Aim: Design IR based serve motion controller	
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Hardware Required: Ardwine UNO, broadboard, IR &	enson,
IR Romote, Micro Servis.	
i tipart	h
Code trans charbaraniste () tara dina	
#include < Sorva-1/2	
# include < Iromote-h>	
int RECV_PIN = 11;	
IRRECT ITTECH (RED_PIN);	₹
decode-results results;	
Servo myservo;	
void setup () }	\(\frac{1}{2}\)
Serial-bogin (96007;	
innec - enable IR In (); 3	
1.625	
if (intervidecade (granults))	
C TO COCCO CIPCOCO COSTO	
Switch (results - value)	
SUSTITUTO	
Cape OXFDOOFF:	
myservo-attach (9);	
Senial - print en ("start");	
break;	
CODE OXFD609F:	
my servo. worte (360)	
my servo. worte (360), Sojal-printh ("Clackarise");	
break j'	
cone OxFOB200F:	
my servio. conte (-360).	Camlin

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break you	to the bound of the second of the second
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default:	
Sonial - print ("Urrec	Lognized code recieved: On').
Sonial-frinkn (rosus	2ts. Wille, HEX)
brook; z	sa pizmodi z chulan 1
<u> </u>	The state of the s
irrecu. resume(); 3	7
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PRIMARED 12 IR BRISED SERVE MOTOR

Late AR DESUITE