Discrete Variables in DGMs

Philip Schulz and Wilker Aziz

https:
//github.com/philschulz/VITutorial

 Deep Generative Models are probabilistic models where the parameters of the conditional distributions are computed by neural networks

- Deep Generative Models are probabilistic models where the parameters of the conditional distributions are computed by neural networks
- Because the ELBO cannot be computed exactly, we need to sample latent values

- Deep Generative Models are probabilistic models where the parameters of the conditional distributions are computed by neural networks
- Because the ELBO cannot be computed exactly, we need to sample latent values
- Main problem: the MC estimator is not differentiable

- Deep Generative Models are probabilistic models where the parameters of the conditional distributions are computed by neural networks
- Because the ELBO cannot be computed exactly, we need to sample latent values
- Main problem: the MC estimator is not differentiable
- ▶ Solution: reparametrisation gradient

Model Gradient

$$rac{\partial}{\partial heta} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z, heta)
ight] - rac{\partial}{\partial heta} \, \mathsf{KL} \left(q(z|\lambda) \mid\mid p(z| heta)
ight)$$

Model Gradient

$$\frac{\partial}{\partial \theta} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z,\theta) \right] - \frac{\partial}{\partial \theta} \mathsf{KL} \left(q(z|\lambda) \mid\mid p(z|\theta) \right)$$

Inference Network Gradient

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z, \theta) \right] - \frac{\partial}{\partial \lambda} \mathsf{KL} \left(q(z|\lambda) \mid\mid p(z|\theta) \right)$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z, \theta) \right]$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z,\theta) \right] = \frac{\partial}{\partial \lambda} \mathbb{E}_{\phi(\epsilon)} \left[\log p(x|\widehat{h^{-1}(\epsilon,\lambda)},\theta) \right] = 0$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} [\log p(x|z,\theta)] = \frac{\partial}{\partial \lambda} \mathbb{E}_{\phi(\epsilon)} \left[\log p(x|\widehat{h^{-1}(\epsilon,\lambda)},\theta) \right] = \mathbb{E}_{\phi(\epsilon)} \left[\frac{\partial}{\partial z} \log p(x|\widehat{h^{-1}(\epsilon,\lambda)},\theta) \times \frac{\partial}{\partial \lambda} \widehat{h^{-1}(\epsilon,\lambda)} \right]$$

Reparametrisation for Discrete Variables?

Revisiting the Inference Gradient

Control Variates and Baselines

Reparametrisation for Discrete Variables?

Revisiting the Inference Gradient

Control Variates and Baselines

Reparametrisation

In order to tranform variables, we need to compute the Jacobian (matrix of derivatives).

$$p(z) = \phi(h(z)) \left| \frac{d}{dz} h(z) \right|$$

The Jacobian is generally not available for discrete variables.

Cumulative Distribution Function

Insert picture here

Continuity

The outcome space of discrete variables is non-continuous. Thus, we cannot take derivatives with respect to real variables.

Reparametrisation for Discrete Variables?

Revisiting the Inference Gradient

Control Variates and Baselines

$$rac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z, \theta)
ight] =$$

$$rac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z,\theta) \right] = \\ rac{\partial}{\partial \lambda} \sum_{z} q(z|\lambda) \log p(x|z,\theta) =$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} [\log p(x|z,\theta)] = \\ \frac{\partial}{\partial \lambda} \sum_{z} q(z|\lambda) \log p(x|z,\theta) = \\ \sum_{z} \frac{\partial}{\partial \lambda} q(z|\lambda) \log p(x|z,\theta)$$

Back to Basic Calculus

$$\frac{d}{d\lambda}\log f(\lambda)$$

Back to Basic Calculus

$$\frac{d}{d\lambda}\log f(\lambda) = \frac{\frac{d}{d\lambda}f(\lambda)}{f(\lambda)}$$

Back to Basic Calculus

$$\frac{d}{d\lambda}\log f(\lambda) = \frac{\frac{d}{d\lambda}f(\lambda)}{f(\lambda)}$$

Consequence

$$\frac{d}{d\lambda}f(\lambda) = \frac{d}{d\lambda}\log f(\lambda) \times f(\lambda)$$

$$\frac{d}{d\lambda}f(\lambda) = \frac{d}{d\lambda}\log f(\lambda) \times f(\lambda)$$

$$\frac{d}{d\lambda}f(\lambda) = \frac{d}{d\lambda}\log f(\lambda) \times f(\lambda)$$

Apply this to the ELBO derivative.

$$\sum_{z} \frac{\partial}{\partial \lambda} q(z|\lambda) \log p(x|z,\theta) =$$

$$\frac{d}{d\lambda}f(\lambda) = \frac{d}{d\lambda}\log f(\lambda) \times f(\lambda)$$

Apply this to the ELBO derivative.

$$\sum_{z} \frac{\partial}{\partial \lambda} q(z|\lambda) \log p(x|z,\theta) =$$

$$\sum_{z} q(z|\lambda) \frac{\partial}{\partial \lambda} \log q(z|\lambda) \times \log p(x|z,\theta) =$$

$$\frac{d}{d\lambda}f(\lambda) = \frac{d}{d\lambda}\log f(\lambda) \times f(\lambda)$$

