

## Revision

**Q1. Solve :**  $x[n] = u(n + 4) - u(n - 2)$ , where

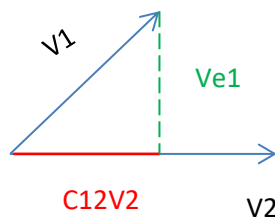
$u[n]$  is



## Analogy between vectors and signals

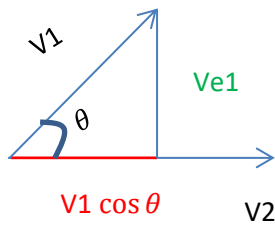
**Vector:** A vector contains magnitude and direction. Eg: Velocity, acceleration, force, electric field etc.

1. Consider two vectors  $V_1$  and  $V_2$ .
2. Vector  $V_1$  can be represented in terms of  $V_2$  in many ways. One of them is by projecting  $V_1$  on  $V_2$ .



$V_1 = C_{12}V_2 + Ve_1$ , where  $Ve_1$  is error vector.

The component of  $V_1$  along  $V_2 = C_{12}V_2$ .



3.  $V_1 \cos \theta = C_{12} V_2$

4. The dot product between two vectors  $V_1$  and  $V_2$  is

$$V_1 \cdot V_2 = |V_1| |V_2| \cos \theta$$

$$\frac{V_1 \cdot V_2}{|V_2|} = |V_1| \cos \theta$$

$$\frac{V_1 \cdot V_2}{|V_2|} = C_{12} V_2$$

$$C_{12} = \frac{V_1 \cdot V_2}{|V_2|^2} = \frac{V_1 \cdot V_2}{V_2 \cdot V_2}$$

$$V_1 = C_{12} V_2$$

$$C_{12} = \frac{V_1 \cdot V_2}{|V_2|^2}$$

If  $C_{12} = 0$ ; then  $V_1 \cdot V_2 = 0$

I.e the vectors  $V_1$  and  $V_2$  are mutually perpendicular to each other. Therefore, there is no component of  $V_1$  along  $V_2$ .

Ex:

$$V_1 = 3i + 3j + 3k$$

$$V_2 = i + j + k$$

$$V_1 = C_{12} V_2$$

$$C_{12} = \frac{V_1 \cdot V_2}{V_2 \cdot V_2} = \frac{3+3+3}{3} = 3$$

## Signals:

1. The dot product between signals V1 and V2 is equivalent to

$$V1.V2 \sim \int_{t_1}^{t_2} f_1(t)f_2(t)dt, \text{ where } f_1(t) \text{ and } f_2(t) \text{ are two signals in the interval } t_1 < t < t_2$$

2.  $f_1(t)$  can be approximated using  $f_2(t)$  as,

$$f_1(t) \approx C_{12}f_2(t); t_1 < t < t_2$$

The error in this approximation is,

$$f_e(t) = f_1(t) - C_{12}f_2(t)$$

3. The mean square error in this approximation is,

$$\varepsilon = \frac{1}{(t_2 - t_1)} \int_{t_1}^{t_2} f_e^2(t) dt$$

$$= \frac{1}{(t_2 - t_1)} \int_{t_1}^{t_2} [f_1(t) - C_{12}f_2(t)]^2 dt$$

$$= \frac{1}{(t_2 - t_1)} \int_{t_1}^{t_2} [f_1(t)^2 + C_{12}^2 f_2(t)^2 - 2C_{12}f_1(t)f_2(t)] dt$$

We want to minimize mean square error,

$f(x) = x^3 - x^2 + 3x + 1$ , we differentiate and equate it to zero.

Similarly, for signal we have to find the value of  $C_{12}$  at which mean square error is minimum by calculating

$$\frac{d\epsilon}{dC_{12}} = 0$$

$$\frac{d \frac{1}{(t_2-t_1)} \int_{t_1}^{t_2} [f_1(t)^2 + C_{12}^2 f_2(t)^2 - 2C_{12} f_1(t) f_2(t)] dt}{dC_{12}} = 0$$

$$\Rightarrow \int_{t_1}^{t_2} [0 + 2C_{12} f_2(t)^2 - 2 f_1(t) f_2(t)] dt = 0$$

$$\Rightarrow C_{12} \int_{t_1}^{t_2} f_2(t)^2 dt = \int_{t_1}^{t_2} f_1(t) f_2(t) dt$$

$$\Rightarrow C_{12} = \frac{\int_{t_1}^{t_2} f_1(t) f_2(t) dt}{\int_{t_1}^{t_2} f_2(t)^2 dt}$$

If  $C_{12} = 0$ ;

Then  $\int_{t_1}^{t_2} f_1(t) f_2(t) dt = 0$ ;

That means, similar to vectors  $f_1(t)$  and  $f_2(t)$  and orthogonal/ perpendicular to each other.

I.e. there is no component of  $f_2(t)$  in  $f_1(t)$ .