



STM 32 F767ZI

TOOLS SET UP AND BASIC CONCEPTS

ÁLVARO CASTRO LEITE DEC 2021





Requirements

Computer with Windows OS

Internet connection

10 Gb of free space on disk

Micro-USB cable

STM32 development board

Java Runtime Environment (JRE)



Agenda

Skill level: Beginner

Why STM32?

Choosing the IDE

What tools are needed?

ST-LINK/V2

Keil MDK-ARM

STM32CubeMX



Agenda

Skill level: Beginner

Create the first Project

Compile the program and Flash the board

Terminal

File Tree

Resources

Conclusion



Why STM32?

- 32 bits professional development board
- Cheap to buy and develop with
- Same toolchain and API through all ranges of products
- Cross compatibility
- Lots of documentation
- And much much more...



Choosing the IDE

During the course we will use the Keil ARM IDE as our main IDE. However there are other alternatives that you may consider using in the future.

The decision to use the Keil ARM IDE was made based in your past experiences, and in the well known performance achieved by those IDE.

A recent alternative for non Windows OS, is the STM32CubeIDE, if you want use that IDE, you must assume all responsibility about that. You can find a installation guide at this link: https://bit.ly/330GSHS

If you want to install the Keil continue to the next slide, if you want to install STM32CubeIDE jump to slide 26.



What tools are needed?

- ST-LINK/V2: It's a ST tool that provides capabilities to load code to the board and on-chip debug functionalities.
- STM32CubeMX: It has a graphical software configuration tool that allows the generation of C initialization code using graphical wizards. And it makes developers' lives easier by reducing development effort, time and cost.
- Keil ARM: It's an IDE that combines project management, run-time environment, build facilities, source code editing and program debugging in a single powerful environment.



ST-LINK/V2

The ST-LINK/V2 is an in-circuit debugger and programmer for the STM8 and STM32 microcontroller families. The single wire interface module (SWIM) and JTAG/serial wire debugging (SWD) interfaces are used to communicate with any STM8 or STM32 microcontroller located on an application board.

https://bit.ly/2MCx4zl



ST-LINK/V2

Get Software





ST-LINK/V2

Install it after download

If your computer has a 32 bits system use "dpint_x86.exe"

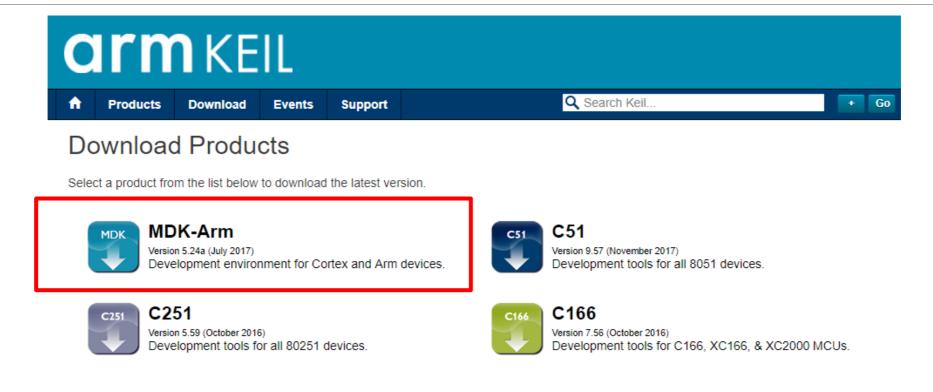
If your computer has a 64 bits system use "dpint_amd64.exe"



The MDK-ARM is a complete software development environment for Cortex[™]-M, Cortex-R4, ARM7[™] and ARM9[™] processor-based devices. MDK-ARM is specifically designed for microcontroller applications, it is easy to learn and use, yet powerful enough to deal with demanding embedded applications.

https://www.keil.com/download/product/





Keil products use a License Management system - without a current license the product runs as a Lite/Evaluation edition with a few Limitations.

