This is the k-nearest neighbors workbook for ECE C147/C247 Assignment #2

Please follow the notebook linearly to implement k-nearest neighbors.

Please print out the workbook entirely when completed.

The goal of this workbook is to give you experience with the data, training and evaluating a simple classifier, k-fold cross validation, and as a Python refresher.

Import the appropriate libraries

```
In [77]:
          import numpy as np # for doing most of our calculations
          import matplotlib.pyplot as plt# for plotting
          from utils.data_utils import load_CIFAR10 # function to load the CIFAR-10 dataset.
          # Load matplotlib images inline
          %matplotlib inline
          # These are important for reloading any code you write in external .py files.
          # see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
          %load_ext autoreload
          %autoreload 2
         The autoreload extension is already loaded. To reload it, use:
           %reload_ext autoreload
In [78]:
          # Set the path to the CIFAR-10 data
          cifar10_dir = '../cifar-10-batches-py' # You need to update this line
          X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)
          # As a sanity check, we print out the size of the training and test data.
          print('Training data shape: ', X_train.shape)
          print('Training labels shape: ', y_train.shape)
          print('Test data shape: ', X_test.shape)
          print('Test labels shape: ', y_test.shape)
         Training data shape: (50000, 32, 32, 3)
         Training labels shape: (50000,)
         Test data shape: (10000, 32, 32, 3)
         Test labels shape: (10000,)
In [79]:
          # Visualize some examples from the dataset.
          # We show a few examples of training images from each class.
          classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
          num classes = len(classes)
          samples per class = 7
          for y, cls in enumerate(classes):
              idxs = np.flatnonzero(y_train == y)
              idxs = np.random.choice(idxs, samples_per_class, replace=False)
              for i, idx in enumerate(idxs):
                  plt_idx = i * num_classes + y + 1
                  plt.subplot(samples_per_class, num_classes, plt_idx)
                  plt.imshow(X_train[idx].astype('uint8'))
                  plt.axis('off')
                  if i == 0:
                      plt.title(cls)
          plt.show()
         plane car bird cat deer dog frog horse ship truck
```

```
In [80]: # Subsample the data for more efficient code execution in this exercise
    num_training = 5000
    mask = list(range(num_training))
    X_train = X_train[mask]
    y_train = y_train[mask]

    num_test = 500
    mask = list(range(num_test))
    X_test = X_test[mask]
    y_test = y_test[mask]

# Reshape the image data into rows
    X_train = np.reshape(X_train, (X_train.shape[0], -1))
```

```
X_test = np.reshape(X_test, (X_test.shape[0], -1))
print(X_train.shape, X_test.shape)

(5000, 3072) (500, 3072)
```

K-nearest neighbors

In the following cells, you will build a KNN classifier and choose hyperparameters via k-fold cross-validation.

```
In [81]: # Import the KNN class
from nndl import KNN

In [82]: # Declare an instance of the knn class.
knn = KNN()

# Train the classifier.
# We have implemented the training of the KNN classifier.
# Look at the train function in the KNN class to see what this does.
knn.train(X=X_train, y=y_train)
```

Questions

- (1) Describe what is going on in the function knn.train().
- (2) What are the pros and cons of this training step?

Answers

- (1) We're just storing the training data (X_train and y_train) in memory
- (2) Pros Easy to implement, training process is fast as there is no processing; Cons Memory instensive, we need to store all the input data

KNN prediction

In the following sections, you will implement the functions to calculate the distances of test points to training points, and from this information, predict the class of the KNN.

```
# Implement the function compute_distances() in the KNN class.
# Do not worry about the input 'norm' for now; use the default definition of the norm
# in the code, which is the 2-norm.
# You should only have to fill out the clearly marked sections.

import time
time_start =time.time()

dists_L2 = knn.compute_distances(X=X_test)

print('Time to run code: {}'.format(time.time()-time_start))
print('Frobenius norm of L2 distances: {}'.format(np.linalg.norm(dists_L2, 'fro')))
```

Time to run code: 22.104963064193726 Frobenius norm of L2 distances: 7906696.077040902

Really slow code

Note: This probably took a while. This is because we use two for loops. We could increase the speed via vectorization, removing the for loops.

If you implemented this correctly, evaluating np.linalg.norm(dists_L2, 'fro') should return: ~7906696

KNN vectorization

The above code took far too long to run. If we wanted to optimize hyperparameters, it would be time-expensive. Thus, we will speed up the code by vectorizing it, removing the for loops.

```
In [87]: # Implement the function compute_L2_distances_vectorized() in the KNN class.
# In this function, you ought to achieve the same L2 distance but WITHOUT any for loops.
# Note, this is SPECIFIC for the L2 norm.

time_start =time.time()
    dists_L2_vectorized = knn.compute_L2_distances_vectorized(X=X_test)
    print('Time to run code: {}'.format(time.time()-time_start))
    print('Difference in L2 distances between your KNN implementations (should be 0): {}'.format(np.linalg.norm(distance))

Time to run code: 0.21875691413879395
    Difference in L2 distances between your KNN implementations (should be 0): 0.0
```

Speedup

Depending on your computer speed, you should see a 10-100x speed up from vectorization. On our computer, the vectorized form took 0.36 seconds while the naive implementation took 38.3 seconds.

Implementing the prediction

Now that we have functions to calculate the distances from a test point to given training points, we now implement the function that will predict the test point labels.

0.726

If you implemented this correctly, the error should be: 0.726.

This means that the k-nearest neighbors classifier is right 27.4% of the time, which is not great, considering that chance levels are 10%.

