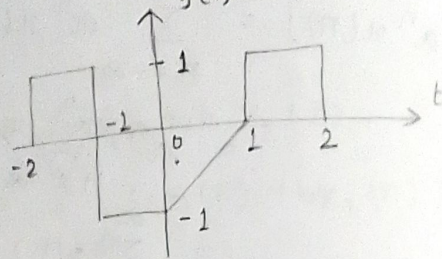
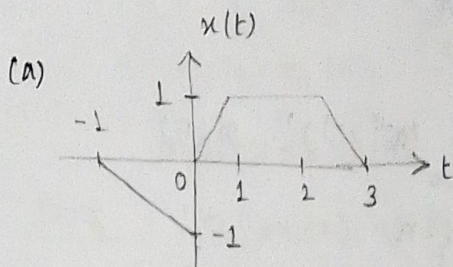


1. For the given signals plot:

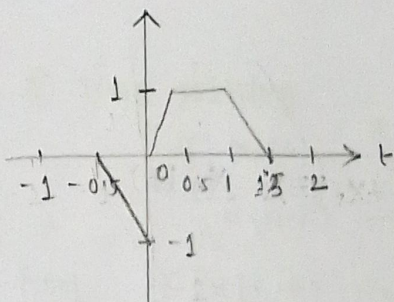
(i)  $x(2t) y(0.5t + 1)$

(ii)  $x(4-t) y(2-t)$

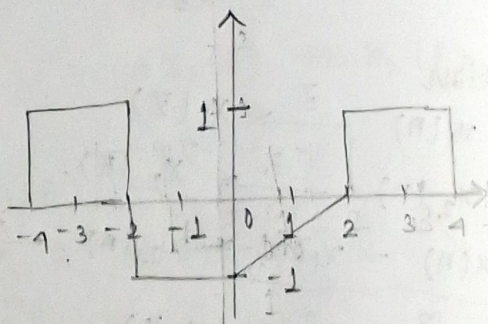


(i)  $x(2t) y(0.5t + 1)$

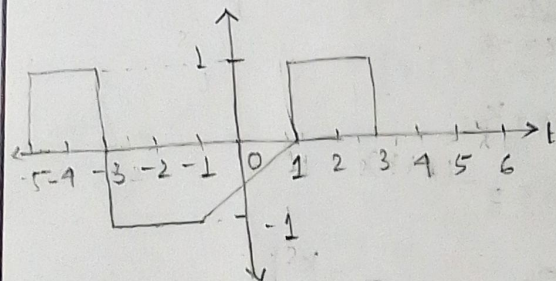
$x(2t)$



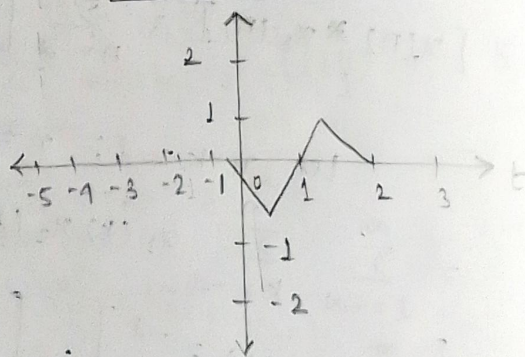
$y(0.5t)$



$y(0.5t + 1)$



$x(2t) y(0.5t + 1)$



$t=0, y(0.5t+1) = y(1) = 0$

$t=1, y(0.5t+1) = y(1.5) = 0$

$t=2, y(0.5 \times 2 + 1) = y(2) = 1$

$t=3, y(0.5 \times 3 + 1) = y(2.5) = 0$

$t=4, y(0.5 \times 4 + 1) = y(3) = 0$

$t=0, x(2 \cdot 0) = x(0) = -1$

$t=1, x(2 \cdot 1) = x(2) = 1$

$t=0.5, x(2 \cdot 0.5) = x(1) = 1$

$t=-0.5, x(-1) = 0$

$t=1.5, x(2 \cdot 1.5) = x(3) = 0$

$t=-1, x(-2) = 0$

$y(t/2)$

$t=0, x(0) = -1$

$t=1, x(0.5) = 0$

$t=2, x(1) = 1$

$t=4, x(2) = 1$

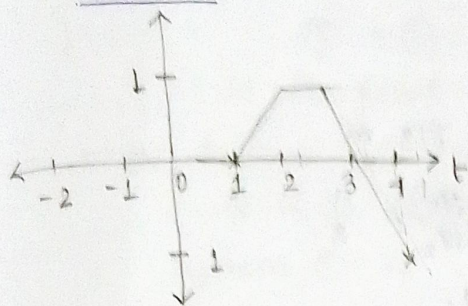
$t=3, x(1.5) = 0$

$t=-2, x(-1) = 0$

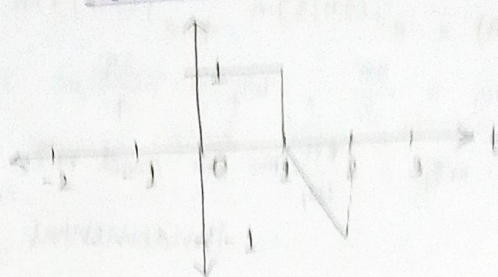


(ii)  $x(4-t)y(2-t)$ .

