



Data Structure and Algorithms

Session-20

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Insertion Sort:

- ✓ In Insertion sort algorithm we divide the given array into 2 parts i.e. Sorted & Unsorted
- ✓ Then from Unsorted we pick the first element and find its correct position in sorted array.
- ✓ Repeat till Unsorted array is not empty.



Insertion Sort Algorithm:

InsertionSort(A):

for $i = 1$ *to* n

$currentNumber = A[i], j = i$

while $(A[j-1] > currentNumber \ \&\& \ j > 0)$

$A[j] = A[j-1]$

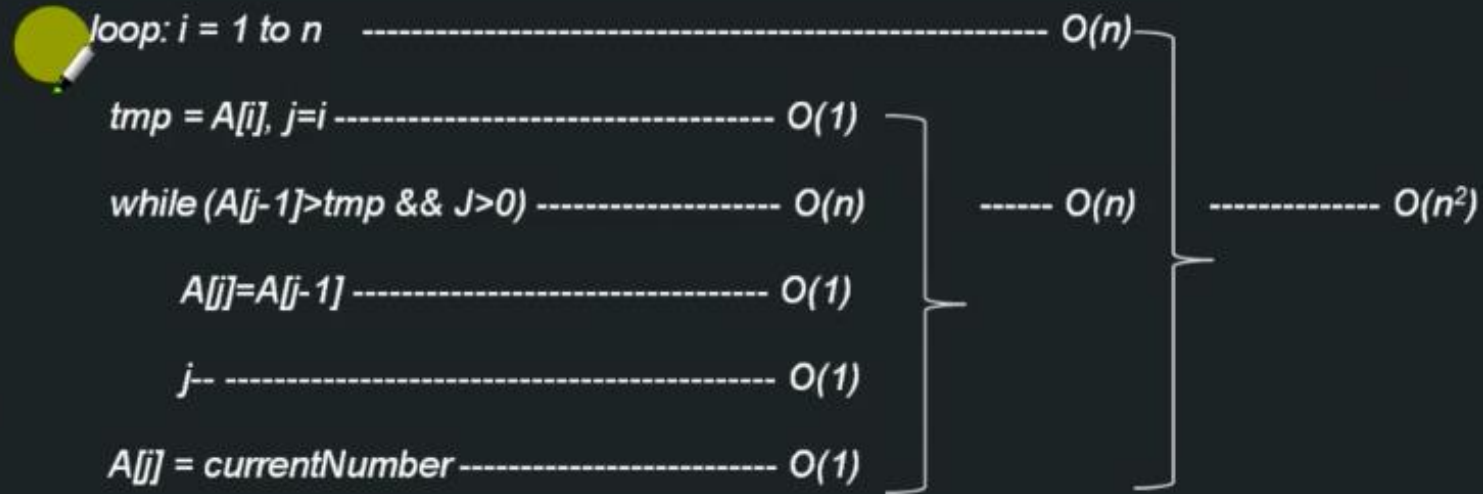
$j--$

$A[j] = currentNumber$



Time & Space Complexity of Insertion Sort Algorithm:

InsertionSort(A):



Time Complexity - $O(n^2)$

Space Complexity - $O(1)$

When to Use/Avoid Insertion Sort:

✓ When to use:

- ✓ No extra space
- ✓ Simple implementation
- ✓ Best when we have continuous inflow of numbers and we want to keep the list sorted

✓ When not to use:

- ✓ Average case is bad

Bucket Sort:

✓ *Bucket sort is a sorting algorithm that works by distributing the elements of an array into a number of buckets.*

✓ *Each bucket is then sorted individually.*

40	10	30	80	70	20	60	50	100
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40	10	30	80	70	20	60	50	100
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- ✓ Create Number of buckets = $\text{ceil}(\sqrt{\text{total number of items}})$
- ✓ Iterate through each number and place it in appropriate bucket
- ✓ Appropriate bucket = $\text{Ceil}((\text{Value} * \text{number of buckets}) / \text{max value in array})$
- ✓ Sort all the buckets
- ✓ Merge all the buckets



Bucket Sort Algorithm:

BucketSort(A):

find no. of buckets to be created and create those buckets $B_1[]$, $B_2[]$...

find divisor value

loop: $i = 0$ to $n-1$

insert $A[i]$ into array $B[]$ using divisor and bucket#

sort $B[]$ with insertion sort (or any sort as per comfort)

concatenate $B_1[]$, $B_2[]$, $B_3[]$...

