

ELL409: MACHINE LEARNING

ASSIGNMENT 3

Support Vector Regression

Vivek Muskan
2017MT10755

Dataset is Boston House Pricing Data, consisting of 506 rows and 13 features and a class containing the Median value of owner-occupied homes to be predicted later.

First will look after SVR implementation using CVXOPT

Theory and Algorithm

We need to solve a dual problem in this, as discussed in the class. (From Bishop Book)

$$\begin{aligned}\tilde{L}(\mathbf{a}, \hat{\mathbf{a}}) = & -\frac{1}{2} \sum_{n=1}^N \sum_{m=1}^N (a_n - \hat{a}_n)(a_m - \hat{a}_m)k(\mathbf{x}_n, \mathbf{x}_m) \\ & -\epsilon \sum_{n=1}^N (a_n + \hat{a}_n) + \sum_{n=1}^N (a_n - \hat{a}_n)t_n\end{aligned}$$

We need to maximize this equation with respect to constraints

$$\sum_{n=1}^N (a_n - \hat{a}_n) = 0$$

$$0 \leq a_n \leq C$$

$$0 \leq \hat{a}_n \leq C$$

Where C and epsilon are hyperparameters.

Using the value of “a” and “a^” found we can find the value of y(x), which is as follows:

$$y(\mathbf{x}) = \sum_{n=1}^N (a_n - \hat{a}_n)k(\mathbf{x}, \mathbf{x}_n) + b$$

Where b is

$$\begin{aligned} b &= t_n - \epsilon - \mathbf{w}^T \phi(\mathbf{x}_n) \\ &= t_n - \epsilon - \sum_{m=1}^N (a_m - \hat{a}_m) k(\mathbf{x}_n, \mathbf{x}_m) \end{aligned}$$

Then we took the average of all the b for which points are support vectors.

The above dual problem is solved using a QP Solver, whose standard form is given below:

$$\begin{aligned} \min_x \quad & \frac{1}{2} x^T P x + q^T x \\ \text{subject to} \quad & Gx \preceq h \\ & Ax = b \end{aligned}$$

We can get the value of x using the following equations:

```
sol = solvers.qp(P,q,G,h,A,b)
sol['x']
```

Hence, we need to convert our dual problem in the above form. So, took x as a matrix of $[a, a^*]$ and then changes each equation accordingly, which is shown below.

Implemented SVR

- At first Data framing and Normalization has been done and then in Order to frame optimization problem into Standard form, Kernel Function is defined.



The different kernel function is introduced as:

$$k(\mathbf{x}_i, \mathbf{x}_j) = (\mathbf{x}_i \cdot \mathbf{x}_j + 1)^d$$

Polynomial kernel equation

$$k(\mathbf{x}_i, \mathbf{x}_j) = \exp(-\gamma \|\mathbf{x}_i - \mathbf{x}_j\|^2)$$

Gaussian radial basis function (RBF)

```
[ ] def Kernel(name, x, y, gamma):  
    if name == 'linear':  
        return np.dot(x,y)  
  
    elif name == 'rbf':  
        #gamma = 1/(np.var(x) + np.var(y))  
        return np.exp(-gamma*np.matmul((x-y).transpose(),(x-y)))  
  
    elif name == 'poly':  
        return (np.dot(x,y)+1)**(2) # Quadratic Kernel  
  
    else:  
        print("Please Enter - 'linear' or 'poly' or 'rbf' ")
```

- After that predictor function which will help in predicting the median using the equation of Hyperplane as $y(x)$:

$$y(\mathbf{x}) = \sum_{n=1}^N (a_n - \hat{a}_n) k(\mathbf{x}, \mathbf{x}_n) + b$$

```
[ ] def predictor(X_train,x,Alpha,B,s, gamma):  
    ans = 0  
    N = int(len(Alpha)/2)  
    for i in range(N):  
        ans += (Alpha[i]-Alpha[N+i])*Kernel(s,x,X_train[i], gamma)  
    return ans
```

- Then we splitted data into Training and Test dataset for K-Fold Cross Validation and Extracted (X,y) for both Training and Testing.

```
# K-Fold
k_fold_size = 101
no_of_fold = int(len(data)/k_fold_size)
count = 0
MSE = 0
for i in range(no_of_fold):

    count+=1
    print("Validation No : ",count," -----")

    X_test = np.array([data[j][: -1] for j in range(i*k_fold_size,(i+1)*k_fold_size)])
    Y_test = np.array([data[j][ -1] for j in range(i*k_fold_size,(i+1)*k_fold_size)])

    X_train = []
    Y_train = []
    for j in range(len(data)):
        if (j<i*k_fold_size) or (j>(i+1)*k_fold_size):
            X_train.append(data[j][: -1])
            Y_train.append(data[j][ -1])
    X_train = np.array(X_train)
    Y_train = np.array(Y_train)
```

- After that I fixed Hyper-parameters and then conversion of optimization equation into standard Matrix form. This was the crux of all steps.

