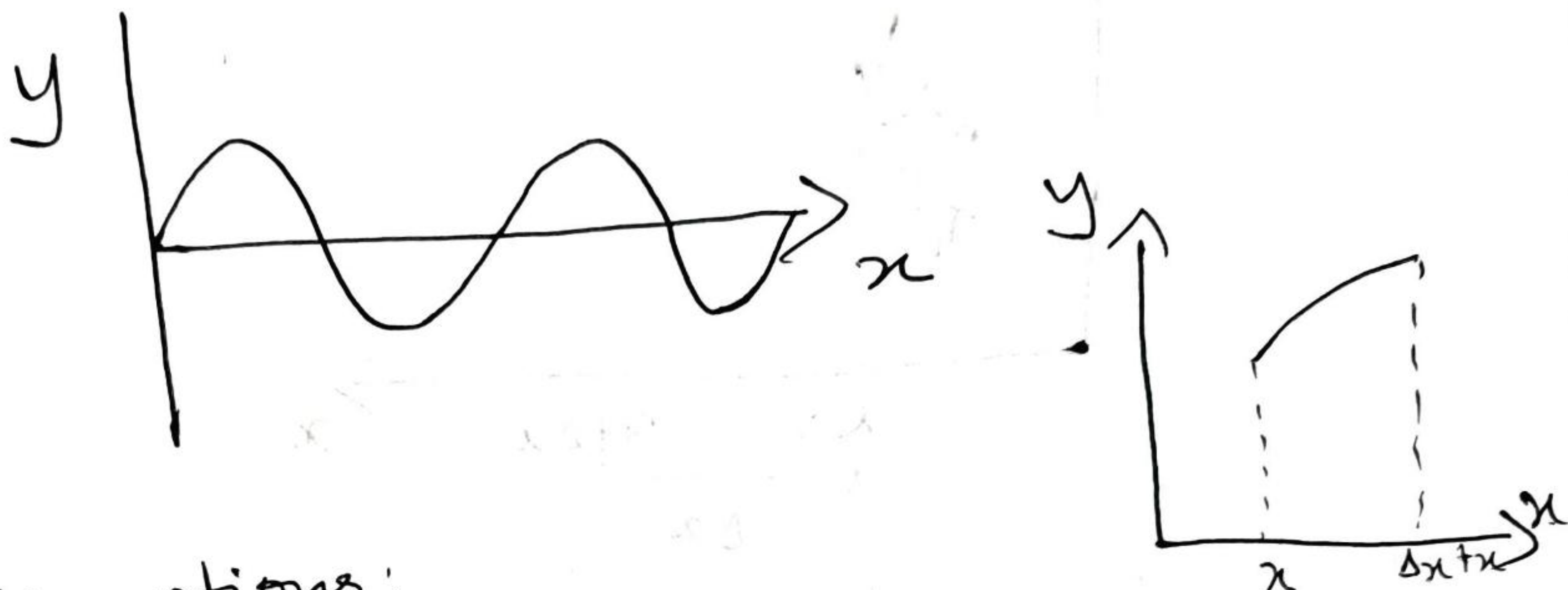


## 1-D Wave equation

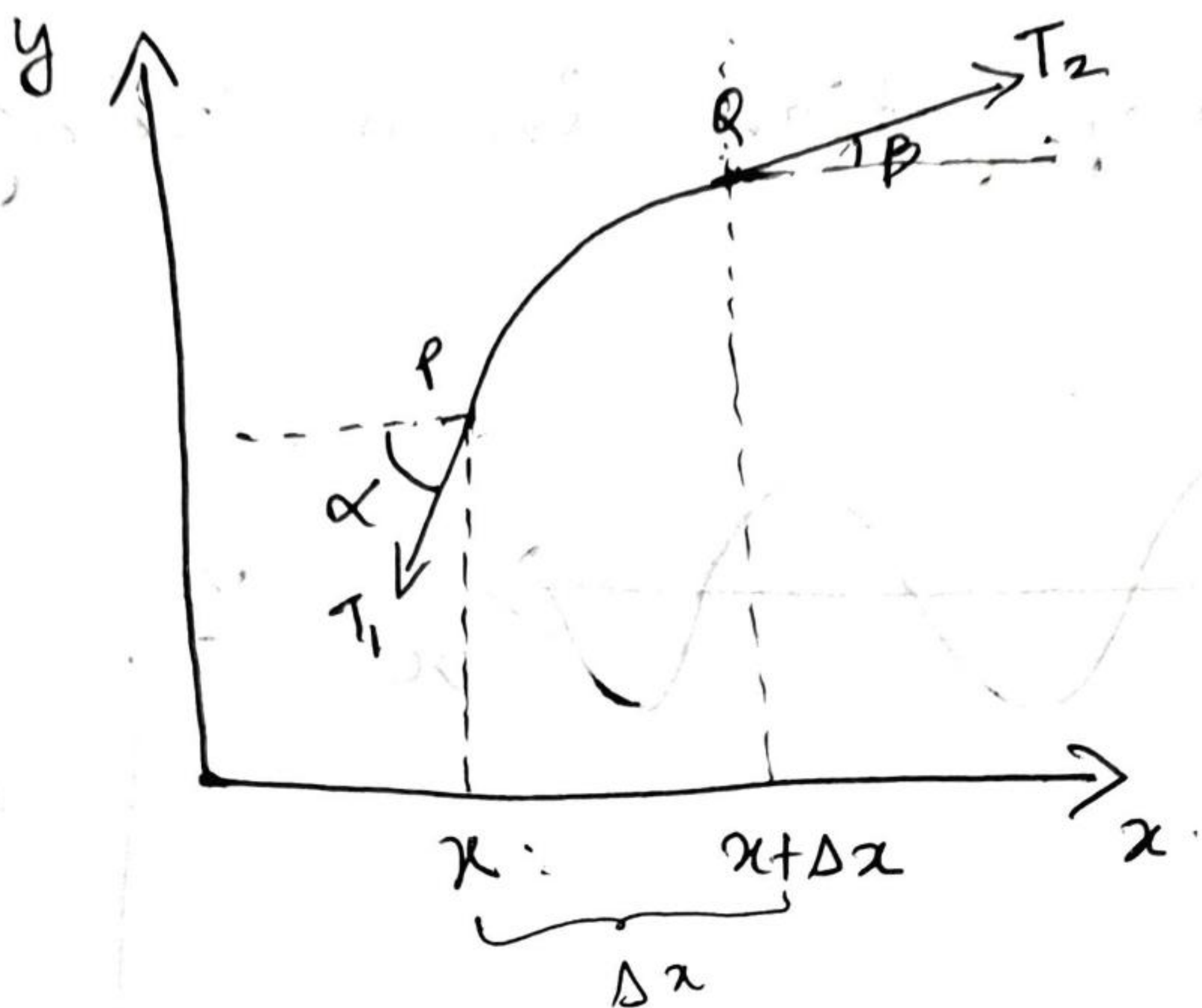
Wave propagation in a string.



