

Norm of a vector

Norm: It is the magnitude/ length of a vector.

If \vec{x} is a vector such that $\vec{x} = \{x_1, x_2, \dots, x_n\}$, then

The L2 norm of a vector is $\|\vec{x}\| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$ (Distance from origin)

Properties of Norm:

1. $\|\vec{x}\| \geq 0$
2. $\|\vec{x}\| = 0$ iff $\vec{x} = \vec{0}$
3. $\|t\vec{x}\| = |t|\|\vec{x}\|$, where t is a scalar.
4. $\|x + y\| \leq \|x\| + \|y\|$, triangular inequality

Unit Vector:

\vec{V} is said to be an unit vector if $\|\vec{V}\| = 1$

L2 Norm:

Q. If $\vec{V} = (-5, 3, 9)$, find the norm of the vector.

Answer: $\|\vec{V}\| = \sqrt{(-5)^2 + (3)^2 + (9)^2} = \sqrt{115}$

Euclidean Distance: Distance between two vectors.

$$\|\vec{x} - \vec{y}\| = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2 + \dots + (x_n - y_n)^2}$$

Q. If $\vec{V1} = (0, 3, 9)$ and $\vec{V2} = (-5, 0, 0)$ find the Euclidean Distance between the two vectors.

$$\|\vec{V1} - \vec{V2}\| = \sqrt{(0 - (-5))^2 + (3 - 0)^2 + \dots + (9 - 0)^2} = \sqrt{115}$$

Norm of a Signal

Properties of Norm:

1. $\|\vec{x}\| \geq \phi$
2. $\|\vec{x}\| = \phi$ iff $x(t) = \phi \quad \forall t$
3. $\|\alpha\vec{x}\| = |\alpha|\|\vec{x}\|$, where α is a scalar.
4. $\|u_1 + u_2\| \leq \|u_1\| + \|u_2\|$, triangular inequality

L1 Norm:

$$\|u\|_1 = \int_{-\infty}^{\infty} |u(t)| dt$$

L2 Norm:

$$\|u\|_2 = \sqrt{\int_{-\infty}^{\infty} (u(t))^2 dt}$$

Used in calculation of power and energy.

Euclidean Distance between two signals:

$$\|u_1(t) - u_2(t)\|^2 = \int_0^T (u_1(t) - u_2(t))^2 dt$$

Moment of a Signal

1st order moment:

$$E[t] = \int_{-\infty}^{\infty} tu(t) dt$$

2nd order moment:

$$E[t^2] = \int_{-\infty}^{\infty} t^2 u(t) dt$$

Linearly Dependent and Linearly Independent Vectors

Linearly Independent:

The vectors v_1, v_2, \dots, v_p are linearly independent, if

$$a_1V_1 + a_2V_2 + \dots + a_pV_p = 0, \text{ for } a_1=a_2=\dots=a_p=0$$

That is you cannot find the linear combination of vectors.

Linearly Dependent:

The vectors v_1, v_2, \dots, v_p are linearly dependent, if

$$a_1V_1 + a_2V_2 + \dots + a_pV_p = 0, \text{ for } a_1=a_2=\dots=a_p \neq 0$$

That is you can find the linear combination of vectors.

Q. $V_1 = [1 \ 2 \ 3]$, $V_2 = [2 \ -1 \ 4]$, $v_3 = [0 \ 5 \ 2]$ is linearly independent or not?

Answer:

$$a_1V_1 + a_2V_2 + \dots + a_pV_p = 0$$

$$\begin{bmatrix} 1 & 2 & 0 \\ 2 & -1 & 5 \\ 3 & 4 & 2 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = 0$$

$$a_1 = -2a_3$$

$$a_2 = a_3$$

$2V_1 + V_2 + V_3 = 0$, so V_1, V_2 and V_3 are linearly dependent.

Module 2:

Continuous Time and Discrete Time System

Classification of Systems:

- I. Linear and Non-Linear System
- II. Time Variant and Time invariant System
- III. Linear Time variant (LTV) and Linear time invariant System (LTI)
- IV. Static and Dynamic System
- V. Causal and Non-Causal system
- VI. Invertible and non-invertible System
- VII. Stable or Unstable systems

Linear and Non-Linear System

A system is said to be **linear** if it satisfies the **superposition** principle.

Consider a system with input $x_1(t)$ and $x_2(t)$ and output $y_1(t)$ and $y_2(t)$.

For linearity:

$$T[a_1x_1(t) + a_2x_2(t)] = a_1T[x_1] + a_2T[x_2]$$

Q. Find a system $y(t) = x^2(t)$ is linear or non-linear.

Ans:

$$T[x_1(t)] = x_1^2(t)$$

$$T[x_2(t)] = x_2^2(t)$$

$$T[a_1x_1(t) + a_2x_2(t)] = [a_1x_1(t) + a_2x_2(t)]^2 = (a_1x_1(t))^2 + (a_2x_2(t))^2 + 2a_1x_1(t)a_2x_2(t)$$

$[a_1x_1(t) + a_2x_2(t)] \neq a_1T[x_1] + a_2T[x_2]$, so it's violating **superposition** principle. So it's a **Non-Linear system**.

Q. Find a system $y(t) = x(t)$ is linear or non-linear.

Ans:

$$T[x_1(t)] = x_1(t)$$

$$T[x_2(t)] = x_2(t)$$

$$T[a_1x_1(t) + a_2x_2(t)] = a_1x_1(t) + a_2x_2(t)$$

$T[a_1x_1(t) + a_2x_2(t)] = a_1T[x_1] + a_2T[x_2]$, so it satisfies **superposition** principle. So it's a **Linear system**.

Time Variant and Time invariant System

A system is said to be time variant if its input/ output characteristic changes with time otherwise the system is time invariant.

The condition for time invariance is:

For discrete time:

$$y(n, k) = y(n - k), \text{ where } y(n, k) = T[x(n - k)]$$

For continuous Time:

$$y(t, k) = y(t - k), \text{ where } y(t, k) = T[x(t - k)]$$

Ex 1: $y(n) = x(n) + x(n - 2)$, find if the system is time variant or Time variant.

$$y(n, k) = T[x(n - k)] = x(n - k) + x(n - 2 - k) \quad (\text{Delay the input and get the result})$$

$$y(n - k) = x(n - k) + x(n - k - 2)$$

$$y(n, k) = y(n - k), \text{ So it is a time invariant system.}$$