$x(4-t)$



$y(2-t)$



$t=0, x(4-0) = x(4)$

$t=1, x(4-1) = x(3) = 0$

$t=2, x(4-2) = x(2) = 1$

$t=3, x(4-3) = x(1) = 1$

$t=4, x(4-4) = x(0) = -1$

$t=-1, x(4+1) = x(5)$

$t=-2, x(4+2) = x(6)$

$t=0, y(2-0) = y(2) = 1$

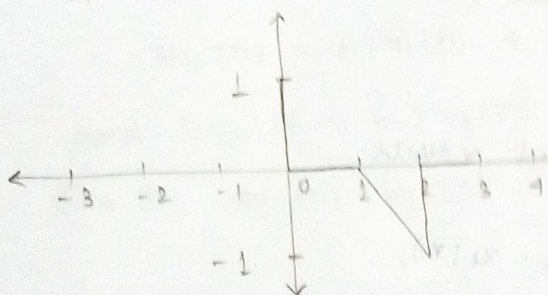
$t=-2, y(2+2) = y(4)$

$t=-1, y(2+1) = y(3)$

$t=1, y(2-1) = y(1) = 1$

$t=2, y(2-2) = y(0) = -1$

$x(4-t)y(2-t)$





2. Check periodic or not. Find fundamental period if signal is periodic.

$$(i) x(n) = e^{j(2\pi/3)n} + e^{j(3\pi/4)n}$$

$$\rightarrow \omega_1 = \frac{2\pi}{3}, \quad \omega_2 = \frac{3\pi}{4}$$

$$\therefore N_1 = \frac{2\pi}{\omega_1} \cdot m = 3m \text{ and } N_2 = \frac{2\pi}{\omega_2} \cdot m = 8/3 \cdot m$$

$$\therefore \text{Fundamental period} = \frac{N_1}{N_2} = \frac{9}{8}$$

$$N = 8N_1 = 9N_2 = 24$$

$$(ii) x(n) = 2\cos 3\pi n + 7\cos 9n$$

$$\rightarrow \omega_1 = 3\pi, \quad \omega_2 = \pi$$

$$\therefore N_1 = \frac{2\pi}{\omega_1} \cdot m = \frac{2}{3} \cdot m \text{ and } N_2 = \frac{2\pi}{\omega_2} \cdot m = \frac{2\pi}{\pi} \cdot m$$

$$\therefore \text{Fundamental period} = \frac{N_1}{N_2} = \frac{3}{1}$$

$$\therefore N = \pi N_1 = 3N_2 = \frac{2}{3} \pi$$

3. Check whether the following systems are static / dynamic, linear / non-linear, time variant / time invariant, causal / non-causal.

$$(i) y(n) = x(n) \cdot x(n-1)$$

It depends on past input values

$\therefore$  It is dynamic.

When o/p  $y_1(n)$  and i/p  $x_1(n)$ ,

$$y_1(n) = x_1(n) \cdot x_1(n-1)$$

When o/p is  $y_2(n)$  and i/p  $x_2(n)$ ,

$$y_2(n) = x_2(n) \cdot x_2(n-1)$$

$$\therefore ay_1(n) = ax_1(n) x_1(n-1) \text{ --- (1)}$$

$$by_2(n) = bx_2(n) x_2(n-1) \text{ --- (2)}$$

$$(1) + (2), ay_1(n) + by_2(n) = ax_1(n) x_1(n-1) + bx_2(n) x_2(n-1) \text{ --- (a)}$$

$$\text{and, } \tau [ax_1(n) + bx_2(n)]$$

$$= \tau [ax_1(n) \cdot x_1(n-1) + bx_2(n) \cdot x_2(n-1)] \text{ --- (b)}$$

$$\therefore (a) \neq (b)$$

$\therefore$  It is a linear system.  
non



Now,  $T[x(n-N)] = x(n-N) \cdot x(n-N-1) \quad \text{--- (1)}$

and,  $y(n-N) = x(n-N) \cdot x(n-N-1) \quad \text{--- (2)}$

$\therefore (1) = (2)$

$\therefore$  It is time invariant system.

$\therefore$  It depends on only past values and not future,

$\therefore$  It is a causal system.

$\therefore$  System (1) is : Dynamic

non-linear

Time invariant

causal.

(2)  $y(n) = 2x(n) + \frac{1}{x(n-1)}$

It depends on past input values

$\therefore$  It is dynamic system.

