

OIL & NATURAL GAS CORPORATION LIMITED B-22 FIELD DEVELOPMENT PROJECT

DATA SHEETS FOR DCS/PLC

Rev. No	Date	Purpose	Prepared by	Reviewed by	Approved by
0	30.04.07	ISSUED FOR BIDS	JD	SD	KSJ

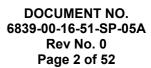




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1. NOTES:

- a) Information filled-in by Consultant/Owner specifies the minimum system requirements.
- b) Vendor shall provide unambiguous information against all items marked as `*' in the following data sheets.
- c) Vendor shall complete the information against all items marked as `**' in the following data sheets.
- d) Note that information provided against all items marked as '**' and `*' must be such that the system performance is not degraded.
- e) Vendor shall categorically confirm all items marked as '#' in the following data sheets. In case no specific confirmation is indicated, it shall be considered as vendor's unconditional compliance.



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2. DISTRIBUTED DIGITAL CONTROL SYSTEM

	* MODEL NO.							
1.#	a) Type of system dist	ribution	Geogra	aphical	[]	Functional	[X]	
	b) Location		Contro	ol Room	[X]			
2.*	System Size							
	a) Considering all input	uts as closed l	oops					
	b) Considering all inp	uts as open lo	ops					
3.**	System availability for	r the specified	l configuration	99.99%	[X]	Offered		
4.*	Max communication b	ous length						
	Standard:	m	With b	ous Expande	er:		_m	
5.*	Maximum number of	sub systems o	n the communica	ation sub sy	stem			
		No. of Nodes	No. of Consoles	Comp Interf		Other Sub- Systems		
	STANDARD							
	WITH BUS EXPANSION							
6.**	Type of sub system(s)	:						
	a) Controller & data ac	a) Controller & data acquisition sub system			[X] Model No			
	b) Controller sub syste	m		[] Model No				
	c) Data acquisition sub	system		[] Model No				
	d) Communication sub	system		[X] Model No				
	e) Operator interface s	ub system		[X] Model No				
	f) Engineer interface su		[X] Model No					
	g) Programmable logic	c controller		[X] Model No				
	h) Supervisory comput		[] Model No			_		
	i) Foreign device interface			[X] Model No				
	j) Personal computer				[X] N	Model No	_	
	k) Hardwired instrume	nts			[X] N	Model No	_	
	l) Unit History Node (JHN)			[] N	Iodel No	_	



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	m) Field multiplexer		[] M	Iodel No	
	n) OPC Server		[X] N	Model No	_
7.*	Foreign Device interfaces required for:				
	ESD Programmable logic controller		[X]		
	PLC based F&G system		[X]		
	Compressors Control System (Note-A)		[X]		
	MOL Pumps Control System (Note-A)		[X]		
	MIP Pumps Control System (Note-A)		[X]		
	GTG Control System (Note-A)		[X]		
	Fine Filter Control System (Note-A)		[X]		
	Chlorinator Package Control System (Note-A	.)	[X]		
	Vibration & Temperature Monitoring systems	(Note-A)	[X]		
	ASC for Compressor Control System (Note-	A)	[X]		
	Others				
	Note-A: Contractor shall indicate the list of the equipment selected.	foreign device interfa	ices as j	per the final confi	guration of
8.#	On line self-diagnostic message	Required	[X]	Module level	[X]
	Local Level		[]	Engg.Console	[X]
9.#	Redundant floating power supply required for	r			
	a) Controller & data acquisition sub system		[X]		
	b) Controller sub system		[]		
	c) Data acquisition sub system		[]		
	d) Communication sub system		[X]		
	e) Operator interface sub system (individual p	power supply)	[X]		
	f) Engineers interface sub system (individual	power supply)	[X]		
	g) Programmable logic controller (PLC) (indi	ividual)	[X]		
	h) Foreign device interface		[X]		
	i) Hardwired inst. including Barriers (individ-	ual if 110VAC)	[X]		
	j) Field multiplexer (FMX)		[]		



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	k) Racks requiring 24 V DC pov	ver supply	У	[X]		
	l) Miscellaneous Instruments			[X]		
10.**	Power supply availability					
	a) AC Voltage for system					
	Details		Supplied		Permissible	
	Voltage	110	0 V ± 10 % UPS			
	Frequency	50	Hz. ± 3%			
	Max. Static Transfer Time	5 n	msec			
	b) DC Voltage for PLC output d	evices –	24V+/- 5%	[X]		
	c) AC Voltage for lighting - 24	c) AC Voltage for lighting - 240V, 50HZ				
11.**#	UPS System Requirement					
	a)* UPS System sizing factor					
	b)**# Type of UPS for DCS sy	rstam	Isolated	[X]		
	b) ** # Type of Or's for DCs sy	Stem	Grounded		Ungrounded	[V]
	a)**# Tyma of LIDC for agyinma	neta		[]	Oligiounded	[X]
	c)**# Type of UPS for equipme	ents	Ungrounded	[X]		
	Other than the system		Isolated	[X]		
10 411	E di D		(use isolation tran	nstormer)		
12.*#	Earthing Requirements					
	a) Type of Earthing system					_
	Type of Earthing System	Reqd	. Resistance up Pit	oto Earth	Remarks	
	Safety Barrier Earth	YES				
	System Earth	YES				
	Electrical Earth YES					
	b) No. of Earth pits	ı	Common	[]	Separate	[X]
			Others			
	c) Connectivity between electri	cal &	Required	[X]	By vendor	[X]
	instrument earthing system					



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13.*	Installation details					
	a) Type of foundation requir	red	Firm	[]	On false floor	[X]
	b) Max. loading for foundation	ion design	Kg/m²			
14.#	Operating Environment		Control Room	[X]	Safe area	[X]
			Controlled atmos	phere		[X]
	2 (4		ATION CUD CY		r	
			ATION SUB-SY	SIEW	<u> </u>	
	* Model No					
1.*	Communication Topology		Bus Structure	[]		
			Closed ring	[]	Any other	
			STAR	[]		
2.#	Redundancy in Communicat	tion	Required	[X]		
3.#	Type of Bus redundancy		Active	[X]	Others	
4.#	Switch-over of communicati	ion Buses A	Auto only	[] A	Auto & manual	[X]
5.*	Type of communication bus		Co-axial	[]	Fibre optics	[]
				Othe	rs	
6.*	Type of communication	Floating Ma	aster	[]		
		Fixed Maste	r []			
		Periodic repo	orting	[]		
		Exception re	porting	[]		
		Deterministi	c []			
		Non-Determ	inistic	[]		
					rs	
7.*	Type of protocol					
8.*	Communication speed					
9.*	Message error checking met	had	CRC	 []	DEM	[]
9.	Wessage error enecking met	nou	CKC			ſJ
				Othe		
10.**#	a) Bus Controller		Required	[]	Not required	[]
	b) Redundant bus controller		Required (if `a' is	s required	d) [X]	



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11.#	a) Redundant Communication interface requ	ired for the following	subsystems:				
	Controller & Data-acquisition Subsystem			[X]			
	Controller Subsystem			[]			
	Data-acquisition Subsystem			[]			
	Communication Subsystem			[X]			
	Operator Interface Subsystem			[X]			
	Engineer Interface Subsystem			[X]			
	Programmable Logic Controller (ESD and Fo	&G PLC)		[X]			
	OPC Server			[X]			
	b) #Single communication interface required	for the following sub	osystems:				
	Personal Computer			[]			
	Compressors Control System (Note-A)			[X]			
	GTG Control System (Note-A)			[X]			
	MOL Pumps Control System (Note-A)			[X]			
	MIP Pumps Control System (Note-A)			[X]			
	Fine Filter Control System (Note-A)			[X]			
	Chlorinator Package Control System (Note-A	A)		[X]			
	Vibration & Temperature Monitoring System (Note-A)						
	ASC for Compressor Control System (Note-	A)		[X]			
	Other		_	[]			
	Note-A: Contractor shall indicate the list of foreign device interfaces as per the final configuration of the equipment selected.						
12.#	Switch-over to redundant communication int	erface Auto only	[] Auto & Manual	[X]			
13.#	Power supply for communication interface		Redundant floating	g [X]			
14.	Communication Loading	60%	[X] (Note-1, 2)				
15.*	Communication Bus Model No.		_				
16#	Type of Communication cable						
	Within control room	Copper cable	[X] Fibre Optic cable	[]			
	Outside Control room	Fibre Optic cable	[X]				



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17#	Communication Cable mechanical protection	l			
	Within control room	Closed GI tray	[] (3I Conduit	[X]
	Outside Control room	GI Conduit	[X] C	losed HDPE pipe	[]
Note-1:	The communication network loading shall no protocols. Networks following non-determin maximum allowable loads recommended by order of 15% at maximum throughput).	istic protocols i.e. IEI	EE 802.	.3 shall be based	on
Note-2:	The loading of all communication interface u 60%.	nits or communication	n proce	ssors shall not ex	ceed
	4. CONTROLLER & DATA-A	CQUISITION SU	JBSYS	STEM	
	*Model No	_			
A.	OFFERED SYSTEM DETAILS				
1.#	Offered subsystem:				
a)	Combined Controller & Data-acquisition			[X]	
b)	Separate Controller and separate Data-acquisition []				
c)	Partly Combined and Partly Separate Control	ller & Data-acquisition	n	[]	
2.#	Type of Controller	Single loop		[] Multi-loop	[X]
3.a)*	Controller Sub-system		Model	No	_
b)*	Data-acquisition subsystem		Model	No	_
c)*	Controller & Data-acquisition when offered of	combined	Model	No	_
B.	GENERAL				
1.*	Number of controllers per 19" Rack (Nest)			-	
2.*	Number of 19" Racks (Nests) per cabinet				_
3.*	Number of Controller cabinets				_
4.*	Cabinet-wise MTBF				hours
5.*	Cabinet-wise MTTR				hours
C.	SPECIFICATION				
1.#	Туре	μp based	[X]	Configurable	[X]
2.#	Enclosure		Genera	al purpose	[X]



