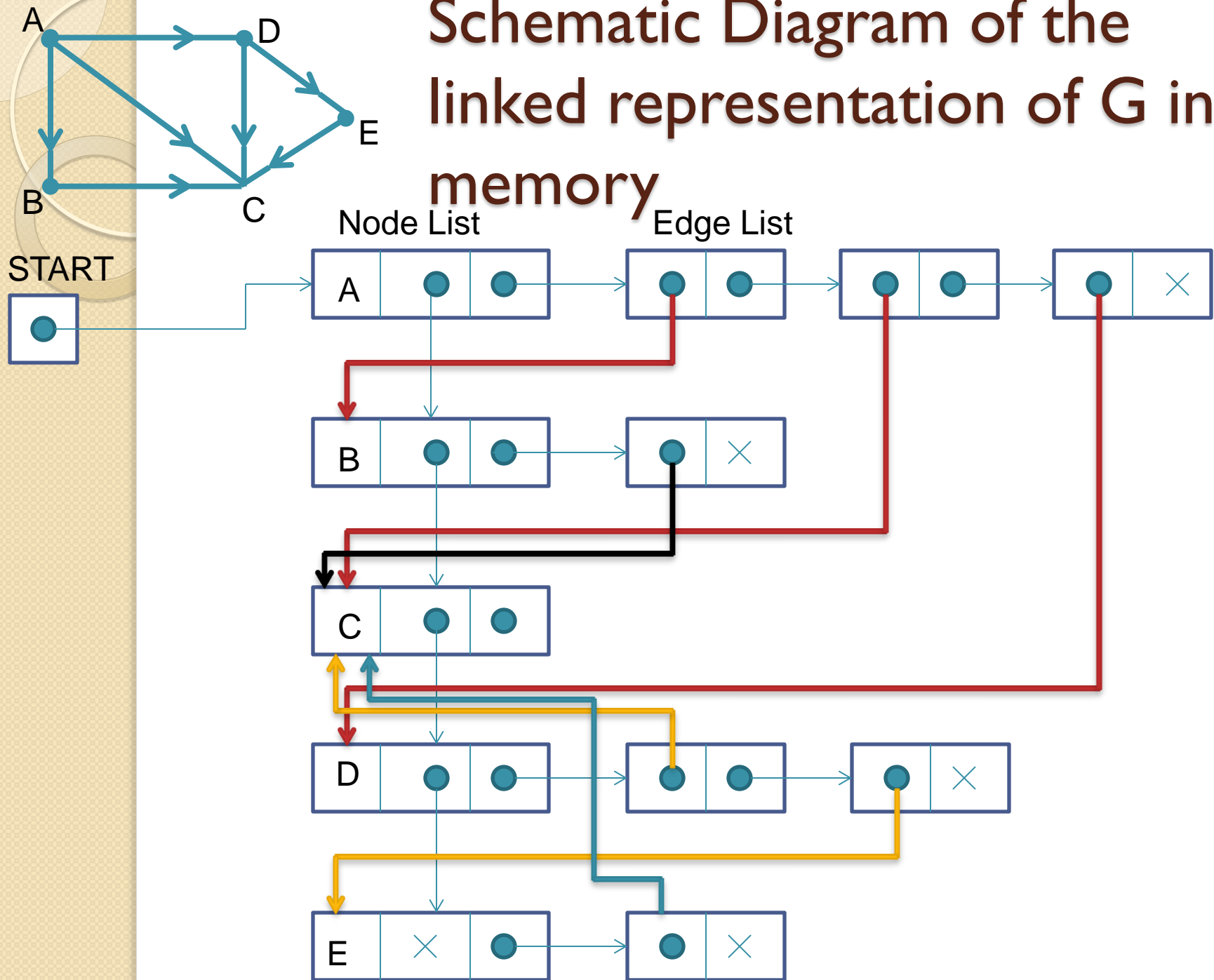
Node List

Edge List