### Assumptions:

- \* Mass of string is uniformly distributed (mass/length = linear density ( $\mu$ ) is constant)
- \* String is perfectly elastic & offers no resistance to bending
- \* Gravitation effects negligible
- \* Oscillations are only along  $y$ -axis (transverse dir'n)
- \* Vertical deflections (amplitude) are small at all times  $\rightarrow$  slopes ( $\frac{dy}{dx}$  are small).





→ The displacement ( $y$ ) will vary with time ' $t$ ' and also with ' $x$ ' the position →  $y(x, t)$

→ Let us consider a portion of string 'PQ'

→ P is at point  $x$  and Q at pt  $x + \Delta x$  in the  $x$  axis.

→ Tension at point P is  $T_1$  ~~making an~~

" " " Q is  $T_2$

Force makes an angle  $\alpha$  at pt 'P' and  $\beta$  at point Q.

Horizontal components of force are equal

$$T_1 \cos(\alpha) = T_2 \cos(\beta) = T \quad \text{--- (1)}$$



vertical component of force  $\rightarrow$  only this force is active

$F_{\text{vertical}} = ma \rightarrow$  Newton's 2nd law of motion

vertical component

$$T_2 \sin \beta - T_1 \sin \alpha = ma \quad \text{--- (2)}$$

$$T_2 \sin \beta - T_1 \sin \alpha = m \cdot \frac{\partial^2 y}{\partial t^2}$$

linear mass density  $\rho = m/l$

in this case  $\rho = m/\Delta x$   $m = \rho \Delta x$

Substitute for  $m$  in eqn (2)

$$T_2 \sin \beta - T_1 \sin \alpha = \rho \Delta x \frac{\partial^2 y}{\partial t^2} \quad \text{--- (3)}$$

$\div$  eqn (3) by (1) throughout

$$\frac{T_2 \sin \beta}{T_2 \cos \beta} - \frac{T_1 \sin \alpha}{T_1 \cos \alpha} = \frac{\rho \Delta x}{T} \frac{\partial^2 y}{\partial t^2}$$

$$\tan \beta - \tan \alpha = \frac{\rho \Delta x}{T} \frac{\partial^2 y}{\partial t^2}$$

$$\left. \frac{\partial y}{\partial x} \right|_{x+\Delta x} - \left. \frac{\partial y}{\partial x} \right|_x = \frac{\rho \Delta x}{T} \frac{\partial^2 y}{\partial t^2}$$



$$\frac{\frac{\partial y}{\partial x}|_{x+\Delta x} - \frac{\partial y}{\partial x}|_x}{\Delta x} = \frac{f}{T} \frac{\partial^2 y}{\partial t^2}$$

↓

This tells us how much did the slope change in b/w  $p$  &  $Q$ .

$$\lim_{\Delta x \rightarrow 0} \frac{\partial^2 y}{\partial x^2} = \frac{f}{T} \frac{\partial^2 y}{\partial t^2}$$

$\Delta x \rightarrow \text{small}$

$$\frac{\frac{\partial y}{\partial x}|_{x+\Delta x} - \frac{\partial y}{\partial x}|_x}{\Delta x} \approx \frac{\partial^2 y}{\partial x^2}$$

$$\Rightarrow \frac{\partial^2 y}{\partial x^2} = \frac{f}{T} \frac{\partial^2 y}{\partial t^2} \quad \text{or} \quad \frac{\partial^2 y}{\partial t^2} = \frac{T}{f} \frac{\partial^2 y}{\partial x^2}$$

$\frac{T}{f}$  is const and positive.

The dimensional analysis

$$\left(\frac{f}{T}\right) = \frac{ML^{-1}}{M(LT^{-2})} = L^{-2}T^2 = \frac{1}{c^2} \quad \frac{\text{kg/m}}{\text{kg m/s}^2} = \frac{1}{\text{m}^2/\text{s}^2}$$

↓  
similar to  
(velocity)<sup>2</sup>

$$\therefore \frac{\partial^2 y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2}$$

or

$$\boxed{\frac{\partial^2 y}{\partial t^2} = c^2 \frac{\partial^2 y}{\partial x^2}} \rightarrow \text{1-D wave eqn}$$