Optimizing KNN hyperparameters

In this section, we'll take the KNN classifier that you have constructed and perform cross-validation to choose a best value of k, as well as a best choice of norm.

Create training and validation folds

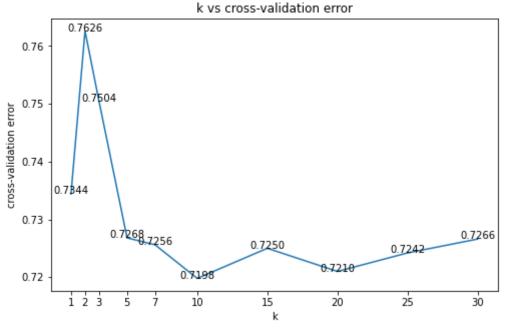
First, we will create the training and validation folds for use in k-fold cross validation.

```
In [89]:
       # Create the dataset folds for cross-valdiation.
       num folds = 5
       X train folds = []
       y_train_folds = []
       # YOUR CODE HERE:
         Split the training data into num folds (i.e., 5) folds.
         X_train_folds is a list, where X_train_folds[i] contains the
           data points in fold i.
         y train folds is also a list, where y train folds[i] contains
          the corresponding labels for the data in X_train_folds[i]
       # ----- #
       fold_size = X_train.shape[0] // num_folds
       for fold in range(num folds):
          X train folds.append(X train[fold*fold size:(fold+1)*fold size])
          y_train_folds.append(y_train[fold*fold_size:(fold+1)*fold_size])
        ______ #
       # END YOUR CODE HERE
```

Optimizing the number of nearest neighbors hyperparameter.

In this section, we select different numbers of nearest neighbors and assess which one has the lowest k-fold cross validation error.

```
errors = [0] * len(ks)
for j in range(len(ks)):
      print (ks[j])
    for i in range(len(X_train_folds)):
        X_train_ = np.concatenate(X_train_folds[:i] + X_train_folds[i+1:])
        y_train_ = np.concatenate(y_train_folds[:i] + y_train_folds[i+1:])
        knn.train(X=X_train_, y=y_train_)
        dists_L2_vectorized = knn.compute_L2_distances_vectorized(X=X_train_folds[i])
        y_pred = knn.predict_labels(dists_L2_vectorized, k=ks[j])
        errors[j] += np.mean(y_pred != y_train_folds[i])
    errors[j] /= len(X_train_folds)
# Plot
plt.figure(figsize=(8,5))
plt.title("k vs cross-validation error")
plt.xticks(ks)
plt.plot(ks, errors, label="cross-validation error")
plt.xlabel("k")
plt.ylabel("cross-validation error")
for i in range(len(ks)):
    plt.text(ks[i], errors[i], "{:.4f}".format(errors[i]), ha = 'center')
plt.show()
# END YOUR CODE HERE
print('Computation time: %.2f'%(time.time()-time_start))
```



Computation time: 26.01

Questions:

- (1) What value of k is best amongst the tested k's?
- (2) What is the cross-validation error for this value of k?

Answers:

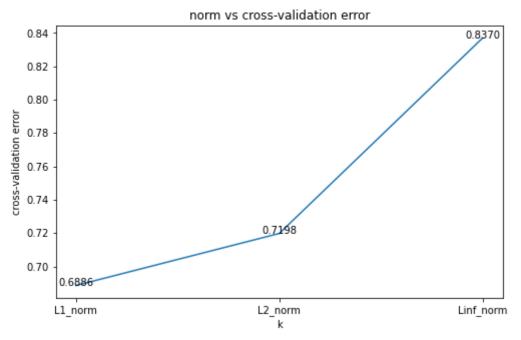
- (1) k = 10
- (2) 0.7198

Optimizing the norm

Next, we test three different norms (the 1, 2, and infinity norms) and see which distance metric results in the best cross-validation performance.

```
In [116...
         time start =time.time()
         L1_norm = lambda x: np.linalg.norm(x, ord=1)
         L2_norm = lambda x: np.linalg.norm(x, ord=2)
         Linf norm = lambda x: np.linalg.norm(x, ord= np.inf)
         norms = [L1_norm, L2_norm, Linf_norm]
         # ----- #
         # YOUR CODE HERE:
         # Calculate the cross-validation error for each norm in norms, testing
            the trained model on each of the 5 folds. Average these errors
            together and make a plot of the norm used vs the cross-validation error
            Use the best cross-validation k from the previous part.
            Feel free to use the compute_distances function. We're testing just
            three norms, but be advised that this could still take some time.
            You're welcome to write a vectorized form of the L1- and Linf- norms
         # to speed this up, but it is not necessary.
         errors = [0] * len(norms)
```

```
for j in range(len(norms)):
    for i in range(len(X_train_folds)):
        X_train_ = np.concatenate(X_train_folds[:i] + X_train_folds[i+1:])
        y_train_ = np.concatenate(y_train_folds[:i] + y_train_folds[i+1:])
        knn.train(X=X_train_, y=y_train_)
        dists = knn.compute_distances(X=X_train_folds[i], norm=norms[j])
        y_pred = knn.predict_labels(dists, k=10)
        errors[j] += np.mean(y_pred != y_train_folds[i])
    errors[j] /= len(X_train_folds)
# Plot
plt.figure(figsize=(8,5))
plt.title("norm vs cross-validation error")
plt.xticks(np.arange(3), ['L1_norm', 'L2_norm', 'Linf_norm'])
plt.plot(range(len(norms)), errors, label="cross-validation error")
plt.xlabel("k")
plt.ylabel("cross-validation error")
for i in range(len(norms)):
    plt.text(i, errors[i], "{:.4f}".format(errors[i]), ha = 'center')
plt.show()
# END YOUR CODE HERE
print('Computation time: %.2f'%(time.time()-time_start))
```



Computation time: 461.55

Questions:

- (1) What norm has the best cross-validation error?
- (2) What is the cross-validation error for your given norm and k?

