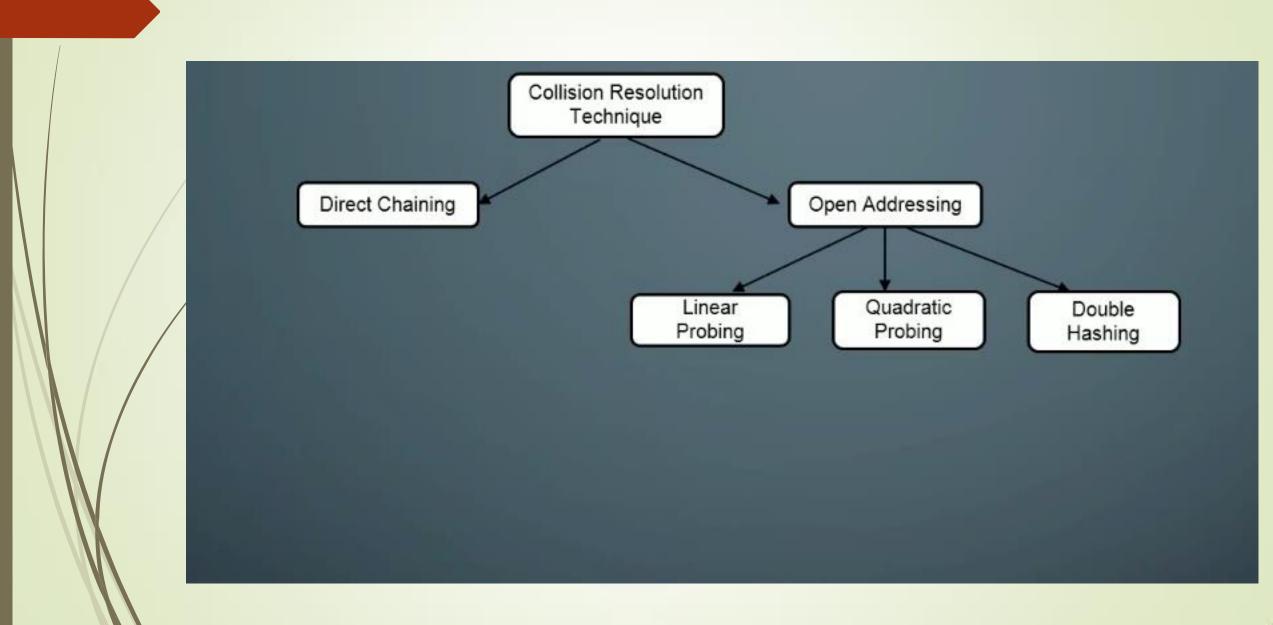


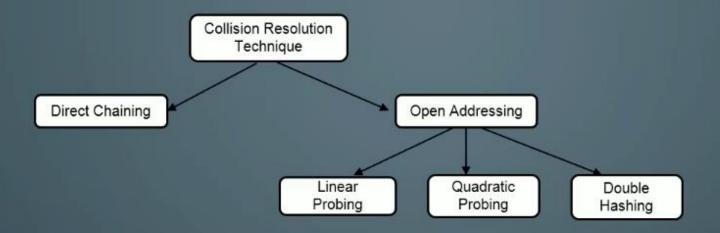
Data Structure and Algorithms

Session-31

Dr. Subhra Rani Patra SCOPE, VIT Chennai



Collision Resolution Techniques:



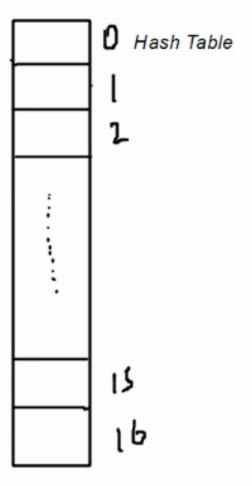
<u>Direct Chaining:</u> Implements the buckets as linked lists. Colliding elements are stored in these lists.

Open Addressing: Colliding elements are stored in other vacant buckets. During storage and lookup, these are found through so-called 'probing'

- Linear Probing:
 - Linear probing is a strategy for resolving collisions, by placing the new key into the closest following empty cell