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3.#	a)Type of controller	Single loop	[]	Multi-loop	[X]
i)	Single loop controller	Indicating	[]	Blind	[]
		Facia size			
	Display	Bar graph	[]	Digital	[]
	Architecture	Split	[]	Unit	[]
	Mounting	Flush	[]	Rack	[]
			Mul	ti-case	[]
	Scan time	Variable	[]	Fixed	[]
		Maximum 500 ms	[]	Other	
	Control cycle time				
	Configuration from	Local level	[]	Central level	[]
	Tuning from	Local level	[]	Central level	[]
	MTBF				hours
	MTTR				hours
	Model No.				
ii)**#	Multi-loop controller	Indicating	[]	Blind	[X]
			Faci	a size	_
	Display	Bar graph	[]	Digital	[]
	Mounting	Flush	[]	Rack	[X]
			Mul	ti-case	[]
	Number of loops per controller		Ava	ilable	
	With 60 % loading	Maximum 100	[X]	Actual Offered	
	Back-up controller	Required	[X]	1:1 Redundacy	
		Provided	[]	Not provided	[]
		One for Three	[]	One for One	[]
				Other	_
	Switch-over time	1 s	[X]	Offered	_
	Scan time	Variable	[]	Fixed	[]



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	DP, Pressure, Flow	Maximum 500msec	[X]	Offered_		
	Temperature, Level	Maximum 1 sec	[X]	Offered_		_
	Control cycle time					_
	Configuration from	Central level	[X]	Local lev	rel	[]
	Tuning from	Central level	[X]	Local lev	rel	[]
	MTBF					hours
	MTTR					hours
	Model No.					_
b)#	Control Modes	Manual	[X]	Auto		[X]
		Cascade	[X]	Compute	r	[X]
c)**#	Tuning constants					
	Tuning Constant	Required	Of	fered	Rema	arks
	PROPORTIONAL BAND	1 - 800 %				
	INTEGRAL RATE	0.05 - 100 repeats/ min.				
	DERIVATIVE TIME	0.01 - 10 min.				
	DEAD TIME	0.07 - 10 min.				
	LEAD LAG TIME	0.005 - 10 min.				
d)#	Reverse/ Direct selection	Required	[X]			
e)#	Anti-Reset wind up feature	Required	[X]			
f)#	Output status on controller failure	Flunk	[X]	Freeze		[X]
		Engineer Configur	able			[X]
4.**#	DATA-ACQUISITION SUBSYSTE	EM				
	Mounting	Rack	[X]			
	Number of Inputs per processor	Analog	[X]	Maximur	n 16	[X]
				Offered_		_
		Digital	[X]	Maximur	n 32	[X]
				Offered_		



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		One for One	[]	
		One for N	[](1	Define 'N')
		Others		
	Switch-over time	1 second	[X]	Offered
	Scan time	Variable	[]	Fixed []
		1 s	[X]	Other
	Control cycle time			
	Configuration from	Central level	[X]	Local level []
	Tuning from	Central level	[X]	Local level []
	MTBF			hours
	MTTR			hours
	Model No.			
5.	CONTROL PROCESSOR			
a)*#	Back up control processor	Required	[X]	
	Provided	[]	Not I	Provided []
	One for one	[X]		
	Any Other			<u> </u>
b)*#	Switch over time	1 Sec.	[X]	Any Other
c)*#	Processor cycle time			
	For Flow and Pressure	250 msec	[X]	Any Other
	For Level and Temp.	500 msec	[X]	Any Other
d)*	No. of Control blocks			_
e)*	Execution rate			_sec/control block
f)*	Updation rate of back up processor	Per Scan	[]	Any Other
g)*#	Mounting	Rack	[X]	
h)*	MTBF Value			
i)*	MTTR Value			
j)*	Model No.			



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6.	DATA ACQUISITION PROCESSOR		
a)*#	Back up control processor	Required	[X] (for more than 16 Analog or 32 Digital inputs)
	One for one	[]	
	One for N	[]	N=
			(Define 'N')
b)*#	Switch over time	1 Sec.	[X]
c)*	No. of Data Acquisition(DA) Blocks		
d)*	Execution rate		sec/DA block
e)*	Updation rate of back up processor	Per Scan	[] Any Other
f)*	Control cycle time		sec
g)*#	Mounting	Rack	[X]
h)*	MTBF Value		
i)*	MTTR Value		
j)*	Model No.		
7.#	Input isolation	Required	[X]
8.#	Output isolation	Required	[X]
9.**#	Type of Input Modules:		

Type of module		Model No.	Isolation	No. of inputs per module
4-20 mA DC(2 wire) (with HART protocol)	[X]			
0-20 mA DC(2 wire)	[]			
4-20 mA DC(non 2 wire)	[X]			
1-5 V DC	[X]			
0.25-1.25 V DC	[]			
OTHER	_			
THERMOCOUPLES (T/E/K PER ANSI MC96.1	[X]			
RTD	[X]			



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	(PT 100 PER DIN 43760)			
	CONTACT POTENTIAL FREE[X]			
	RS 232C/RS 422/RS 485 [X]			
	BCD [X]			
10.**#a)	Type of Output Modules:			'
	Type of module	Model No.	Isolation	No. of outputs per module
	4-20 mA DC(2 wire) [X] (with HART protocol)			
	Other []			
	b) Type of Discrete Outputs:			
	Type of module	Model No.	Isolation	No. of outputs per module
	POTENTIAL FREE CONTACT [X]			
11.**	Power supply for Transmitters	24 V DC	[X]	Other
		With Controlle	er []	
	Redundant common power supply system	m []		
12.**#	Intrinsically safe	Yes	[X]	No []
	With Extern	nal barrier	[X]	
	Without Exter	rnal barrier	[]	
13.*	Maximum number of alarm settings			
14.**#	A/D Converter resolution	1500 steps	[X]	Actual
15.**#	D/A Converter resolution	1500 steps	[X]	Actual
16.**#	Load Driving capability	750 Ω	[X]	Actual
17.#	Load Driving capability of transmitter @	24 V DC 600 Ω	[X]	
18.**#	Maximum allowable source resistance for	or:		
	Thermocouple input module	$2\underline{000~\Omega}$		
	RTD input module			Ω



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					'	. 490 .0 0. 02		
19.#	On-line Diagnostic message avai	lable at		Local	level	[X]		
				Centr	alised level	[X]		
20.**	# Memory type for Configuration	Retent	ive	[X]	Volatile	[]		
	If Retentive	Erasiv	e	[X]	Non-erasiv	re []		
		*Erasi	ng by	-				
	If Volatile	Batter	y back-up	[X]				
		*Batte	ry type	*Batt	ery life			
		Charge	eable	[X]				
		Contin	uous trickle cl	narge		[X]		
		Configurat	ion protection	time 7	72 hours	[X] Note 3		
		Batter	y drain indicati	on		[X]		
	*Retentive memory back up							
	Note 3: Battery back-up shall be provided to protect the controller configuration data for a of 10 hours or more or the system shall tolerate black out condition for at least or without data corruption/ data loss and auto boot in case of power black out condi							
21.#	CPU/MEMORY LOADING							
	a) CPU loading		60%	[X]				
	b) Memory Utilisation		60%	[X]				
	c) I/O processor loading		60%	[X]				
	(if separate from processor carr	ying out control fun	ction)					
	d) Communication processor loa	ding 60°	%	[X]				
22.**	ALGORITHMS							
_	ALGORITHMS	REQUIRED	OFFER	ED F	OR	REMARKS		
_			SINGLE LOOP		ULTI- OOP			
	BASIC FUNCTIONS							
	Manual loader	[X]	[]		[]			
	Cascade(with set point tracking)	[X]	[]					
	High alarm limit	[X]	[]		[]			
	Extra High Alarm	[X]	[]		[]			



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Low Alarm	[X]	[]	[]	
Extra Low Alarm	[X]	[]	[]	
Rate of change alarm	[X]	[]	[]	
Deviation Alarm	[X]	[]	[]	
Output High	[X]	[]	[]	
Output Low	[X]	[]	[]	
High Dev. from set point	[X]	[]	[]	
Low Dev. from set point	[X]	[]	[]	
CONTROL ALGORITHMS				
Proportional Control	[X]	[]	[]	
PI	[X]	[]	[]	
Error Square PID	[X]	[]	[]	
Adaptive Gain	[X]	[]	[]	
Ratio Control	[X]	[]	[]	
PID with Dead Band	[X]	[]	[]	
ARITHMATIC				
Additional Subtraction	[X]	[]	[]	
Multiplication	[X]	[]	[]	
Division	[X]	[]	[]	
Absolute value	[X]	[]	[]	
Square Root	[X]	[]	[]	
Average	[X]	[]	[]	
Summation (Integration)	[X]	[]	[]	
Bias	[X]	[]	[]	
Ramp Function	[X]	[]	[]	
LINEARIZATION				
Square Root Extraction	[X]	[]	[]	
Flow Computation(Pressure & Temp. compensation)	[X]	[]	[]	
Thermocouple Linearisation & compensation	[X]	[]	[]	
RTD Linearisation	[X]	[]	[]	
Polynomial	[X]	[]	[]	
DYNAMIC				



