
LIX

École Polytechnique

The Realm of Cut-Elimination

Incorporating Tables into Proofs

by Vivek Nigam & Dale Miller

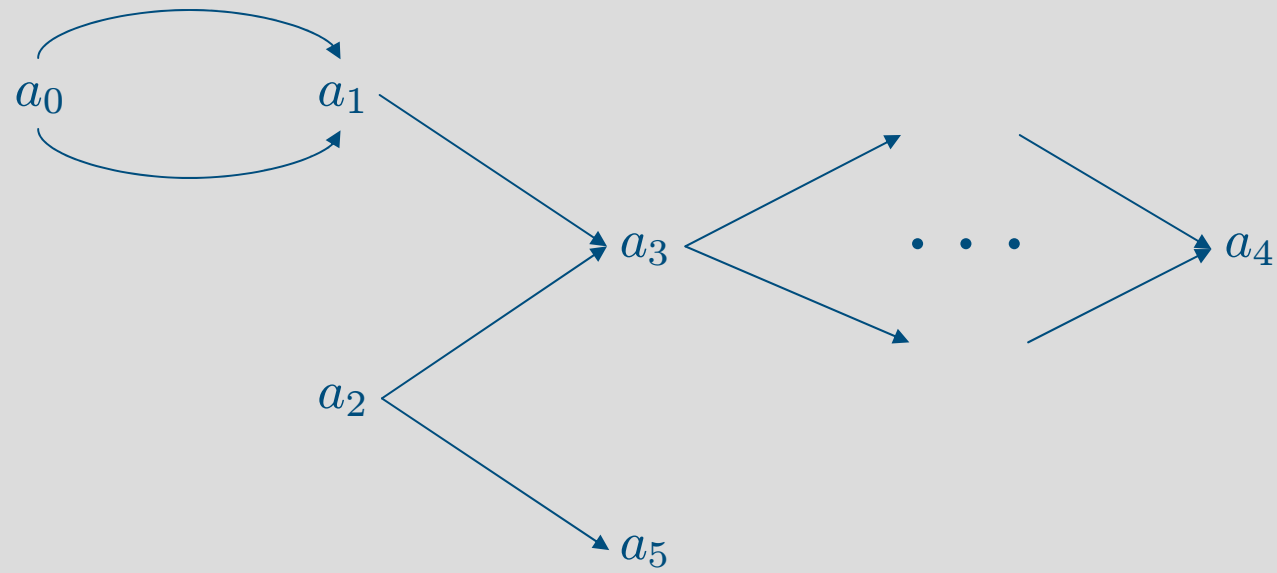
14th of May, 2007

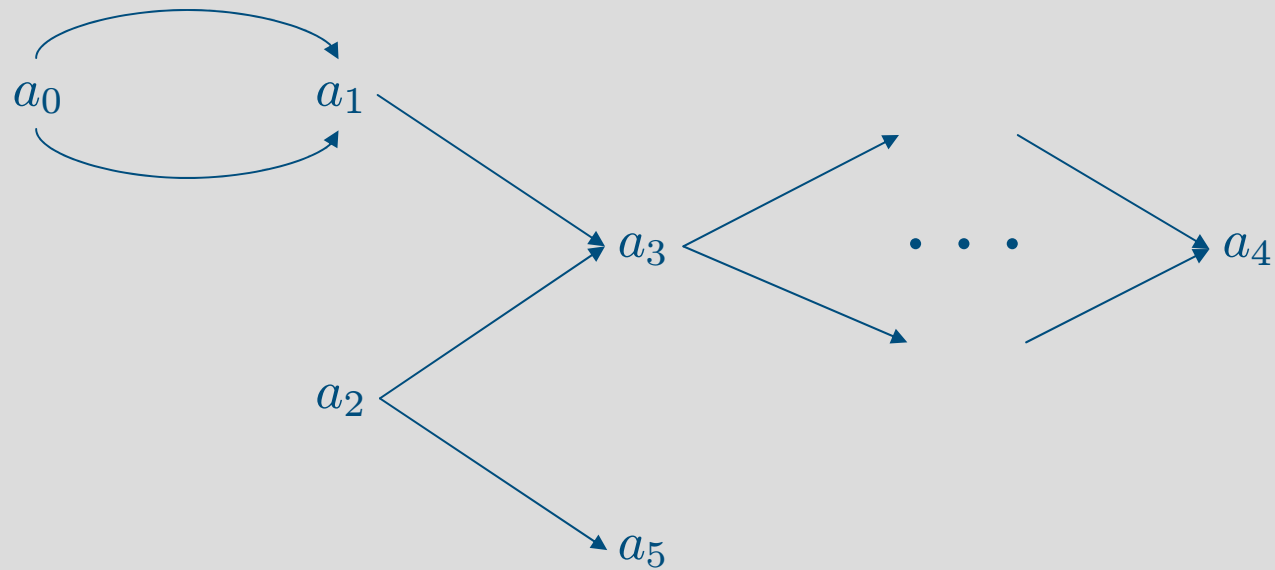


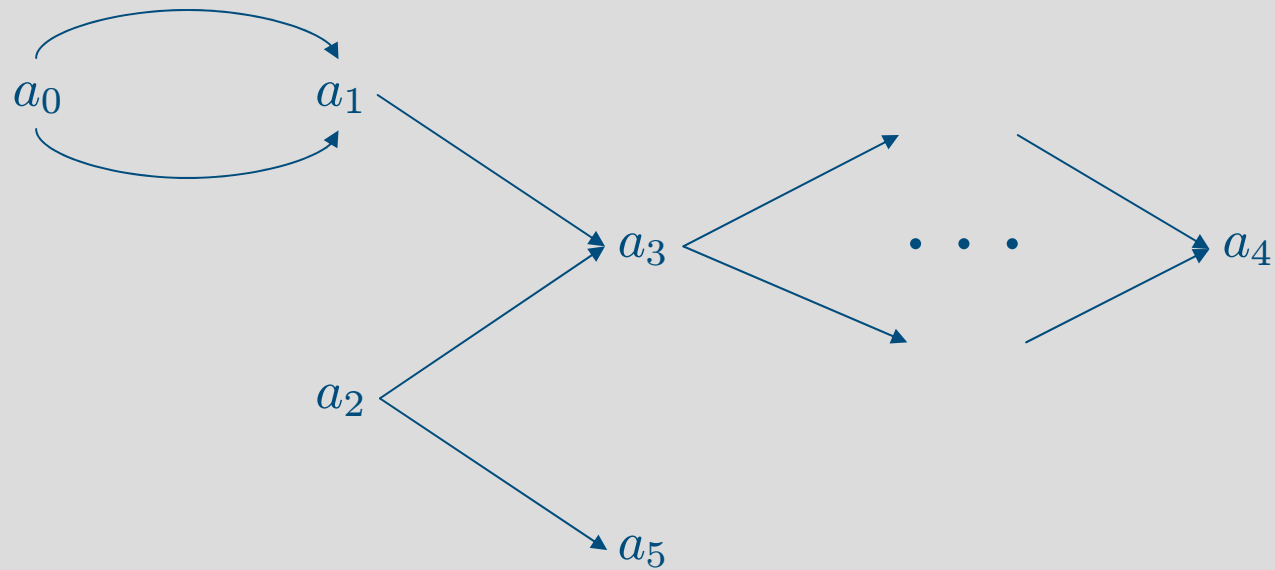
Agenda

■ Motivational Examples

- Focusing
- Finite Successes and Finite Failures
- Applications
- Conclusions and Future Works

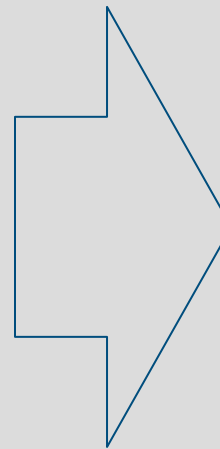



$$\forall x(\text{path } x \ x)$$
$$\forall x \forall y \forall z (\text{arr } x \ z \wedge \text{path } z \ y \supset \text{path } x \ y)$$
$$\text{path } a_1 \ a_4 \wedge \text{path } a_2 \ a_4$$



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Common Subgoal

$$\text{path } a_3 \ a_4$$

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Another example (without cuts)

- Change to an equivalent goal:

$$A \wedge G \equiv A \wedge (A \supset G)$$

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But we are only **increasing non-determinism**:

- There are now more proofs for the goal;
- How to give a purely **proof theoretic solution** where common subgoals aren't re-proven.

