

Module-5 (Linear Transformations)

Tutorial sheet-1

Note: We use short form 'LT' for 'Linear transformation'

1. In each part, determine whether T is LT.

(a) $T(x, y, z) = (0, 0)$ (b) $T(x, y, z, w) = (1, -1)$

(c) $T(x, y, z) = (x - y + z, 0)$ (d) $T(x, y, z) = (z, yz, x + y + z)$

(e) $T(x, y, z) = (2y, x + z, -3y)$.

2. Find the standard matrix for the operator $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by

$$w_1 = 4x_1 - 3x_2 + x_3$$

$$w_2 = 2x_1 - x_2 + 5x_3$$

$$w_3 = x_1 + 2x_2 - 2x_3$$

and then calculate $T(-1, 2, 4)$ by directly substituting in the equation and also by matrix multiplication.

4. Let $L : P_1 \rightarrow P_2$ be a LT for which, $L(x + 1) = x^2 - 1$ and $L(x - 1) = x^2 + x$ then,
 - (i) what is $L(7x + 3)$?
 - (ii) what is $L(ax + b)$?
5. Let $L : V \rightarrow W$ be a LT, then prove that kernel of L is a subspace of V and $\text{range}(L)$ is a subspace of W .
6. Let $L : V \rightarrow W$ be a LT, then prove that L is one - one if and only if $\text{kernel}(L) = 0_V$.
7. Let $L : R^3 \rightarrow R^3$ be defined by $L(x, y, z) = (x - y, x + 2y, z)$, then:
 - (i) Show that L is a LT .
 - (ii) Find a basis for $\text{kernel}(L)$.
 - (iii) Find a basis for $\text{range}(L)$.
 - (iv) Is L one-one?
 - (v) Is L onto?
 - (vi) Is L invertible?
 - (vii) Find the matrix corresponding to the standard basis of R^3 .
8. Let $L : P_2 \rightarrow P_2$ be a LT defined by $L(ax^2 + bx + c) = (a + 2b)x + (b + c)$, then:
 - (i) Check whether, $x^2 + 2x + 1 \in \text{range}(L)$.
 - (ii) Check whether, $-4x^2 + 2x - 2 \in \text{null}(L)$.
9. Let $L : P_2 \rightarrow R^2$ be defined by $L(p(x)) = (p(1), p'(1))$, then:
 - (i) Show that L is a LT .
 - (ii) Find a basis for $\text{null}(L)$.
 - (iii) Find a basis for $\text{range}(L)$.
 - (iv) Find the matrix of L corresponding to $S = 1 + x^2, 1, x - 1$.
10. Let $L : P_2 \rightarrow P_1$ be a LT defined by $L(p(x)) = xp(x) + p(0)$. Let $S = \{x + 1, x - 1\}$ and $T = \{x^2 + 1, x - 1, x + 1\}$ be the bases for P_1, P_2 respectively. Find the matrix of the LT with respect to S and T . Compute $L(-3x + 3)$ using the definition of L as well as using the matrix of L .