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L	_ead/Lag	[X]	[]	[]	
Γ	Dead time	[X]	[]	[]	
Т	imer	[X]	[]	[]	
F	eed Forward	[X]	[]	[]	
L	LIMITER				
L	Low Output Limiter	[X]	[]	[]	
H	High Output Limiter	[X]	[]	[]	
A	Alarm Limiter	[X]	[]	[]	
S	Set point Limiter	[X]	[]	[]	
S	SELECTOR				
L	Low Selector	[X]	[]	[]	
H	High Selector	[X]	[]	[]	
N	Mean value Selector	[X]	[]	[]	
A	Auto Ranging for Dual transmitters	[X]	[]	[]	
C	Over-ride	[X]	[]	[]	
L	LOGIC				
A	And	[X]	[]	[]	
C)r	[X]	[]	[]	
N	Nor	[X]	[]	[]	
N	Not	[X]	[]	[]	
N	MISCELLANEOUS FUNCTIONS				
	Bump-less transfers between all ontrol nodes	[X]	[]	[]	
Γ	Direct or Reverse outputs	[X]	[]	[]	
1	All algorithms available as standard firmware l	blocks shall be	carried out using	ng the above blo	cks.
	5. OPERATOR INTI	ERFACE SU	<u>UB-SYSTEM</u>	1	
	*Model No				
A.	GENERAL				
1.#	Number of Operator Consoles	One	[]	Two	[]
		Three	[X]	Other	
2.#	Inter-changeability between operator con	nsoles	Red	quired	[X]



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								Not R	equired	l	[]
3.#		On-line sy	stem diagnostics on Con-	sole CRT	s Required	l		[X]			
								Modu	le level		[X]
4.#		On-line co	nfiguration change					Requi	red		[X]
5.**		High volta	ge isolation		Reqd. Other	[X]		Optica	al Barri	er	[]
6.*		MTBF						_			hours
7.*		MTTR									hours
B.		OPERATO	OR CONSOLE								
1.*		Console's l	basic electronics		Redunda	int co	mmon		[]		
		Individual	electronics for each CR	Т	[]				Other_		
		μр Туре			16 bit			[]	32 bit		[]
								Other	_		
		μp Make/ ι	model								
		Memory si	ze								MB
2.**#		Type of Da	atabase		Global a	t opei	rator co	onsole	[]		
					Function	ally s	separate	e			[]
		Data Stora	ge Devices:								
		S.No.	ITEM MODEL No.	FUNCT	TION	REDUNDANCY			7	REMARKS	
		1.	Hard Disk Drive			REG	QUIRE	D [X]]		
		2.	CD ROM Drive			REG	QUIRE	D [X]]		
		3.	Floppy Disk Drive			REG	QUIRE	D [X]		
		4.	Others								
		Redundand	cy is required if common	electroni	cs for all	CRTs	is prov	vided.			
3.**#		Number of	Devices (per console)								
	S.N o.	T	YPE OF DEVICE		OF DEVIC			OF DEVICES POSSIBLE			REMARKS
	1.	CRT/TFT	Γ	THRE	EE						
	2.	KEYBOA	ARD SETS	ONE/	CRT						



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	3.	ALARM	& EVENT PRINTER	ONE						
	4.	LOG PR	INTER	ONE						
	5.	HARD (COPY UNIT	ONE@					@ Common for all consoles	
	6.	TAPE D	RIVE	ONE						
	7.	FLOOPY	7,CD & WINCHESTER	ONE EAC	СН					
4.#		Inter-chan	geability between CRTs			Requi	red [[X]		
5.#		Switch-ov	er of peripherals on consol	le electronic	s' failure	Auto	[[X]		
6.*		Data base	update rate				-		<u>S</u>	
7.**		Users' men	mory requirement			M	Iin. 51	2 KB	[X]	
						Sy	ystem	capacity	<u>KB</u>	
8. Keyboard Set										
a)#		Type of ke	eyboard	Me	embrane typ	be [X	ζ] (Other		
b)#		Number o	f Operators' keyboards	On	e per CRT	[X	(Other		
c)#		Number o	f Engineer's keyboards per	operator co	nsole	O	ne		[X]	
						Tv	wo		[]	
d)*		Number o	f maintenance keyboards			O	ne		[]	
						O	ther_			
e)**#		Keyboard	Security against unauthorize	zed access	Required	[X	K] I	Key-lock	(X)	
						O	ther_			
f)**#		Maximum	number of keystrokes for	accessing vi	iews as per	standard	displa	ıy hierar	chy:	
		S.NO	TYPE OF VIEW	R	EQUIRED		OFFE	ERED	REMARKS	
		1.	GROUP VIEW	T	WO					
		2.	LOOP VIEW	TI	HREE					
		3.	LOOP IN ALARM	T	WO					
		4. GRAPHICS VIEW TWO								
g)#		Dual func	tion keys for single keystro	•	I	Required	l [X]			



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h)**#	Number of	dual function keys per CRT	48	[X]	Offered		
i)**#	a) Number of	of devices for cursor control	Three/ CRT	[X]			
	b) Devices t	for cursor control	Keyboard	[X]	Mouse	[X]	
	Touch-scr	een / Trackball		[X]	Light pen	[]	
				Oth	er		
10.**#	CRTs and D	Displays					
a)#	Size of CR	Γ	21" diagonal	[X]			
b)#	Type of CR	T	Colour	[X]	Other TFT		
c)	Number of	background colours	Seven (7)	[X]	Actual		
d)	Number of	foreground colours	Seven (7)	[X]	Actual		
e)	Number of	display characters	80 x 40 line	[X]	Actual		
f)			Number of cha Actual		Minimum 96	ASCII [X]	
g)	Character c	onstruction character 5x7 do	ts [X]	Actı	ıal <u></u>		
	Pattern 7x8	dots		[X]	Actual		
h)	Length of ta	ag number (characters) 9 alphar	numeric	[X]	Other		
i)	Length of d	lescription (characters) 15 alpha	numeric	[X]	Other		
j)#	Display upo	date rate	2 sec	[X]	Other		
k)#	Dynamic gr	raphics	Required	[X]	On each CI	RT [X]	
1)#	Control thro	ough dynamic graphics	Required	[X]			
m)**	CRT displa	ys and Call-up time					
	S.NO.	TYPE OF DISPLAY	REQUIRED	CALL-U	P TIME(S)*	REMARKS	3
	1.	OVERVIEW	YES				
	2.	GROUP DISPLAY	YES				
	3.	LOOP DISPLAY	YES				
	4.	DYNAMIC GRAPHICS	YES				
	5.	REAL-TIME TREND	YES				
	6.	HISTORIC TREND	YES				
	7.	ALARM SUMMARY	YES				
	8.	ALARM HISTORY	YES				



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	9.	CONFIGURATION		YES				
	10.	DIAGNOSTIC		YES				
n)*	Additional	vendor standard displays						
	S.NO.	TYPE OF DISPLAY		AVAILABLE	0	FFERED	REMARKS	
o)**#	Display Hi	ierarchy	I			1		
	SL. NO.	DESCRIPTION		REQUIRE MENT		SYSTEM PABILITY	REMARKS	
	1.	NO. OF OVERVIEW PAGES		AS REQD.				
	2.	NO. OF GROUPS/OVERVIEW		AS REQD.				
	3.	NO. OF LOOPS/GROUP		8				
	4.	NO. OF GRAPHIC PAGES		AS REQD.				
		NO. OF POINT IN ALARM SUMMARY		AS REQD.				
		NO. OF POINTS IN AALRM HISTORY		AS REQD.				
		NO. OF TRENDS PER DISPLAYS		AS REQD.				
		NO. OF MULTI-TREND DISPLAYS		AS REQD.				
	9.	OTHERS		AS REQD.				
p)*	Zooming f	acility		Available	[]	I		
q)**	Windowin	g facility		Required	[X]	(Note-4)		
Note 4	: Opening of r	more than four windows on t	the sam	ne screen shall b	e restrict	ed by the syst	em.	
r)**#	Trending f	unctions:						
	i) Real-tim	ne trend						
	Number of	f parameters Re	equired	ALL TAGS	Sys	stem capacity		
	Time base			Maximum 10 s	[]	Other		
	Time perio	od		10 Min.		Other		
	ii) Historic	eal trend						
	Number of	Number of parameters Requir			Svs	System capacity		