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LJF system [Liang & Miller]

$$\frac{[N, \Gamma] \xrightarrow{N} [R]}{[N, \Gamma] \longrightarrow [R]} D_l \quad \frac{[\Gamma] - P \rightarrow}{[\Gamma] \longrightarrow [P]} D_r \quad \frac{[\Gamma], P \longrightarrow [R]}{[\Gamma] \xrightarrow{P} [R]} R_l \quad \frac{[\Gamma] \longrightarrow N}{[\Gamma] - N \rightarrow} R_r$$

$$\frac{[\Gamma, N_a], \Theta \longrightarrow \mathcal{R}}{[\Gamma], \Theta, N_a \longrightarrow \mathcal{R}} \llbracket_l \quad \frac{[\Gamma], \Theta \longrightarrow [P_a]}{[\Gamma], \Theta \longrightarrow P_a} \llbracket_r$$

$$\frac{}{[\Gamma] \xrightarrow{A_n} [A_n]} I_l \quad \frac{}{[\Gamma, A_p] - A_p \rightarrow} I_r$$

$$\frac{}{[\Gamma], \Theta, \perp \longrightarrow \mathcal{R}} false_l \quad \frac{[\Gamma], \Theta \longrightarrow \mathcal{R}}{[\Gamma], \Theta, true \longrightarrow \mathcal{R}} true_l \quad \frac{}{[\Gamma] - true \rightarrow} true_r$$

$$\frac{[\Gamma], \Theta, A, B \longrightarrow \mathcal{R}}{[\Gamma], \Theta, A \wedge B \longrightarrow \mathcal{R}} \wedge_l \quad \frac{[\Gamma] - A \rightarrow \quad [\Gamma] - B \rightarrow}{[\Gamma] - A \wedge B \rightarrow} \wedge_r \quad \frac{[\Gamma] - A \rightarrow \quad [\Gamma] \xrightarrow{B} [R]}{[\Gamma] \xrightarrow{A \supset B} [R]} \supset_l \quad \frac{[\Gamma], \Theta, A \longrightarrow B}{[\Gamma], \Theta \longrightarrow A \supset B} \supset_r$$

$$\frac{[\Gamma], \Theta, A \longrightarrow \mathcal{R}}{[\Gamma], \Theta, \exists y A \longrightarrow \mathcal{R}} \exists_l \quad \frac{[\Gamma] - A[t/x] \rightarrow}{[\Gamma] - \exists x A \rightarrow} \exists_r \quad \frac{[\Gamma] \xrightarrow{A[t/x]} [R]}{[\Gamma] \xrightarrow{\forall x A} [R]} \forall_l \quad \frac{[\Gamma], \Theta \longrightarrow A}{[\Gamma], \Theta \longrightarrow A} \forall_r$$

Playing with polarities

$$\{a, a \supset b, b \supset c\}$$

Playing with polarities

b is negative

$\{a, a \supset b, b \supset c\}$

$$\begin{array}{c}
 \frac{\overline{[\Gamma] - a \rightarrow} \quad I_r \quad \overline{[\Gamma] \xrightarrow{b} [b]} \quad I_l}{\supset_l} \\
 \frac{[\Gamma] \xrightarrow{a \supset b} [b]}{[\Gamma] \rightarrow [b]} \quad D_l \\
 \frac{[\Gamma] \rightarrow b}{[\Gamma] - b \rightarrow} \quad R_r \quad \frac{\overline{[\Gamma] \xrightarrow{c} [c]} \quad I_l}{\supset_l} \\
 \hline
 [\Gamma] \xrightarrow{b \supset c} [c]
 \end{array}$$