IDEA: Equation consist (a, a^{\wedge}) as variable so take them as single vector [a a^{\wedge}] and then from dimension of P and backtracking summation I got following equation for every Matrix:

$$\begin{aligned}
 p &= \begin{bmatrix} K & -K \\ -K & K \end{bmatrix} & q &= \begin{bmatrix} y - \epsilon \\ -y - \epsilon \end{bmatrix} & I_{N \times N} &= \text{Identity} \\
 G &= \begin{bmatrix} -I & 0 \\ 0 & -I \\ I & 0 \\ 0 & I \end{bmatrix} & h &= \begin{bmatrix} 0 \\ 0 \\ cI \\ cI \end{bmatrix} & 0_{N \times N} &= \text{Zero} \\
 & & & & y_{N \times 1} &= \text{Label} \\
 & & & & K_{N \times N} &= \text{Kernel} \\
 A &= \begin{bmatrix} I & -I \end{bmatrix} & b &= \begin{bmatrix} 0 \end{bmatrix}
 \end{aligned}$$

```

# Hyper-parameters
epsilon = 0.1
C = 100
ker = 'linear'
gamma = 0.1

# Optimization Conversion
K = []
for x1 in X_train:
    row = []
    for x2 in X_train:
        row.append(Kernel(ker, x1, x2, gamma))
    K.append(row)

# Sub matrices
N = len(X_train)
K = matrix(np.array(K), tc='d')
I = matrix(np.eye(N), tc='d')
O = matrix(np.zeros([N, N]), tc='d')
Ones_N_1 = matrix(np.ones([N, 1]), tc='d')
Zeros_N_1 = matrix(np.zeros([N, 1]), tc='d')
y = matrix(Y_train, tc='d')

# Transformation into Standard Form
P = (1/2)*matrix([[K, -K], [-K, K]], tc='d')
q = matrix([(y-epsilon*Ones_N_1), -(y+epsilon*Ones_N_1)], tc='d')
G = matrix([[-I, O, I, O], [O, -I, O, I]], tc='d')
h = matrix([Zeros_N_1, Zeros_N_1, C*Ones_N_1, C*Ones_N_1], tc='d')
A = matrix([[matrix(1, (1, N), tc='d'), [matrix(-1, (1, N), tc='d')]]], tc='d')
b = matrix([0], tc='d')

```

All the useful matrices like Identity, Zeros, Ones and Kernel etc. is defined under Sub-matrices section of the code.

- Then Using CVXOPT, this problem has been solved to get $[a, a^*]$ and then B has been obtained.
- Then Using prediction on test data, I calculated the MSE keeping a margin of epsilon.

```
# Solving Optimization Problem
sol = solvers.qp(P,q,G,h,A,b)

x = sol['x']
B = matrix(1,(1,N),tc='d')*(matrix([[K],[-K]],tc='d')*x + matrix([(y-epsilon*Ones_N_1)]))
B /= N

# print(x.size)
# print(B.size)

# Prediction Stage
Y_predicted = []
sq_err = 0
for t,y in zip(X_test,Y_test):
    fx = predictor(X_train, t, x, B, ker,gamma)
    Y_predicted.append(fx)

    if(abs(y-fx) > epsilon):
        sq_err += (abs(y-fx)-epsilon)**2

Y_predicted = np.array(Y_predicted)
MSE += sq_err
#print("Squared Err from ",count,"th fold = ",sq_err)

# Data Visualisation
plt.scatter(X_test[:,0], Y_predicted, color = 'm',label = "Predicted")
plt.scatter(X_test[:,0], Y_test, color = 'g', label = "Actual")
plt.xlabel("1st Column of X")
plt.ylabel("Median Val")
plt.title("Validation Fold No : %d\nKernel=%s, C=%d, epsilon=%f, Gamma=%f\n MSE=%f"%(i+1,ker,C,epsilon,gamma,sq_err))
plt.legend()
plt.show()
```

- I took average of MSE over all folds and a scatter plot of predicted values (PINK) has been plotted versus 1st column of test data along with actual label (GREEN) to observe the deviation of prediction from actual value.