ABCDEFG PQRSTUV MNOPQRS QWERTY HASH FUNCTION

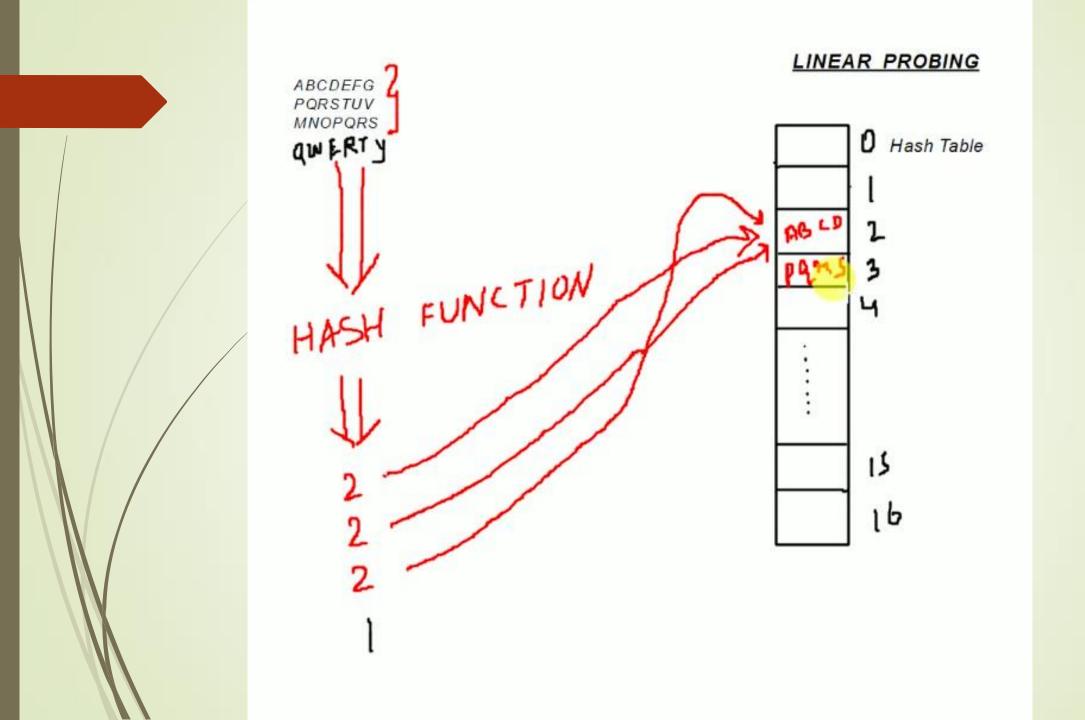
LINEAR PROBING

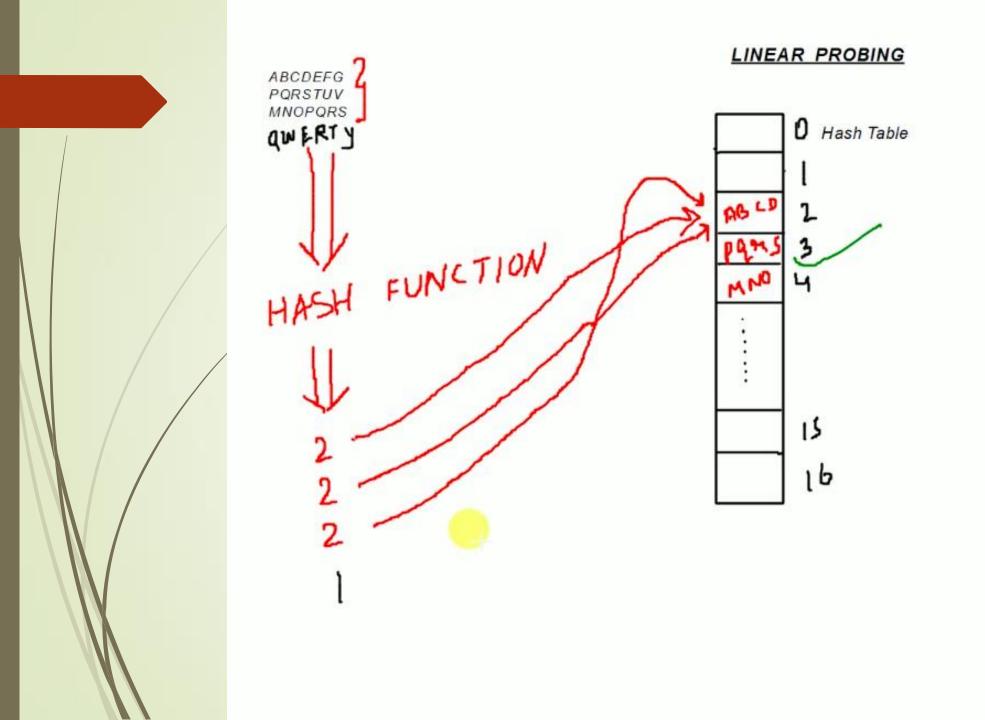


LINEAR PROBING ABCDEFG PQRSTUV MNOPQRS QWERTY **0** Hash Table HASH FUNCTION 15 lβ

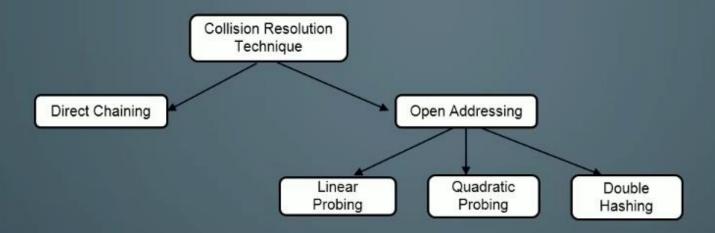
LINEAR PROBING ABCDEFG PQRSTUV MNOPQRS **0** Hash Table QWERTY BB CD HASH FUNCTION 15 lβ

LINEAR PROBING ABCDEFG PQRSTUV MNOPQRS 0 Hash Table QWERTY AB LD HASH FUNCTION 15 16





Collision Resolution Techniques:



Direct Chaining: Implements the buckets as linked lists. Colliding elements are stored in these lists.

Open Addressing: Colliding elements are stored in other vacant buckets. During storage and lookup, these are found through so-called 'probing'

- Linear Probing:
 - · Linear probing is a strategy for resolving collisions, by placing the new key into the closest following empty cell
- Quadratic Probing:
 - Quadratic probing operates by taking the original hash index and adding successive values of an arbitrary quadratic polynomial until an open slot is found.