## Sol'n of wave eqn

Let us consider a 1-D wave eqn

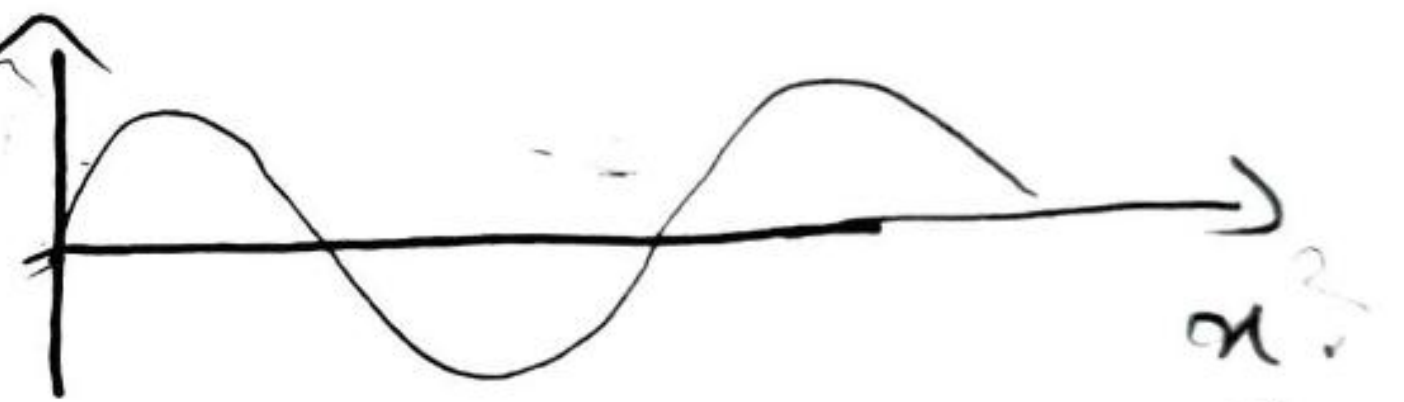
$$\frac{\partial^2 y}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2}$$

$v \rightarrow$  velocity of the wave.

Let us consider a sol'n  $y = f(x - vt)$

Goal: To show that this  $y = f(x - vt)$  will satisfy the wave equation.

$y(x, t)$ , ~~to~~ considering a wave moving in  $+x$  dir'n. with  $y$  uniform amp



at time  $t=0$ , if  $y$  is traveling a dist  $x'$   
after time ' $t$ '  $y$  would have moved  
dist ' $vt$ '. Since we are talking about  
forward moving ~~pt~~ wave, the new dist  
at ~~pt~~ the point would be  $(x - vt)$   
for a wave moving in  $(-ve)$   $x$  dir'n  
it would be  $(x + vt)$



$$y = f(x - vt)$$

$$(x - vt) = \tau$$

chain rule.

$$y = f(\tau)$$

$$\frac{\partial y}{\partial t} = \frac{\partial f}{\partial \tau} \cdot \frac{\partial \tau}{\partial t}$$

$$\therefore \frac{\partial \tau}{\partial t} = -v$$

$$\frac{\partial y}{\partial t} = -v \cdot \frac{\partial f}{\partial \tau}$$

Ansly

$$\frac{\partial^2 y}{\partial t^2} = \frac{\partial}{\partial \tau} \left( \frac{\partial f}{\partial \tau} \right) \cdot \frac{\partial \tau}{\partial t}$$

$$\frac{\partial \tau}{\partial t} = -v$$

$$\therefore \frac{\partial^2 y}{\partial t^2} = +v^2 \frac{\partial^2 f}{\partial \tau^2}$$

Ansly.

$$\frac{\partial y}{\partial x} = \frac{\partial f}{\partial \tau} \cdot \frac{\partial \tau}{\partial x}$$

$$\frac{\partial \tau}{\partial x} = 1$$

$$\therefore \frac{\partial y}{\partial x} = \frac{\partial f}{\partial \tau}$$

$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial \tau} \left( \frac{\partial f}{\partial \tau} \right) \cdot \frac{\partial \tau}{\partial x}$$

Since  $\frac{\partial \tau}{\partial x} = 1$

we get

$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial^2 f}{\partial \tau^2}$$

~~Ans~~



Substituting in wave eqn.

$$\frac{1}{\cancel{v^2}} \times \cancel{v^2} \frac{\partial^2 f}{\partial \tau^2} = \frac{\partial^2 f}{\partial \tau^2}$$

we get L.H.S. = R.H.S.

Hence proved that  $y = f(x - vt)$  is a solution of wave eqn.

Similarly  $y = f(x + vt)$  will also be a solution of wave eqn.

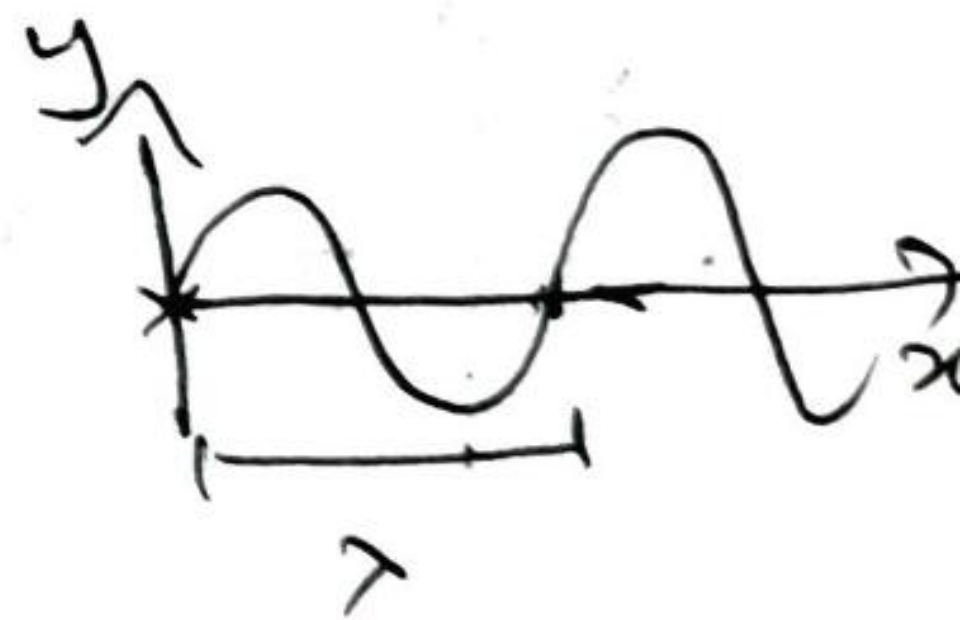
even  $y = f(x + vt) + f(x - vt)$  will also be a solution of wave eqn.

For harmonic waves:

$$y = A \sin \frac{2\pi}{\lambda} (x - vt)$$

$(x - vt) \rightarrow$  is in units of 'm'

$2\pi \rightarrow$  is  $\odot$  to change in to radians.