Playing with polarities

b is negative

$$\begin{array}{c}
 \frac{\overline{[\Gamma] - a \rightarrow} I_r \quad \overline{[\Gamma] \xrightarrow{b} [b]} I_l}{\overline{[\Gamma] \xrightarrow{a \supset b} [b]} \supset_l} \\
 \frac{\overline{[\Gamma] \xrightarrow{a \supset b} [b]} D_l}{\overline{[\Gamma] \rightarrow [b]} R_r} \\
 \frac{\overline{[\Gamma] \rightarrow b} \quad \overline{[\Gamma] \xrightarrow{c} [c]} I_l}{\overline{[\Gamma] - b \rightarrow} R_r \quad \supset_l} \\
 \overline{[\Gamma] \xrightarrow{b \supset c} [c]}
 \end{array}$$

$\{a, a \supset b, b \supset c\}$

b is positive

$$\begin{array}{c}
 \frac{\overline{[b, \Gamma] - b \rightarrow} I_r \quad \overline{[b, \Gamma] \xrightarrow{c} [c]} I_l}{\overline{[b, \Gamma] \xrightarrow{b \supset c} [c]} \supset_l} \\
 \frac{\overline{[b, \Gamma] \xrightarrow{b \supset c} [c]} D_l}{\overline{[b, \Gamma] \rightarrow [c]} R_l} \\
 \frac{\overline{[\Gamma], b \rightarrow [c]} R_l}{\overline{[\Gamma] - a \rightarrow} I_r \quad \overline{[\Gamma] \xrightarrow{b} [c]} \supset_l} \\
 \overline{[\Gamma] \xrightarrow{a \supset b} [c]}
 \end{array}$$

Changing polarities doesn't affect **provability**:

$$LJF^t$$

$$\mathcal{P}; \Gamma \longrightarrow G$$

$$\frac{\mathcal{P}; [\Gamma] \longrightarrow [L_1] \quad \cdots \quad \mathcal{P}; [\Gamma] \longrightarrow [L_n] \quad \mathcal{P} \cup \Delta_P; [\Gamma \cup \Delta_L] \longrightarrow [R]}{\mathcal{P}; [\Gamma] \longrightarrow [R]} mc$$

Changing polarities doesn't affect **provability**:

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Proposition: LJF^t is sound and complete w.r.t. LJF

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Tables are a partially ordered set of lemmas

$$\mathcal{T} = \langle \mathcal{A}, \prec \rangle \quad \Rightarrow$$

Multi Cut Derivation

$$\frac{\Gamma \longrightarrow A_1 \quad \cdots \quad \Gamma \longrightarrow A_n \quad \Gamma, A_1, \dots, A_n \xrightarrow{\Pi} G}{\Gamma \longrightarrow G} \text{ } mc$$

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$\mathcal{T} = \langle \mathcal{A}, \prec \rangle \Rightarrow$

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Where do tables come from:

- Interactive theorem proving – Boyer & Moore;
- Logic Programming – *Memoization*;
- In *Proof Carrying Code*, can be extracted from an known proof (e.g. depth first traversal);

Consider: **Horn Theory** and Tables composed only of **atoms**

Proposition 1. *Let Γ be a set of Horn clauses, $A \in \mathcal{P} \cap \Gamma$, and Ξ be an arbitrary LJF^t proof tree for $\mathcal{P}; [\Gamma] -_G \rightarrow$. Then every occurrence of a sequent with right-hand side the atom A is the conclusion of an $I_r^t(A)$ rule.*