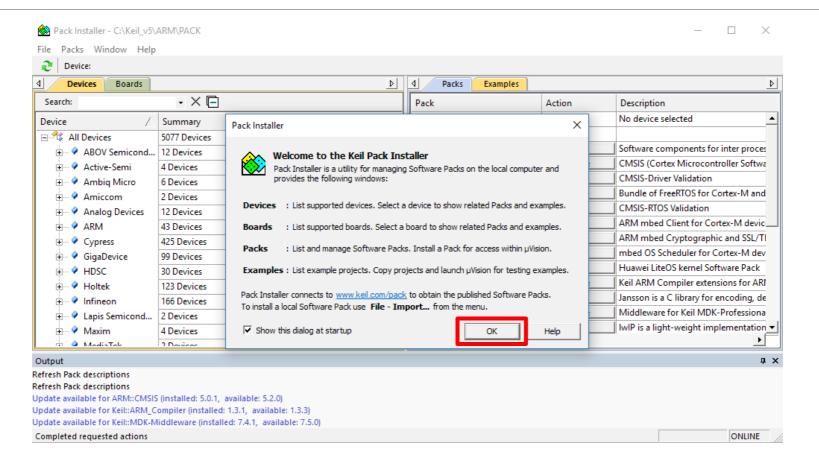


After download install it

And open Keil for the first time

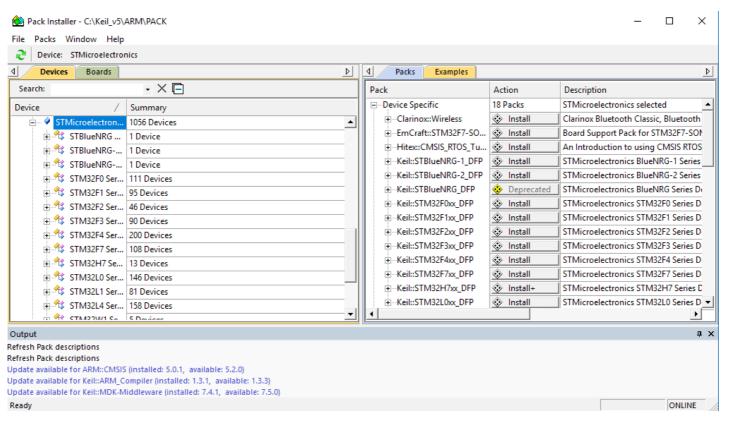






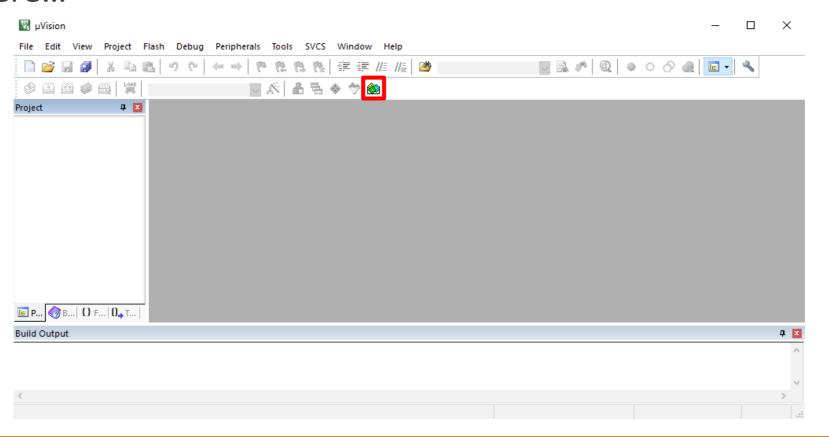


If you don't see this menu...