Answers:

- (1) L1 norm
- (2) 0.6886

Evaluating the model on the testing dataset.

Now, given the optimal k and norm you found in earlier parts, evaluate the testing error of the k-nearest neighbors model.

Error rate achieved: 0.722

Question:

How much did your error improve by cross-validation over naively choosing k=1 and using the L2-norm?

Answer:

0.004

In []:

```
In [ ]:
       import numpy as np
       import pdb
       class KNN(object):
         def __init__(self):
           pass
         def train(self, X, y):
           0.00
           Inputs:
           - X is a numpy array of size (num_examples, D)
           - y is a numpy array of size (num_examples, )
           self.X_train = X
           self.y_train = y
         def compute_distances(self, X, norm=None):
           Compute the distance between each test point in X and each training point
           in self.X_train.
           Inputs:
           - X: A numpy array of shape (num_test, D) containing test data.
           - norm: the function with which the norm is taken.
           Returns:
           - dists: A numpy array of shape (num_test, num_train) where dists[i, j]
            is the Euclidean distance between the ith test point and the jth training
           if norm is None:
            norm = lambda x: np.sqrt(np.sum(x**2))
            \#norm = 2
           num test = X.shape[0]
           num_train = self.X_train.shape[0]
           dists = np.zeros((num_test, num_train))
           for i in np.arange(num test):
            for j in np.arange(num_train):
              # YOUR CODE HERE:
              # Compute the distance between the ith test point and the jth
              # training point using norm(), and store the result in dists[i, j].
              # ============== #
              dists[i, j] = norm(X[i] - self.X_train[j])
              # ------ #
              # END YOUR CODE HERE
              # ----- #
           return dists
         def compute_L2_distances_vectorized(self, X):
           Compute the distance between each test point in X and each training point
           in self.X_train WITHOUT using any for loops.
           Inputs:
           - X: A numpy array of shape (num_test, D) containing test data.
           - dists: A numpy array of shape (num test, num train) where dists[i, j]
            is the Euclidean distance between the ith test point and the jth training
           num test = X.shape[0]
           num_train = self.X_train.shape[0]
           dists = np.zeros((num_test, num_train))
           # ----- #
           # YOUR CODE HERE:
             Compute the L2 distance between the ith test point and the jth
             training point and store the result in dists[i, j]. You may
           # NOT use a for loop (or list comprehension). You may only use
              numpy operations.
           # HINT: use broadcasting. If you have a shape (N,1) array and
              a shape (M,) array, adding them together produces a shape (N, M)
           X_norm = np.sum(np.square(X), axis=1)
           X_norm = X_norm.reshape(X_norm.shape[0], 1)
           X_train_norm = np.sum(np.square(self.X_train), axis=1)
           X_dot_X_train = X @ (self.X_train).T
           dists = np.sqrt(X_norm + X_train_norm - 2*X_dot_X_train)
```

```
# END YOUR CODE HERE
 return dists
def predict_labels(self, dists, k=1):
 Given a matrix of distances between test points and training points,
 predict a label for each test point.
 Inputs:
 - dists: A numpy array of shape (num_test, num_train) where dists[i, j]
  gives the distance betwen the ith test point and the jth training point.
 Returns:
 - y: A numpy array of shape (num_test,) containing predicted labels for the
  test data, where y[i] is the predicted label for the test point X[i].
 num_test = dists.shape[0]
 y_pred = np.zeros(num_test)
 for i in np.arange(num_test):
  # A list of length k storing the labels of the k nearest neighbors to
  # the ith test point.
  closest_y = []
   # YOUR CODE HERE:
   # Use the distances to calculate and then store the labels of
   # the k-nearest neighbors to the ith test point. The function
   # numpy.argsort may be useful.
   # After doing this, find the most common label of the k-nearest
   # neighbors. Store the predicted label of the ith training example
   # as y_pred[i]. Break ties by choosing the smaller label.
   # ------ #
   sortedIdxs = np.argsort(dists[i])
   closest_y = self.y_train[sortedIdxs[:k]]
   y_pred[i] = np.argmax(np.bincount(closest_y))
   # END YOUR CODE HERE
   # ----- #
 return y_pred
```

Saturday, January 22, 2022 7:35 PM

Samples:
$$(x^{(i)}, y^{(i)})$$
,, $(x^{(i)}, y^{(i)})$
 $x^{(i)} \in \mathbb{R}^n$
 $y^{(i)} \in \{1, ..., c\}$