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	Time base	1 min.	[]	Other	_
	Time period	31 Days	[]	Other	_
s)*	Dynamic graphic generation:				
	Number of standard symbols available				_
	Number of user defined symbols				_
11.**	Logging Function				
	a) Number of tags to be logged R	equired <u>ALL TAGS</u> Sys	stem cap	pacity	
	b) Number of log reports	RequiredS	/stem ca	npacity	_
	Alarm History per shift	[X]	Event	logging	[X]
	Hourly logs	[X]	Shiftly	y logs	[X]
	Daily logs	[X]	Week	ly logs	[X]
	Shutdown report	[X]	Trip i	nitiated log	[X]
			Other	s(Note-5)	MIS
Note-	-5 : Other log reports shall be furnished d	uring detailed engineering	g.		
	c)# Log formats		User	lefinable	[X]
12.**#	Memory type for Configuration	Retentive	[X]	Volatile	[]
	If Retentive	Erasive	[X]	Non-erasive	[]
			*Eras	ing by	_
	If Volatile		Batter	y back-up	[X]
		*Battery type	*E	Battery life	_
		Chargeable			[X]
		Continuous trickle	charge		[X]
		Configuration prote	ection ti	me 72 hours	[X]
		Battery drain indica	tion		[X]
		*Retentive memory	back u	p[X]	
13.*	System boot-up from	Operator console	[] E	ingineer console	[]
		Other	_		
14#	Auto boot-up on power On		Requi	red	[X]



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15.**#	Assignab	le trend recording:					
	a) Numbe	er of points to be recorde	ed	Required	Syste	m capacity	
	b) Numb	er of pens per recorder		Maximum 3	[]	Other	
	c) Record	der size		6" x 6"	[]	Other	
	d) Record	ding speed		1"/ hour	[]	Other	
	e) Selecti	ion of Operator assignabl	le tag from	Operator Console	[]		
16.*#	Storage d	lisks					
	a)* Type	of storage disk		Floppy	[X]	Winches	ter [X]
				Optical	[X]	CD	[X]
	b)** Nun	nber of disks and capacit	у				
SL. NO. TYPE OF DISC NUMBER (ER (MINIMUM)	MEMORY CAPACITY PER DISK		REMARKS
	1.	FLOPPY	TWO PE	R CONSOLE			
	2.	WINCHESTER	TWO PE	R CONSOLE			
	3.	OPTICAL	TWO PE	TWO PER CONSOLE			
	4.	CD	TWO PE	R CONSOLE			
	5.	OTHER					
17.*	Any othe	r feature available as a st	andard:				
	a)				_		
	b)				_		
	c)				_		
	d)				_		
	e)				_		
18.#	CPU Loa	ding				60 %	[X]
19.#	Memory	Utilisation				60 %	[X]
		6. ENGINEE	ER INTE	RFACE SUB-SY	YSTE	<u>M</u>	
	*Model N	No		_			
1.#	Number o	of Engineering Console		Three	[X] N	ote 6	



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	Note 6: Engineering console for Sulphur block shall be in DHDT Control Room.										
2.#	Number of CRTs per Engg.Console	Two	[]	One	[X]						
3.*	Type of electronics	Individual per CRT	[]	Common	[]						
	Number of CRT's per electronics				_						
	μP type	32 bit	[]	16 bit	[]						
	Memory size				_						
	Model No.				_						
4.#	Number of engineering keyboards	One per CRT	[X]	Other	_						
5.#	Number of Operation keyboards	One per CRT	[X]	Other	_						
6.*	Maintenance keyboard	Required	[]								
7.#	Functional Capability	Same as operator into	subsystem	[X]							
8.#	Basic functions of Engineering Console										
a)	System configuration and reconfiguration		[X]								
b)	Group & multi-groups alarm inhibiting		[X]								
c)	Plant views with/ without plant operation		[X]								
d)	Graphic page compilation		[X]]							
e)	Setting/ resetting real-time clock		[X]								
f)	Loop tuning on selectable basis		[X]								
g)	System maintenance and diagnostics		[X]								
9.#	CRT specification	As operator interfac	e subsy	rstem	[X]						
10.#	Keyboard specification	As operator interfac	e subsy	rstem	[X]						
11.**#	High voltage isolation	Required	[X]								
	Protection type	Optical barrier	[X]	Other	_						
12.#	Peripheral requirements:										
	i) Printer (C&M)	Required	[X]								
	ii) Hard copy unit	Required	[]								
	iii) Other		_								
13.#	Data base station (DBS)	Required	[]								



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	i) Capacity	Actual	_	Used		
	Engineering console shall have dual disc.					
	7. LOGGI	NG PRINTER				
	*Model No.	_				
1.**	Type of hard copy unit	Electrostatic	[]	Laser Jet Printer	X]	
		Coloured	[X]			
2.**	Printing Speed	6 PPM or more	[X]	Actual		
3.#	Screen selection from	Operator console	[X]	Engg. console [X]	
	PLC console	[]				
4.**	Maximum distance from operator console	AS PER CONT	ROL R	OOM LAYOUT		
	Limitation (if any)		_			
5.**	Number of channels	Required	_	Offered		
6.	a) Electrostatic:					
	i)* Paper type		_			
	ii)** Paper size	A4	[X]	Offered		
	iii)* High voltage protection type	Optical barriers	[X]	Other		
	b)* Printer	Type	_	Speed		
	i)** Resolution	640 dpi	[]	Actual		
	ii)** Paper Width	254 mm	[]	Actual		
	iii) Paper Type	Continuous fanfold	[]	Actual		
	iii)** Paper Feed	Friction	[]	Pin Feed []	
	iv)** Acoustic Cover	Required	[X]			
	v)** Noise level (in dBA) while printing at a	distance of 1 m:				
		Required	< 65 d	IBA		
		Offered				
		with cover	[]	without cover []	
7.*	Cord length offered	As per actual layout	Max.	possiblem		
8.#	Mounting	Self contained with Integral stand [X]				

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8. ALARM/EVENT PRINTER

	*Model No				
1.**	Type of Printer	Serial	[X]	Actual	_
2.**	Number of character type	96 ASCII	[X]	Actual	_
3.**	Printing speed	120 cps	[X]	Actual	_
4.**	Number of print columns	Minimum 132	[X]	Actual	_
5.**	Paper width	381 mm	[X]	Actual	_
6.#	Paper type	Continuous fanfol	ld [X]		
7.**	Number of copies	Three	[X]	Actual	_
		Other			
8.#	Acoustic cover	Required	[X]		
9.#	Paper feed	Friction feed	[X]	Pin Feed	[]
10.#	Bi-directional printing feature	Required	[X]	Required	[X]
11.#	Identification of alarms and events	Required	[X]	By dual colours	[X]
		Other			
12.#	Test pattern generation	Required	[X]		
13.*	Cord length offered As	per Control room layout	Max.pc	ossible m	
14#	Mounting	Self contained wit	th Integra	al stand	[X]
15.**	Noise level (in dBA) while printing at	a distance of 1 m:			
	a) Required	< 65 dBA			
	b) Offered				
	with cover	[]	witho	out cover	[]
	9. CONFIGURATION	AND MAINTENAN	NCE P	RINTER	
	*Model No.				
1.**	Type of hard copy unit	Electrostatic	[]	Laser Jet Printer	[X]
	Coloured	[X]			
2.**	Printing Speed	6 PPM or more	[X]	Actual	_
	U 1				



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3.#	Screen selection from	Operator console	[X]	Engg. console	[X]
	PLC console	[]			
4.**	Maximum distance from operator console	AS PER CONTROL	L ROC	OM LAYOUT	
	Limitation (if any)		_		
5.**	Number of channels	Required	_	Offered	_
6.	a) Electrostatic:				
	i)* Paper type		_		
	ii)** Paper size	A4	[X]	Offered	_
	iii)* High voltage protection type	Optical barriers	[X]	Other	<u> </u>
	b)* Printer	Туре		Speed	_
	i)** Resolution	640 dpi	[]	Actual	<u> </u>
	ii)** Paper Width	254 mm	[]	Actual	<u> </u>
	iii) Paper Type	Continuous fanfold	[]	Actual	_
	iii)** Paper Feed	Friction	[]	Pin Feed	[]
	iv)** Acoustic Cover	Required	[X]		
	v)** Noise level (in dBA) while printing a	t a distance of 1 m:			
	Required	< 65 dBA			
	Offered		_		
		with cover	[]	without cover	[]
7.*	Cord length offered	As per actual layout	Max	possible	m
8.#	Mounting	Self contained with	Integr	al stand	[X]
	<u>10. HAR</u>	D COPY UNIT			
	*Model No.				
1.**	Type of hard copy unit	Electrostatic	[]	Laser Jet Printe	r [X]
	Coloured	[X]			
2.**	Printing Speed	6 PPM or more	[X]	Actual	<u> </u>
3.#	Screen selection from	Operator console	[X]	Engg. console	[X]
	PLC console	[]			



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4.**	Maximum distance from operator console	AS PER CONTROL ROOM LAYOUT					
	Limitation (if any)						
5.**	Number of channels	RequiredOffered					
6.	a) Electrostatic:						
	i)* Paper type						
	ii)** Paper size	A4 [X] Offered					
	iii)* High voltage protection type	Optical barriers [X] Other					
	b)* Printer	Type Speed					
	i)** Resolution	640 dpi [] Actual					
	ii)** Paper Width	254 mm [] Actual					
	iii) Paper Type	Continuous fanfold [] Actual					
	iii)** Paper Feed	Friction [] Pin Feed	[]				
	iv)** Acoustic Cover	Required [X]					
	v)** Noise level (in dBA) while printing at	a distance of 1 m:					
	Required	< 65 dBA					
	Offered						
	with cover	[] without cover	[]				
7.*	Cord length offered	As per actual layout Max. possible	m				
8.#	Mounting	Self contained with Integral stand	[X]				
	11. HARDW	IRED CONSOLE					
	*Model No	<u> </u>					
1.	Number of Hardwired console per operator	console:					
	SL.NO. OPERATOR CONSOLE	NUMBER OF HARDWIRED CONSOLES	REMARKS				
	1. OPERATOR CONSOLE -	1 AS REQUIRED					
	2.						
	3.						
2.	Instrument Located on Hardwired consoles:	: (AS REQUIRED)					
	TYPE OF INSTRUMENT	NO REQUIRED WITH OPERATOR C	ONSOLE				