When o/p is  $y_1(n)$  and i/p is  $x_1(n)$ ,

$y_1(n) = 2x_1(n) + \frac{1}{x_1(n-1)}$

$\therefore ay_1(n) = a \cdot 2x_1(n) + \frac{a}{x_1(n-1)} \quad \text{--- (1)}$

and  $by_2(n) = b \cdot 2x_2(n) + \frac{b}{x_2(n-1)} \quad \text{--- (2)}$

$\therefore (1) + (2), ay_1(n) + by_2(n) = a(2x_1(n) + \frac{1}{x_1(n-1)}) + b(2x_2(n) + \frac{1}{x_2(n-1)})$   
(a)

and,  $T[ax_1(n) + bx_2(n)]$

$= 2a[ax_1(n) + \frac{ab}{x_1(n-1)}] + b[\frac{ax_1(n)}{b} + \frac{a}{bx_2(n-1)}] \quad \text{--- (b)}$

$\therefore (a) \neq (b)$  non-linear

$\therefore$  It is a time invariant system.

Now,  $T[x(n-N)] = 2x(n-N) + \frac{1}{x(n-N-1)} \quad \text{--- (1)}$

and  $y(n-N) = 2x(n-N) + \frac{1}{x(n-N-1)} \quad \text{--- (2)}$

$\therefore (1) = (2)$

$\therefore$  It is a time invariant system.

$\therefore$  It depends only on past and present values and not future,

$\therefore$  It is a causal system.



∴ System ② is : Dynamic  
non-Linear  
Time invariant  
causal

③  $y(n) = nx(n)$

∴ It depends on present values.

∴ It is a static system.

Now,  $ay_1(n) = anx_1(n)$  — (1)

and,  $by_2(n) = bnx_2(n)$  — (2)

① + ②,  $ay_1(n) + by_2(n) = anx_1(n) + bnx_2(n)$  — (a)

also,  $T[ax_1(n) + bx_2(n)]$   
 $= anx_1(n) + bnx_2(n)$  — (b)

∴ (a) = (b). linear

∴ It is a ~~time invariant~~ system.

Now,  $T[x(n-N)] = (n-N)x(n-N)$

and  $y(n-N) = (n) ~~nx~~ x(n-N)$

∴ It is a time variant system.

∴ It depends on present values.

∴ It is a causal system.

∴ System ③ is : Static  
Linear

Time variant  
causal.

④  $y(n) = x^2(n)$

∴ It depends on only present values.

∴ It is a static system.

Now,  $ay_1(n) = ax_1^2(n)$  — (1)

$by_2(n) = bx_2^2(n)$  — (2)

∴ ① + ②,  $ay_1(n) + by_2(n) = ax_1^2(n) + bx_2^2(n)$

also,  $T[ax_1(n) + bx_2(n)]$

$= ax_1^2(n) + bx_2^2(n)$

∴ It is a linear system.



Now,  $T[x(n-N)] = x^*(n-N)$ .

and  $y(n-N) = x^*(n-N)$ .

∴ it is time invariant system.

∴ It depends only on present values.

it is a causal system.

∴ System ④ is :  
static  
linear  
time invariant  
causal.

4. Determine Z-transform :

①  $x(n) = n^3 u(n)$ .

$$\begin{aligned} Z[x(n)] = X(z) &= \sum_{n=0}^{\infty} n^3 \cdot z^{-n} \quad \left[ u(n) = \begin{cases} 1, & n \geq 0 \\ 0, & n < 0 \end{cases} \right] \\ &= [0 + 1^3 + 2^3 + 3^3 + \dots] [z^{-1} + z^{-2} + \dots] \\ &= [1^3 + 2^3 + 3^3 + \dots] [z^{-1} + z^{-2} + \dots] \\ &= \left[ \frac{n(n+1)(2n+1)}{6} \right] [z^{-1} + z^{-2} + \dots] \end{aligned}$$

②  $x(n) = na^n u(n)$ .

$$\begin{aligned} Z[x(n)] = X(z) &= \sum_{n=0}^{\infty} na^n z^{-n} \quad Z[a^n u(n)] = \frac{z}{z-a}, \quad |z| > |a| \\ &= \sum_{n=0}^{\infty} n(a z^{-1})^n \\ \therefore Z[na^n u(n)] &= -z \cdot \frac{d}{dz} \left( \frac{z}{z-a} \right) \quad [\text{using differentiation property}] \\ &= -z \cdot \left( \frac{-a}{(z-a)^2} \right) \\ &= \frac{az}{(z-a)^2} \end{aligned}$$

③  $x(n) = nu(n)$

$$\begin{aligned} Z[x(n)] = X(z) &= \sum_{n=0}^{\infty} n z^{-n} \\ &= \sum_{n=0}^{\infty} 0 + z^{-1} + 2z^{-2} + 3z^{-3} + \dots \end{aligned}$$

$$\begin{aligned} Z[u(n)] &= 1 + z^{-1} + z^{-2} + \dots \\ \therefore Z[n u(n)] &= -z \cdot \frac{d}{dz} \cdot (1 + z^{-1} + z^{-2} + \dots) \quad [\text{using differentiation property}] \\ &= -z [0 + -z^{-2} - 2z^{-3} - \dots] \\ &= 0 + z^{-1} + 2z^{-2} + \dots = z^{-1} + 2z^{-2} + \dots \end{aligned}$$