Apply this to the ELBO derivative.

$$\sum_{z} \frac{\partial}{\partial \lambda} q(z|\lambda) \log p(x|z,\theta) =$$

$$\sum_{z} q(z|\lambda) \frac{\partial}{\partial \lambda} \log q(z|\lambda) \times \log p(x|z,\theta) =$$

$$\mathbb{E}_{q(z|\lambda)} \left[\frac{\partial}{\partial \lambda} \log q(z|\lambda) imes \log p(x|z, heta)
ight]$$

Comparison Between Estimators

► Score function gradient

$$\mathbb{E}_{q(z|\lambda)}\left[rac{\partial}{\partial \lambda}\log q(z|\lambda) imes \log p(x|z, heta)
ight]$$

Reparametrisation gradient

$$\mathbb{E}_{\phi(\epsilon)} \left[\frac{\partial}{\partial \lambda} \log p(x|h^{-1}(\epsilon,\lambda),\theta) \right]$$

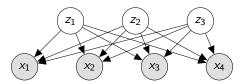
Example Model

Let us consider a latent factor model for topic modelling. Each document x consists of n i.i.d. categorical draws from that model. The categorical distribution in turn depends on the binary latent factors $z = (z_1, \ldots, z_k)$ which are also i.i.d.

$$z_j \sim \text{Bernoulli}(\phi)$$
 $(1 \le j \le k)$
 $x_i \sim \text{Categorical}(g(z))$ $(1 \le i \le n)$

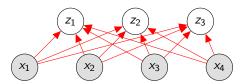
Here $g(\cdot)$ is a function computed by neural network with softmax output.

Example Model

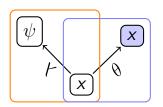


At inference time the latent variables are marginally dependent. For our variational distribution we are going to assume that they are not (recall: mean field assumption).

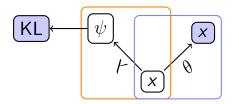
Inference Network



The inference network needs to predict k Bernoulli parameters ψ . Any neural network with sigmoid output will do that job.

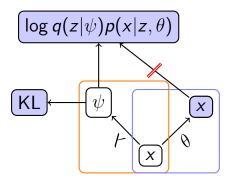


inference model

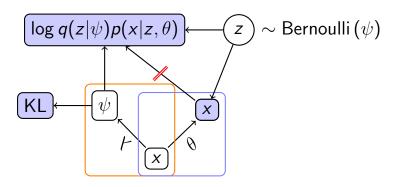


inference model





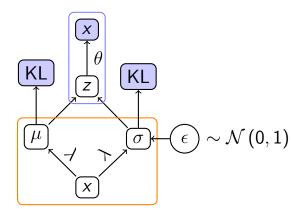
inference model



inference model

generation model

inference model



Pros and Cons

- Pros
 - Applicable to all distributions
 - Many libraries come with samplers for common distributions

Pros and Cons

- Pros
 - Applicable to all distributions
 - Many libraries come with samplers for common distributions
- Cons
 - High Variance!

Reparametrisation for Discrete Variables?

Revisiting the Inference Gradient

Control Variates and Baselines

Baselines

We attempt to centre the gradient estimate. To do this we learn a quantity C that we subtract from the reconstruction loss.

$$\log q(z|\lambda) \left(p(x|z,\theta) - C \right)$$

We call *C* a baseline. It does not change the expected gradient (Williams, 1992).

Baselines

We can make baselines input-dependent to make them more flexible.

$$\log q(z|\lambda) \left(p(x|z,\theta) - C(x) \right)$$

However, baselines may not depend on the random value z! Quantities that may depend on the random value (C(z)) are called **control variates**. See Blei et al. (2012); Ranganath et al. (2014); Gregor et al. (2014).

Baselines

Baselines are predicted by a regression model (e.g. a neural net). The model is trained using an L_2 -loss.

$$\min \left(C(x) - p(x|z,\theta)\right)^2$$

 Reparametrisation not available for discrete variables.

- Reparametrisation not available for discrete variables.
- Use score function estimator.

- Reparametrisation not available for discrete variables.
- Use score function estimator.
- High variance.

- Reparametrisation not available for discrete variables.
- Use score function estimator.
- High variance.
- Always use baselines for variance reduction!

David M. Blei, Michael I. Jordan, and John W. Paisley. Variational bayesian inference with stochastic search. In *ICML*, 2012. URL http://icml.cc/2012/papers/687.pdf.

Karol Gregor, Ivo Danihelka, Andriy Mnih, Charles Blundell, and Daan Wierstra. Deep autoregressive networks. In Eric P. Xing and Tony Jebara, editors, *ICML*, pages 1242–1250, 2014. URL http://proceedings.mlr.press/v32/gregor14.html.

Rajesh Ranganath, Sean Gerrish, and David Blei.
Black Box Variational Inference. In Samuel Kaski and Jukka Corander, editors, *AISTATS*, pages 814–822, 2014. URL http://proceedings.mlr.press/v33/ranganath14.pdf.

Ronald J. Williams. Simple statistical gradient-following algorithms for connectionist reinforcement learning. *Machine Learning*, 8(3-4): 229–256, 1992. URL https://doi.org/10.1007/BF00992696.