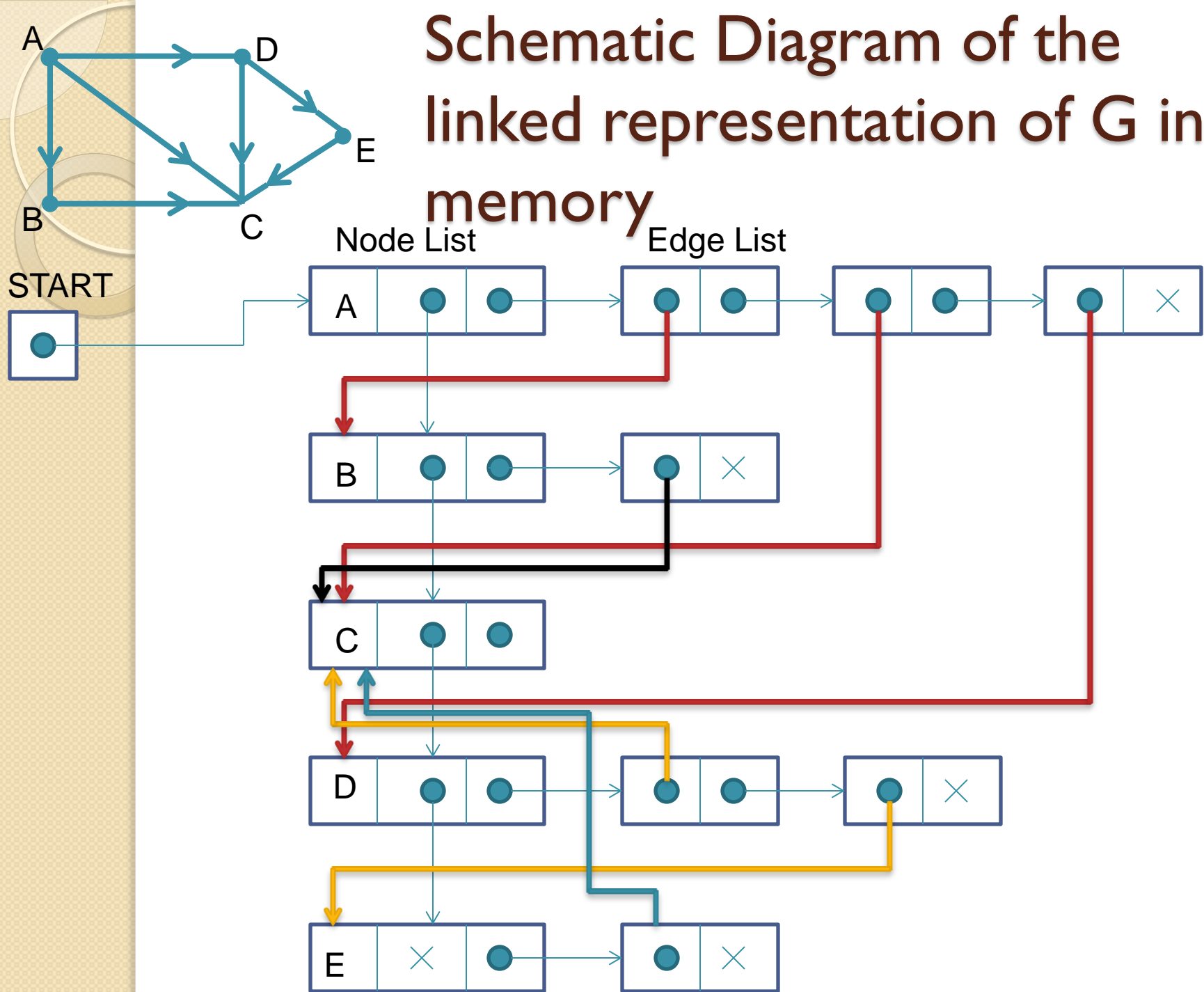
Node	Adjacency List
A	B, C, D
B	C
C	
D	C, E
E	C

