## Example code at: https://github.com/SuperDroidRobots/Encoder-Buffer-Breakout

counting the oposite direction you can swap A and B in that channel. Single Encoder Breakout Note: Pull up resistors solder jumpers. If you are using encoders and they Arduino Uno require pull ups resistors these need to be bridge. Unsolder if no you don't need pull up resistors Motor with encoder Pin Out: Purple: Hall Sensor B IG32, IG42, IG52 Electric Motors Blue : Hall Sensor A Brown: Hall Sensor Vcc Green: Hall Sensor GND Motor Controller Red : +Motor Black:-Motor

Note: In case encoders are

Single Encoder Breakout

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## Example code at:

Arduino Uno

https://github.com/SuperDroidRobots/Encoder-Buffer-Breakout

Motor Controller

you can swap A and B in that channel.

Dual Encoder Breakout

Note: Pull up resistors solder jumpers. If you are using encoders and they require pull ups resistors these need to be bridge. Unsolder if no you don't need pull up resistors

Motor with encoder Pin Out:

Purple: Hall Sensor B
Blue: Hall Sensor A
Brown: Hall Sensor Vcc
Green: Hall Sensor GND

Red :+Motor Black :-Motor

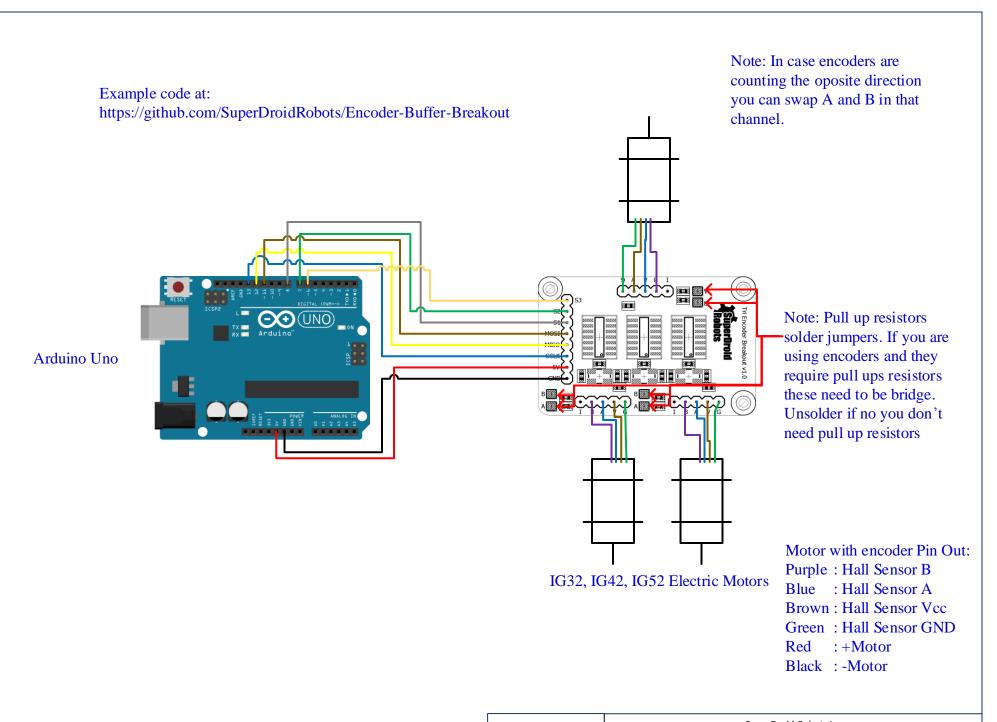


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Dual Encoder Breakout Wiring Diagram

IG32, IG42, IG52 Electric Motors

Note: In case encoders are counting the oposite direction





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