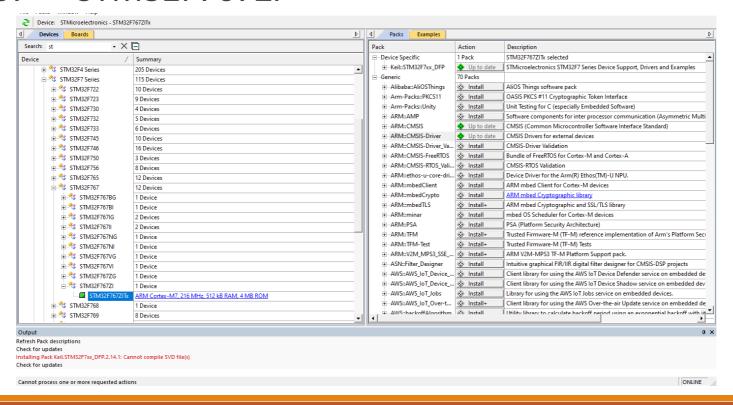
Click here...





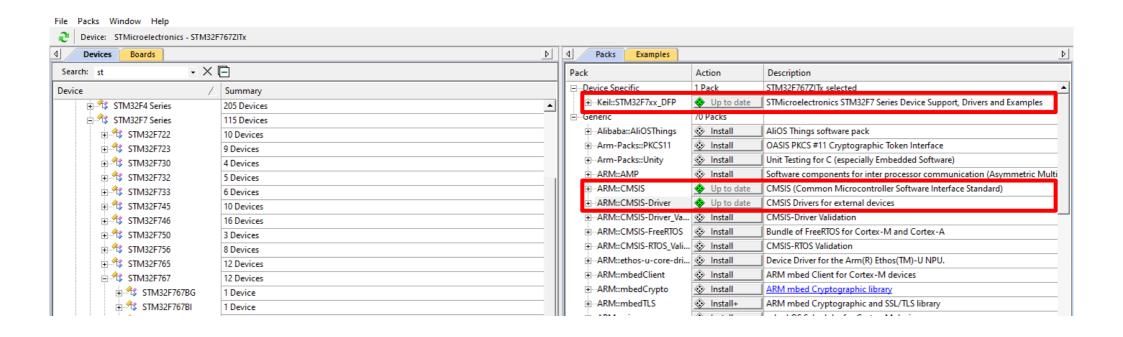
In "Device" tab select: STMicroelectronics -> STM32F7 Series -> STM32F767 -> STM32F767ZI

If you still don't see this menu wait until the update finishes





Install the following 3 packs





STM32Cube includes STM32CubeMX, a graphical software configuration tool that allows the generation of C initialization code, for STM32 microcontrollers very easily, using graphical wizards.