# Schematic Diagram of the linked representation of G in memory

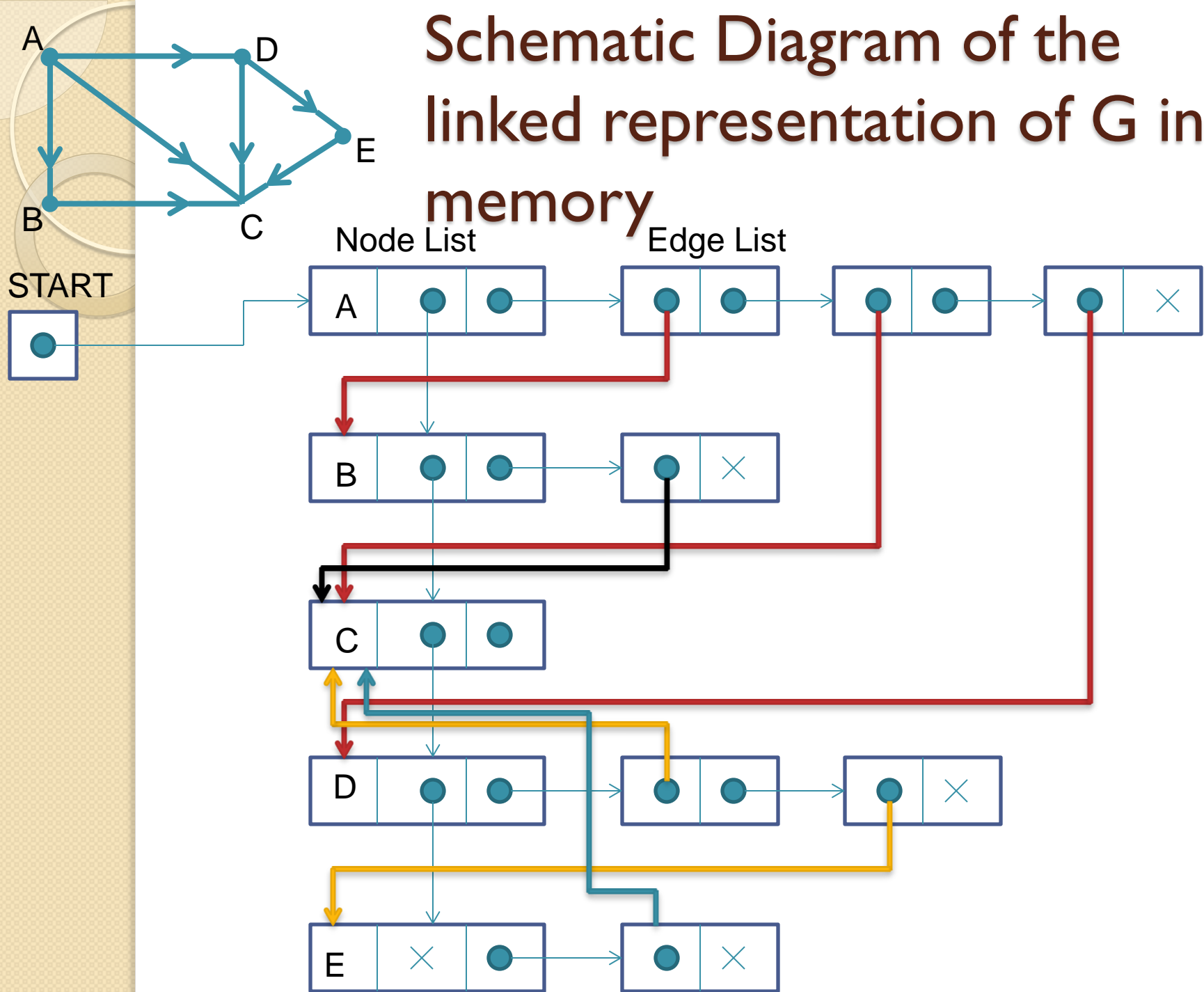


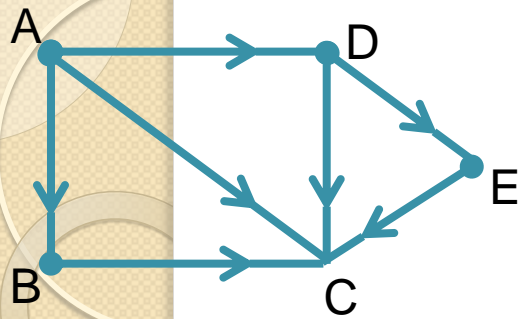


# Schematic Diagram of the linked representation of G in memory



# Schematic Diagram of the linked representation of G in memory





# Graph G in memory

START

4

Node NEXTADJ

1		3	
2	C	9	0
3		8	
4	A	7	3
5		1	
6	E	0	11
7	B	2	6
8		10	
9	D	6	1
10		0	

DEST LINK

1	2 (c)	7
2		5
3	7 (B)	10
4	9 (D)	0
5		8
6	2 (C)	0
7	6 (E)	0
8		9
9		12
10	2 (C)	4
11	2 (c)	0
12		0