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	OPERATOR CONSOLE - 1	OPERATOR CONSOLE - 2	OPERATOR CONSOLE - 3
ASSIGNABLE RECORDERS			
INDICATING CONTROLLERS			
INDICATORS			
RECORDERS			
TOTALIZERS			
HARDWIRED ANNUNCIATORS	YES		
INDICATING LAMPS	YES		
SWITCHES	YES		
PUSHBUTTONS	YES		
TELEPHONE SETS	YES		
HAND SETS FOR COMMUNICATION SYSTEM	YES		
OTHERS			

3.#	Power supply for Instruments(except lamps, switches, pushbuttons)110 V, 50 Hz	[X]
4.#	Power supply for switches,lamps,pushbuttons etc. 110 V DC [] 24 V dc	[X]

12. PROGRAMMABLE LOGIC CONTROLLER (ESD and F&G)

	*Model No				
1#	Functional requirement	Plant Shutdow	n and Interl	ocks	[X]
2#	System Configuration Type				
2.1#	Single PLC				
	a) Redundant dual processor		[]		
	b) Minimum Redundant dual processor	with dual I/O	[X]	I/O auto-testing	[X]
		SIL-3 TUV At	oproved as r	er IEC-61508	[X]



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3.	PROCESSOR SYSTEM				
3.1**#	Functional capability	Logic Functions	[X]		
		Timing Functions	Functions [X] Range:0-99,99		S
		Least count: 0.01 s			
	*Other available as standard				
3.2#	Interfacing capability	I/O Racks	[X]	DCS Bus	[X]
		PLC Console	[]	Printer	[X]
				Other	
3.3*	Memory capacity		_		
3.4*	Memory used		_		
3.5*	Spare memory available		_		
3.6**#	Memory type	Retentive	[X]	Volatile	[]
	If Retentive	Erasive	[X]	Non-erasive	[]
		*Erasing by	_		
	If Volatile	Battery back-up	[X]		
	*Battery type	*Battery life	_		
	Chargeable		[X]		
		Continuous trickle o	charge		[X]
		Configuration prote	ction ti	me 72 hours	[X]
		Battery drain indica	tion		[X]
		Retentive memory b	oack up	(X)	
3.7**	Scan Time	250 ms	[X]	Actual	ms
		20 ms	[]		
3.8*	Power supply redundancy/ processor	Individual	[]		
	Redundant F	loating	[]		
3.9.#	Outputs on processor system failure	Freeze	[X]	Open	[X]
		Close	[X]	Configurable	[X]



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	(Outputs shall be configured to open on processor failure, unless otherwise specified)							
3.10*	Maximum distance between processor & console				AS PER CONTROL ROO			
				Allo	wable	<u>m</u>		
4#	INPUT/ OUTPU	JT SYSTEM						
4.1#	Type	Discrete	[X]	Other				
4.2#	Mounting		19" Rack	[X]	Other			
4.3	SINGLE or DU	AL I/O CONFIGURA	ATION					
4.3.1#	Online replacem	ent of I/O modules	Required	[X]				
4.3.2#	I/O status Indica	tion	Required	[X]	Local level	[X]		
	PLC Console		[]					
4.3.3**	Input Isolation		Required	[X]	Optical	[X]		
			Other					
	Output Isolation		Required	[X]	Optical	[X]		
			Other					
4.3.4*	I/O Capability							
	TYPE O	F MODULE	MODEL No.	CAPACITY	I/O's US	ED		
		4-20 mA						
	INPUT	1-5 V DC						
		Contact						
	OUTPUT	4-20 mA						
		Contact						
4.3.5#	Input Type		Intrinsic sa	afe [X]	Non-Intrinsic Sa	fe [X]		
				With	n external barriers	s [X]		
4.3.6*	Maximum distar	nce between I/O rack	& processor AS F	PER CONTROL	L ROOM LAYO	<u>UT</u>		
			Allowable	<u>m</u>				
4.3.7#	Dual I/O		Required	[X]	Not Required	[]		
	Auto testing of	I/O's	Required	[X]				
4.3.8**	Power Supply/ I	/O rack	Individual	[]	Dual Redundant	[X]		



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4.3.9**	I/O Rack to processor link Inc		Individual		[]]	Dual Rec	dundant	[X]
4.3.10*	Remote I/O capability		Available	ilable		Not A	vailable	[]
4.3.11	Input Module							
	a)# Input Type		Volt free co	ontact	[X]	4-20 mA		[X]
	contact rating		1.5 A @ 22	0 V dc	[X]	2 A @	24 V dc	[X]
	:		5 A @ 220	V ac	[X]	Other_		_
	b)# Maximum number of Inputs per module:		ıle:					
	Single I/O		Eight		[]	Offere	d	_
			Other		_			
	Dual I/O		Sixteen		[X]	Offere	d	_
			Other		_			
	c) Input Interrogation v	oltage	110 V dc		[]	24 V d	le	[X]
			Other		_			
	d) Transmitter power su	ipply	24 V dc		[X]	With I/C) module	[]
	e)							
	TYPE OF MODULE	MODEL No.	INPUTS / MODULE	INPUT IMPE		Ξ (Ω)	INRUSI CURRE	
	4-20 mA []							
	24 V dc []							
	110 V dc []							
4.3.12.	Output module							
	a)# Output Type		Volt free co	ontact	[X]	4-20 m	nA	[]
					(Note	e-1)		
	Contact rating		1.5 A @ 22	0V dc	[X]	2 A @	24 V dc	[X]
			5 A @ 220	V ac	[]			
	b)** Maximum number	of Outputs per mo	odule:					
	Single I/O		Eight		[]	Offere	d	_
						Other_		_
	Dual I/O		Sixteen		[X]	Offere	d	_



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			Other_		_
c)*					
OUTPUT CONTACT RATING	G MODEL No.	NUMBER (OF OUTP	UTS/M(DULE
110 V, 0.5 A dc (INDUCTIVE)					
110 V, 5.0 A ac					
24 V, 2.0 A dc					
Note –1: If necessary Vendor sho and higher ratings if necessary in		g relays to meet	the rating	gs specif	ied here
d) Output Load Capability			600 Ω		[X]
I/O System for Triple Modular	Redundant (TMR) Co	onfiguration: (IF APPL	ICABL	E)
Process I/O modules					
Online replacement	Required	[X]	With h	ot slots	[]
I/O Capability					
TYPE OF MODULE	MODEL No.	CAPACI	ТҮ	I/O's	USED
INPUT					
OUTPUT					
Input Type	Intrinsic sa	ife [X]	Non-intri	nsic safe	[X]
Number of I/O channels per I/O	Three	[X]			
Maximum distance between I/O ra	ack & processor				m
Power supply per I/O Rack	Dual Redu	ndant []	Triplica	ate	[X]
I/O Rack to processor link	Triplicate	[X]			
I/O Conditioning modules:					
Online replacement	Required	[X]			
I/O status indication	Required	[X]			
Input isolation	Required	[X]	Optical	l	[X]
		Othe	r_		
Output isolation	Required	[X]	Optical	l	[X]
			Other_		
I/O Capability					



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	E OF MODULE	ODULE MODEL No. CAPACITY		ГҮ	I/O's US				
	INPUT								
	OUTPUT								
4.4.2.5*	Maximum distance b	etween Conditi	oning ra	ck & I/O r	rack				m
4.4.2.6#	I/O Conditioning mo	dule redundanc	у	Required	l	[X]	Not r	equired	[]
4.5.2.7#	Auto-testing			Required	l	[X]			
4.4.2.8#	Power supply per I/C	rack		Dual		[]	Other	r	_
4.4.2.9#	Input conditioning m	odule:							
	a)# Input Type			Volt free	contact	[]			
	Contact rating			1.5 A @	220 Vdc	[X]	24 V	,2 A dc	[X]
				5 A @ 22	20 V ac	[X]	Other	r	_
	b)** Maximum num	ber of Inputs pe	r module	e Thirty	-two	[]	Other	r	_
	c) Input Interrogation	n voltage		110	OV DC	[]	Other	r	_
	d)								
	TYPE OF MODULE	MODEL No.		UTS / DULE	INPUT IMPED		(Ω)	INRUSH CURRE	
	110 V dc []								
	24 V dc []								
4.5.2.10	Output module:				·				
	a)# Output Type			Volt free	contact	[]			
	Contact rating			110 V, 0	.5 A DC	[]	24 V	2 A DC	[]
						Other	_		
	b)** Maximum num	ber of Outputs p	oer modu	ıle		Thirt	y-two		[]
	c)*								
	OUTPUT CONTA	CT RATING	MOI	DEL No.	NUM	BER O	F OUT	PUTS/MO	DULE
	110 V, 0.5 A dc (IN	NDUCTIVE)							
	110 V, 5.0 A ac								
	240 V, 2.0 A dc								