After a dist ' $\lambda$ ' the wave repeats

$\therefore$  this  $\lambda \rightarrow$  wavelength

$$y = A \sin \left( \frac{2\pi}{\lambda} x - \frac{2\pi}{\lambda} vt \right)$$



$k = \frac{2\pi}{\lambda} \rightarrow$  angular wave number

$\omega = 2\pi\nu \rightarrow$  ang. freq

$$\frac{v}{\lambda} = \nu$$

$$y = A \sin(kx - \omega t)$$

Similarly  $y = A \cos(kx - \omega t)$  is also solution of wave eqn.

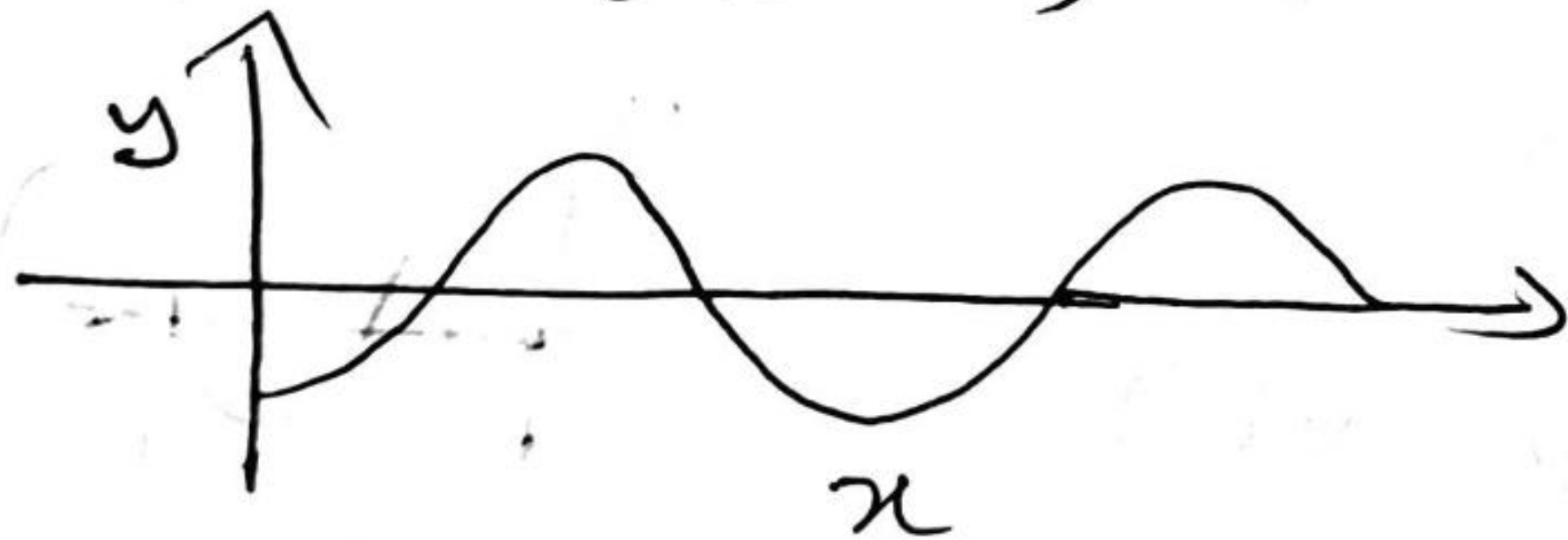
$y$  can also be written as

$$y = A \sin(\omega t - kx) \text{ or } A \cos(\omega t - kx)$$

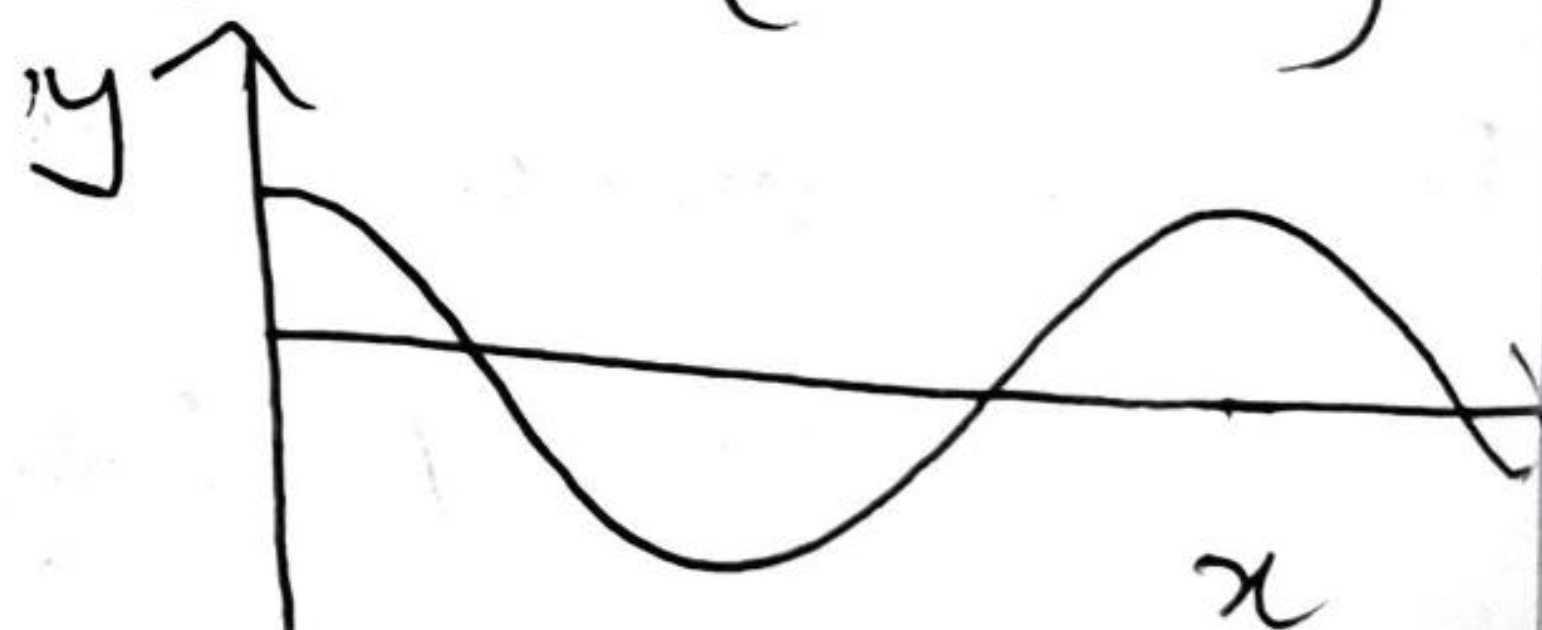
and all these are talking about forward moving waves.