Time & Space complexity of Bucket Sort Algorithm:

BucketSort(A):

find no. of buckets to be created and create those buckets $B1[], B2[] \dots$ ----- $O(1)$

find divisor value ----- $O(1)$

loop: $i = 0$ to $n-1$ ----- $O(n)$

 insert $A[i]$ into array $B[]$ using divisor and bucket# ----- $O(1)$

sort $B[]$ ----- $O(n \log n)$

concatenate $B1[], B2[], B3[] \dots$ ----- $O(n)$

Time Complexity = $O(n) + O(n \log n) + O(n)$

= $O(n \log n)$

Space Complexity – $O(n)$

When to Use/Avoid Bucket Sort:

40	10	30	80	70	20	60	50	100
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✓ When to use:

- ✓ *When input is uniformly distributed over a range*


✓ When not to use:

- ✓ *When space is a concern*

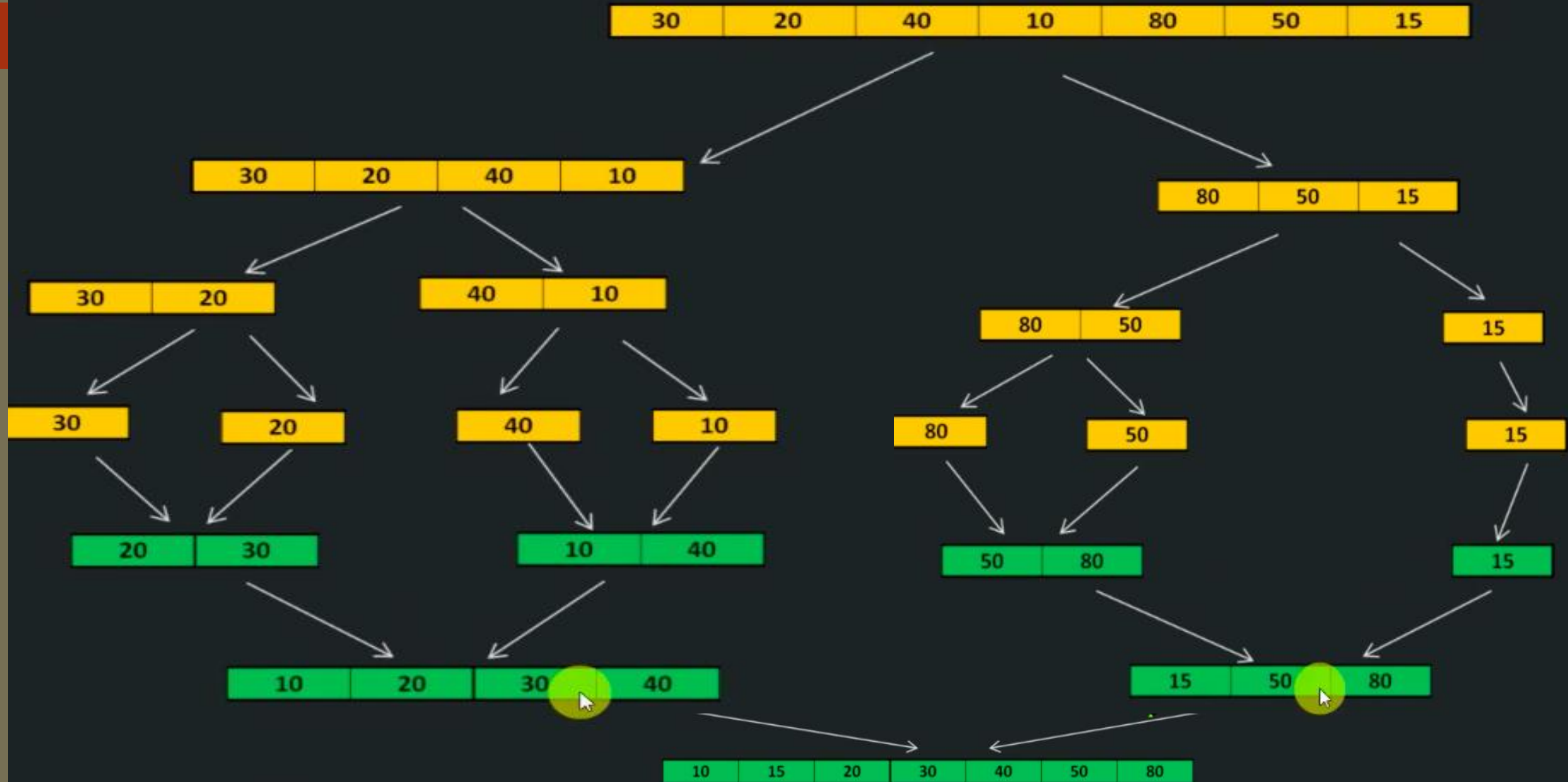




Merge Sort:

- ✓ Merge Sort is a Divide and Conquer algorithm.
 - ✓ It divides input array in two halves, keeps breaking those 2 halves recursively until they become too small to be broken further.
 - ✓ Then each of the broken pieces are merged together to inch towards final answer.
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Merge sort



Merge Sort Algorithm:

mergeSort(A,l,r)

if $r > l$

middle $m = (l+r)/2$

mergeSort(A,l,m)

mergeSort(A,m+1,r)

merge(A,l,m,r)

merge(A,p,m,r):

create tmp arrays L & R and copy A,p,m into L & A,m+1,r into R

$i = j = 0$;

loop: $k = p$ to r

if $L[i] < R[j]$

$A[k] = L[i]$; $i++$

else

$A[k] = R[j]$; $j++$

30	20	40	10	80	50	15
----	----	----	----	----	----	----

10	20	30	40
----	----	----	----

15	50	80
----	----	----

10	15	20	30	40	50	80
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Time & Space complexity of Merge Sort Algorithm:

mergeSort(A,l,r): ----- $T(n)$

if $r > l$ ----- $O(1)$

middle $m = (l+r)/2$ ----- $O(1)$

mergeSort(A,l,m) ----- $T(n/2)$

mergeSort(A,m+1,r) ----- $T(n/2)$

merge(A,l,m,r) ----- $O(n)$

merge(A,p,m,r):

 create tmp arrays L & R and copy A,p,m into L & A,m+1,r into R ----- $O(n)$

i = *j* = 0; ----- $O(1)$

 loop: *k* = *p* to *r* ----- $O(n)$

if $L[i] < R[j]$ ----- $O(1)$

$A[k] = L[i]; i++$ ----- $O(1)$

else ----- $O(1)$

$A[k] = R[j]; j++$ ----- $O(1)$

----- $O(n)$

Time & Space complexity of Merge Sort Algorithm:

$$T(n) = O(1) + O(1) + T(n/2) + T(n/2) + O(n)$$

$$= 2T(n/2) + O(n)$$

$$= 2(2T(n/4) + O(n/2)) + O(n)$$

$$= 4(T(n/4)) + 2*O(n) + O(n) \quad // O(n/2) \text{ can be represented as } O(n)$$

$$= 2^k T(n/2^k) + k*O(n)$$

$$= 2^k T(n/2^k) + k*O(n) \quad \{ \text{now lets replace 'k' with } \log n \text{ to meet the base condition} \}$$

$$= 2^{\log n} * 1 + \log n * O(n)$$

$$= o(n \log n)$$

$$\text{Equation\#1: } T(n) = 2T(n/2) + O(n)$$

$$\text{Equation\#2: } T(n/2) = 2T(n/4) + O(n/2)$$

$$\text{Equation\#3: } T(n/4) = 2T(n/8) + O(n/4)$$

$$\text{Base Condition: } T(1) = 1$$

$$\text{Space Complexity} = O(n)$$

1) If $a > b^k$, then $T(n) = \Theta(n^{\log_b a})$

2) If $a = b^k$

a. If $p > -1$, then $T(n) = \Theta(n^{\log_b a} \log^{p+1} n)$

b. If $p = -1$, then $T(n) = \Theta(n^{\log_b a} \log \log n)$

c. If $p < -1$, then $T(n) = \Theta(n^{\log_b a})$

3) If $a < b^k$

a. If $p \geq 0$, then $T(n) = \Theta(n^k \log^p n)$

b. If $p < 0$, then $T(n) = O(n^k)$

When to Use/Avoid Merge Sort:

✓ When to use:

- ✓ When you need a stable sort
- ✓ When Average expected time is $O(n \log n)$

✓ When not to use:

- ✓ When space is a concern like embedded systems



Thank
you