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5.	PLC CONSOLE		*Mo	del No
5.1	Number of CRTs	One	[X]	Other
	Туре	Colour	[X]	Monochromatic []
	Size	21" Diagonal	[X]	Other
	*Character Size	_	_	
	*Screen Capacity		_	
5.2	Redundant Link between processor system &	& console		Required []
5.3	Number of Keyboards	One per CRT	[X]	
	Туре	Membrane	[X]	Offered
5.4	Printer	Required One	[X]	Model
	Paper width	Approx. 381 mm	[]	Offered
	Printing speed		cps	
	Number of copies	Three	[]	Offered
5.5	Programme storage	Required	[X]	On Floppy disk []
		Capacity	MB	Access time ms
		Other		
5.6	System Boot-up on power-on	Auto	[X]	
5.7	Software features:			
	a) Online Programming	Required	[X]	
	b) Online Programme modification	Required	[X]	
	c) Disable/Force facility	Required	[X]	
	d) Power flow on Ladder/ logic	Required	[X]	
	e) First out alarm Capability	Required	[X]	
	f) Self diagnostics	Required	[X]	
	g) I/O mapping	Required	[X]	
	h) Plant operation	Required	[]	
	i) Alarm Printing	Required	[X]	
	j) Documentation	Required	[X]	



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	k) Ladder Logic Monitoring	R	equired	[X]				
	l) Graphic capability	R	equired	[X]				
	m) Shutdown Report Generation & printing Required							
		N	umber of pages		<u></u>			
5.8*	Additional special software:							
	a)							
	b)							
	c)							
	d)							
	e)							
5.9	Interface with DCS			*Model No				
	a)** Type of Interface	Se	erial	[]	Bi-directional []			
	RS-232 C			[]	Other			
	b)* Protocol Type	M	ODBUS	[]	Other			
	c)* Module details:							
	CONFIGURATION	INTERFACE NUMBER OF MODEL No. MODULES		NUMBER OF ADAPTERS PER MODULE				
	DUAL PROCESSOR							
	TWO INDEPENDENT PLC's							
	TRIPLE MODULAR REDUNDANT							
	d)* Total time taken to Display alarms generated by PLC on DCS operator consoles							
5.10#	Power Supply							
	a) System	1	0 V ac,50 Hz UI	PS[X]				
	b) Interrogation voltage	24	V dc	[X]				
	c) Output Contact Voltage	24	V dc	[X]				
	d) AC Voltage Distribution	V	endor's scope	[X]				
	e) DC Voltage Distribution	Vendor's Scope		[X]				
	f) Dual redundant 24 V dc	V	endor's Scope	[X]				



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	<u> 13. FUREIGN DE</u>	LVICE INTERFA	<u>ACE</u>		
A)	INTERFACE WITH PLC		*Mo	del No	_
1.**	Type of Interface	Serial	[]	Bi-directional	[]
		RS-232 C/422/485	[]	Other	_
2.	Type of Redundancy:				
a)#	For Dual redundant processor/ TMR system	Dual Redundant	[X]		
		Active	[X]		
	** Switchover time			<u>S</u>	
b)	For two PLC configuration	One per PLC	[]		
3.*	Input capability:	Number of digital in	nputs		_
4.*	Standard interface software available for	MODBUS	[]		
		Other			
5.*	Proven interface software available for follow	wing PLC's:			
	a) Make	_	Mod	el No	_
	b) Make	_	Mod	el No	_
	c) Make	<u> </u>	Mod	el No	_
	d) Make	_	Mod	el No	_
6.#	Functional Requirements:				
	Type of communication	Simplex	[]	Duplex	[X]
	Automatic Time synchronization	Required	[X]		
	Transfer of PLC diagnostics	Required	[X]		
	Interface diagnostics available at	Central level	[X]	Local level	[X]
	Single message transfer in case of two PLC		Requ	uired	[]
			Othe	er	
B)	INTERFACE WITH OTHER FOREIGN DE	EVICES	*Mo	del No	_
1.**#	Type of Interface	Serial [] Other	RS-2	232 C/422/485	[
2.#	Communication Protocol	MODBUS	[X]	Vendor Standard	[]
3.#	Type of Redundancy	Dual Redundant	[X]	Active	[X]



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	** Switchover time			S	
4.*	Input capability:	Number of Analog	inputs		
	Number of Digital inputs		_		
5.*	Standard interface software available for	MC	DBUS	PROTOCOL	[X]
			Othe	r	
6.*	Proven interface software available for follo	owing vendors:			
	a) Make	_	Mod	el No	
	b) Make	<u> </u>	Mod	el No	
	c) Make	_	Mod	el No	
	d) Make	_	Mod	el No	<u> </u>
7.#	Functional Requirements:				
	Type of communication	Simplex	[]	Duplex	[X]
	Automatic Time synchronization		Requ	iired	[X]
	Transfer of device diagnostics		Requ	iired	[X]
	Transfer of device data & validation codes		Requ	iired	[X]
	Transfer of calibration data		Requ	iired	[X]
	Interface diagnostics available at	Central level	[X]	Local level	[X]
			Othe	r	
8.*	Time taken to transfer data from Device to I	DCS operator console	·	<u>S</u>	
	Note-Contractor shall fill up this sheet separ	rately for each foreign	n devic	e.	
C)	Interface with Anti Surge Control system				
1.*#	Type of Interface	Serial	[x]	RS 232/485	[x]
		A a 41. a			
2 //		Any other			
2.#	Communication Protocol	Vendor Standard	[x]	MOD BUS	[]
3.#	No. of AS control system	Two	[x]		
	Interfaces	Maximum			
4.*	Input capability	No. of Analog inpu			
		No. of Digital inpu	ts		



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5.*	Proven interface available for anti-surge cor	ntrol system			
	a) Make	_	Mod	el No	_
	b) Make		Mod	el No	
	c) Make		Mod	el No	
	d) Make	_	Mod	el No	_
6.#	Functional Requirement				
	Type of communication		Dup	lex	[x]
	Automatic Time Synchronisation		Requ	d.	[x]
	Transfer of AS control		Requ	1.	[x]
	system diagnostics				
	Interface diagnostics available at	Central level	[x]	Local level	[x]
			Any	other	
7.*	Time taken to transfer data				
	from AS system to operator console				
8.*	Model No.			_	
D)	Interface with Vibration Monitoring system				
1.*#	Type of Interface	Serial	[x]	RS 232	[]
	RS 422/485	[x]	Any	other	
2.#	Communication Protocol	Vendor Standard	[x]	MOD BUS	[X]
3.#	No. of VM System	As per Input/Outpu	ut sumn	nary	[x]
	Interfaces				
4.*	Input capability	No. of Analog inpu	uts		
	•	No. of Digital inpu	ıts		
5.*#	Proven interface software		Mak	e- Bentley Nevada	a [x]
	available for VM system		Any	other	
6.#	Functional Requirement				
	Type of communication		Simp	olex	[x]
	Automatic Time Synchronisation		Requ	i .	[x]



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	Transfer of VM System		Reqd		[x]
	diagnostics				
	Interface diagnostics available at	Central level	[x]	Local level	[x]
	Any other			_	
7.*	Time taken to transfer data from			_	
	VM system to operator console				
8.*	Model No.			_	
	14. HARDWIF	RED INSTRUME	NTS		
A)	INDICATOR/ INDICATING CONTROL	LER/ RECORDER (1	NOT AI	PPLICABLE)	
1#	Туре	Digital	[]	Other	_
		μp based	[]	Configurable	[]
		Other			
2#	Mounting	Flush	[]	Multi-case	[]
		Other			
3#	Enclosure	General purpose	[]		
4#	Intrinsic safe	Yes	[]]	IEC Class	<u> </u>
	With	external Barriers	[]		
5#	Power supply for transmitters	24 V dc	[]	Other	<u> </u>
	with instrument	[] Redundant con	nmon	[]	
6#	Input	4-20 mA dc(2-wir	e) []		
7#	Self diagnostic feature	Required	[]	Local level	[]
			Other	r_	
8#	Communication with DCS	Available	[]	Not available	[]
9.	Indicator		*Moo	del No	_
	a)# Number of inputs per instrument	One	[]	Two	[]
			Other	r_	
	b)# Input selection for display	Continuous	[]		
	thru' instrument keyboard		[]		



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c)#	Display requirement	Bar graph	[] Digital []
10	Indicating Controller		*Model No
	a)* Architecture	Integral	[] Split []
	b)# Output	4-20 mA dc	[]
	c)* Number of I/O per instrument	Analog inputs	Analog outputs
	d)# Scan time	250 ms	[] Other
	e)# Display requirement	Bar graph	[] Digital []
	f)# Display selection	Continuous	[]
	thru' instrument keyboard		[]
	g)# Control mode selection	Required	[]
	Auto/ cascade/ manual		[]
	Local/ computer		[]
	h)# Set point adjustment	Required	[]
	i)# Manual loader	Required	[]
	j)# Auto tracking of controller	Required	[]
	k)# Other Specification: As per control	ler and data-acquisition	on subsystem.
11	Recorder (NOT APPLICABLE)		*Model No
	a)** Chart	Strip	[X] Size
	b)* Recording type		<u> </u>
	c)* Chart speed	25 mm/hr	[X]
B)	HARDWIRED ANNUNCIATOR		*Model No
	a)# Type	Audio	[X] Visual [X]
	b)# Sequence	As per ANSI/ISA	-18.1 F3A / A2
	c)# Mounting	Flush	[X]
	d)# Power supply location	with logic	[X]
	e)# Logic Unit	Integral	[X] Separate []
	f)# Display type	Back lighted	[X] Two lamp/alarm [X]
		Clustered LED Ty	ppe/Alarm [X]