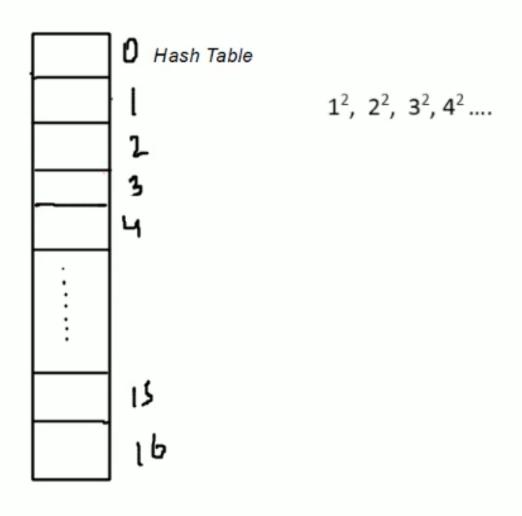


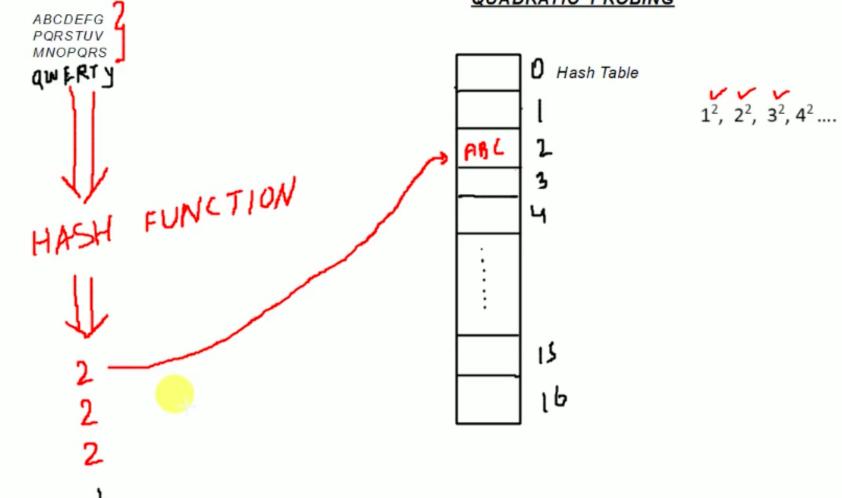
ABCDEFG PQRSTUV

MNOPQRS

QWERTY

HASH FUNCTION

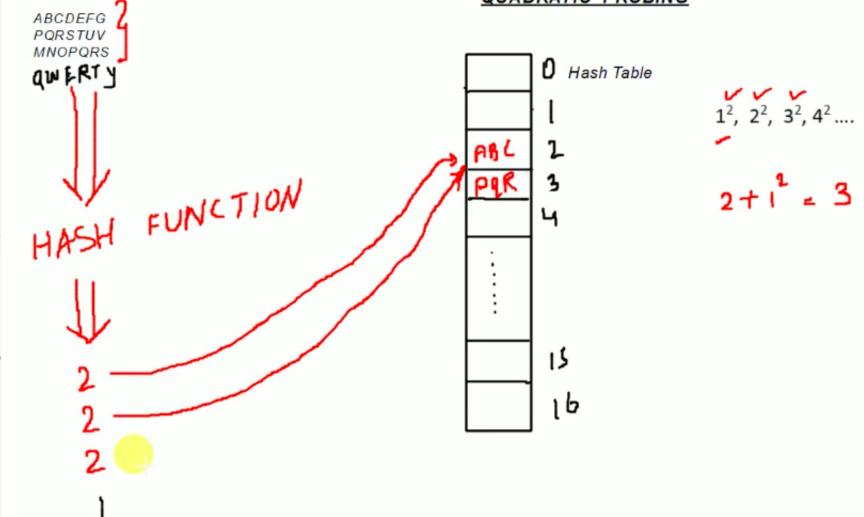


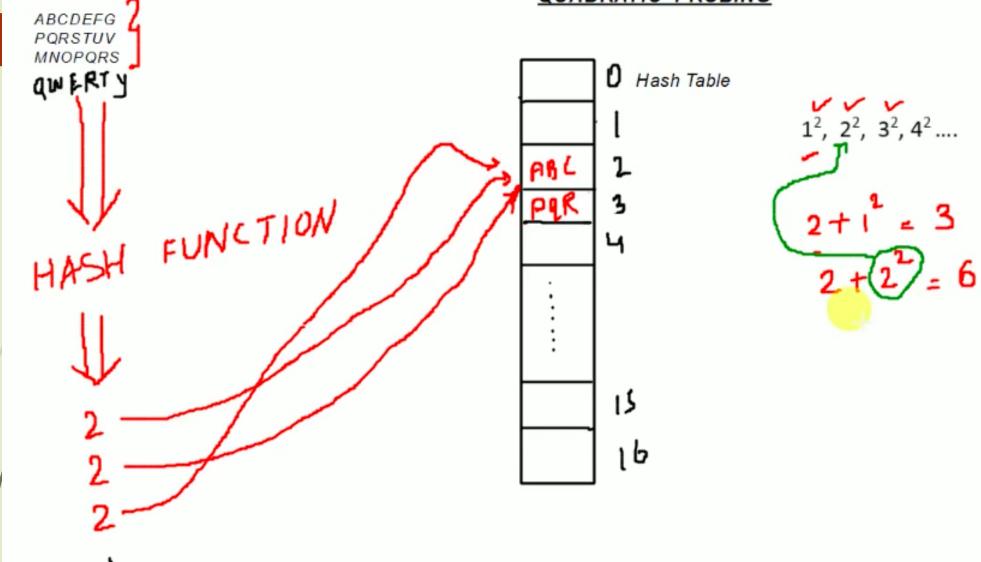


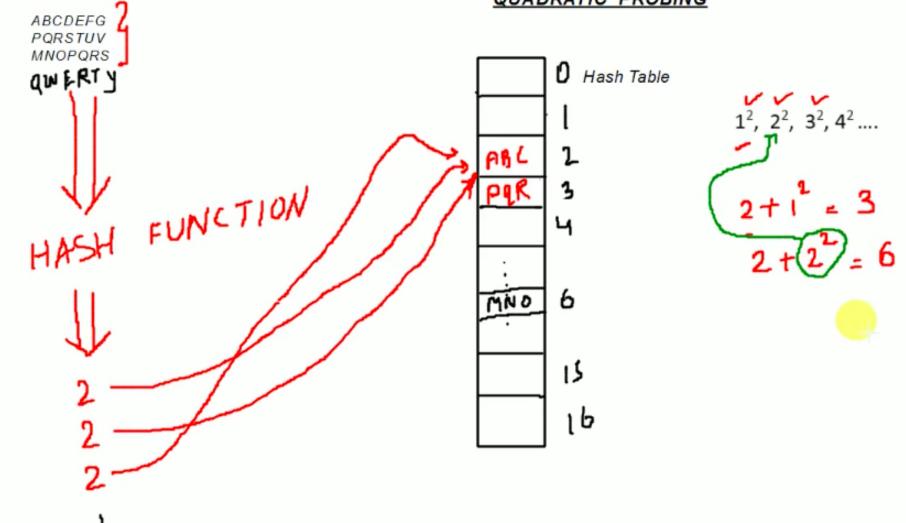
QUADRATIC PROBING ABCDEFG PORSTUV MNOPORS QW FRT Y 0 Hash Table ABL HASH FUNCTION 15 lβ