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Coming back to the Example

$$\begin{array}{c}
 \frac{\frac{\frac{\{path\ a_3\ a_4\}; [\Gamma, path\ a_3\ a_4] \xrightarrow{arr\ a_1\ a_3} [arr\ a_1\ a_3]}{\{path\ a_3\ a_4\}; [\Gamma, path\ a_3\ a_4] \rightarrow [arr\ a_1\ a_3]} \quad I_l^t}{\{path\ a_3\ a_4\}; [\Gamma, path\ a_3\ a_4] - arr\ a_1\ a_3 \rightarrow} \quad \frac{\{path\ a_3\ a_4\}; [\Gamma, path\ a_3\ a_4] - path\ a_3\ a_4 \rightarrow}{\{path\ a_3\ a_4\}; [\Gamma, path\ a_3\ a_4] - arr\ a_1\ a_3 \wedge path\ a_3\ a_4 \rightarrow} \quad I_r^t \\
 \hline
 \{path\ a_3\ a_4\}; [\Gamma, path\ a_3\ a_4] \rightarrow [path\ a_1\ a_4] \quad D_l^t, \forall_l^t, \forall_l^t, \forall_l^t, \supset_l^t
 \end{array}$$

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Coming back to the Example

$$\frac{\Gamma \longrightarrow A \quad \Gamma \longrightarrow G}{\Gamma \longrightarrow A \wedge G} \Longrightarrow \frac{\mathcal{P}; [\Gamma] \longrightarrow [A] \quad \mathcal{P} \cup \{A\}; [\Gamma, A] \longrightarrow [A \wedge G]}{\mathcal{P}; [\Gamma] \longrightarrow [A \wedge G]} mc$$

Consider: **Horn Theory** and Tables composed by **literals**

Use definitions (FOLD – McDowell & Miller):

$$\frac{\{\mathcal{P}; [\Gamma\theta], \Theta\theta \longrightarrow \mathcal{R}\theta \mid \theta = mgu(H, A) \text{ for some clause } H \triangleq B\}}{\mathcal{P}; [\Gamma], \Theta, A \longrightarrow \mathcal{R}} \text{Def}_l, A \notin \mathcal{P}$$

$$\frac{\mathcal{P}; [\Gamma] -_{B\theta} \rightarrow}{\mathcal{P}; [\Gamma] -_A \rightarrow} \text{Def}_r, A \notin \mathcal{P}, \text{ where } H \triangleq B, \text{ and } H\theta = A$$

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Theorem 1. *Let \mathcal{D} be a set of definitions, Γ be a set of literals with positive polarity, and $L \in \Gamma$. Let Ξ be an arbitrary proof tree of $\mathcal{P}; [\Gamma] -_G \rightarrow$ in $FO\lambda^{\Delta t}$, then all subproofs Ξ' of Ξ , that prove the literal L , are trivial.*

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Declarative Interpretation for *Memoization*

Both finite successes and finite failures are stored in a table, and if:

- There is another attempt to prove a **finite success**, the proof search ends with success;
- **Follows from the previous result;**

Declarative Interpretation for *Memoization*

Both finite successes and finite failures are stored in a table, and if:

- There is another attempt to prove a **finite success**, the proof search ends with success;
 - **Follows from the previous result;**
- There is another attempt to prove a **finite failure**, this proof search fails immediately
 - **Follows from the following result:**

Proposition 1. *Let A be an atom such that $\Gamma \longrightarrow A$ is not provable in $FO\lambda^\Delta$, and $A \in \mathcal{P}$. Let Ξ be an arbitrary $FO\lambda^{\Delta^t}$ derivation for $\mathcal{P}; [\Gamma] -_G \rightarrow$. Then all sequents in Ξ , with right-hand side A , are open leafs.*

Proof Carrying Code – Table as Proof Objects

If tables are used as **proof objects** they seem to enjoy the following crucial properties:

- Small
- Easy to Check,
- Flexible

Proposition 1. *Let Ξ be a LJF proof of $\Gamma \longrightarrow G$, and let \mathcal{T} be a table obtained from Ξ . There exists a proof for $\text{mcd}(\mathcal{T}, \Gamma \longrightarrow G)$ such that all of its branches have trivial proofs.*

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Conclusions and Future Works

- **Extend these results to stronger logics**
 - Hereditary Harrop Formulas;
 - μ -Mall (Sequent calculus with Induction and Co-induction).
- **Investigate connections with Interactive Theorem Proving**
 - Use a sequence of lemmas to prove a theorem in such a way that the gaps between them are “easy” to be found.