eg

$$y = A \sin(kx - \omega t)$$



$$y = A \sin(\omega t - kx)$$



In terms of exponential terms

$y = A e^{i(\omega t - kx)}$  is also a solution of wave moving forward.



## Velocities in wave motion:



When a wave progresses through a medium, the individual oscillators that make up the medium do not progress through the medium with the waves. Their motion is simple harmonic limited to oscillations, either transverse or longitudinal, about their equilibrium position.

→ Three velocities in wave motion.

(1) particle velocity: which is the simple harmonic velocity of the oscillator about its equilibrium position  $\left(\frac{\partial y}{\partial t}\right)$

(2) Wave velocity or phase velocity  $\left(\frac{\partial x}{\partial t}\right)$

The velocity with which planes of equal phase, crest or trough progress through medium



### (3) Group velocity:

When a number of waves of diff freq, wavelengths and velocities may be superimposed to form a group. Motion of such ~~to~~ pulse is described by group velocity.

Relation b/w ~~the~~ particle velocity & wave vel

$$y = A \sin(kx - \omega t).$$

$$\frac{\partial y}{\partial t} = \cancel{A \sin} - A \omega \cos(kx - \omega t).$$

$$\frac{\partial y}{\partial x} = A k \cos(kx - \omega t).$$

$$\cos(kx - \omega t) = - \frac{1}{A \omega} \frac{\partial y}{\partial t}$$

$$\cos(kx - \omega t) = \frac{1}{A k} \frac{\partial y}{\partial x}$$

$$-\frac{1}{A \omega} \frac{\partial y}{\partial t} = \frac{1}{A k} \frac{\partial y}{\partial x}$$

$$\frac{\partial y}{\partial t} = - \frac{\omega}{k} \frac{\partial y}{\partial x}$$



$$\frac{\partial y}{\partial t} = -c \frac{\partial y}{\partial x}$$

$$c = \frac{2\pi v}{2\pi/\lambda} = \omega/k$$

$$\frac{\partial y}{\partial t} = - \frac{\partial x}{\partial t} \cdot \frac{\partial y}{\partial x}$$

The particle velocity is given as the product of wave velocity and the gradient of the wave profile preceded by a  $(-)$  sign for a wave moving in  $(+x)$  dir'n.

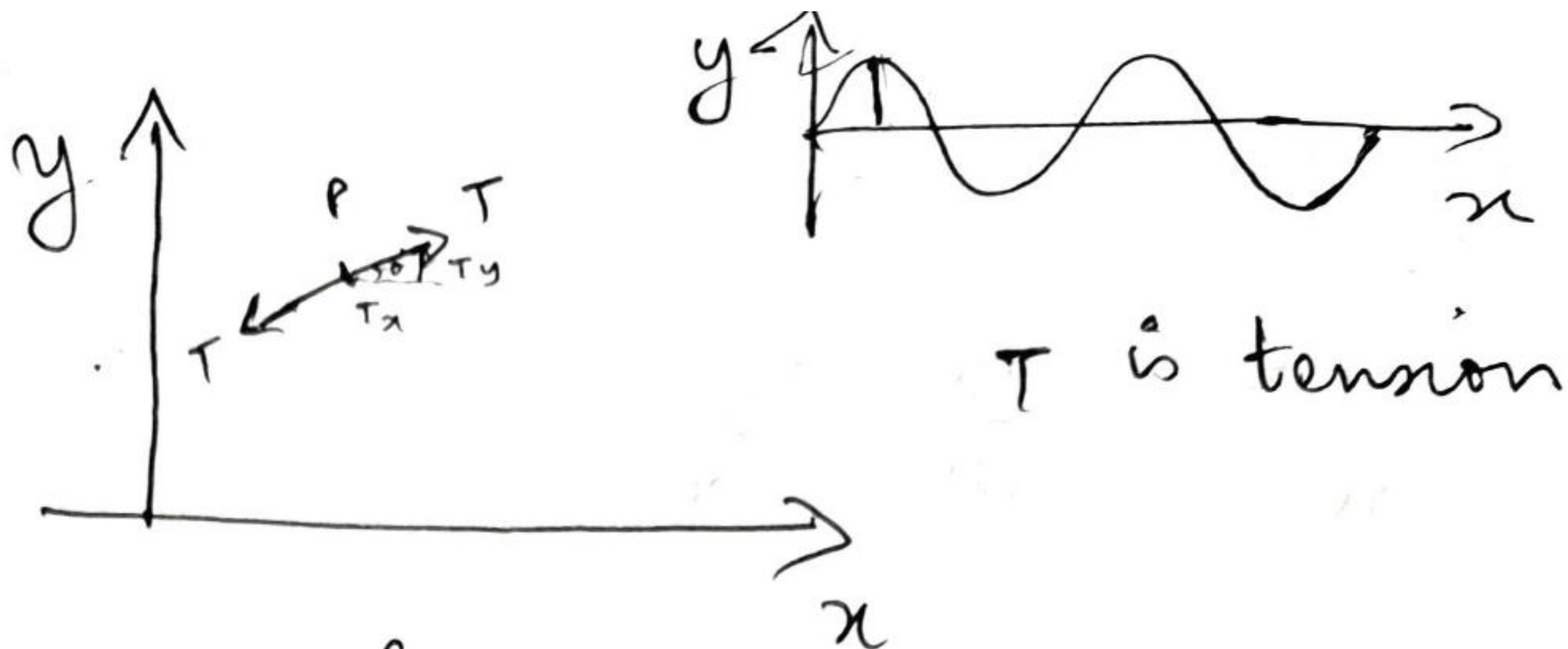
### Impedance of a string:

Any medium through which waves propagate will present an impedance to the waves.