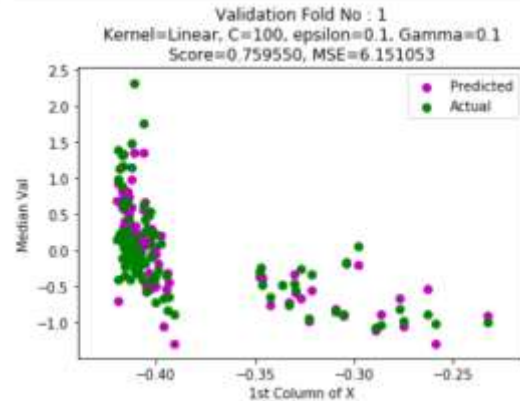
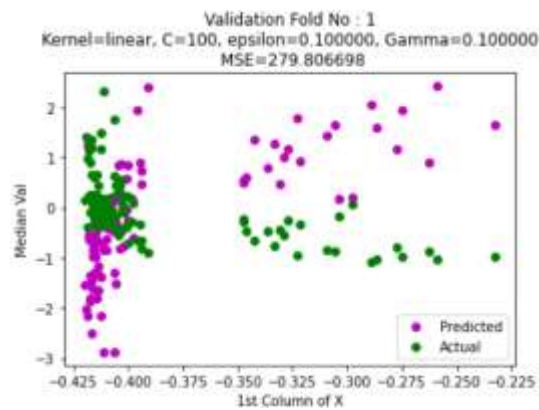
- Keeping all other aspect same, using Sci-kit learn, SVR has been used to plot similar graphs to compare.

Comparative Graph Plotting

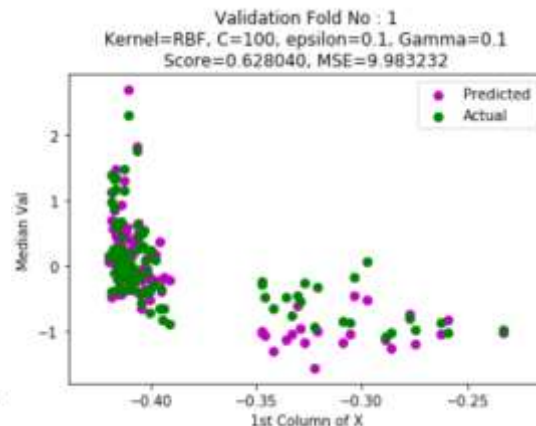
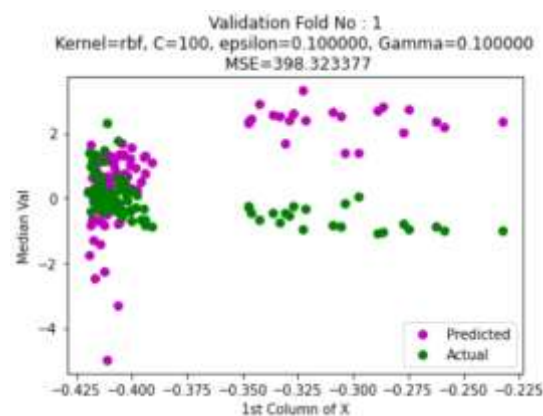
Implemented SVR

