Module 3 CPU Scheduling

Basic Concepts

- In a system with a single CPU core, only one process can run at a time
- Others must wait until the CPU's core is free and can be rescheduled
- The objective of multiprogramming is to have some process running at all times, to maximize CPU utilization
- Several processes are kept in memory at one time.
- When one process has to wait for any I/O, the operating system takes the CPU away from that process and gives the CPU to another process

add store read from file wait for I/O store increment Alternating sequence index write to file of CPU and I/O bursts. wait for I/O load store add store read from file wait for I/O

load store

CPU burst I/O burst CPU burst · I/O burst CPU burst I/O burst

CPU Scheduler

- Short-term scheduler selects from among the processes in ready queue, and allocates the CPU to one of them
 - Queue may be ordered in various ways
- CPU scheduling decisions may take place when a process:
 - 1. Switches from running to waiting state
 - 2. Switches from running to ready state
 - 3. Switches from waiting to ready
 - 4. Terminates
- Scheduling under 1 and 4 is non-preemptive
- All other scheduling is preemptive

Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
 - switching context
 - switching to user mode
 - jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running

Scheduling Criteria

- CPU utilization keep the CPU as busy as possible
- **Throughput** number of processes that complete their execution per time unit
- Turnaround time amount of time to execute a particular process
- Waiting time amount of time a process has been waiting in the ready queue
- **Response time** amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)

Scheduling Algorithm Optimization Criteria

- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time

First-Come, First-Served (FCFS) Scheduling

$$\begin{array}{ccc} \underline{Process} & \underline{Burst\ Time} \\ P_{1} & 24 \\ P_{2} & 3 \\ P_{3} & 3 \end{array}$$

• Suppose that the processes arrive in the order: P_1 , P_2 , P_3 . The Gantt Chart for the schedule is:

	P_1		P ₂	P ₃	
0		24		7 3	0

- Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
- Average waiting time: (0 + 24 + 27)/3 = 17

FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order:

$$P_{2}$$
, P_{3} , P_{1}

• The Gantt chart for the schedule is:



- Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
- Average waiting time: (6 + o + 3)/3 = 3
- Much better than previous case
- Convoy effect short process behind long process
 - Consider one CPU-bound and many I/O-bound processes

Shortest-Job-First (SJF) Scheduling

- Associate with each process the length of its next CPU burst
 - Use these lengths to schedule the process with the shortest time
- SJF is optimal gives minimum average waiting time for a given set of processes
- The difficulty is knowing the length of the next CPU request

Example of SJF

<u>Process</u>	Burst Time
$P_{_{I}}$	6
$P_{_2}$	8
$P_{_{3}}$	7
$P_{_4}$	3

SJF scheduling chart

	P ₄	P ₁	P ₃	P ₂
0	3	9	16	5 24

• Average waiting time = (3 + 16 + 9 + 0) / 4 = 7

Example of Shortest-remaining-timefirst

 Now we add the concepts of varying arrival times and preemption to the analysis

<u>Process</u>	<u>Arrival Time</u>	Burst Time
$P_{_{I}}$	O	8
$P_{_2}$	1	4
$P_{_{3}}$	2	9
$P_{_4}$	3	5

Preemptive SJF Gantt Chart



• Average waiting time = [(10-1)+(1-1)+(17-2)+5-3)]/4 = 26/4 = 6.5 msec

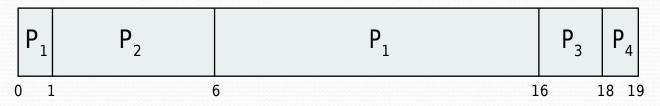
Priority Scheduling

- A priority number (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer = highest priority)
 - Preemptive
 - Nonpreemptive
- SJF is priority scheduling where priority is the inverse of predicted next CPU burst time
- Problem = Starvation low priority processes may never execute
- Solution ≡ Aging as time progresses increase the priority of the process

Example of Priority Scheduling

	<u>Process</u>	Burst Time	Priority
$P_{_{1}}$	10	3	
P_{2}	1	1	
P_{3}	2	4	
$P_{_4}$	1	5	
P_{5}	5	2	