In case of string, moving in motion a transverse dir'n ( $y$ ) to the wave ( $x$ )

$$Z = \frac{\text{Transverse force}}{\text{Transverse velocity}} = \frac{F_y}{v_y}$$





Transverse force  $F_y = T_y = -T \sin \theta$ .  
 -ve sign is because force is ~~is~~ acting downward & slope is (ve)  
 Since  $\theta$  is small

$$F_y = -T \tan \theta$$

$$= -T \frac{\partial y}{\partial x}$$

$$F_y = -T \frac{\partial y}{\partial x}$$

$$y(x,t) = A \sin(kx - \omega t)$$

$$\frac{\partial y}{\partial x} = A k \cos(kx - \omega t)$$

$$\therefore F_y = -T A k \cos(kx - \omega t)$$

For transverse velo (particle vel)

$$v_y = \frac{\partial y}{\partial t}$$

$$\frac{\partial y}{\partial t} = v_y = -A \omega \cos(kx - \omega t)$$



$$\therefore F_y \quad Z = \frac{F_y}{V_y}$$

$$Z = \frac{-T A k \cos(kx - \omega t)}{-A \omega \cos(kx - \omega t)}$$

$$Z = + \frac{T k}{\omega}$$

$$\boxed{Z = \frac{T}{c}}$$

$c \rightarrow$  wave velocity.

$T = \rho c^2$  from wave eqn.

$$\therefore Z = \rho c$$

$\rho \rightarrow$  linear mass density.



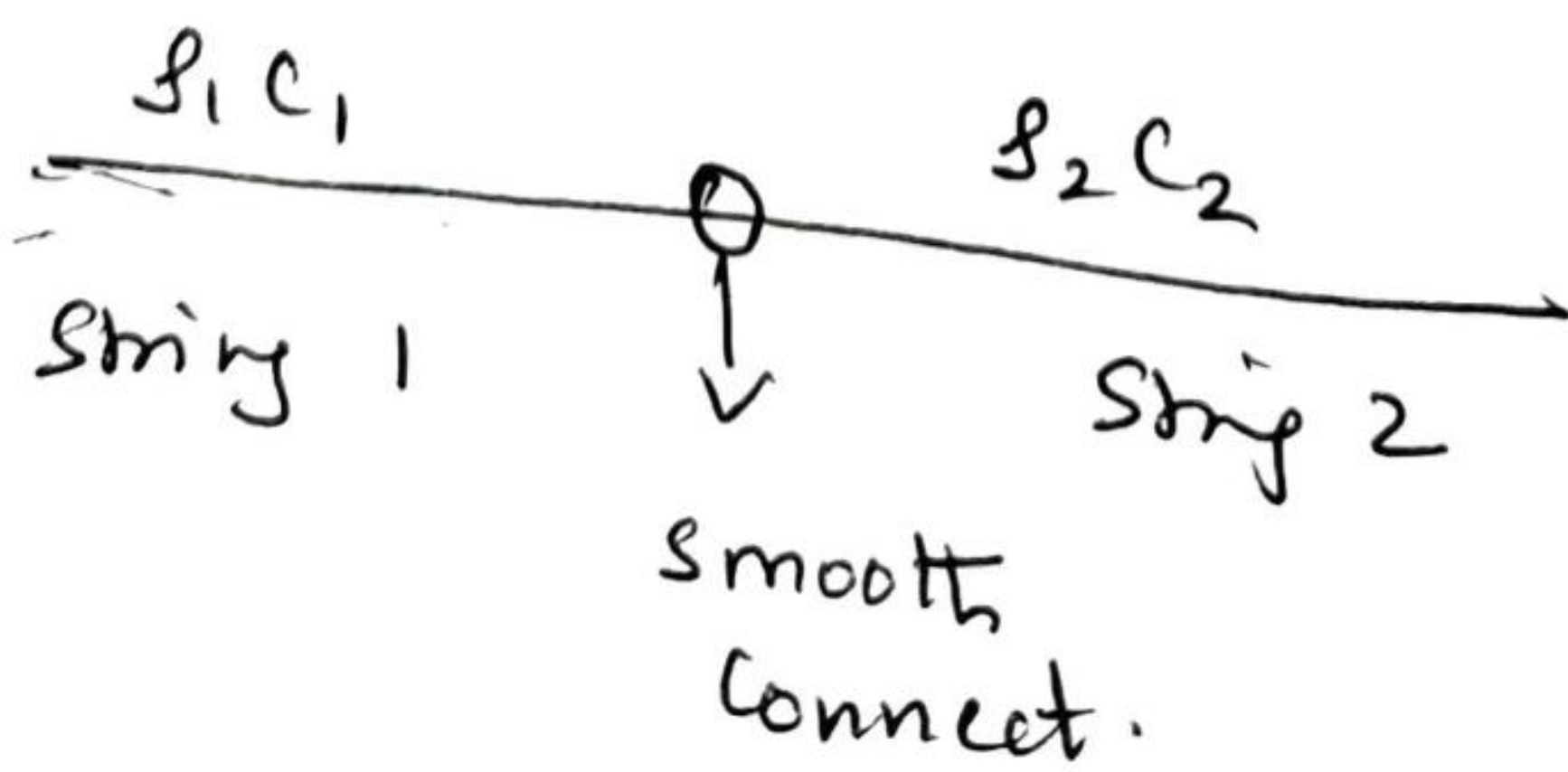
## Reflection and Transmission of waves on a string at a boundary

We have seen that a string possesses a characteristic impedance ' $\rho c$ ' to the waves travelling along it.

