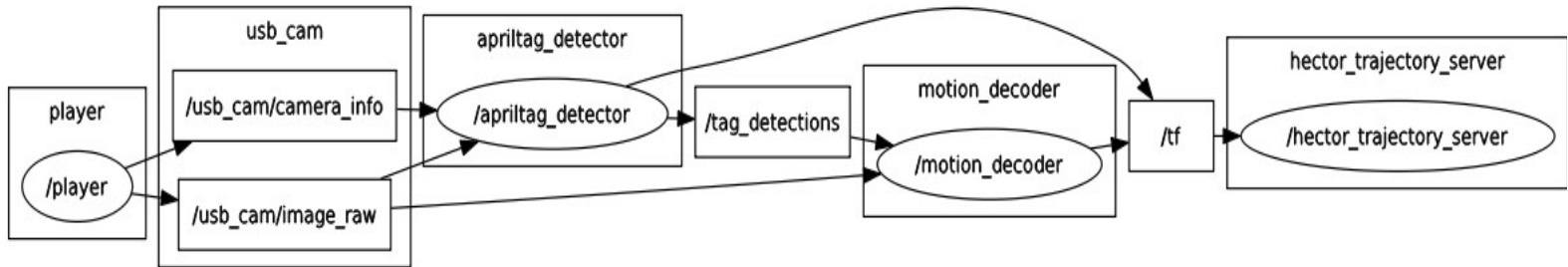# Ros Assignment Programming Assignment 3

1. Ros graph:

2. I plan to use these packages for the localization of the RC car with respect to the infrastructure using april tags.

3. The assignment was excellent in terms of helping me get an understanding of the different packages in ROS. It also aided me in working with different launch files and gave me a solid grounding on parsing data from

messages of different types. Yes this assignment helped me in getting a taste of ROS!

Yes the difficulty level was also manageable as the assignment was broken down into several parts which helped me in understanding the concepts better.