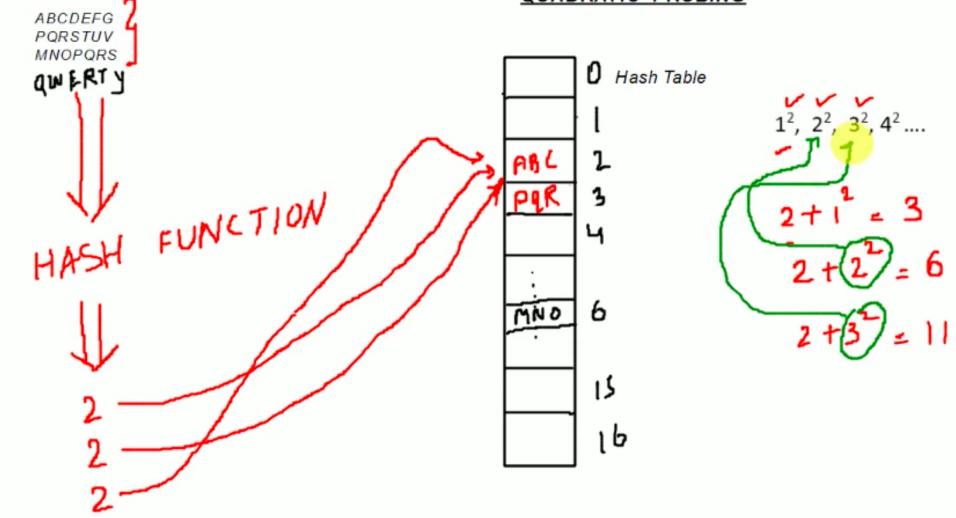
1², 2², 3², 4²....

2+12 = 3

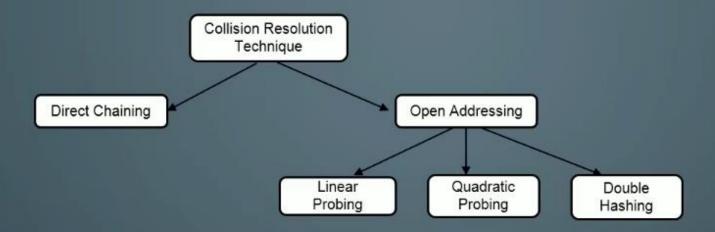








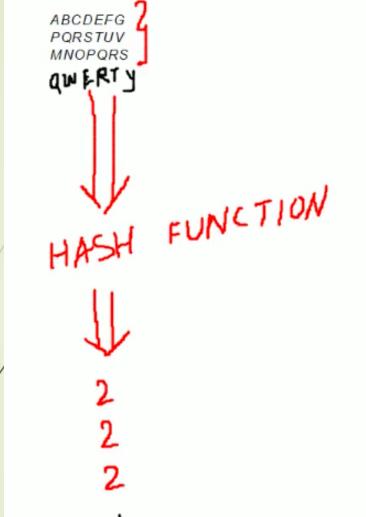
Collision Resolution Techniques:

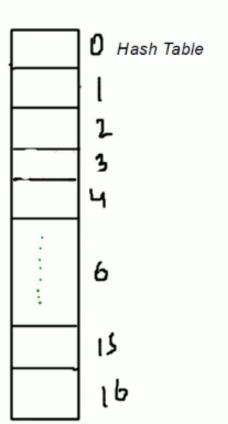


<u>Direct Chaining:</u> Implements the buckets as linked lists. Colliding elements are stored in these lists.

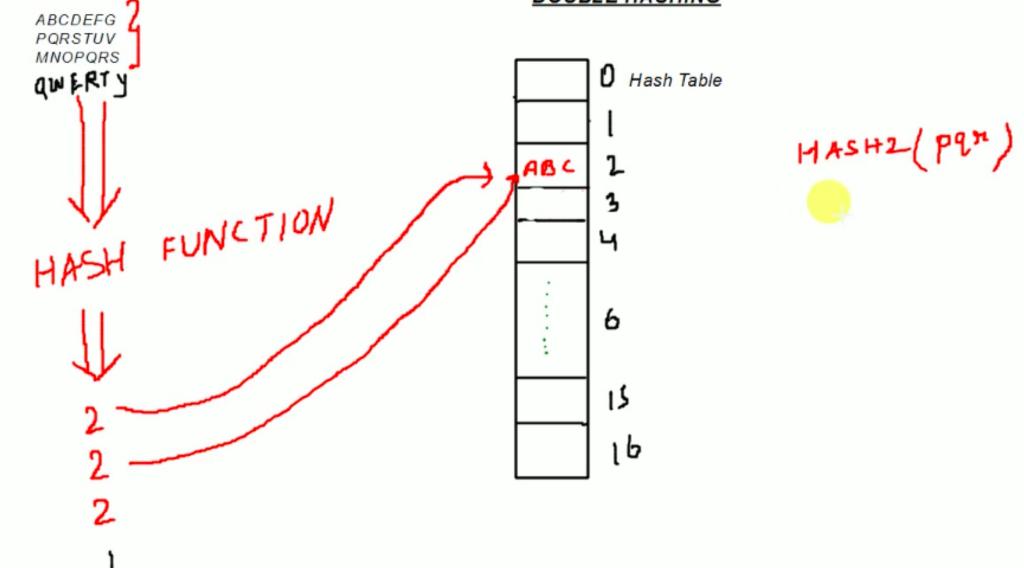
Open Addressing: Colliding elements are stored in other vacant buckets. During storage and lookup, these are found through so-called 'probing'

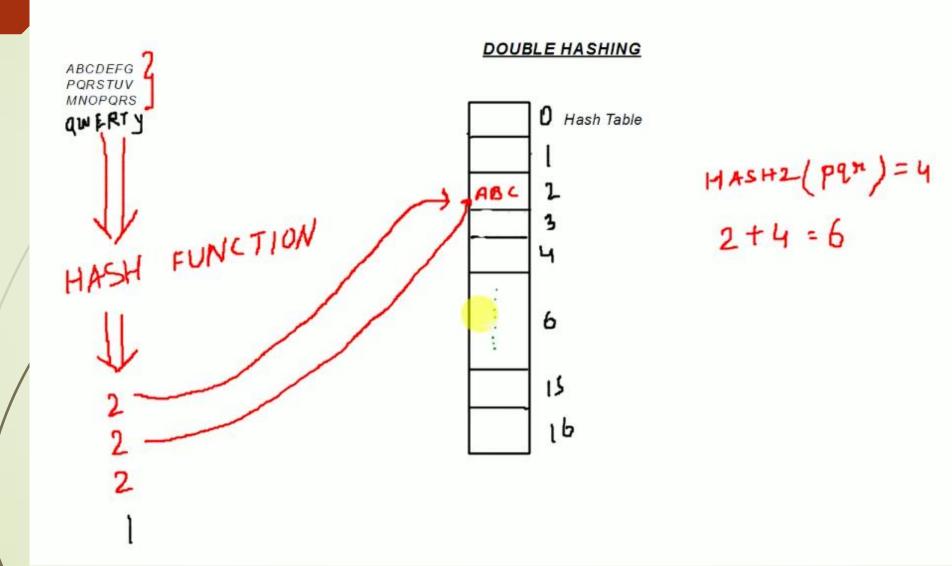
- Linear Probing:
 - Linear probing is a strategy for resolving collisions, by placing the new key into the closest following empty cell
- Quadratic Probing:
 - Quadratic probing operates by taking the original hash index and adding successive values of an arbitrary quadratic polynomial until an open slot is found.
- Double Hashing:
 - Interval between probes is computed by another hash function.