Model:
$$P_{r}(y^{(i)} = i \mid x^{(i)}, \theta) = Softmax(x^{(i)})$$

$$= e^{\omega_{i}T_{x}\omega_{x}} + b:$$

$$\sum_{k=1}^{C} e^{\omega_{k}T_{x}\omega_{x}} + b_{x}$$

Hence to get the optimum for ameters, we need to maximise the by likelihood

$$mor f(0) = min - f(0)$$

A Our loss function is negative of log heldhood

$$\mathcal{L} = \frac{1}{m} \sum_{j=1}^{m} \log \left[\frac{e^{aja} (x^{(i)})}{\sum_{i \in a_{m}} (x^{(i)})} \right]$$

$$\mathcal{L}_{i} = \log \left[\frac{e^{aja} (x^{(i)})}{\sum_{i \in a_{m}} (x^{(i)})} \right] = \left[aja (x^{(i)}) - \log \sum_{i \in a_{m}} (x^{(i)}) \right]$$

$$\text{Let :}$$

$$\int_{0}^{\infty} \left(x^{(i)}\right) = \frac{e^{a_{i}^{y}}(x^{(i)})}{\sum_{k=1}^{\infty} e^{a_{k}(x^{(i)})}}$$

Using:
$$\left[\frac{g(x)}{g(x)}\right]' = \left[\frac{g(x)f'(x)}{g(x)f'(x)} - f(x)\frac{g''(x)}{g(x)}\right]^2$$

veget,

$$\frac{\partial \sigma_{y}(i) (\chi^{(i)})}{\partial \alpha_{i} (\chi^{(i)})} = \begin{cases}
\frac{e}{\sum_{k=1}^{n} e^{\alpha_{k} (\chi^{(i)})} e^{\alpha_{j}(i)} (\chi^{(i)})}{e^{\alpha_{j}(i)} (\chi^{(i)})} - e^{\alpha_{k} (\chi^{(i)})} \\
\frac{e}{e^{\alpha_{k} (\chi^{(i)})}} e^{\alpha_{k} (\chi^{(i)})}
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using whain Rule:

$$\frac{\partial di}{\partial \alpha_{i}(x^{(i)})} = \frac{\partial \partial [\sigma_{i}(x^{(i)}(x^{(i)})]}{\partial \alpha_{i}$$

Now:

$$\frac{\partial \dot{d}_{i}}{\partial \omega_{i}} = \frac{\partial \log \left(\sqrt{\omega} \cdot (\sqrt{\omega}) \right)}{\partial \omega_{i}} = \frac{\partial \log \left(\sqrt{\omega} \cdot (\sqrt{\omega}) \cdot (\sqrt{\omega}) \right)}{\partial \omega_{i}} = \frac{\partial \log \left(\sqrt{\omega} \cdot (\sqrt{\omega}) \cdot (\sqrt{\omega})}{\partial \omega_{i}} = \frac{\partial \log \left(\sqrt{\omega} \cdot (\sqrt{\omega}) \cdot (\sqrt$$

$$= \frac{1}{2} \frac{\log \left(\sqrt{(x^{(i)})} \right)}{\log \left(\sqrt{(x^{(i)})} \right)} \frac{1}{2} \frac{\sqrt{(x^{(i)})}}{\sqrt{(x^{(i)})}} \times^{(i)}$$

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$$= \frac{1}{2} \frac{\log \left(\sqrt{(x^{(i)})} \right)}{\log \left(\sqrt{(x^{(i)})} \right)} \times^{(i)}$$

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$$\frac{\partial di}{\partial b} = \frac{\partial b g [g \dot{u} (x \dot{u})]}{\partial b} = \frac{\partial b g [g \dot{u} (x \dot{u})]}{\partial b} \frac{\partial b g [g$$

This is the softmax workbook for ECE C147/C247 Assignment #2

Please follow the notebook linearly to implement a softmax classifier.

Please print out the workbook entirely when completed.

The goal of this workbook is to give you experience with training a softmax classifier.

```
In [201...
          import random
          import numpy as np
          from utils.data utils import load CIFAR10
          import matplotlib.pyplot as plt
          %matplotlib inline
          %load ext autoreload
          %autoreload 2
         The autoreload extension is already loaded. To reload it, use:
           %reload_ext autoreload
In [202...
          def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000, num_dev=500):
              Load the CIFAR-10 dataset from disk and perform preprocessing to prepare
              it for the linear classifier. These are the same steps as we used for the
              SVM, but condensed to a single function.
              # Load the raw CIFAR-10 data
              cifar10_dir = '../cifar-10-batches-py' # You need to update this line
              X_train, y_train, X_test, y_test = load_CIFAR10(cifar10 dir)
              # subsample the data
              mask = list(range(num_training, num_training + num_validation))
              X_val = X_train[mask]
              y_val = y_train[mask]
              mask = list(range(num training))
              X_train = X_train[mask]
              y_train = y_train[mask]
              mask = list(range(num test))
              X_test = X_test[mask]
              y test = y test[mask]
              mask = np.random.choice(num_training, num_dev, replace=False)
              X_dev = X_train[mask]
              y_dev = y_train[mask]
              # Preprocessing: reshape the image data into rows
              X train = np.reshape(X_train, (X_train.shape[0], -1))
              X_val = np.reshape(X_val, (X_val.shape[0], -1))
              X_test = np.reshape(X_test, (X_test.shape[0], -1))
              X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))
              # Normalize the data: subtract the mean image
              mean_image = np.mean(X_train, axis = 0)
              X_train -= mean_image
              X_val -= mean_image
              X test -= mean image
              X dev -= mean image
              # add bias dimension and transform into columns
              X train = np.hstack([X train, np.ones((X_train.shape[0], 1))])
              X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
              X test = np.hstack([X test, np.ones((X test.shape[0], 1))])
              X dev = np.hstack([X dev, np.ones((X dev.shape[0], 1))])
              return X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev
          # Invoke the above function to get our data.
          X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev = get_CIFAR10_data()
          print('Train data shape: ', X_train.shape)
          print('Train labels shape: ', y_train.shape)
          print('Validation data shape: ', X_val.shape)
          print('Validation labels shape: ', y_val.shape)
          print('Test data shape: ', X_test.shape)
          print('Test labels shape: ', y_test.shape)
          print('dev data shape: ', X_dev.shape)
          print('dev labels shape: ', y_dev.shape)
         Train data shape: (49000, 3073)
         Train labels shape: (49000,)
         Validation data shape: (1000, 3073)
         Validation labels shape: (1000,)
         Test data shape: (1000, 3073)
         Test labels shape: (1000,)
         dev data shape: (500, 3073)
         dev labels shape: (500,)
```

Training a softmax classifier.