http://www.st.com/en/development-tools/stm32cubemx.html





Get Software



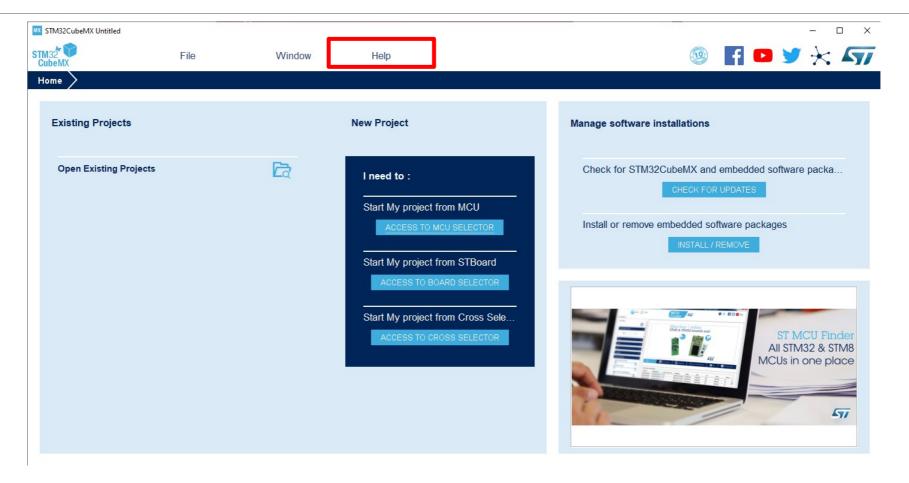


Install Cube after download

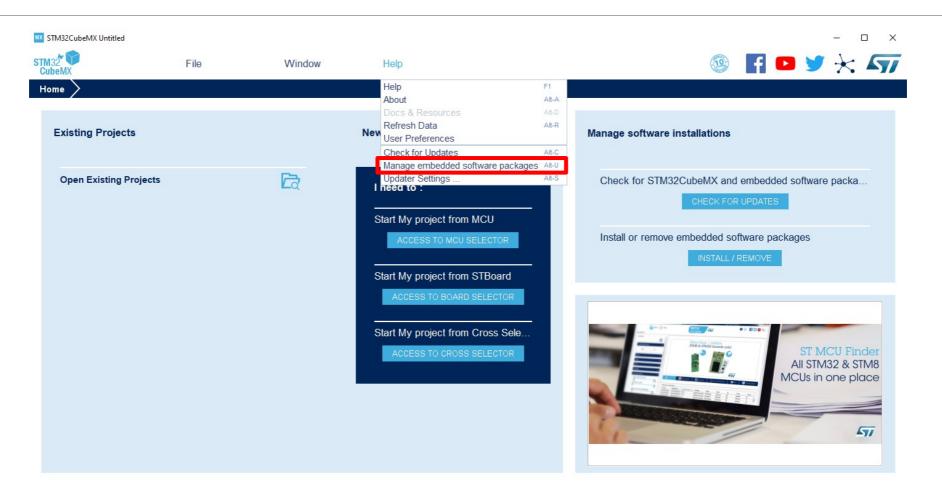
It requires Java Runtime Environment

Open STM32CubeMX when installation is finished



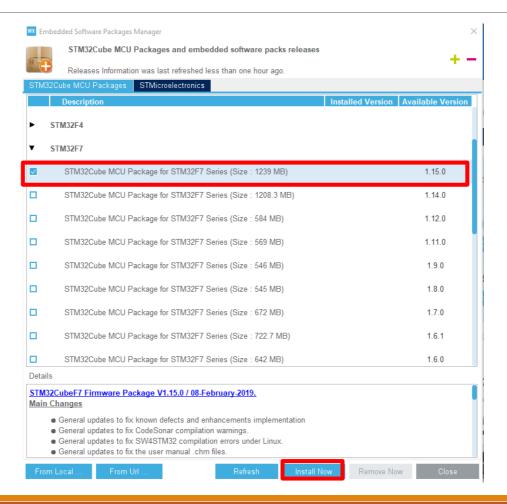








Install the latest:



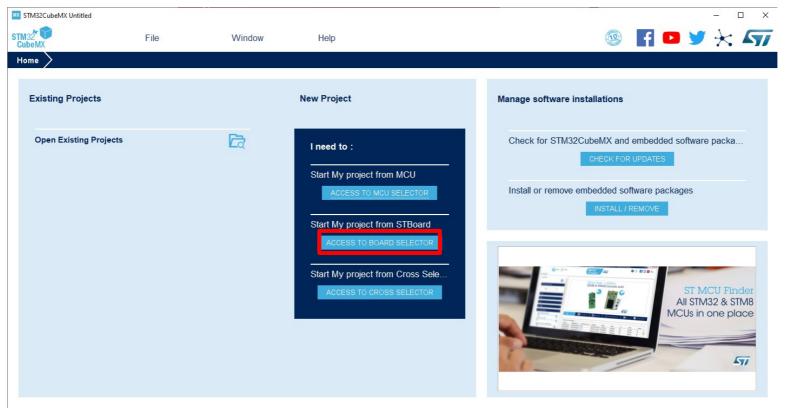
Click "Install"



And... that's it. Installation complete.

