System of first order linear DE's with

Constant Coelficients - Solution by Laplace Transform melkod.

1.
$$\frac{dx}{dt} = -x + y$$
$$\frac{dy}{dt} = 2x$$
$$x(0) = 0, \quad y(0) = 1$$

Sol: Let [[x(t)] = x(s) and [[y(t)] = γ(s).

Applying Laplace hansform on the system, we get

i.e.,
$$SX(S) - X(O) = -X(S) + Y(S)$$

=) $(S+1) \times (S) = Y(S)$

$$4\lambda(4) - 5x(8) = \lambda(0)$$

A) & B) represent a lineon system of two equations in two unknown x(A) and y(A).

By Cramer's whe, we have

$$X(s) = \begin{vmatrix} 0 & -1 \\ 1 & s \end{vmatrix}$$

$$\begin{vmatrix} 8(s+1)-2 \\ -2 & s \end{vmatrix}$$

$$(x(s)=\frac{1}{3^2+3-2})$$

...
$$X(3) = \frac{1}{3^2 + 3 - 2}$$
 and

Applying inverse LT, we set
$$x(E)_{=}$$
 $L^{-1}[x(8)]$ and $y(E)_{=}$ $L^{-1}[Y(8)]$.

 $x(L)_{=}$ $L^{-1}[Y(8)]$.

$$x(t) = \begin{bmatrix} 1 \\ 3^{2} + 3 - 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ (3 + \frac{1}{2})^{2} - \frac{1}{4} - 2 \end{bmatrix}$$

$$= \begin{bmatrix} -1 \\ (3/2) \\ (3+\frac{1}{2})^{2} - (\frac{3}{2})^{2} \end{bmatrix}$$

$$= \frac{2}{3} \begin{bmatrix} -1 \\ (3/2) \\ (3+\frac{1}{2})^{2} - (\frac{3}{2})^{2} \end{bmatrix}$$

$$x(t) = \frac{3}{5} e^{-\frac{1}{7}t} \sinh(\frac{5}{3}t)$$

NoW,

=)
$$y(t) = \begin{bmatrix} -1 \\ (3+\frac{1}{2})^2 - (\frac{3}{2})^2 \end{bmatrix}$$

 $\frac{3+1}{2} = \frac{3+\frac{1}{2}}{2} + \frac{1}{2} \cdot (\frac{3}{2})$
 $\frac{3+\frac{1}{2}}{2} + \frac{1}{2} \cdot (\frac{3}{2})$
 $\frac{1}{3} \cdot \begin{bmatrix} -1 \\ (3+\frac{1}{2})^2 - (\frac{3}{2})^2 \end{bmatrix} + \frac{1}{3} \cdot \begin{bmatrix} (3/2) \\ (3+\frac{1}{2})^2 - (\frac{3}{2})^2 \end{bmatrix}$
 $\frac{1}{3} \cdot \begin{bmatrix} -1 \\ (3+\frac{1}{2})^2 - (\frac{3}{2})^2 \end{bmatrix} + \frac{1}{3} \cdot \begin{bmatrix} (3/2) \\ (3+\frac{1}{2})^2 - (\frac{3}{2})^2 \end{bmatrix}$
Hence he required solution of the size $y(t) = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t) \\ y(t) = \frac{1}{3} \end{bmatrix} = \frac{1}{3} \cdot \begin{bmatrix} y(t)$