Vivek Mudgal

address:
A-313, LLR Hall
IIT Kharagpur
Kharagpur, WB 721302 INDIA

email: vivekmudgal001@iitkgp.ac.in
*web:*vivekmudgal.in
voice: +91 7407777007
GitHub: https://github.com/vivekmudgal

Education

Indian Institute of Technology Kharagpur *July 2015 - July 2019(Expected)*
B.Tech in Electrical Engineering CGPA: 8.22 /10
Minor in Computer Science and Engineering

Gyan Ganga International School *March 2014*
All India Senior School Certificate Examination 90.6%
All India Secondary School Examination CGPA: 10/10

Research

IIT Kharagpur May 2017 - July 2017
Discrete-time Control Systems *Prof. in charge:Dr. Arun Ghosh*

- Designed and implemented a discrete time controller for a non linear magnetic leviation model on Simulink
- Observed the effect of the change in sampling time and compared the controller with continous time controllers
- Currently working on developing a 2-DOF controller and implementing it on real world system.

Aerial Robotics Kharagpur January 2016 - Present
Team Member, Control and Embedded Systems *Prof. in charge:Dr Somesh Kumar*

- Designed and fabricated a dual flip flop based emergency kill switch of a quadrotor for safety purpose
- Made the Simulink model of a quadrotor along with PID control to study its dynamics and control

Position of Responsibility

Technology Robotix Society, IIT Kharagpur February 2017-Present
Head

- I am responsible for designing an autonomous event to be held at Kshitij 2018, Asias largest techno- management fest. I help conduct technical workshops across India to spread the culture of robotics. Also I organize weekly lectures on manual and autonomous robotics for over 300 students round the year along with workshops and hackathons. I lead a three-tier team to successful planning and execution of all these events.

IEEE Robotics Winter Workshop December 2016
Autonomous Robotics Mentor

- I conducted a week-long workshop for 43 first and second year undergraduates at IIT Kharagpur. As a final project of the workshop I helped the students build a gesture controlled robot capable of removing small obstacles in its path. I taught about microcontrollers, and concepts like ADC, Timers, Interrupts, Communication Protocols and basic control theory.

Projects

Smart Steer Wheel Chair Attachment April 2016

- Worked in a 20 membered team for Inter hall Hardware Modelling to make an autonomous Wheelchair
- Contributed in interfacing sensors including SONARs, GPS; writing obstacle avoidance algorithms on ROS and designing Eagle CAD circuits

Achievements

International Aerial Robotics Competition August 2017

- Represented IIT Kharagpur in the "2017 Dream Angel Cup" held in Beijing. Won an award for the Most Innovative Design in Asia/Pacific Venue

Inter Hall Hardware Modelling February 2016

- Part of a Gold winning team which designed an attachment to increase the utility of an ordinary wheelchair

JEE Advanced June 2015

- Secured an All India Rank of 975 in JEE Advanced, 2015 among those who qualified with a percentile of 99.5

Coursework

IIT Kharagpur

Completed
Electrical Machines
Analog Electronics
Signals & Networks
Introduction to Electronics
Transform Calculus
Programming & Data Structures

Ongoing
Control Systems Engineering
Linear Algebra
Digital Electronics
Power Electronics
Data Analytics

Additional Courses

Completed
Control of Mobile Robots(Coursera)

Ongoing
Machine Learning (Coursera)

Skills

Computer Languages
C/C++ (Proficient), Python, MATLAB

Software & Tools
ROS, OpenCV, Arduino, AVR, Git, Linux, LaTeX, Eagle CAD, LabView, PSpice, Simulink

October 9, 2017