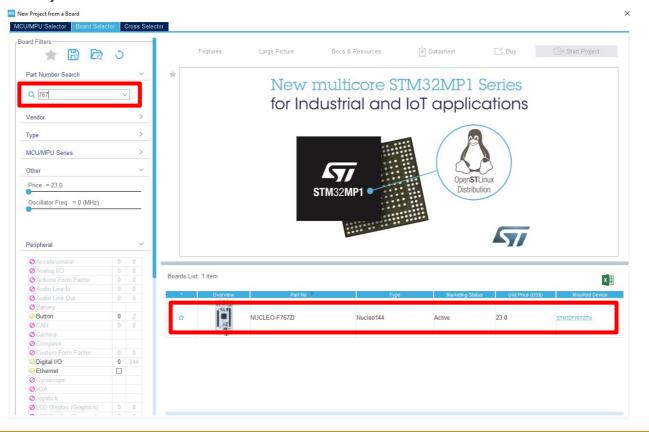


Open STM32CubeMX. Select "Access to Board Selector".



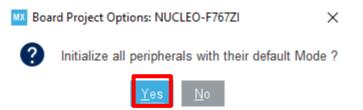


Search for "767", and double click in "Nucleo-F767ZI".



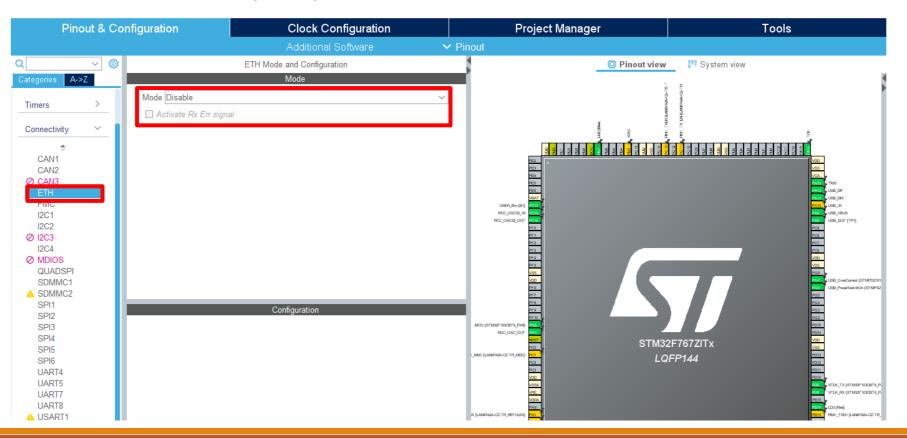


Initialize all peripherals in default mode.



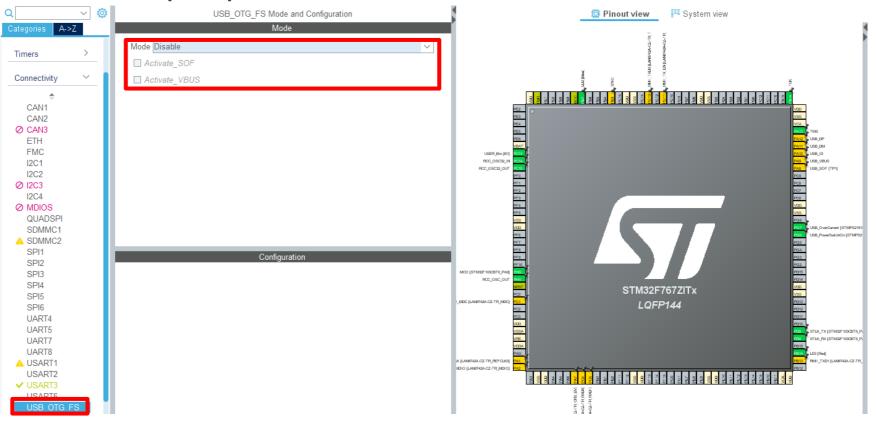


Disable the Ethernet peripheral.



