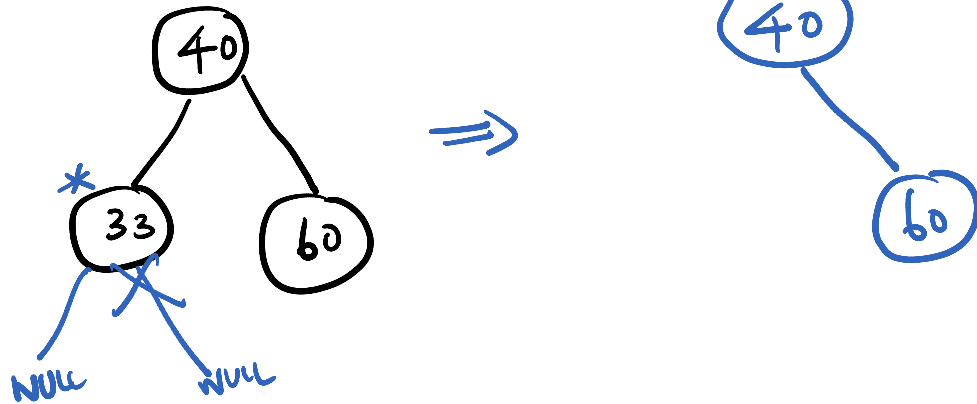


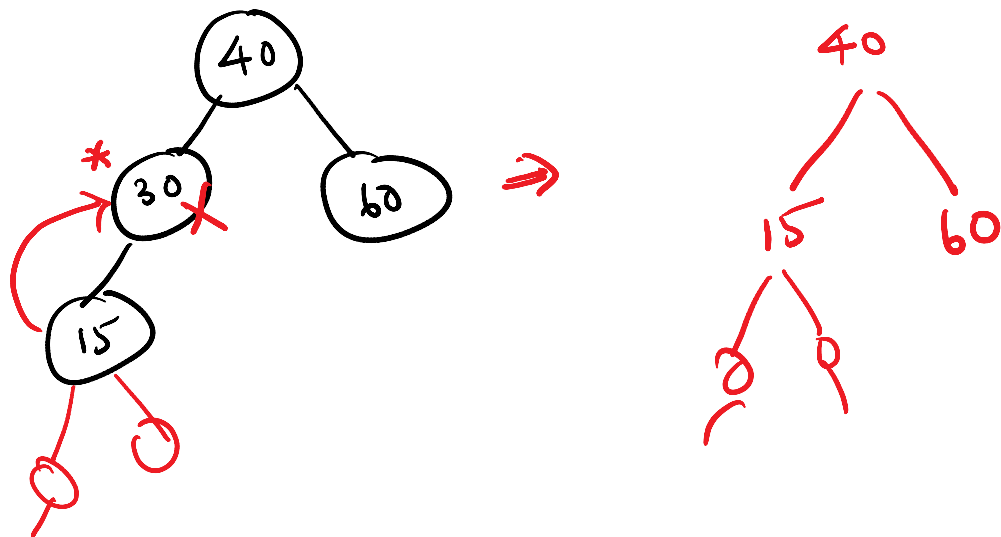
Binary Search Tree

(Deleting node from BST)

