# VE CODES

Module-3

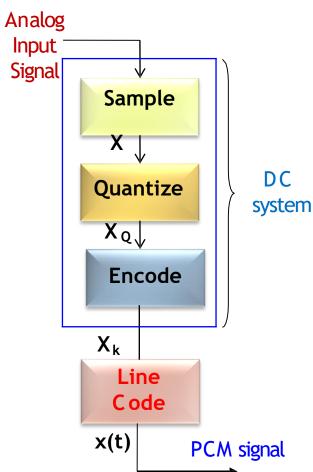
## Topics to be discussed

- Introduction and need for the codes
- Representation of line codes
- Properties and applications of line codes
- Power spectral density of
  - NRZ unipolar,
  - NRZ polar,
  - NRZ bipolar and
  - Manchester Codes

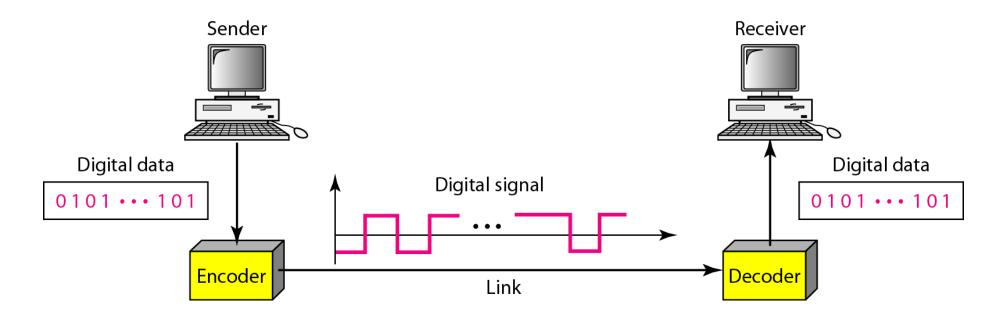
- In this section, we see how we can represent digital data by using digital signals.
- The conversion involves three techniques:
- 1. Line Coding,
- 2. Block Coding and
- 3. Scrambling
- Line coding is always needed.
- Block coding and Scrambling may or may not be needed.

 The output of an Digital Communication System or ADC can be transmitted over a baseband channel.

- The digital information must first be converted into a physical signal.
- The physical signal is called a **line code**.
- Line coders use the terminology
- MARK to mean binary one and
- **SPACE** to mean **binary zero**.



- Converting a string of 1's and 0's (digital data) into a sequence of signals that denote the 1's and 0's.
- For example a high voltage level (+V) could represent a "1" and a low voltage level (0 or -V) could represent a "0".

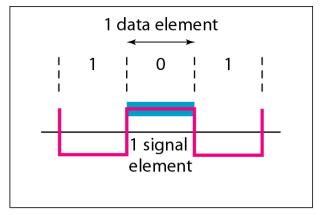


#### **Mapping Data symbols onto Signal levels**

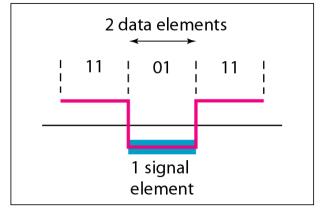
- A data symbol (or element) can consist of a number of data bits:
  - 1,0 or
  - · 11,10,01,... ...
- A data symbol can be coded into a single signal element or multiple signal elements
  - $\mathbf{1} \to + \mathbf{V}$  and  $\mathbf{0} \to -\mathbf{V}$
  - $\mathbf{1} \rightarrow +V \& -V$  and  $\mathbf{0} \rightarrow -V \& +V$
- The **ratio** 'r' is the number of data elements carried by a signal element.

#### Relationship between data rate and signal rate

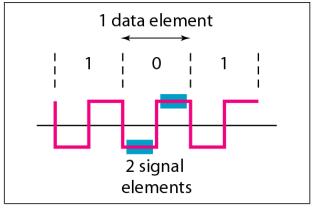
- The data rate defines the number of bits sent per second (bps).
- It is often referred to the bit rate.
- The signal rate is the number of signal elements sent in a second and is measured in **bauds**.
- It is also referred to as the modulation rate.
- Goal is to increase the data rate whilst reducing the baud rate.



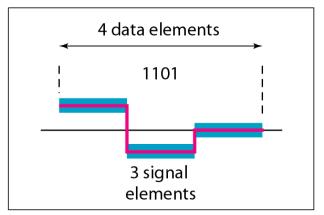
a. One data element per one signal element (r = 1)



c. Two data elements per one signal element (r = 2)



b. One data element per two signal elements  $\left(r = \frac{1}{2}\right)$ 



d. Four data elements per three signal elements  $\left(r = \frac{4}{3}\right)$ 

#### **Data rate and Baud rate**

The baud or signal rate can be expressed as:

$$S = C \times N \times \frac{1}{r} (bauds)$$

- where N is data rate
- C is the case factor (worst, best & avg.)
- r is the ratio between data element & signal element

Although the actual bandwidth of a digital signal is infinite, the effective bandwidth is finite.

#### Numerical

• A signal is carrying data in which one data element is encoded as one signal element (r = 1). If the bit rate is 100 kbps, what is the average value of the baud rate if C is between 0 and 1?