The following cells will take you through building a softmax classifier. You will implement its loss function, then subsequently train it with gradient descent. Finally, you will choose the learning rate of gradient descent to optimize its classification performance.

```
from nndl import Softmax

In [204...  # Declare an instance of the Softmax class.
    # Weights are initialized to a random value.
    # Note, to keep people's first solutions consistent, we are going to use a random seed.

np.random.seed(1)

num_classes = len(np.unique(y_train))
num_features = X_train.shape[1]

softmax = Softmax(dims=[num_classes, num_features])
```

Softmax loss

```
In [205... ## Implement the loss function of the softmax using a for loop over
# the number of examples
loss = softmax.loss(X_train, y_train)
In [206... print(loss)
```

Question:

2.327760702804897

You'll notice the loss returned by the softmax is about 2.3 (if implemented correctly). Why does this make sense?

Answer:

Initially all weights are close to 0 (0.0001) so e^w becomes 1; Sofmax becomes 1/10; and -log(softmax) becomes 2.3. In loss we're taking a mean of for all examples, which are 2.3. Hence the average loss is 2.3

Softmax gradient

```
In [207...
         ## Calculate the gradient of the softmax loss in the Softmax class.
          # For convenience, we'll write one function that computes the loss
          # and gradient together, softmax.loss_and_grad(X, y)
          # You may copy and paste your loss code from softmax.loss() here, and then
             use the appropriate intermediate values to calculate the gradient.
          loss, grad = softmax.loss_and_grad(X_dev,y_dev)
          # Compare your gradient to a gradient check we wrote.
          # You should see relative gradient errors on the order of 1e-07 or less if you implemented the gradient correct
          softmax.grad_check_sparse(X_dev, y_dev, grad)
         numerical: 0.394800 analytic: 0.394800, relative error: 3.192154e-08
         numerical: -0.559981 analytic: -0.559981, relative error: 8.947427e-10
         numerical: -1.673186 analytic: -1.673186, relative error: 1.066596e-08
         numerical: 1.881785 analytic: 1.881785, relative error: 3.070772e-10
         numerical: 0.921359 analytic: 0.921359, relative error: 3.323017e-08
         numerical: 1.654556 analytic: 1.654556, relative error: 5.940917e-09
         numerical: -0.069415 analytic: -0.069415, relative error: 2.468808e-07
         numerical: -0.658161 analytic: -0.658161, relative error: 4.087038e-09
         numerical: 1.061699 analytic: 1.061699, relative error: 2.079294e-08
         numerical: -3.228319 analytic: -3.228319, relative error: 1.398503e-08
```

A vectorized version of Softmax

To speed things up, we will vectorize the loss and gradient calculations. This will be helpful for stochastic gradient descent.

```
In [208...
          import time
In [211...
          ## Implement softmax.fast_loss_and_grad which calculates the loss and gradient
               WITHOUT using any for loops.
          # Standard loss and gradient
          tic = time.time()
          loss, grad = softmax.loss_and_grad(X_dev, y_dev)
          toc = time.time()
          print('Normal loss / grad_norm: {} / {} computed in {}s'.format(loss, np.linalg.norm(grad, 'fro'), toc - tic))
          tic = time.time()
          loss_vectorized, grad_vectorized = softmax.fast_loss_and_grad(X_dev, y_dev)
          toc = time.time()
          print('Vectorized loss / grad: {} / {} computed in {}s'.format(loss_vectorized, np.linalg.norm(grad_vectorized,
          # The losses should match but your vectorized implementation should be much faster.
          print('difference in loss / grad: {} /{} '.format(loss - loss_vectorized, np.linalg.norm(grad - grad_vectorized
          # You should notice a speedup with the same output.
```

Normal loss / grad_norm: 2.3312721708461672 / 384.9360658044393 computed in 0.056385040283203125s

Stochastic gradient descent

We now implement stochastic gradient descent. This uses the same principles of gradient descent we discussed in class, however, it calculates the gradient by only using examples from a subset of the training set (so each gradient calculation is faster).

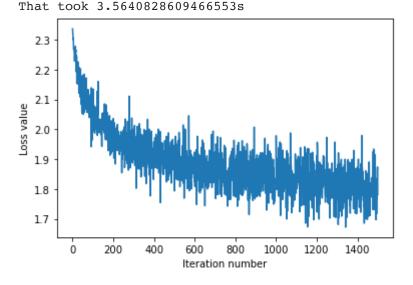
Question:

How should the softmax gradient descent training step differ from the svm training step, if at all?