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	g)# *window size		_		
	h)# Hooters	External to DCS	[X]	Solid state	[X]
	i)# Alarm Acknowledgement	Integral	[]	Separate	[X]
C)	HARDWIRED SWITCHES/ PUSHBUTTO	NS	*Mak	e	_
			*Mod	el No	_
	a)# Contact type	Silver alloy plated	[X] M	lake before break	[X]
	b)# Sealed Contact housing	Required	[X]		
	c)# Contact rating	5 A @ 220 V ac	[X] 2	A @ 24 V dc	[X]
		5 A @ 110 V ac	[X]		
	d) Lamp type	Clustered LED Typ	e/Alarn	n[X]	
D)	RECEIVER SWITCHES (ALARM CARD)	(NOT APPLICA	ABLE)		
	*Make_	*Mo	del No.		
	a)# Type of input	4-20 mA (2 wire)	[]	1-5 V dc	[]
	b)# Type of contact	SPDT	[]		
	c)# Contact rating	2 A @ 24 V dc	[]	Other	_
	d)# Number of settings per module	One	[]	Two	[]
	e)# Power Supply	24 V dc	[]	Other	_
	f)* Mounting	Rack	[]	Surface	[]
E)	TRIP AMPLIFIER (NOT APPLICABLE)		*Mak	e	_
			*Mod	el No	_
	a)# Type of input Grounded the	rmocouple	[]	Type T/E/K	[]
		RTD Pt 100 DIN 43	3760		[]
	b)* Maximum source resistance		2000	Ω	
	c)# T/c burn-out Protection	Required	[]	Upscale	[X]
		Downscale	[]		
	d)# RTD open protection	Required	[] F	ield Configurable	[]
	e)# Type of contact	SPDT	[]		
	f)# Contact rating	2 A @ 24 V dc	[]	Other	_



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	g)# Number of settings per module	One	[]	Two	[]
	h)# Power supply	110 V ac, 50 Hz	[]	Other	_
	i)* Mounting	Rack	[]	Surface	[]
F)	MV/I CONVERTER (NOT APPLICABLE)		*Make	_
	*Model No	_			
	a)# Type of input Grounded ther	mocouple	[]	Type T/E/K	[]
	b)* Maximum source resistance		2000 9	<u>0</u>	
	c)# Thermocouple burn-out protection	Required	[]		
	d)# Cold junction compensation	Required e)# Signal linearisati	[] ion	Required	[]
	f)* Input isolation	Available	[]	Not available	[]
	g)# Output	4-20 mA	[]		
	h)# Maximum load resistance	600 Ω @ 24 V dc	[]		
	i)# Power supply	110 V ac, 50 Hz	[]	Other	_
	j)* Mounting	Rack	[]	Surface	[]
G)	SIGNAL ISOLATOR		*Make	e	_
			*Mode	el No	_
	a)# Input		4-20 n	nA dc (2 wire)	[X]
	b)# Output		4-20 n	nA dc	[X]
	c)# Isolation		Requi	red	[X]
	d)# Number of outputs		Two		[X]
	e)# Power Supply	110 V ac, 50 Hz	[]	24 V dc	[]
			Other		_
	f)# Mounting	Rack	[]	Surface	[]
	15. INTRINSIC S	AFETY BARRII	ERS		
1	Function To	limit the transfer of en	nergy to	hazardous area.	
2	Hazardous area Classification	NEC Division 1 Gr.	В, С &	D	
3	Location	Control room	[X]	Safe Area	[X]
4	Specifications				



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4.1#	Type		MTL 5000 s	series or	equiva	alent	[X]
			Single		[X]	Dual	[]
			Non Isolatir	ng	[]	Isolating	[X]
			Three Port		[X]		
			Voltage Le	vel – 250) V**		[X]
	and the state of t	1. 1.1.1.1.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2	0.77				
		voltage level is less than 250 n permitted isolation voltage	· ·		er the	harrier cahinet	
(b)	Barrier cabinet shall b	be provided with redundant p					or the
4.2*	pplied isolation voltage External Powe		Required		ſ]	Not Required	[]
	110 V, 50 Hz	11 3	[]		24 V	_	[]
	,		Others_				. ,
4.3*	Barrier specifi	cation			_		
4.3.1	Transfer accur	acy Ter	mperature 0.05	%	[X]	Analog 0.075	% [X]
4.3.2	Response time	;	Analog 250	μsec	[X]	Digital 10 mse	ec [X]
4.3.3	Status indicati	on	Required		[X]		
4.3.4	Cold Junction	Error	1°C		[X]		
4.3.5	Cable Paramet	ers	As per enclo	osed tabl	e		
4.4#	Maximum fau	lt voltage	250 V rms.		[X]		
4.5*	Grounding	Individ	ual thru' bus ba	ar	[]		
5#	Certification	Appro	val Certificate	from rec	ognize	ed statutory body	y
Not	tes: 5)# Vendor to ensu	re that the Barriers are suitab	ole for the follo	wing cat	ole par	ameters.	
	SIGNAL TYPE	CABLE TYPE	R(Ω/km)	L(M)	h/km)	$L/R(H/\Omega)$	C(pF/m)
	4-20 mA & CON	12p X 0.5 mm ² Shielded	39.7	-		25	400
	TAC	(16 strand					
	TS	each of dia 0.2 mm)					
6)#	The type and I order.	Model No. of transmitters and	d I/P converters	s shall be	intim	ated after the pl	acement of
7)#	In case of bulk are to be used	Power Supply, dual channel	l Barriers must	be used	whene	ever non-isolatir	ng barriers
	16. CONSO	OLES, CONTROL PA	NEL, CABI	NET A	ND A	ACCESSOR	<u>IES</u>
	*Model No						
1*	Installation Lo	ecation					
	a) Location		Indoor		[X]		
	b) Flooring		False		[X]	Concrete	[X]



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	c) Floor Loading Limits		N	Ю	[]	1200 k	g/m ²	[]
	d) Vibration		N	lo	[X]	Yes		[]
	e) Air Conditioning		Y	Zes Zes	[X]	No		[]
2	General Details							
	a)# Type		S	elf Supported	d [X]	Free S	tanding	[X]
	b)# Panel		E	Inclosed Cubi	icle [X]			
	c) Graphic requirements		N	Non-Graphic	[X]	Semi-C	Graphic	[]
	d)# Lighting Requiremen	nt	N	lo	[]	Yes		[X]
		For	Inside Pane	l/Cabinet	[X]	Door S	Switch	[X]
		Power su	ipply 230 V	ac, 50 HZ	[X]	Other_		_
	e)* Ventilation		Y	Zes Zes	[X]	No		[]
			V	Vith louvers	[]	With F	an	[]
	f)# Fan Failure Alarm		F	Required	[X]			
		(On Operator	Console	[X]			
	g)# Doors		Y	'es	[X]	No		[]
			R	Rear	[X]	Side		[]
	h)# Door Width		Γ	Oouble Door	[]			
	Each max of	300 mm (for system c	abinets)	[X]			
	Each max. o	f 600mm ((for panels)		[X]			
	i)# Special Features		V	ibration-prod	of [X]	Explos	ion-proo	f []
			Ι	Prip proof	[]	Pressu	rized	[]
	j)# Cable entry		E	Bottom	[X]	Тор		[]
			(Glands	[X]			
	k)# Receptacles		For 110 V	/240 V ac	[X]	For Telep	hone Set	[X]
3	a) Size and Quantity:							
	Note: Height for all cabi	nets shall b	oe 2200 mm	Max., includ	ing channel	base of 1	00 mm.	
	DESCRIPTION	MAKE	DIMI	ENSIONS IN	mm	QTY.		IGHT
			WIDTH	HEIGHT	DEPTH			FULLY ADED



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_				1			
	CONTROL PANEL						
	DCS SYSTEM CABINET						
	AS POWER DISTRIBUTION CABINET						
•	DC POWER DISTRIBUTION CABINET						
	TRIP AMPLIFIER/ AUXILLARY CABINET						
	PLC I/O CABINET						
•	PLC PROCESSOR CABINET						
•	PLC CONSOLE						
•	OPERATOR CONSOLE						
•	ENGINEER CONSOLE						
•	HARDWIRED CONSOLE						
	b) Channel Base		1	00 X 50 X 6	mm [X]	MS	[X]
4#	Painting Colour:						
	a) External		(Opaline Green	(IS 275)		[]
			I	ight Admiral	ty Grey (IS	697)	[]
	b) Internal		P	Pale Cream(IS	352)	[X]	
			E	Beige (IS 388))		[]
	c) Channel Base		E	Black			[X]
	d) Panel Finish		N	Non Glossy H	igh Satin		[X]
5	Constructional details:						
	a) Control Panel						
	b)* Front Plate	CRO	CA 3.2 mm	thick steel	[X]		
		HR	CA 5 mm th	nick steel	[X]	Welded to Frame	[X]
	c)# Side and Top Plates	CRO	CA 2 mm T	hick steel	[]	Welded to frame	[]
	d)# System Cabinets Fro	nt, Sides &	Тор		CRCA 2	mm Thick steel	[X]
					Welded	to frame	[X]