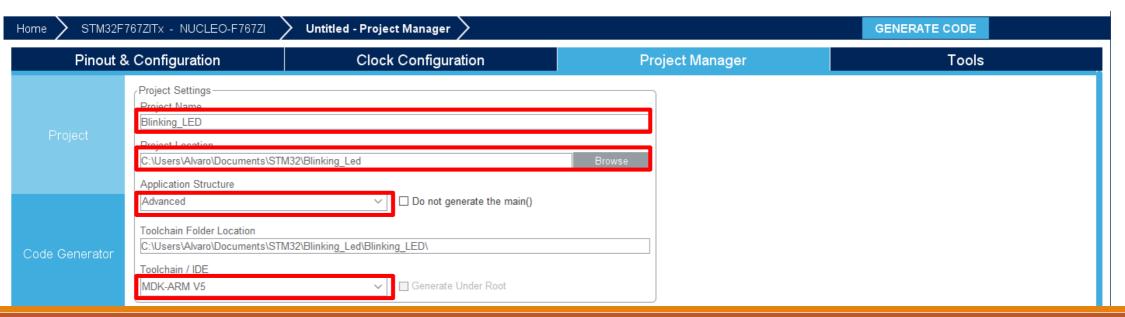


Disable the USB peripheral.





Go to "Project Manager", give a name to the project, choose the location of the project, set the structure to advanced, and set the Tollchain to "MDK-ARM V5". To avoid complications the save path mustn't have spaces or other special characters.





Under "Code Generator" select "Copy only the necessary library files", and "Generate peripheral initialization as a pair of '.c/.h' files per peripheral.

Pinout & Configuration		Clock Configuration	Project Manager	Tools
Project		ne project folder		
Code Generator	Generated files Generated files Generate peripheral initialization as a pair of '.c/.h' files per peripheral Backup previously generated files when re-generating Keep User Code when re-generating Delete previously generated files when not re-generated HAL Settings Set all free pins as analog (to optimize the power consumption) Enable Full Assert			



Generate the code.

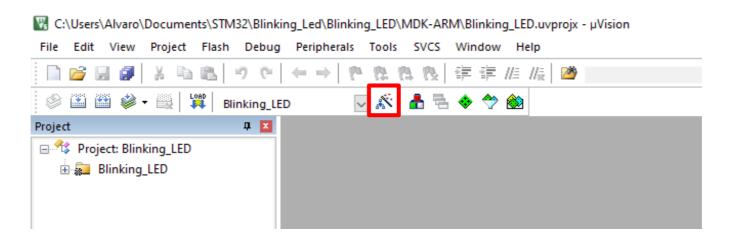


And Open the Project



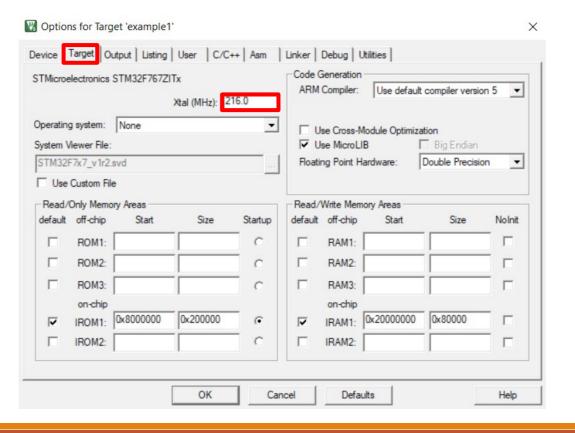


Open the settings menu.



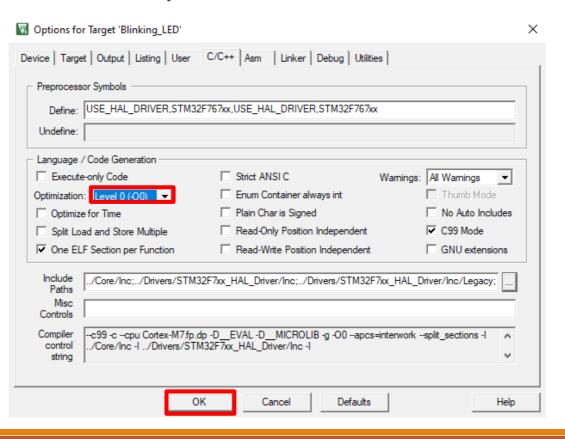


Under Outup tab, set Xtal to 216.