Answer:

In SVM, we have a different loss function compared to softmax. So gradient calculation will change but gradient decent will remain same

```
In [212...
          # Implement softmax.train() by filling in the code to extract a batch of data
          # and perform the gradient step.
          import time
          tic = time.time()
          loss_hist = softmax.train(X_train, y_train, learning_rate=1e-7,
                                num_iters=1500, verbose=True)
          toc = time.time()
          print('That took {}s'.format(toc - tic))
          plt.plot(loss_hist)
          plt.xlabel('Iteration number')
          plt.ylabel('Loss value')
          plt.show()
         iteration 0 / 1500: loss 2.3365926606637544
         iteration 100 / 1500: loss 2.0557222613850827
         iteration 200 / 1500: loss 2.0357745120662813
         iteration 300 / 1500: loss 1.9813348165609888
         iteration 400 / 1500: loss 1.9583142443981612
         iteration 500 / 1500: loss 1.8622653073541355
         iteration 600 / 1500: loss 1.853261145435938
         iteration 700 / 1500: loss 1.8353062223725827
         iteration 800 / 1500: loss 1.829389246882764
         iteration 900 / 1500: loss 1.8992158530357484
         iteration 1000 / 1500: loss 1.97835035402523
```



iteration 1100 / 1500: loss 1.8470797913532633
iteration 1200 / 1500: loss 1.8411450268664082
iteration 1300 / 1500: loss 1.7910402495792102
iteration 1400 / 1500: loss 1.8705803029382257

Evaluate the performance of the trained softmax classifier on the validation data.

```
## Implement softmax.predict() and use it to compute the training and testing error.

y_train_pred = softmax.predict(X_train)
print('training accuracy: {}'.format(np.mean(np.equal(y_train,y_train_pred), )))
y_val_pred = softmax.predict(X_val)
print('validation accuracy: {}'.format(np.mean(np.equal(y_val, y_val_pred)), ))

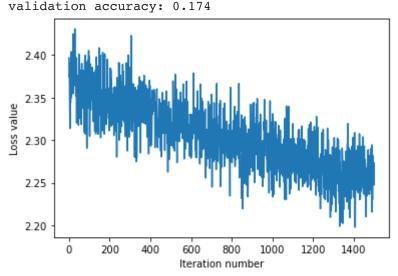
training accuracy: 0.3811428571428571
validation accuracy: 0.398
```

Optimize the softmax classifier

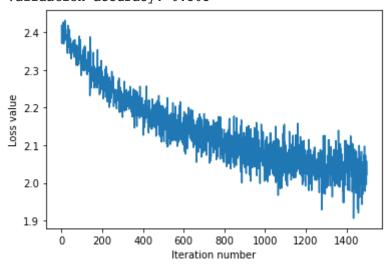
You may copy and paste your optimization code from the SVM here.

```
# YOUR CODE HERE:
   Train the Softmax classifier with different learning rates and
     evaluate on the validation data.
     - The best learning rate of the ones you tested.
     - The best validation accuracy corresponding to the best validation error.
   Select the SVM that achieved the best validation error and report
    its error rate on the test set.
learning_rates = [1e-9, 1e-8, 5e-7, 2e-7, 1e-7, 8e-6, 5e-6, 1e-6, 1e-5]
validation_accuracies = []
for learning_rate in learning_rates:
   tic = time.time()
   loss_hist = softmax.train(X_train, y_train, learning_rate=learning_rate,
                        num_iters=1500, verbose=False)
   toc = time.time()
   print('That took {}s'.format(toc - tic))
   y_train_pred = softmax.predict(X_train)
   print('training accuracy: {}'.format(np.mean(np.equal(y_train,y_train_pred), )))
   y_val_pred = softmax.predict(X_val)
   print('validation accuracy: {}'.format(np.mean(np.equal(y_val, y_val_pred)), ))
   validation_accuracies.append(np.mean(np.equal(y_val, y_val_pred)))
   plt.plot(loss_hist)
   plt.xlabel('Iteration number')
   plt.ylabel('Loss value')
   plt.show()
best_learning_rate = learning_rates[np.argmax(validation_accuracies)]
best_validation_accuracy = np.max(validation_accuracies)
print('best validation accuracy: {}'.format(best_validation_accuracy))
print('best validation error: {}'.format(1-best_validation_accuracy))
print('best learning rate: {}'.format(best_learning_rate))
loss_hist = softmax.train(X_train, y_train, learning_rate=best_learning_rate,
                        num iters=1500, verbose=False)
y_test_pred = softmax.predict(X_test)
print('test accuracy: {}'.format(np.mean(np.equal(y_test, y_test_pred)), ))
print('test error: {}'.format(1-np.mean(np.equal(y_test, y_test_pred)), ))
# END YOUR CODE HERE
```

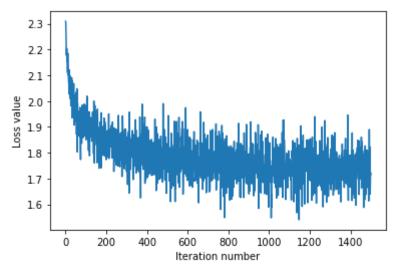
That took 5.370471000671387s training accuracy: 0.15177551020408164



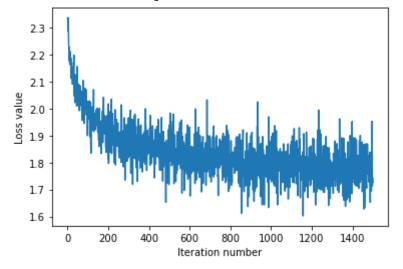
That took 2.529613971710205s training accuracy: 0.2861020408163265 validation accuracy: 0.303



