Laplace Transform

Limitations of Fourier Transform

- The FT can be used to analyse the stable system
- It cannot analyse the unstable system
- It is used to transform a time domain signal into frequency domain.

Laplace transform is used to overcome these limitations. Laplace transform is used to analyse both stable and unstable systems.

Advantages of Laplace Transform:

- It is used to analyse both stable and unstable systems in continuous time domain.
- It is used to transform a time domain signal to complex frequency domain i.e s-domain.
- It is used easier to analyse the system in s-domain.

Laplace Transform:

LT of continuous time signal x(t) is defined as,

$$L\{x(t)\} = X\{s\} = \int_{-\infty}^{\infty} x(t)e^{-st}dt$$

Where $s = \sigma + j\omega$

It exists even for non-absolutely integrable signal. It exists neither for energy nor power signals.

In $s = \sigma + j\omega$, σ is the damping factor and it provides information about stability, and ω is angular frequency, unit rad/sec.

s is a complex variable.

Bilateral Laplace Transform:

 $L\{x(t)\} = X\{s\} = \int_{-\infty}^{\infty} x(t)e^{-st}dt$ is known as bilateral Laplace Transform as the range of integration is from $[-\infty, \infty]$.

 $L\{x(t)\} = X\{s\} = \int_0^\infty x(t)e^{-st}dt$ is known as unilateral Laplace Transform as the range of integration is from $[0,\infty]$.

RoC:

RoC (Region of Convergence) is the region of S plane (σ vs $j\omega$). It represents the area in which LT is finite and outside RoC the LT is infinite.

Inverse Laplace Transform:

$$x(t) = \frac{1}{2\pi j} \int_{\sigma - i\omega}^{\sigma + j\omega} X(s) e^{st} ds$$

Relation between LT and FT:

Let X(s) is the LT of x(t).

Then,

$$X(s) = \int_{-\infty}^{\infty} x(t)e^{-\sigma t}e^{-j\omega t}dt$$

$$X(s) = FT\{x(t).e^{-\sigma t}\}\$$

When $\sigma = 0$,

$$X(s) = FT\{x(t)\} = X(\omega)$$
, where $X(\omega)$ is the FT of $x(t)$ if $s = j\omega$.

This condition satisfies only when the given signal x(t) is absolutely integrable.

Condition for existence of Laplace Transform:

$$X(s) = \int_{-\infty}^{\infty} x(t)e^{-\sigma t}e^{-j\omega t}dt$$

Let
$$x(t)e^{-j\omega t} = x_1(t)$$

$$X(s) = \int_{-\infty}^{\infty} x_1(t)e^{-\sigma t}dt$$

For X(s) to exist, $x_1(t)$ should be absolutely integrable. i.e.

$$\int_{-\infty}^{\infty} |x_1(t)| dt < \infty \Rightarrow \int_{-\infty}^{\infty} |x(t)e^{-\sigma t}| dt < \infty$$

The range of σ for which $\int_{-\infty}^{\infty} |x(t)e^{-\sigma t}| dt < \infty$ satisfies is known as RoC or Region of Convergence.

Q. Find the region of convergence or RoC of signal $x(t) = e^{2t}u(t)$

Answer:

$$x(t) = e^{2t}u(t)$$

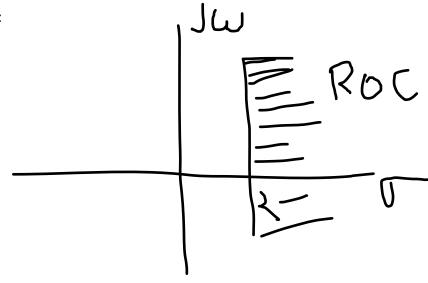
$$\int_{-\infty}^{\infty} |x(t)e^{-\sigma t}|dt = \int_{-\infty}^{\infty} |e^{2t}u(t)e^{-\sigma t}|dt = \int_{0}^{\infty} |e^{2t}e^{-\sigma t}|dt$$

 $\Rightarrow \int_0^\infty \left| e^{(2-\sigma)t} \right| dt$ should be less than ∞

$$\int_0^\infty \left| e^{(2-\sigma)t} \right| dt < \infty \text{ if } (2-\sigma) < 0$$

$$\Rightarrow \sigma > 2$$

RoC:



Poles and zeroes:

Zeros: Zeros of a LT are the values of s for which the numerator of the LT becomes zero.