#### **Solution:**

#### Numerical

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#### **Solution:**

• We assume that the average value of C is 1/2. The baud rate is then

$$S = c \times N \times \frac{1}{r} = \frac{1}{2} \times 100,000 \times \frac{1}{1} = 50,000 = 50 \text{ kbaud}$$

- Properties that should be taken in to considerations for choosing a good signal element referred to as line encoding:
- Baseline Wandering
- 2. DC components
- 3. Self Synchronization
- 4. Error Detection
- 5. Noise and Interference
- 6. Complexity

#### **Baseline wandering**

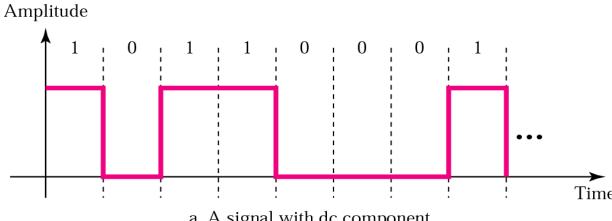
- In decoding a digital signal, the receiver calculates a running average of the received signal power.
- This average is called the baseline.
- The incoming signal power is evaluated against this baseline to determine the value of the data element.
- A long string of 0s or 1s can cause a drift in the baseline (baseline wandering) and make it difficult for the receiver to decode correctly.
- A good line coding scheme needs to prevent baseline wandering.

#### DC component

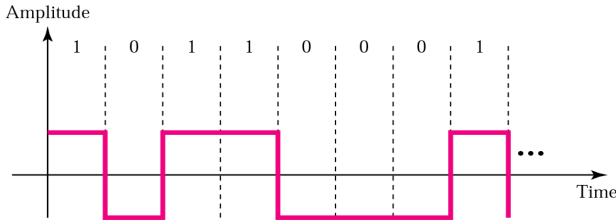
• When the voltage level in a digital signal is constant for a while, there is an increase in the low frequencies of the signal (results of Fourier analysis).



 Most of the channels are bandpass and may not support low frequencies



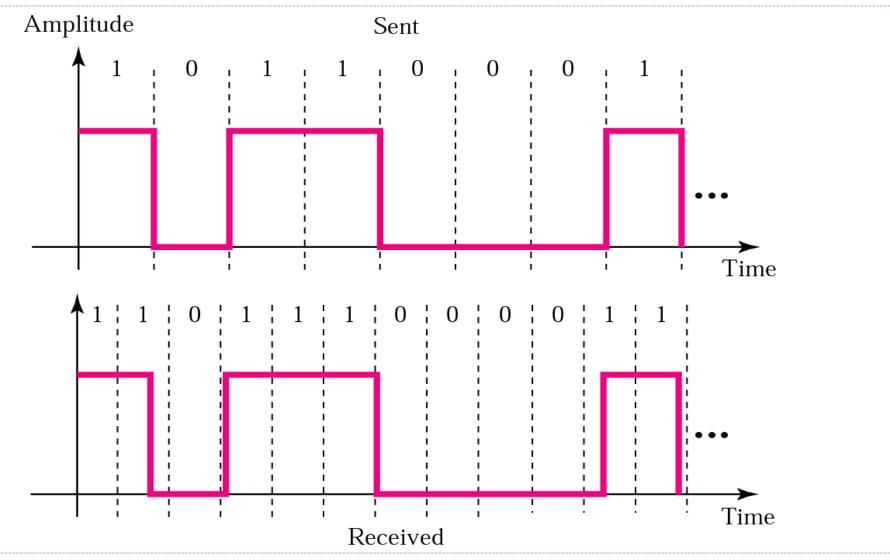
a. A signal with dc component



b. A signal without dc component

#### **Self Synchronization**

- To correctly interpret the signals received from the sender, the receiver's bit intervals must correspond exactly to the sender's bit intervals.
- If the receiver clock is faster or slower, the bit intervals are not matched and the receiver might misinterpret the signals.
- Self-synchronizing signal includes timing information.
- This can be achieved if there are transitions in the signal that alert the receiver to the beginning, middle, or end of the pulse.



• In a digital transmission, the receiver clock is 0.1 percent faster than the sender clock. How many extra bits per second does the receiver receive if the data rate is 1 Kbps? How many if the data rate is 1 Mbps?

#### Solution:

• In a digital transmission, the receiver clock is 0.1 percent faster than the sender clock. How many extra bits per second does the receiver receive if the data rate is 1 Kbps? How many if the data rate is 1 Mbps?

#### Solution:

At 1 Kbps:

1000 bits sent → 1001 bits received → 1 extra bps

At 1 Mbps:

1,000,000 bits sent → 1,001,000 bits received → 1000 extra bps

#### **Error detection**

- Errors occur during transmission due to line impairments.
- Some codes are constructed such that when an error occurs it can be detected.

#### For example:

- A particular signal transition is not part of the code.
- When it occurs, the receiver will know that a symbol error has occurred.

#### **Noise and interference**

- There are line encoding techniques that make the transmitted signal "immune" to noise and interference.
- This means that the signal cannot be corrupted, it is stronger than error detection.

#### **Complexity**

- The more robustness and resilient the code becomes, the more complex it is to implement the code.
- And the price is often paid in baud rate or required bandwidth.