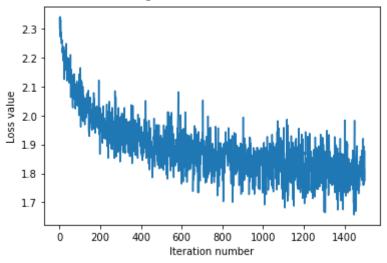
That took 2.3880419731140137s training accuracy: 0.4126326530612245 validation accuracy: 0.42



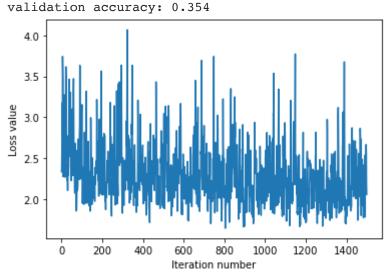
That took 2.314687967300415s training accuracy: 0.39516326530612245 validation accuracy: 0.399



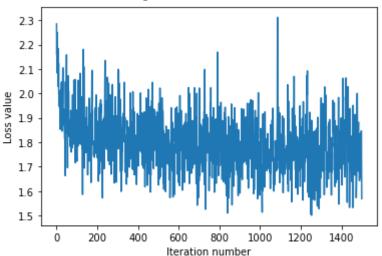
That took 2.2825448513031006s training accuracy: 0.3826530612244898 validation accuracy: 0.389



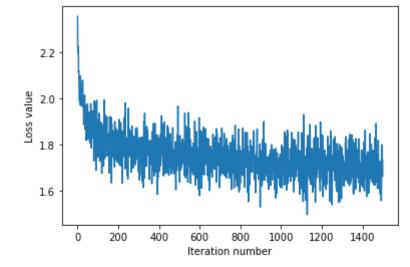
That took 6.018434047698975s training accuracy: 0.37620408163265306



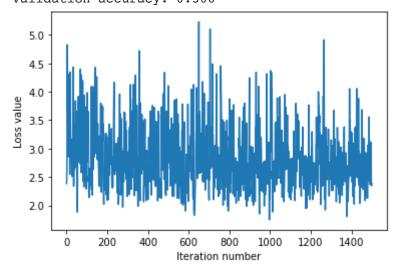
That took 2.9429879188537598s training accuracy: 0.41459183673469385 validation accuracy: 0.39



That took 3.5817999839782715s training accuracy: 0.42136734693877553 validation accuracy: 0.407



That took 4.134116172790527s training accuracy: 0.3256734693877551 validation accuracy: 0.306