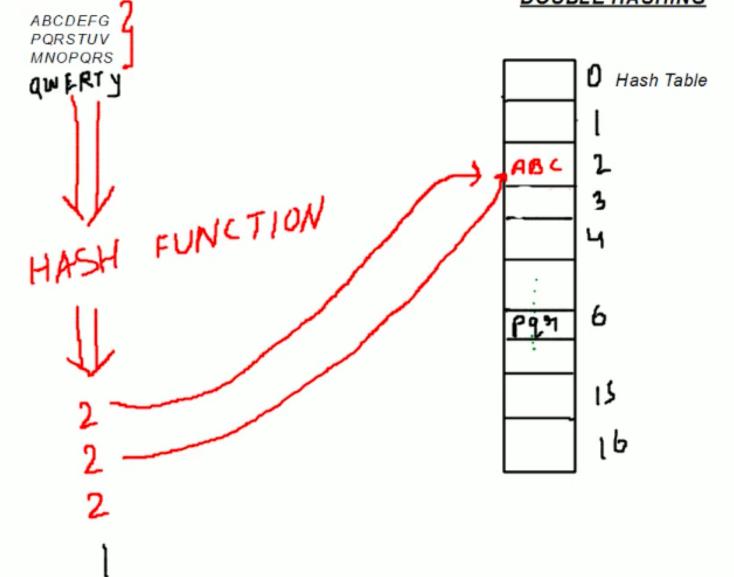


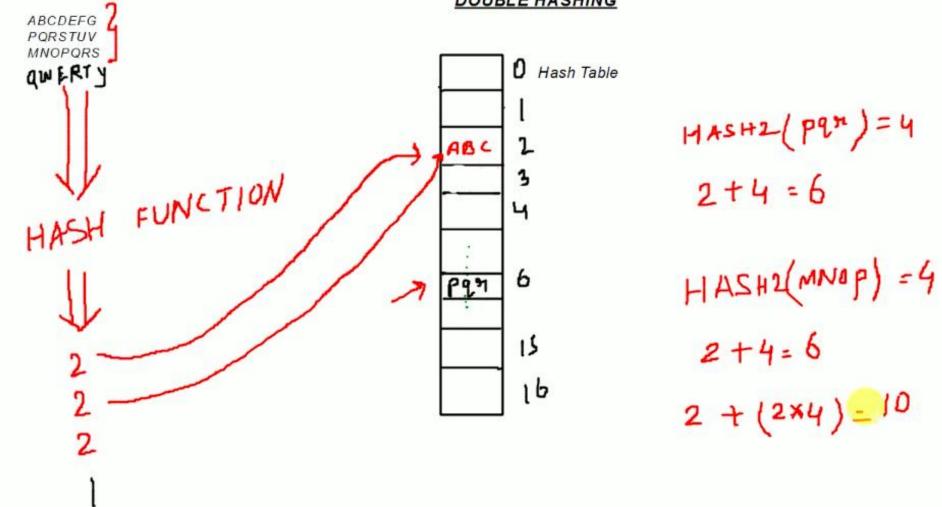


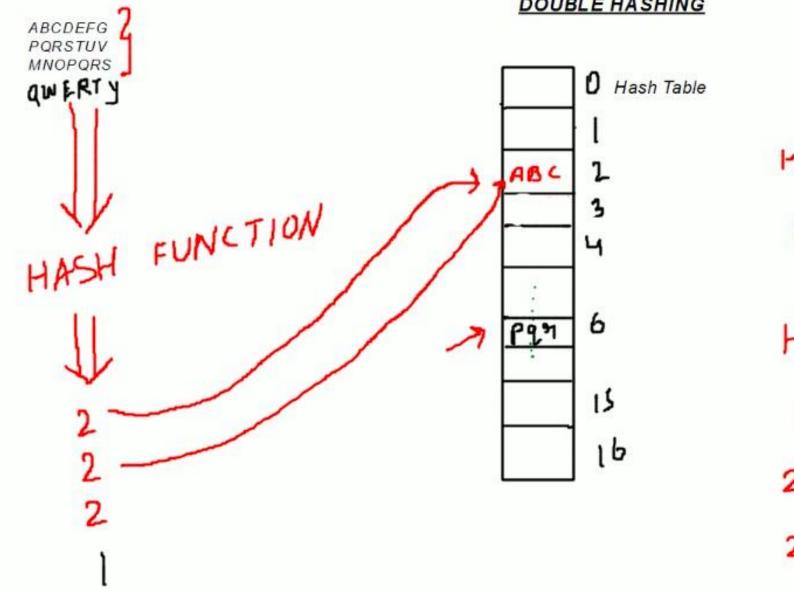
DOUBLE HASHING ABCDEFG PORSTUV MNOPORS 0 Hash Table QWERTY ABC HASH FUNCTION 6 15 16











$$HASH2(MNOP) = 4$$

 $2+4=6$
 $2+(2\times4)=10$
 $2+(3\times4)=14$

$$A = \frac{9}{12}, \frac{9}{12}, \frac{1}{12}, \frac{15}{12}$$

$$h_1(k) = 2k + 2 \quad m = 10$$

$$h_2(k) = 3k + 1$$

I cest ki at first free place from

(utv xi) 1. m where [i = 0 to (m-1)]