Priority scheduling Gantt Chart



• Average waiting time = 8.2 msec

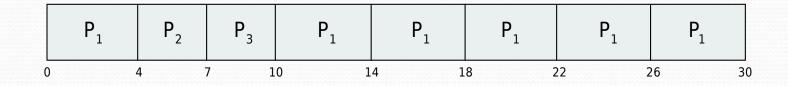
Round Robin (RR)

- Each process gets a small unit of CPU time (time quantum q), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are *n* processes in the ready queue and the time quantum is *q*, then each process gets 1/*n* of the CPU time in chunks of at most *q* time units at once. No process waits more than (*n*-1)*q* time units.
- Timer interrupts every quantum to schedule next process
- Performance
 - $q \text{ large} \Rightarrow \text{FIFO}$
 - q small $\Rightarrow q$ must be large with respect to context switch, otherwise overhead is too high

Example of RR with Time Quantum = 4

 $\begin{array}{ccc} \underline{Process} & \underline{Burst\ Time} \\ P_{_{1}} & \underline{24} \\ P_{_{2}} & \underline{3} \\ P_{_{3}} & \underline{3} \end{array}$

• The Gantt chart is:

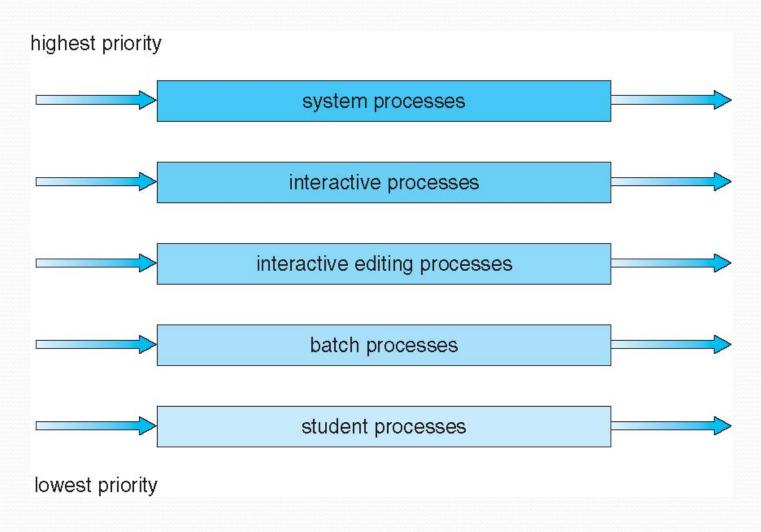


- Typically, higher average turnaround than SJF, but better *response*
- q should be large compared to context switch time

Multilevel Queue

- Ready queue is partitioned into separate queues, eg:
 - **foreground** (interactive)
 - background (batch)
- Each queue has its own scheduling algorithm:
 - foreground RR
 - background FCFS
- Scheduling must be done between the queues:
 - Fixed priority scheduling; (i.e., serve all from foreground then from background). Possibility of starvation
 - Time slice each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR and 20% to background in FCFS

Multilevel Queue Scheduling

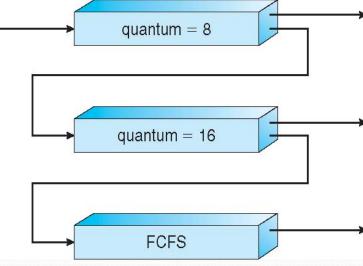


Multilevel Feedback Queue

- A process can move between the various queues; aging can be implemented this way
- Multilevel-feedback-queue scheduler defined by the following parameters:
 - number of queues
 - scheduling algorithms for each queue
 - method used to determine when to upgrade a process
 - method used to determine when to demote a process
 - method used to determine which queue a process will enter when that process needs service

Example of Multilevel Feedback Queue

- Three queues:
 - Q_0 RR with time quantum 8 milliseconds
 - Q_1 RR with time quantum 16 milliseconds
 - *Q*, FCFS
- Scheduling
 - A new job enters queue Q_o which is served FCFS
 - When it gains CPU, job receives 8 milliseconds
 - If it does not finish in 8 milliseconds, job is moved to queue Q_1
 - At Q_1 job is again served FCFS and receives 16 additional milliseconds
 - If it still does not complete, it is preempted and moved to queue Q₂



Any queries?