best validation accuracy: 0.42

best validation error: 0.5800000000000001

best learning rate: 5e-07 test accuracy: 0.393 test error: 0.607

```
In [ ]:
            import numpy as np
         3
            class Softmax(object):
          4
         5
         6
              def __init__(self, dims=[10, 3073]):
                self.init_weights(dims=dims)
         7
         8
         9
              def init_weights(self, dims):
        10
                Initializes the weight matrix of the Softmax classifier.
        11
                Note that it has shape (C, D) where C is the number of
        12
        13
                classes and D is the feature size.
        14
        15
                self.W = np.random.normal(size=dims) * 0.0001
        16
        17
              def loss(self, X, y):
        18
        19
                Calculates the softmax loss.
        20
        21
                Inputs have dimension D, there are C classes, and we operate on minibatches
        22
                of N examples.
        23
                Inputs:
        24
        25
                - X: A numpy array of shape (N, D) containing a minibatch of data.
                - y: A numpy array of shape (N,) containing training labels; y[i] = c means
        26
        27
                  that X[i] has label c, where 0 <= c < C.
        28
        29
                Returns a tuple of:
        30
                - loss as single float
        31
        32
                # Initialize the loss to zero.
        33
        34
                loss = 0.0
        35
                36
        37
                # YOUR CODE HERE:
        38
                # Calculate the normalized softmax loss. Store it as the variable loss.
        39
                   (That is, calculate the sum of the losses of all the training
                # set margins, and then normalize the loss by the number of
        40
        41
                # training examples.)
        42
        43
        44
                m = X.shape[0]
        45
                for j in range(m):
        46
                  z = self.W @ X[j]
        47
                  e_x = np.exp(z - np.max(z))
        48
                  softmax = e_x / np.sum(e_x)
                  loss += -np.log(softmax[y[j]])
        49
        50
                loss /= m
        51
        52
                53
                # END YOUR CODE HERE
        54
        55
        56
                return loss
        57
              def loss_and_grad(self, X, y):
        58
        59
                Same as self.loss(X, y), except that it also returns the gradient.
        60
        61
        62
                Output: grad -- a matrix of the same dimensions as W containing
        63
                 the gradient of the loss with respect to W.
        64
        65
        66
                # Initialize the loss and gradient to zero.
        67
                loss = 0.0
                grad = np.zeros_like(self.W)
         68
        69
        70
        71
                # YOUR CODE HERE:
        72
                # Calculate the softmax loss and the gradient. Store the gradient
        73
                # as the variable grad.
        74
        75
                m = X.shape[0]
        76
                for j in range(m):
                  z = self.W @ X[j]
        77
        78
                  e_x = np.exp(z - np.max(z))
        79
                  softmax = e_x / np.sum(e_x)
        80
                  loss += -np.log(softmax[y[j]])
        81
        82
                  for i in range(len(softmax)):
        83
                    if (y[j] == i):
                     grad[i] += -(1-softmax[i]) * X[j]
        84
        85
        86
                      grad[i] += softmax[i] * X[j]
        87
        88
                loss /= m
                grad /= m
        89
        90
```

```
91
        92
        # END YOUR CODE HERE
        93
 94
 95
        return loss, grad
 96
      def grad_check_sparse(self, X, y, your_grad, num_checks=10, h=1e-5):
 97
 98
 99
        sample a few random elements and only return numerical
100
        in these dimensions.
101
102
103
        for i in np.arange(num_checks):
          ix = tuple([np.random.randint(m) for m in self.W.shape])
104
105
          oldval = self.W[ix]
106
          self.W[ix] = oldval + h # increment by h
107
          fxph = self.loss(X, y)
108
109
          self.W[ix] = oldval - h # decrement by h
110
          fxmh = self.loss(X,y) # evaluate f(x - h)
111
          self.W[ix] = oldval # reset
112
113
          grad_numerical = (fxph - fxmh) / (2 * h)
114
          grad_analytic = your_grad[ix]
          rel_error = abs(grad_numerical - grad_analytic) / (abs(grad_numerical) + abs(grad_analytic))
115
116
          print('numerical: %f analytic: %f, relative error: %e' % (grad_numerical, grad_analytic, rel_
117
118
      def fast_loss_and_grad(self, X, y):
119
120
        A vectorized implementation of loss and grad. It shares the same
        inputs and ouptuts as loss and grad.
121
122
        loss = 0.0
123
124
        grad = np.zeros(self.W.shape) # initialize the gradient as zero
125
        126
127
        # YOUR CODE HERE:
        # Calculate the softmax loss and gradient WITHOUT any for loops.
128
129
130
131
        z = X @ self.W.T
        \max z = np.\max(z, axis=1, keepdims=True)
132
133
        e_x = np.exp(z - max_z)
134
        e_x_sum = np.sum(e_x, axis=1, keepdims=True)
135
        softmax = e_x / e_x_sum
136
        loss = -np.log(np.choose(y, softmax.T))
137
        loss = np.mean(loss)
138
139
140
        softmax[np.arange(X.shape[0]),y] -= 1
141
        grad += (X.T @ softmax).T
142
        grad /= X.shape[0]
143
144
145
146
        147
        # END YOUR CODE HERE
148
149
150
        return loss, grad
151
152
      def train(self, X, y, learning_rate=1e-3, num_iters=100,
153
               batch_size=200, verbose=False):
154
155
        Train this linear classifier using stochastic gradient descent.
156
157
        Inputs:
        - X: A numpy array of shape (N, D) containing training data; there are N
158
159
          training samples each of dimension D.
160
        - y: A numpy array of shape (N,) containing training labels; y[i] = c
          means that X[i] has label 0 <= c < C for C classes.
161
        - learning_rate: (float) learning rate for optimization.
162
        - num_iters: (integer) number of steps to take when optimizing
163
        - batch size: (integer) number of training examples to use at each step.
164
165
        - verbose: (boolean) If true, print progress during optimization.
166
167
        Outputs:
168
        A list containing the value of the loss function at each training iteration.
169
170
        num train, dim = X.shape
        num_classes = np.max(y) + 1 # assume y takes values 0...K-1 where K is number of classes
171
172
        self.init_weights(dims=[np.max(y) + 1, X.shape[1]]) # initializes the weights of self.W
173
174
175
        # Run stochastic gradient descent to optimize W
176
        loss_history = []
177
178
        for it in np.arange(num_iters):
179
          X_batch = None
          y_batch = None
180
181
```

```
# ----- #
182
183
       # YOUR CODE HERE:
184
         Sample batch size elements from the training data for use in
185
           gradient descent. After sampling,
           - X_batch should have shape: (dim, batch_size)
186
187
           - y batch should have shape: (batch size,)
       # The indices should be randomly generated to reduce correlations
188
189
       # in the dataset. Use np.random.choice. It's okay to sample with
       # replacement.
190
191
       192
       idx = np.random.randint(X.shape[0], size=batch_size)
193
       X_batch = X[idx, :]
194
       y_batch = y[idx]
195
196
       # ----- #
       # END YOUR CODE HERE
197
       198
199
       # evaluate loss and gradient
200
201
       loss, grad = self.fast_loss_and_grad(X_batch, y_batch)
202
       loss_history.append(loss)
203
204
       # YOUR CODE HERE:
205
206
       # Update the parameters, self.W, with a gradient step
       # ------ #
207
208
       self.W = self.W - learning_rate * grad
209
       # ----- #
210
211
       # END YOUR CODE HERE
       # ------ #
212
213
       if verbose and it % 100 == 0:
214
         print('iteration {} / {}: loss {}'.format(it, num_iters, loss))
215
216
217
      return loss_history
218
    def predict(self, X):
219
220
221
      Inputs:
222
      - X: N x D array of training data. Each row is a D-dimensional point.
223
224
     Returns:
     - y_pred: Predicted labels for the data in X. y_pred is a 1-dimensional
225
      array of length N, and each element is an integer giving the predicted
226
227
228
229
     y_pred = np.zeros(X.shape[1])
                  _____#
230
231
      # YOUR CODE HERE:
232
     # Predict the labels given the training data.
233
      # ----- #
      z = X @ self.W.T
234
235
      \max z = np.\max(z, axis=1, keepdims=True)
236
      e_x = np.exp(z - max_z)
237
      e_x_sum = np.sum(e_x, axis=1, keepdims=True)
238
      softmax = e_x / e_x_sum
      y_pred = np.argmax(softmax, axis=1)
239
240
      241
      # END YOUR CODE HERE
242
      # ================= #
243
244
      return y_pred
245
246
```