V = halk 1. m

1		
6		
1		
2		
3		
4		
5		
678		
7		
8		
9		اــــــا
1-	2000	7000

Key	(Cocalion (U)	V	beope
1	1 27% 10	_	1
3	9	-	S
2	6	.	
.01	2x9+3].x10=1	-	1
6	(2×6+3)1.6=1	-	1
į į	(2 X11 +3) 4. 1005	4	3
13 (× 13.43]4.10=9		
7	(2x7 +3]-1.10+	2	
12			
	[3×13+]1	.15	
	13 (3 (2 x3+3) y. 10-3 2 (2x2+3) y. 10-3 6 (2x6+3) y. 10-3 11 (2x1+3) y. 10-3 11 (2x1+3) y. 10-9 1 (2x1+3) y. 10-9	3 (2 x3+3) y. 10 - 2 (2x2+3) y. 10=1 - 6 (2x6+2)/10=1 - 11 (2x11+2) y. recs 4 12 (2x1+2) y. recs 4 13 (2x1+2) y. recs 4 14 (2x1+2) y. recs 4 15 (2x1+2) y. recs 4 17 (2x1+2) y. recs 4 18 (2x1+2) y. recs 4 19 (2x1+2) y. recs 4 10 (2x1+2) y. recs 4 11 (2x1+2) y. recs 4

$$V(U) = \begin{bmatrix} 3 \times 11 + 1 \end{bmatrix} + 4 \times 0 = 4$$

$$(u + v \times i) \cdot 1 \cdot m$$

$$(5 + 4 \times 6) \cdot 1 \cdot 10$$

$$(5 + 4 \times 1) \cdot 10$$

$$= 9$$

$$(7 + 4 \times 2) \times 10$$

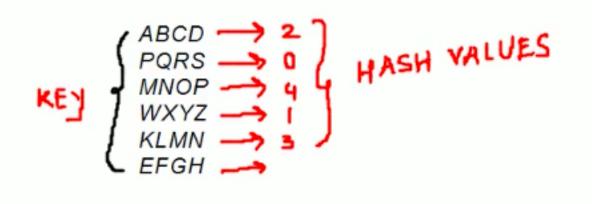
$$= 9$$

$$(7 + 4 \times 2) \times 10$$

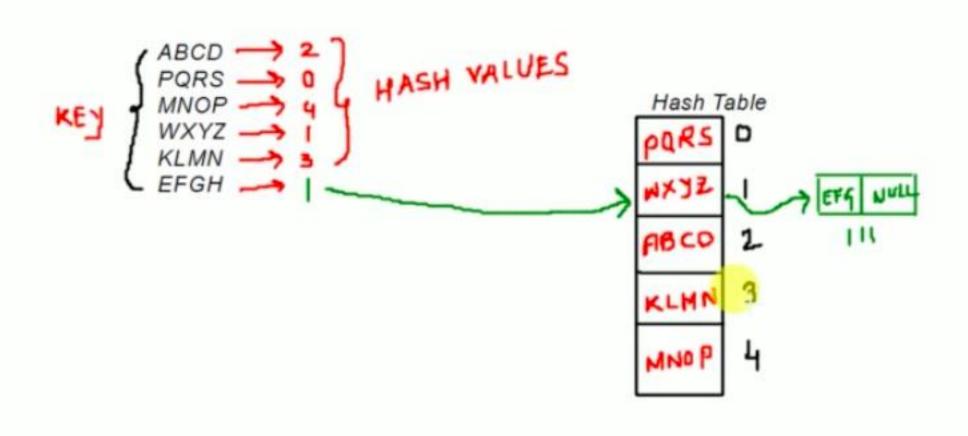
[3×7+1] 7-10 =2 [7+2x0]1/10 (7 +2×17 ·/·10 =9 [7+2×2]-1-10=0) (7+2×3) × 10=3 [7+2×2]~ 10=8 [7+2×5]1.10=7 [7+2×6]"1.10=9 [HX7]1.10=1 (7+2×8).1.10=3

What happens when Hash Table is full?

- Direct Chaining:
 - This situation will never arise.