Poles: Poles of a LT are the values of s for which the denominator of the LT becomes zero.

Ex:

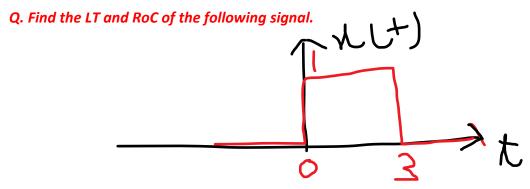
$$X(s) = \frac{s+2}{(s+3)(s+4)}$$

It has one zero at s=-2 and two poles at s=-3 and s=-4.

Properties of RoC:

- 1. RoC does not include any poles.
- 2. For right sided signal, RoC is right side to the right most pole.
- 3. For left sided signal, RoC is left side to the left most pole.

- 4. For the absolute integrability of a signal or the stability of a system, RoC should include imaginary axis.
- 5. For both sided signals, RoC is a strip in the s-plane.
- 6. For finite duration signals, RoC is the entire s plane excluding s=0 or $+\infty$ or $-\infty$



Answer:

$$X(s) = \int_{-\infty}^{\infty} x(t)e^{-st}dt = \int_{0}^{3} 1 \cdot e^{-st}dt = \frac{1}{-s} |e^{-st}|_{0}^{3} = \frac{e^{-3s} - 1}{-s} = \frac{1 - e^{-3s}}{s}$$

RoC:

For finite duration signal, RoC is the entire s-plane except 0 or $+\infty$ or $-\infty$

Case 1: at zero

$$X(0) = \frac{1 - e^0}{0} = \frac{0}{0}$$

L'hopital's Rule:

If
$$\lim_{x \to \infty} \frac{f(x)}{g(x)} = \frac{0}{0}$$
 or $\lim_{x \to \infty} \frac{f(x)}{g(x)} = \frac{\infty}{\infty}$, then $\lim_{x \to \infty} \frac{f'(x)}{g'(x)}$

$$X(0) = \frac{3e^{-3s}}{1} = 3$$
 finite, so s=0 present in RoC.

 $X(+\infty)=0$ finite, so $s=+\infty$ present in RoC.

$$X(-\infty) = \frac{\infty}{\infty}$$
, use L'hopital's Rule

$$X(-\infty) = \frac{3e^{-3s}}{1} = \infty$$
 which is not finite, so s=-\infty not present in RoC.

The RoC is entire s plane exluding $s=-\infty$.

Properties of LT:

Check the extra file uploaded in teams named Laplace and z transform table.pdf.

Initial Value Theorem:

$$\chi(t) \leftrightarrow \chi(s)$$

Then at initial value $x(0^+) = \lim_{s \to \infty} sX(s)$

It is applicable when the following conditions are satisfied.

- 1. Applicable only when x(t) = 0, t < 0
- 2. x(t) must not contain impulse or higher order singularities at t=0.

Q. Determine the initial values of x(t) whose X(s) is

$$X(s) = \frac{7s+10}{s(s+2)}$$

Answer:

Initial Value theorem states that,

$$x(t) \leftrightarrow X(s)$$

Then at initial value $x(0^+) = \lim_{s \to \infty} sX(s)$

$$x(0^+) = \lim_{s \to \infty} s[\frac{7s + 10}{s(s + 2)}]$$

$$x(0^+) = \lim_{s \to \infty} \left[\frac{7s + 10}{(s + 2)} \right] = \frac{7}{1}$$

Final Value Theorem:

$$x(t) \leftrightarrow X(s)$$

Then at initial value $x(\infty) = \lim_{s \to 0} sX(s)$

It is applicable when the following conditions are satisfied.