SK-learn

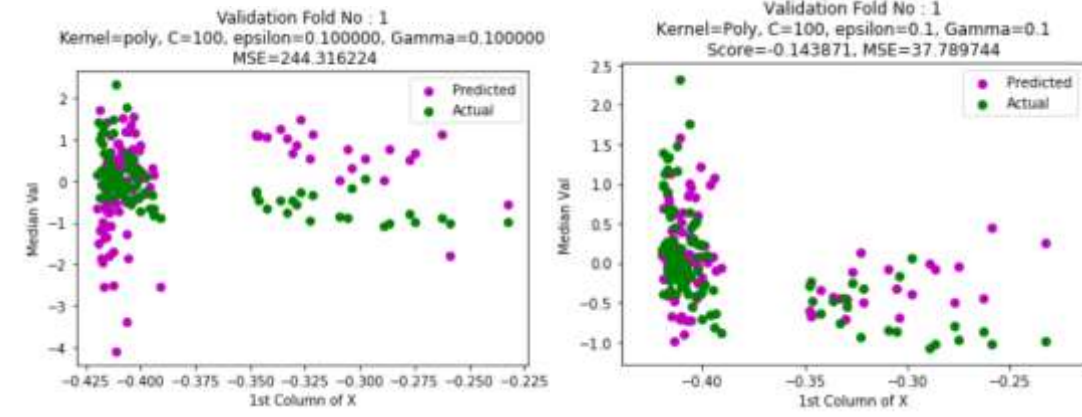
Kernel: Linear



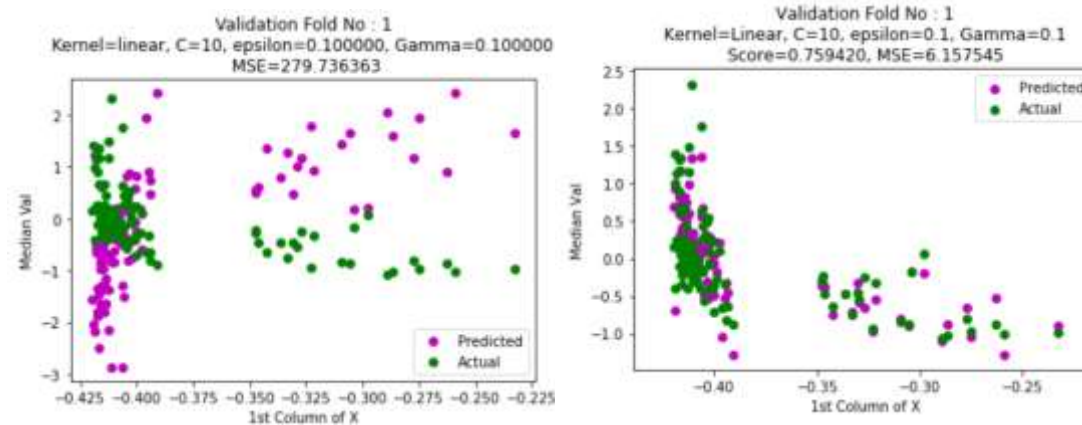
Kernel: RBF



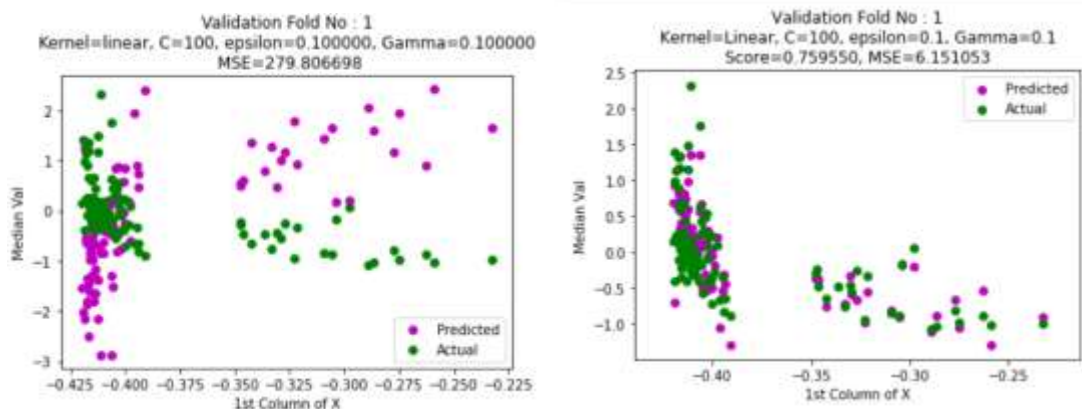
Kernel: Poly 2nd Degree



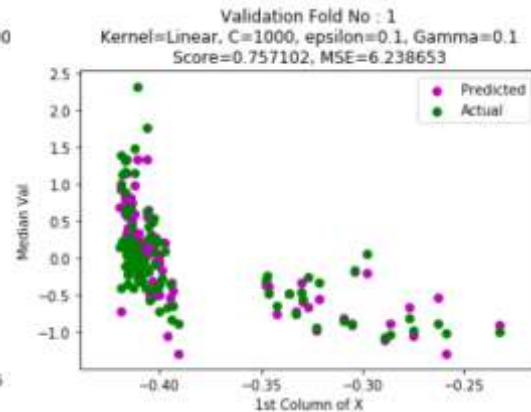
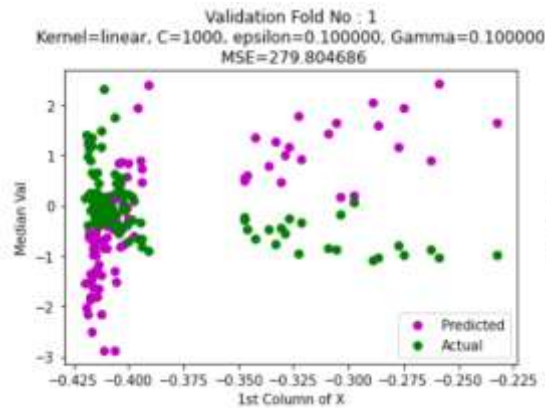
C = 10