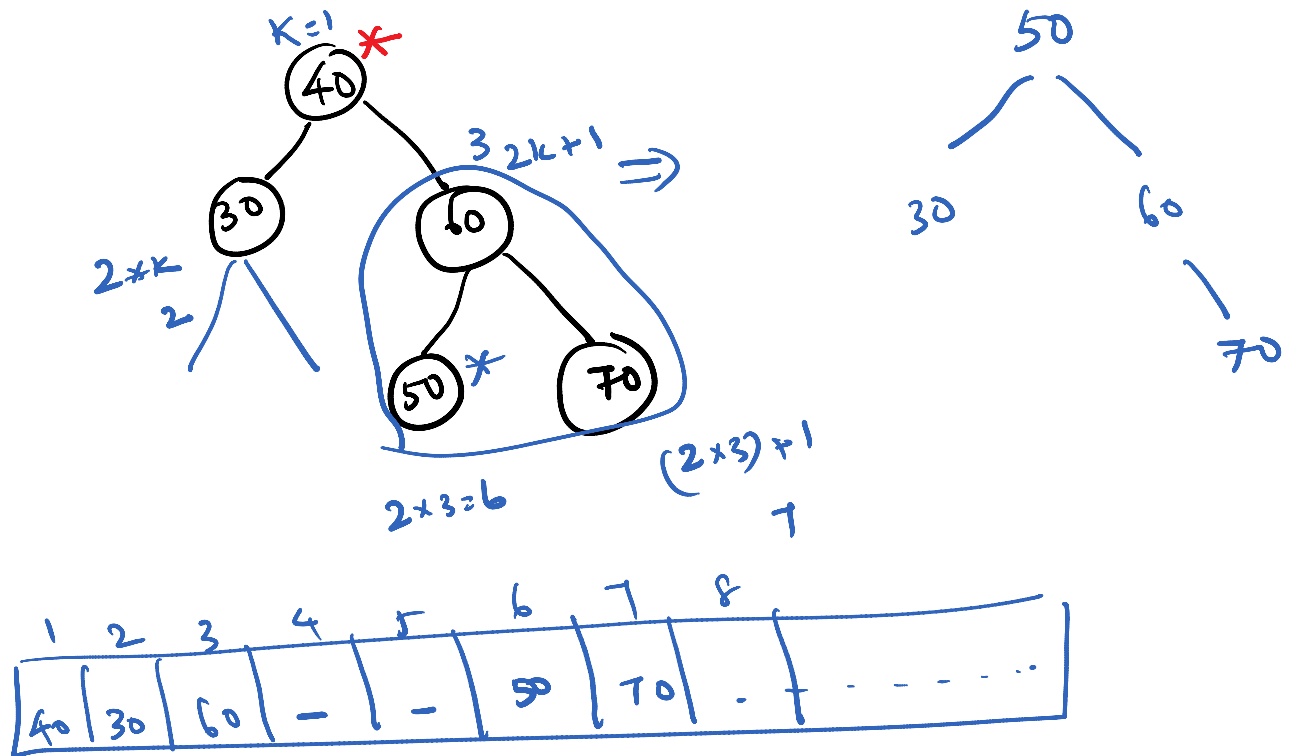
When N has no children



When N has exactly one child



When N has two children



Algorithm to delete a node from binary search tree

1. Algorithm delete(K, r)
2. // K is a node of key to be deleted
3. {
4. if $r \neq \text{null}$
5. if ($K < r.\text{key}$)
6. delete($K, r.\text{left}$)
7. else if ($K > r.\text{key}$)
8. delete($K, r.\text{right}$)
9. else if ($r.\text{right} = \text{null}$) and ($r.\text{left} = \text{null}$)
10. $r = \text{null}$
11. else if ($r.\text{left} = \text{null}$)
12. $r = r.\text{right}$
13. else if ($r.\text{right} = \text{null}$)
14. $r = r.\text{left}$
15. else

```
16.     r.key = deletemin (r.rightchild)
17. }
```

Tree Traversal

Traversal is applicable only of binary tree. It involves examining every node in the given data

Techniques

Pre-Order Traversal (DLR)

In-Order Traversal (LDR)

Post-Order Traversal (LRD)