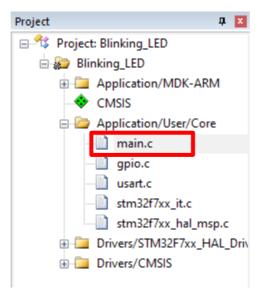
Under C/C++ tab, set the optimization level to 0.





Create the first Project

Open the main.c file





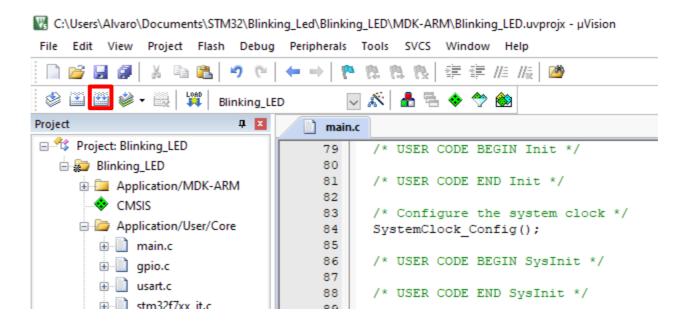
Create the first Project

Add those two lines of code at lines 101 and 102.



Compile a program

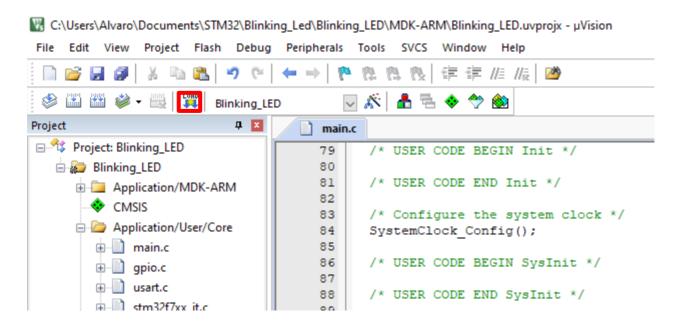
To compile all target files (this is going to take a while)





Flash the board

Connect the development board to your pc through a micro USB cable (don't use the connection next to the ethernet port)





Flash the board

When the flash is finished press the reset button on the board (black button)

The blue LED should blink at a frequency of 0,5Hz.



Terminal

A good terminal is very convenient if you want work with serial port. You can use termite or this terminal:

https://sites.google.com/site/terminalbpp/



File tree

Inside the project Directory, there are many sub directories and files, some of the most important are:

- *Drives*: where the CubeMX puts the drivers, you don't need to touch here
- *Inc*: where the user header files are, and where you should put all the header files you will create

(continues on the next page)



File tree

- MDK-ARM: where all the files for the Keil configurations and the output files of the compilation are, at this moment you only should touch the file with the extension .uvprojx (this file open the keil project)
- *Src*: where the user source files are, and where you should put all the source files you will create
- .ioc: STM32CubeMX file, contains all the Cube info for the project
- .gitignore: to specify intentionally untracked files to be ignore by git



Resources

The following slides have some documentation that you should have with you every time you are working with the development board, in order to consult some information in case of doubts.



Resources

STM32F76xxx and STM32F77xxx advanced Arm®-based https://bit.ly/2SrZbQS

Description of STM32F7 HAL and Low-layer drivers https://bit.ly/2JsqPcE

STM32CubeMX for STM32 configuration and initialization C code generation

https://bit.ly/2OXkEmM



Resources

STM32F7 Series and STM32H7 Series Cortex®-M7 processor programming manual https://bit.ly/2qiOYJC

STM32 Nucleo-144 boards https://bit.ly/2Df5i65

Getting started with STM32F7 Series MCU hardware development https://bit.ly/2StPQIj

General-purpose timer cookbook https://bit.ly/2ITtSKB



Conclusion

Now you should have all tools installed and configured.

You should know how to create a project, compile and flash the board

Good work