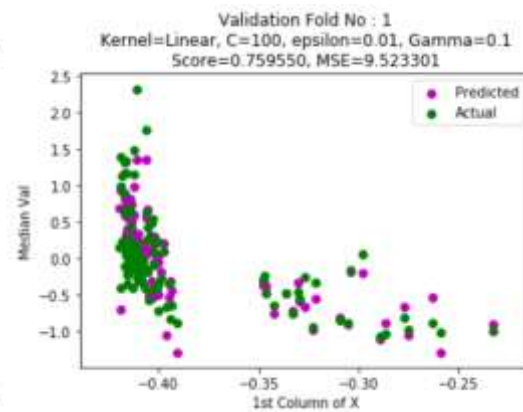
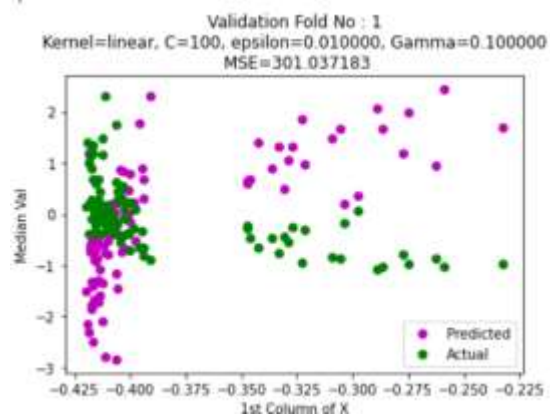
C = 100



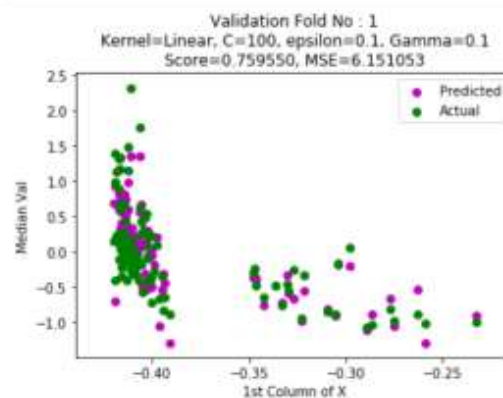
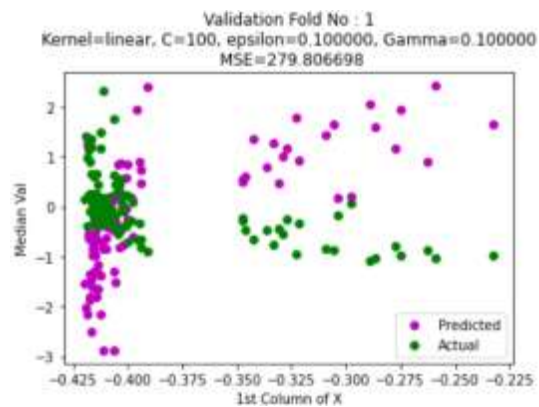
C = 1000



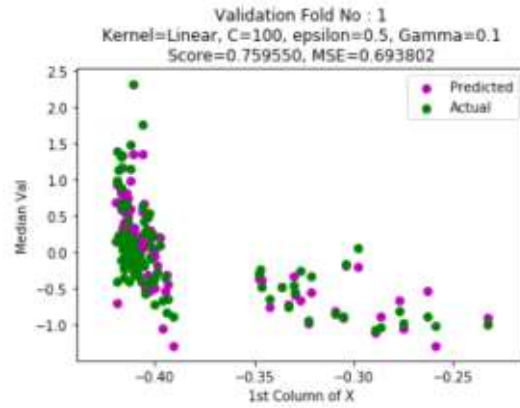
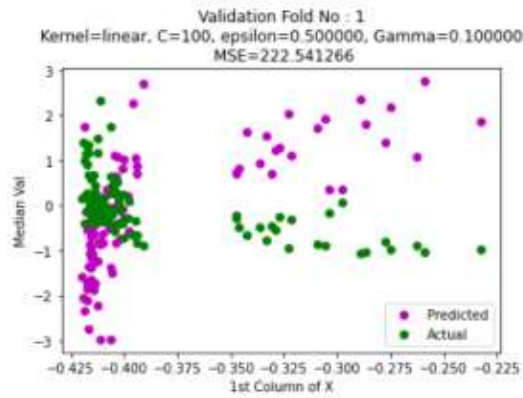
Epsilon = 0.01



Epsilon = 0.1



Epsilon = 0.5



Best Parameters came out to be:

Kernel: Linear

C = 100, Epsilon = 0.5

So, here is a plot of each validation fold for above parameters:

Implemented SVR

SK-Learn