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	e)# Door Panel	CRCA 1.6 mm T	hick steel [X]	Single Side hinge []
		Both Side hinge	[]	Concealed Hinges [X]
		Flush Pull Handl	e [X]	Lever type Handle []
	f)* Anchor Bolt Size			
	g)# Frame angle size	50 X 50 X 4mm	[X]	
	h)** Lifting Eye Bolt	Required	[X]	Size
	i) Card Rack Size	19" Rack	[X]	
	j)* Card Rack Type	Swing out pivote	d []	Fixed []
6.	Wiring:			
	a)# Type	General Purpose	[X]	
		Intrinsic Safe [X]	For Barrier Racks &	other
			Inti	rinsically safe equipment.
	b) Wiring details	As per no	tes attached [X]	
	c)# 110 V ac, 50 Hz UPS Wiri	ng		
	External to Cabinet/Panel	min. 3 x 2 armoured.	• •	ctor PVC insulated and
	Inside the Cabinet/Panel	min. 19 st	rands, 16 AWG Coppe	er conductor PVC insulated.
	d)# 230 V ac Wiring	1.5 mm ² C	Copper Conductor PVC	C Insulated Armoured.
	Low voltage int. to cabinet/pa	nel min. 19 st	rands, 16 AWG Coppe	er Conductor PVC insulated.
	e)# Signal Wiring / 24 V dc W	iring		
	External to cabinet/ panel		win twisted, individua all drain, PVC insulate	l shielded, overall shielded and armoured.
	Inside the Cabinet Panel		min. 7 x 20 AWG Cop twin twisted and shiel	•
	f)# Terminal Type	Screw cla	mp type with Pressure	Plate.
	g)# Terminal size for Signal	Suitable fo	or min. 2.5 mm² size C	Conductor
	h) For Power Distribution	Suitable fo	or min. 4 mm² size Co	nductor
	i)# Terminal Block	Clip-on C	hannel Mounted stack	Type
	j) Wiring Colour Code			
	i)# Power supply (110 V, 240	V ac) Ho	t Red	[X]



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		-	Neutral	Black	[X]
			Earth	Green	[X]
	ii)# PLC dc Wiring (24 V dc)		Positive	Red	[X]
		- -	Negative	Black	[X]
	iii)# Alarm System			White	[X]
	iv)# Control & Shutdown			Yellow	[X]
	v)# Analog Signals (Intrinsically	y safe)	Light Blue	[X]	
7**#	Power Distribution Box				
	a) Location	Inside conso	le/ panel/ cabin	et [X]	
	b) Power supply Isolation	-		nt with fuse and swit I, else MCB shall be	
	c) Fuse Type/Rating	HRC		[X]	
	d) Switch Type/Rating	DPST / 5 A	@ 230 V ac	[X]	
	<u>17. N</u>	OTES ON	WIRING		
1#	All wiring shall conform to API R be routed under false flooring with				
2#	All wiring inside racks, cabinets, a plastic raceways arranged to perm adjustments, repair and removal.				
	All wiring in the raceways shall be vendor at marshalling rack with casectional area shall not exceed 50 shall be used for wire entry into in	able glanding % of the race	including supply way cross section	y of cable glands. To onal area. Rubber Pla	otal wiring cross- astic grommets
3#	Separate wiring raceways shall be intrinsically safe wiring. Parallel r				
4#	Vendor can alternately offer pre-fapanels.	abricated cabl	es for interconn	ection between diffe	erent cabinets and
5#	Wire termination shall be done us	ing self insula	ting crimping lu	ıgs.	
6#	More than two wires shall not be for looping shall be avoided.	terminated on	one side of sing	gle terminal. The use	of shorting links
7#	Terminal housing shall be strictly Following points should be considered.		nsiderations for	accessibility and ma	intenance.
a)#	Distance between terminal strip ar	nd side of the	cabinet parallel	to the strip, up to 50	terminals, shall

be minimum 50 mm.



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b)#	Distance between terminal strip and, top and bottom of the cabinet shall be minimum 75 mm.				
c)#	Distance between two adjacent terminal strips shall be minimum 100 mm.				
d)#	Additional distance for each additional 25 terminals shall be minimum 25 mm.				
e)#	Distance between cable gland plate and the bottom of the strip shall be minimum 300 mm.				
8#	All terminal strips shall be mounted on suitable anodised metallic or plastic stand-off.				
9#	No splicing is allowed in between wire/ cable straight run.				
10#	Terminal strips shall be arranged group-wise for incoming and outgoing cables separately. 20% spare terminals shall be provided as a minimum.				
11#	Cabinet and rack layout shall be made considering proper accessibility and maintenance. 15% spare accessories like relays, switches, lamps, fuses etc., shall be provided as a minimum.				
12#	Terminal blocks for intrinsically safe wiring shall be separate.				
NOTE: The distances given in point no 7 are excluding the width of the race-way					

NOTE:	The distances given in point no. 7 are	excluding the width	of the race-way.		
	<u>18.</u>	TRAINING KIT	<u> </u>		
	*Model No				
1#	Number of Training Consoles	One	[X]		
2#	Number of CRT's	One	[X]	Other TF	<u>r</u>
3#	Type of Consoles electronics	Individual	[]	Other	
4** #	Type of keyboards				
	Engineering Keyboard	Required	[X]	One	[X]
	Operator Keyboard	Required	[X]	One	[X]
	Maintenance Keyboard	Required	[]	One	[]
5#	Number of printers	One	[X]		
6	System requirements:				
	a)** System modules:				
	DEVICE NAME	MODEL No.	MODULE TYPE INSTALLED (list out all installed cards in sub-system)		MODULE S OFFERED
	CONTROLLER & DATA ACQUISITION SUB- SYSTEM		J		
	ENGINEER INTERFACE SUB-				



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	SYSTEM					
	OPERATOR					
	INTERFACE SUB-					
	SYSTEM ANY OTHER (places					
	ANY OTHER (please specify)					
	b)# Signal simulator/ generate	or	Required	[X]		
	c)# Application software to n	neet al	1			
	functional requirements of system. Required [X]					
7#	Facilities and capabilities	Sta	nd alone system for the	ne following fu	nctions:	
		Tra	[X]			
		Training of plant operators Training of maintenance staff			[X]	
		Che	ecking of system hard	ware and elect	ronics module	
8#	Software Packages	Dis	tillation column			[]
		Boi	ler			[]
		Rea	actor			[]
		An	y other		<u>—</u>	
9#	Minimum I/O requirement	Ana	alog Inputs for contro	1:	24	[]
		Ana	alog Inputs for Data-A	Acquisition:	36	[]
		Ana	alog Outputs:		24	[]
		Dig	gital Inputs:		12	[]
Note:	Training Kit must include all component hardware including all functionally distributed database, storage hardware/software, engineering console (if separately necessary for the system).					
	19. SEQUE	ENCE	E OF EVENT RE	CORDER (SER)	
	*Model No					
A.	Offered System Details					
1#	a) Dedicated Sequence of I	Event	Recorder []			
	b) Combined with PLC			[X]		
2*	Total no. of cabinets offered					
	a)* SER Cabinets					
	b)* Alarm Card Cabinets					



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3*	MTBF		hours	
4*.	MTTR		hours	
B.	SPECIFICATIONS			
1#	Type	μP Based	[X] Configurable	[X]
	CPU Ty	ре		
2#	Type of Enclosure	General Pur	pose [X]	
3#	Configuration	Single	[X] Duplex	[]
		Switch Over	r Time (if Duplex)	_sec
4#	Scan time		msec	
5#	Processor cycle time		msec	
6#	Resolution Required	1 msec	[] 100 msec	[]
		10 msec	[] 50 msec	[]
		Any Other	PLC Scan Time	
7*	INPUT DETAILS			
	a) Input Isolation	Required	[]	
	b) Type of Input Modules	1	T	
	Type of Module	Model No.	No. of Inputs per module	
	4-20 mA DC 2 wire (HART) []			
	0-20 mA DC (2 wire) []			
	1-5 V DC []			
	0.25-1.25 V DC []			
	Potential Free Contact [X]			
	RS 232 C []			
	c) Max. No. of Input / Module			
	Analog	8	[] 16	[]
		32	[]	
	Contacts	16	[] 32	[]
	d) A/D Converter Resolution	1500 steps	[X] Actual	
	e) Load riving Capability	750 Ω	[X] Actual	_



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8*	SER Capability					
	Analog Resolution Contact Input Resolution			mse	С	
				mse	e	
9*	SER PC		Required	[X]	Not Required	[]
		Function of PC:				
		SEI	R Configuration	[X]		
		Ala	rm Display	[X]		
		Dia	gnostics	[X]		
		Any	Other			
		Alarm Printer	Required	[X]		
		Type	Laser	[X]		
		Alarm Data Storage	Required	[X]		
		Storage Time	96 hours	[X]		
10*	Interfacing with: (II	NCLUDED IN PLC)				
		PLC	Yes	[]	No	[]
		DCS	Yes	[]	No	[]
		AIMS	Yes	[]	No	[]
11*	No. of Input Points		256 Nos.	[]		
			512 Nos.	[]		
			1024 Nos.	[]		
12*	Power Supply		110 V 50 Hz	[X]		