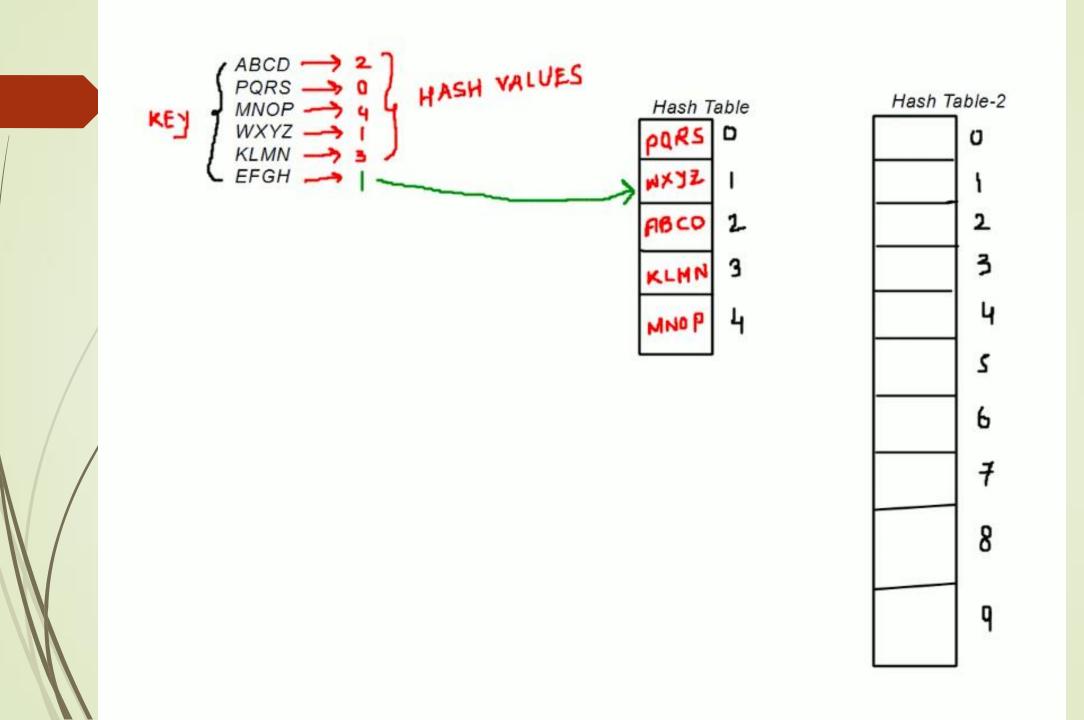


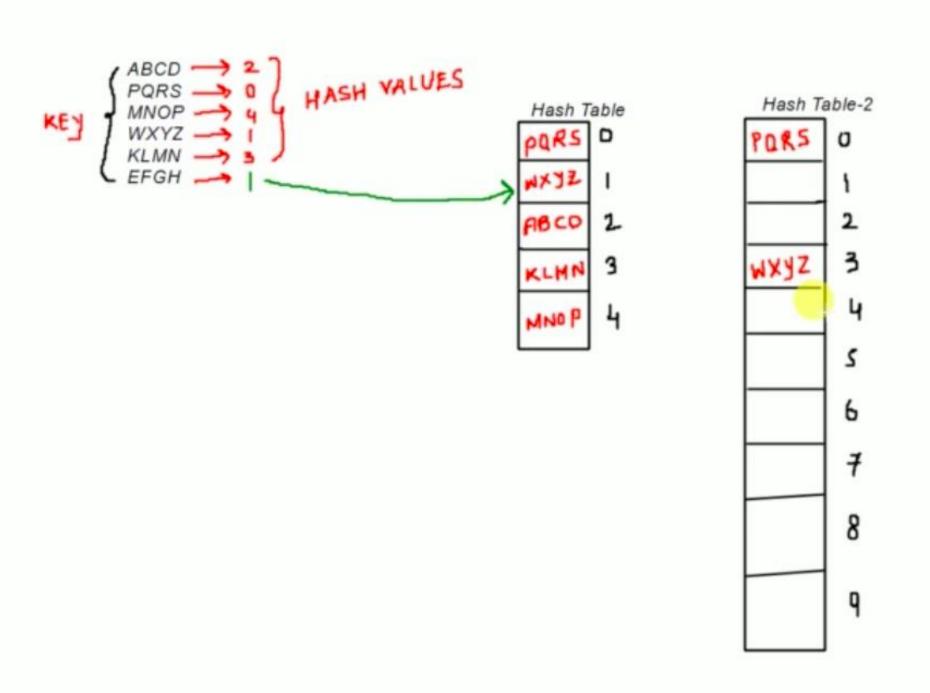




What happens when Hash Table is full?

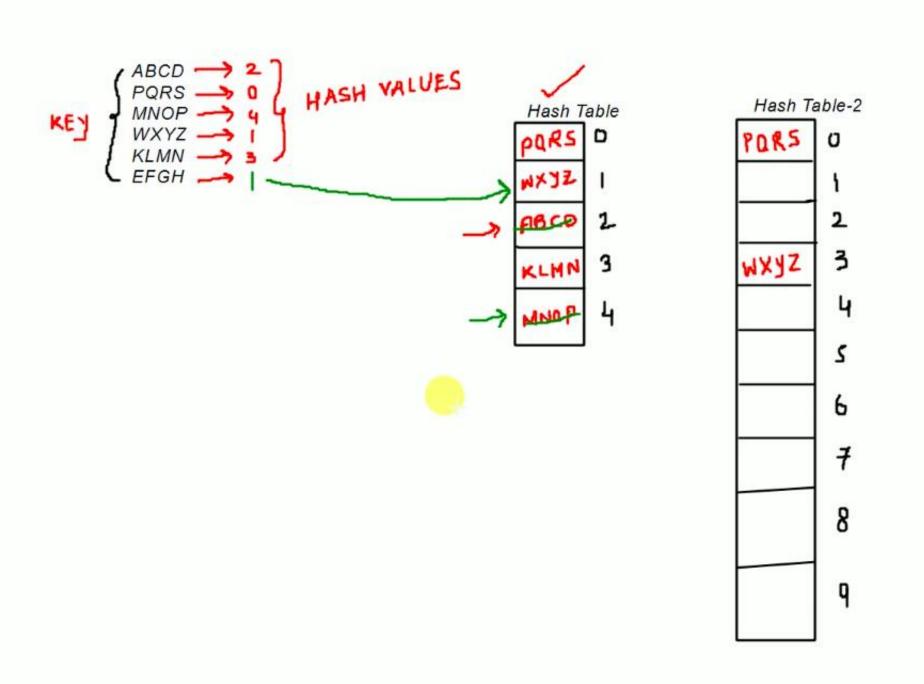
- Direct Chaining:
 - This situation will never arise.
- Open Addressing:
 - Need to create 2X size of current Hash Table and redo Hashing for existing keys.





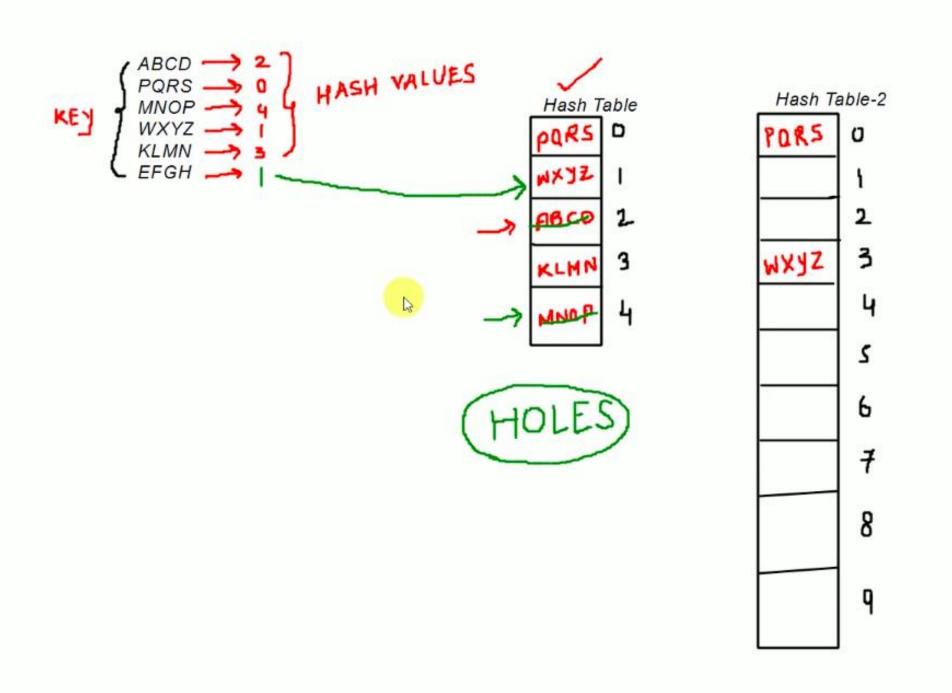
Pros & Cons of Collision Resolution Technique:

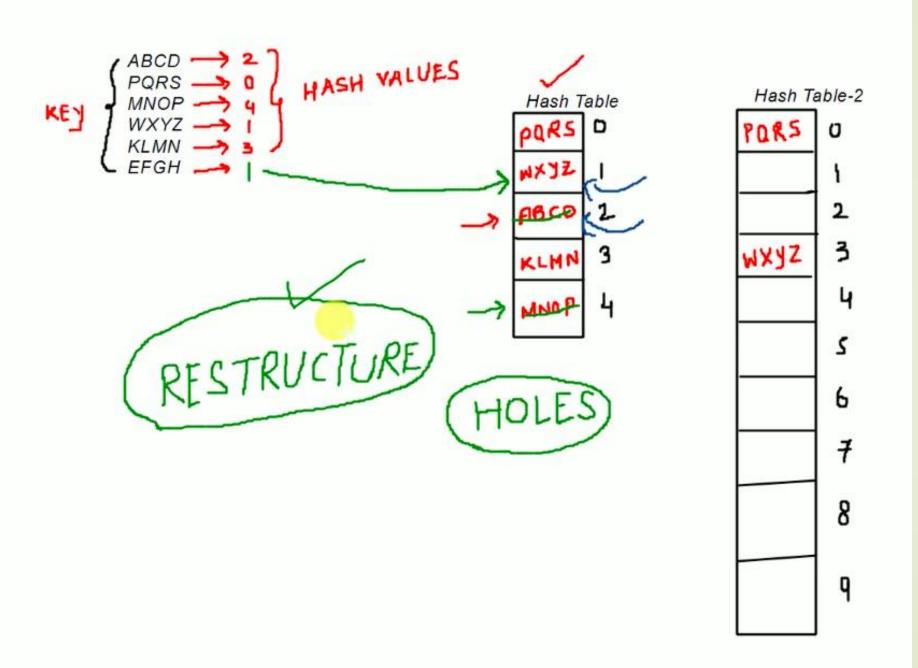
- Direct Chaining:
 - No fear of exhausting Hash Table buckets.
 - Fear of big Linked Lists (can effect performance big time).
- Open Addressing:
 - Easy implementation.
 - Fear of exhausting Hash Table buckets
- If Input size is known then always use "Open Addressing", else can use any of the two.



Pros & Cons of Collision Resolution Technique:

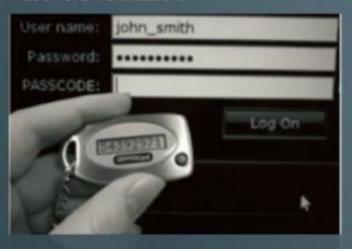
- Direct Chaining:
 - No fear of exhausting Hash Table buckets.
 - Fear of big Linked Lists (can effect performance big time).
- Open Addressing:
 - Easy implementation.
 - Fear of exhausting Hash Table buckets
- If Input size is known then always use "Open Addressing", else can use any of the two.
- If Deletion is very high, then we should always go for 'Direct Chaining'.



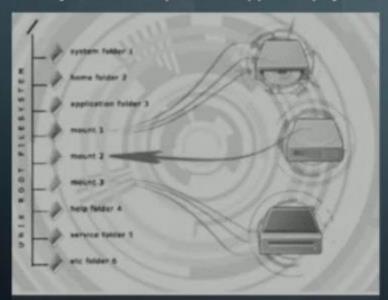


Practical Use of Hashing:

✓ Password Verification:



File Systems : File path is mapped to physical location on disk



FACEBOOK's SERVER



Personal Computer



Username: abc@bla.com

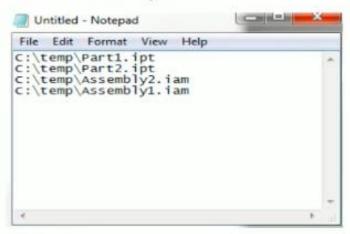
Password: 123456

- 1. Save the password at it is. i.e 123456
- 2. Convert the Key (password) into hash value and save the hash value instead of password. say ruh67#87Fg6yhe@^%!

Hard Disk

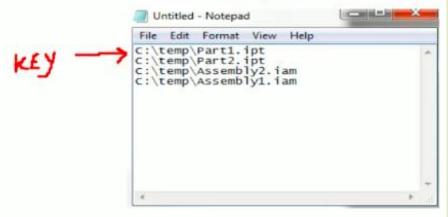


List of Files in temp folder



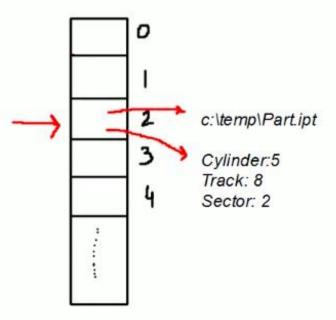


List of Files in temp folder









Pros & Cons of Hashing:

- Pros:
 - On an average Insertion/Deletion/Search operation takes O(1) time.
- Cons:
 - In the worst case Insertion/Deletion/Search might take O(n) time (when hash functions is not good enough).

Hashing vs other DS:

Particulars	Array	Linked List	Tree	Hashing
Insertion	O(n)	O(n)	O(Log n)	O(1) / O(n)
Deletion	O(n)	O(n)	O(Log n)	O(1) / O(n)
Searching	О(п)	O(n)	O(Log n)	O(1) / O(n)

Thank,