1. Applicable only when x(t) = 0, t < 0

2. sX(s) must have poles in the left half of the s-plane

Q. Determine the final values of x(t) whose X(s) is

$$X(s) = \frac{7s+10}{s(s+2)}$$

Answer:

$$x(\infty) = \lim_{s \to 0} sX(s)$$

$$\chi(\infty) = \lim_{s \to 0} s \left[\frac{7s + 10}{s(s + 2)} \right]$$

$$x(\infty) = \lim_{s \to 0} \left[\frac{7s + 10}{(s + 2)} \right] = \frac{10}{2} = 5$$

Inverse Laplace Transform:

Q. Find x(t).

$$X(s) = \frac{10(s+4)}{s^2(s+2)}$$

Answer:

Using Partial fractions,

$$X(s) = \frac{10(s+4)}{s^2(s+2)} = \frac{A}{s^2} + \frac{B}{s} + \frac{c}{s+2}$$

$$\frac{10(s+4)}{s^2(s+2)} = \frac{A(s+2)}{s^2} + \frac{Bs(s+2)}{s} + \frac{cs^2}{s+2}$$

$$=> 10(s+4) = A(s+2) + Bs(s+2) + cs^2$$

When s = 0,

$$10(0+4) = A(0+2)$$

A=20

When s = -2,

$$10(-2+4) = c(-2)^2$$

C=5

By applying the value of A and C, We will get B=-5

$$X(s) = \frac{10(s+4)}{s^2(s+2)} = \frac{A}{s^2} + \frac{B}{s} + \frac{c}{s+2} = \frac{20}{s^2} + \frac{-5}{s} + \frac{5}{s+2}$$

$$x(t) = 20t - 5u(t) + 5e^{-2t}$$

Laplace Transform to solve Differential equations:

Q. Use Laplace Transform to Solve Differential Equations

$$y'' - y = e^{2t}$$
, $y(0) = 0$, $y'(0) = 1$

Solution:

$$y(t) \leftrightarrow Y(s)$$

$$y'(t) \leftrightarrow sY(s) - y(0)$$

$$y''(t) \leftrightarrow s(sY(s) - y(0)) - y'(0)$$

$$L\{e^{2t}\} = \frac{1}{s-2}$$

$$s^{2}Y(s) - sy(0) - y'(0) - Y(s) = \frac{1}{s - 2}$$

$$s^{2}Y(s) - 1 - Y(s) = \frac{1}{s - 2}$$

$$Y(s)(s^2 - 1) = 1 + \frac{1}{s - 2} = \frac{s - 2 + 1}{s - 2} = \frac{s - 1}{s - 2}$$

$$Y(s) = \frac{s-1}{(s-2)(s+1)(s-1)} = \frac{1}{(s-2)(s+1)}$$

$$Y(s) = \frac{1}{(s-2)(s+1)}$$

Find Inverse LT to get y(t).

Using Partial fractions,

$$Y(s) = \frac{1}{(s-2)(s+1)} = \frac{A}{s-2} + \frac{B}{s+1}$$

$$\frac{1}{(s-2)(s+1)} = \frac{A(s+1)}{s-2} + \frac{B(s-2)}{s+1}$$

$$1 = A(s+1) + B(s-2)$$

Putting s=-1,

$$B = -\frac{1}{3}$$

Putting s=-2,

$$A = \frac{1}{3}$$

$$Y(s) = \frac{A}{s-2} + \frac{B}{s+1} = \frac{1}{3(s-2)} - \frac{1}{3(s+1)}$$

$$y(t) = \frac{1}{3}(e^{2t} - e^{-t})$$

Z Transform:

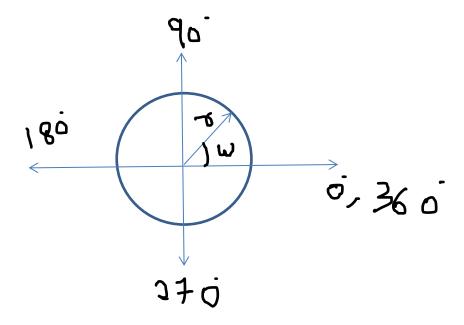
For Discrete time signals we can find the z-transform.

$$\chi[n] \leftrightarrow \chi[z]$$

$$X[z] = \sum_{n = -\infty}^{\infty} x[n] z^{-n}$$

Where z is a complex variable and its polar form is $z=re^{j\omega}$

Where r is the magnitude of z i.e |z| and ω is the complex value or angle.



Bi-directional Z-transform:

$$X[z] = \sum\nolimits_{n = -\infty}^{\infty} x[n]z^{-n}$$

Unidirectional z-Transform:

$$X[z] = \sum_{0}^{\infty} x[n]z^{-n}$$

Problem: $x[n] = a^n u(n)$. Find the Z transform and RoC.

Answer:

$$X[z] = \sum_{n=-\infty}^{\infty} a^n u(n) \ z^{-n} = \sum_{n=0}^{\infty} a^n \ z^{-n} = \sum_{n=0}^{\infty} (az^{-1})^n = \frac{1}{1-az^{-1}}$$
 when $|az^{-1}| < 1$ by using GP

$$\left|\frac{a}{z}\right| < 1$$

$$r = |z| > a$$

Z Transform to solve Differential equations:

$$Z(y(n)) = Y(z)$$

$$Z(y(n+1)) = z(Y(z) - y(0))$$

$$Z(y(n+2)) = z^{2}(Y(z) - y(0) - y(1)z^{-1})$$

$$Z(y(n-1)) = z^{-1}Y(z) - y(-1)$$

$$Z(y(n-2)) = z^{-2}Y(z) + z^{-1}y(-1) + y(-2)$$

Q. Z Transform to Solve Differential Equations

$$y(n+2) + 4y(n+1) + 3y(n) = 2^n$$
, $y(0) = 0$ and $y(1) = 1$

Solution:

$$y(n + 2) + 4y(n + 1) + 3y(n) = 2^n$$

$$Z(y(n+2) + 4y(n+1) + 3y(n)) = Z(2^n)$$

$$Z(y(n+2)) + 4Z(y(n+1)) + 3Z(y(n)) = \frac{z}{z-2}$$

$$z^{2}(Y(z) - y(0) - y(1)z^{-1}) + 4z(Y(z) - y(0)) + 3Y(z) = \frac{z}{z-2}$$

$$z^{2}(Y(z) - y(1)z^{-1}) + 4z(Y(z)) + 3Y(z) = \frac{z}{z-2}$$

$$z^{2}Y(z) - z + 4z Y(z) + 3Y(z) = \frac{z}{z - 2}$$

$$Y(z)(z^2 + 4z + 3) - z = \frac{z}{z - 2}$$

$$Y(z) = \frac{z^2 - z}{(z - 2)(z + 1)(z + 3)}$$

Q. Find the Impulse response H(z) for the given system

$$y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n)$$

Solution:

$$y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n)$$

$$Z(y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2)) = Z(x(n))$$

As initial conditions are not given, assume y(0) = 0 and y(-1) = 1

$$Y(z) - \frac{3}{4}z^{-1}Y(z) + \frac{1}{8}z^{-2}Y(z) = X(z)$$

$$Y(z)(1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}) = X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1}{1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}}$$

Q. Find the Impulse response H(z) for the given system

$$y(n) = 3x(n) + y(n-1)$$

Solution:

$$H(z) = \frac{3}{1 - z^{-1}}$$