D L R — Pre
L D R — In
L R D — Post

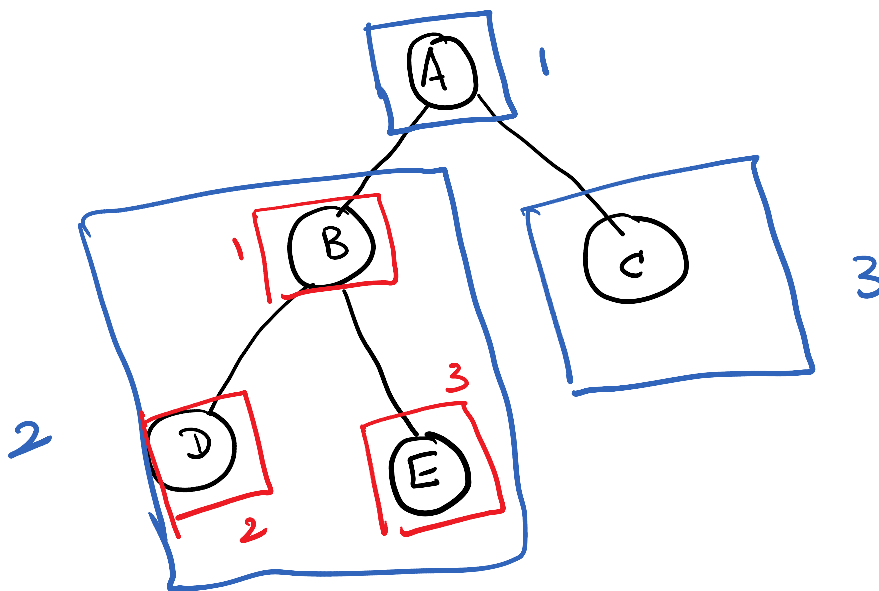
D- Process the root node ✓

L – Process Left subtree ✓

R – Process Right subtree ✓

PREORDER TRAVERSAL

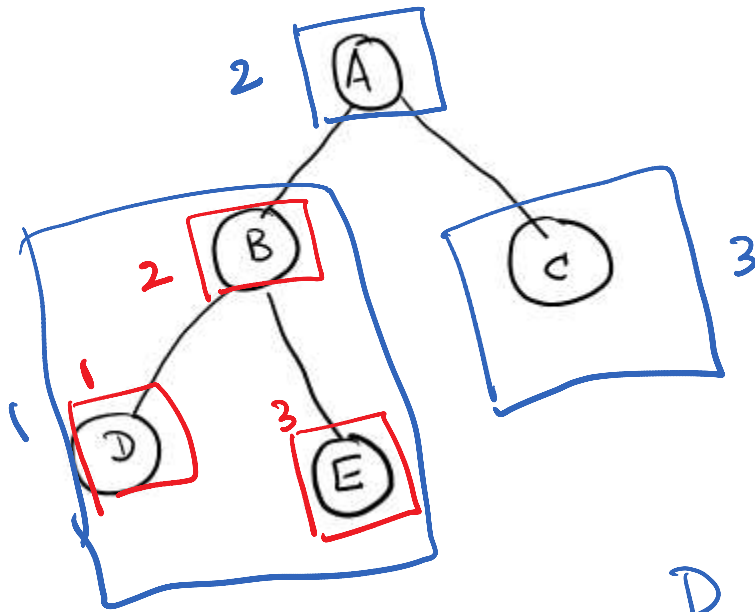
D L R



A B D E C

INORDER TRAVERSAL

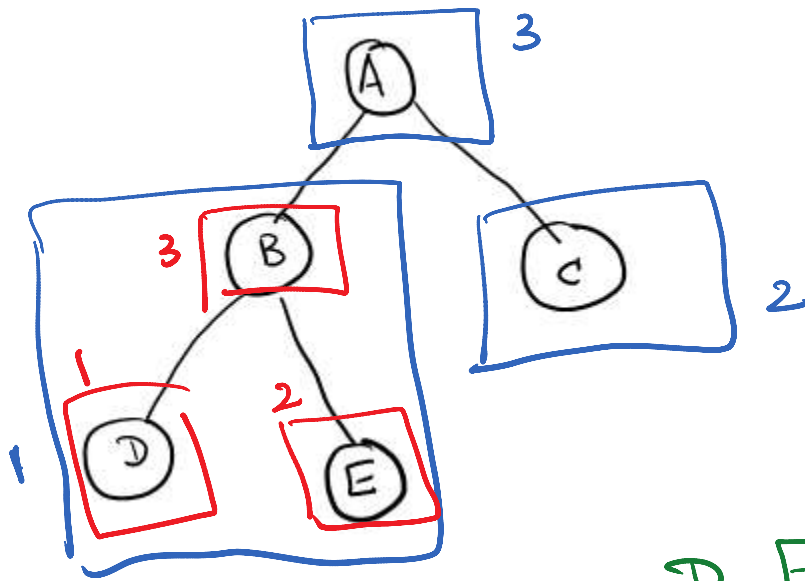
✓
L D R ✓



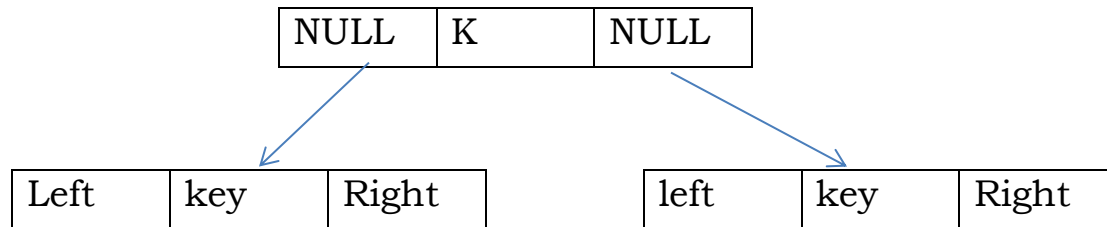
D B E A C

POSTORDER TRAVERSAL

✓ L ✓ R ✓ D ✓



D E B C A



Algorithm to search node in BST

Algorithm Search(K,r)

{ // K – node to be searched, r is a pointer

if (r=NULL)

 return(false) // no node in the tree

else if (K=r.key)

 return (true) // node found in the tree

else if (K<r.key)

 Search(K, r.left) // 'k' may in left subtree

else if (K>r.key)

 Search(K, r.right) // 'k' may in right subtree

}

Algorithm to insert a node in a BST

Algorithm INSERT(K,r)

```
{
if (r=null)
    new(r)
    r.key = K
    r.left = null
    r.right=null
}
else if (K<r.key)
    INSERT(K, r.left)
else if (K>r.key)
    INSERT(K, r.right)
else if (K = r.key)
    Print ("Node already present")
}
```