Lets now study how a wave will respond to a sudden change of impedance.

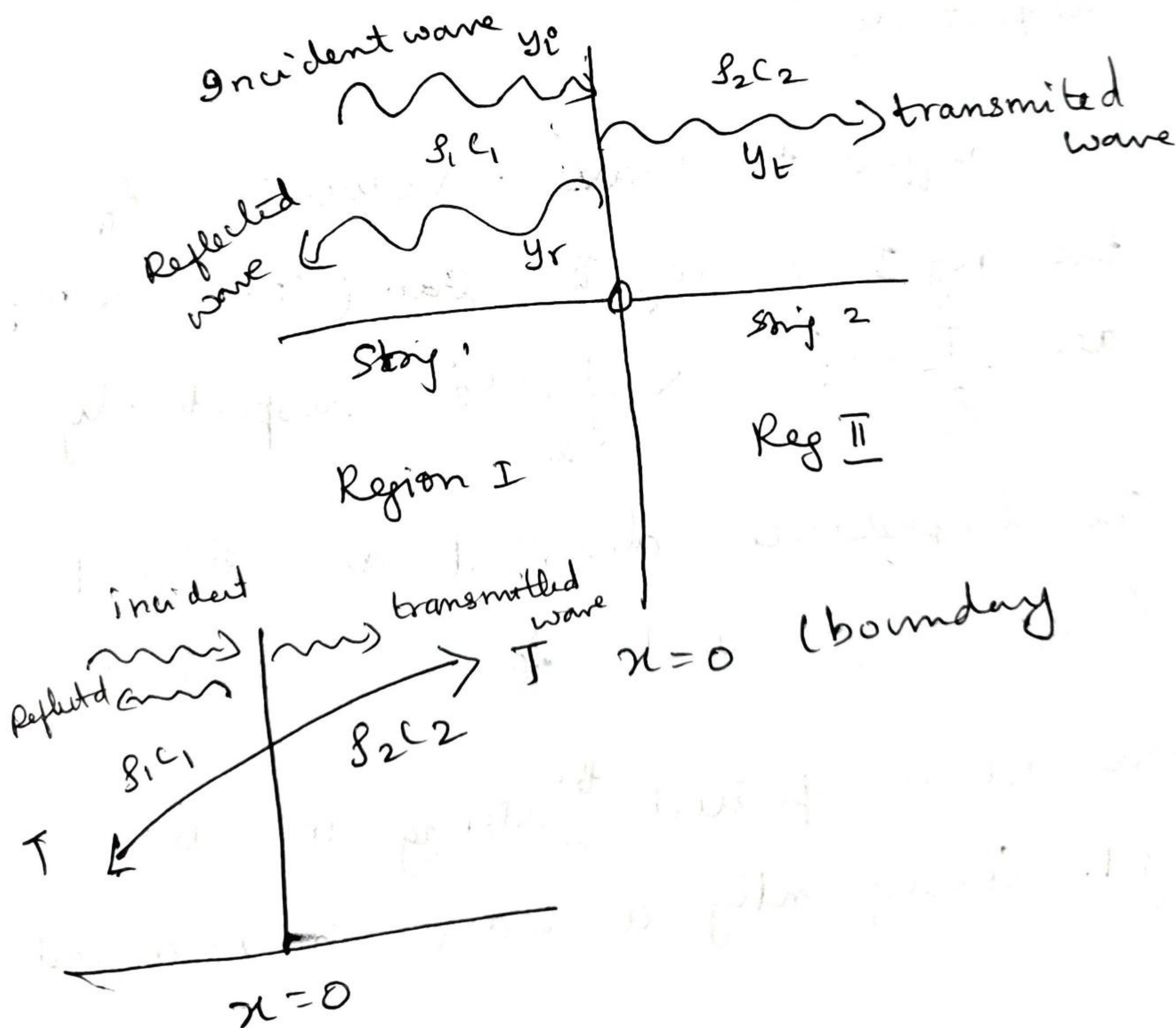
What would happen at the interface?

Let us consider a string (string 1 + string 2) that has two impedances.





Let us take the Tension ( $T$ ) in the string to be uniform throughout the string. Since the linear mass densities are different, Velocities will also be different. Since we are considering monochromatic waves (angular frequency)  $\omega$  will be same throughout.





→ The string formed by joining two diff strings are ~~be~~ imposed upon them a ~~common~~ constant Tension 'T' along the whole string.

→ The linear density of string 1 & string 2 are different & represented as  $\mu_1$  &  $\mu_2$  respectively.

→ The different wave velocities of two reg I & reg. II ~~are~~ (string 1 & string 2) are  $\frac{T}{\mu_1} = c_1^2$  &  $\frac{T}{\mu_2} = c_2^2$  respectively.

→ The impedance denoted as string 1 is  $Z_1 = \mu_1 c_1$  and for string 2 is  $Z_2$ .

→ Now let us perturb the string in the reg I. Consequently a wave is produced.



and let this be incident wave that will travel along the reg I and will face a discontinuity in impedance at the pt  $x=0$ , as in figure.

Here at this point,  $x=0$  part of the incident wave will be reflected in reg I and part of the wave will be transmitted in reg II - having impedance

$$Z_2 = \rho_2 c_2$$

Thus the displacement of the waves in region I & II ~~is~~ are defined as follows

The displacement of incident wave in reg with amp  $A_1$  travelling in the  $x$  dir'n with velocity  $c_1$  is

$$y_i = A_1 e^{i(\omega t - kx)} \quad \text{--- (1)}$$



The displacement of reflected wave in reg I with amp  $B_1$ , travelling in  $-x$  dir with velocity  $c_1$ .

$$y_r = B_1 e^{i(\omega t + k_1 x)} \quad \text{--- (2)}$$

the displacement of transmitted wave in reg II with amp  $A_2$ , travelling in  $+x$  dir with velocity  $c_2$ .

$$y_t = A_2 e^{i(\omega t - k_2 x)} \quad \text{--- (3)}$$

Thus the reflections & transmission amplitudes ( $B_1$  &  $A_2$ ) w.r. to  $A_1$  can be found by applying the boundary condition at  $x=0$ , where there is a discontinuity in impedance.

