

PROGRAM 12 : IR BASED SERVO MOTOR

Aim: Design IR based servo motor controller

Hardware Required : Arduino UNO, breadboard, IR sensor, IR Remote, Micro Servo.

Code:

```
#include <Servo.h>
#include <IRremote.h>
int RECV_PIN = 11;
IRrecv irrecv (RECV_PIN);
decode_results results;
Servo myservo;
void setup() {
  Serial.begin(9600);
  irrecv.enableIRIn();
}

void loop() {
  if (irrecv.decode(&results))
  {
    switch (results.value)
    {
      case 0xFD00FF:
        myservo.attach(9);
        Serial.println("start");
        break;
      case 0xFD609F:
        myservo.write(360);
        Serial.println("Clockwise");
        break;
      case 0xFD20DF:
        myservo.write(-360);
```

~~Serial-Write~~

Serial-println ("counter dekarize");

break;

default :

Serial-println ("Unrecognized code recieved = 0x");

Serial-println (results.value, HEX);

break; }

irrecv.resume(); }