Thus the boundary cond'n at  $x=0$ .

- (1) Geometrical cond'n  $\rightarrow$  displacement is same in reg I & reg II (i.e) same immediately ~~at reg~~ to the left and right at  $x=0$  for all time, so there is no discontinuity of displacement.



$$y_i + y_r = y_t \quad \text{--- (4)}$$

(ii) Dynamical cond'n

→ transverse force  $T \left( \frac{\partial y}{\partial x} \right)$  at  $x=0$  is continuous & there is a continuous slope.

$$T \frac{\partial y_i}{\partial x} + T \frac{\partial y_r}{\partial x} = T \frac{\partial y_t}{\partial x} \quad \text{--- (5)}$$

Applying the boundary cond'n at  $x=0$ .

cond'n (i)

$$y_i + y_r = y_t$$

Substituting (1), (2), (3) in eqn (4).

$$A_1 e^{i(\omega t - k_1 x)} + B_1 e^{i(\omega t + k_1 x)} = A_2 e^{i(\omega t - k_2 x)}$$

at  $x=0$ .

$$A_1 e^{i\omega t} + B_1 e^{i\omega t} = A_2 e^{i\omega t}$$

$$A_1 + B_1 = A_2 \quad \text{--- (6)}$$

Applying the second boundary cond'n

$$\frac{\partial y_i}{\partial x} = -A_1 k_1 e^{i(\omega t - k_1 x)} \quad \left. \vphantom{\frac{\partial y_i}{\partial x}} \right\}$$



$$\left. \frac{\partial y_r}{\partial x} = B_1 k_1 e^{i(\omega t + k_1 x)} \right\} - \textcircled{7}$$

$$\frac{\partial y_t}{\partial x} = -A_2 k_2 e^{i(\omega t - k_2 x)}$$

Applying eqn (7) in (5)

$$-TA_1 k_1 e^{i(\omega t - k_1 x)} + TB_1 k_1 e^{i(\omega t + k_1 x)}$$

$$= -TA_2 k_2 e^{i(\omega t - k_2 x)}$$

at  $x=0$

$$-TA_1 k_1 e^{i\omega t} + TB_1 k_1 e^{i\omega t} = -TA_2 k_2 e^{i\omega t}$$

$$-TA_1 k_1 + TB_1 k_1 = -TA_2 k_2 \text{ --- } \textcircled{8}$$

we know

$$k = \omega/c \text{ --- } \textcircled{9}$$

Substituting (9) in (8)

$$-TA_1 \frac{\omega}{c_1} + TB_1 \frac{\omega}{c_1} = -TA_2 \frac{\omega}{c_2}$$

$$\text{know } T/c_1 = \mathcal{Z}_1 = Z_1, \quad T/c_2 = \mathcal{Z}_2 = Z_2$$

$$-Z_1 A_1 + Z_1 B_1 = -Z_2 A_2$$



$$Z_1 A_1 - Z_1 B_1 = Z_2 A_2$$

$$Z_1 (A - B) = Z_2 A_2 \quad \text{--- (10)}$$

Using eqn (8) and eqn (10) ~~is~~ to cal-  
the reflection & Transmission coeff.

we have

$$A_1 + B_1 = A_2 \quad \text{--- (6)}$$

$$\text{(10)} \Rightarrow Z_1 (A_1 - B_1) = Z_2 (A_1 + B_1)$$

$$Z_1 A_1 - Z_1 B_1 = Z_2 A_1 + Z_2 B_1$$

$$(Z_1 - Z_2) A_1 = (Z_1 + Z_2) B_1$$

$$B_1 = \frac{(Z_1 - Z_2) A_1}{(Z_1 + Z_2)}$$

Thus the reflection coeff of amplitude

is

$$\frac{B_1}{A_1} = \frac{Z_1 - Z_2}{Z_1 + Z_2} \quad \text{--- (11)}$$



30  
Similarly from eqn (6)

$$B_1 = A_2 - A_1$$

Substit in eqn (10)

$$Z_1 (A_1 - A_2 + A_1) = Z_2 A_2$$

$$Z_1 (2A_1 - A_2) = Z_2 A_2$$

$$2Z_1 A_1 - Z_1 A_2 = Z_2 A_2$$

$$2Z_1 A_1 = (Z_1 + Z_2) A_2$$

$$\frac{A_2}{A_1} = \left( \frac{2Z_1 A_1}{Z_1 + Z_2} \right) A_1$$

Thus the transmission coeff of amplitude

$$\boxed{\frac{A_2}{A_1} = \frac{2Z_1}{Z_1 + Z_2}} \quad \text{--- (12)}$$



Thus the coeff (12) & (11) are independent of  $\omega$ . and holds Thus ratio depends only upon the ratio of impedance, Eqn (12) & (11) in terms of  $k$ .

$$Z = \frac{T}{C} = \frac{T}{\omega} K$$

in this case  $T$  &  $\omega$  are same

$$Z \propto K$$

$\therefore$

$$\frac{B_1}{A_1} = \frac{k_1 - k_2}{k_1 + k_2}$$

$$\& \frac{A_2}{A_1} = \frac{2k_1}{k_1 + k_2}$$

in terms of  $\rho$

$$T = \rho c^2 = \rho \omega^2 / k^2$$

in this case  $T$  &  $\omega$  are const.

$$\therefore K \propto \sqrt{\rho}$$

$$\frac{B_1}{A_1} = \frac{-\sqrt{\rho_1} - \sqrt{\rho_2}}{\sqrt{\rho_1} + \sqrt{\rho_2}}$$

$$\frac{A_2}{A_1} = \frac{2\sqrt{\rho_1}}{\sqrt{\rho_1} + \sqrt{\rho_2}}$$

In EM waves

$$Z = \frac{1}{n} = \frac{v}{c}$$

$$n = \frac{c}{v}$$

$n = R-I$  of medium