

Vivek Onkarnath Rathi

200256752

ECE 558 Project 03

CODE –

```
# -*- coding: utf-8 -*-
```

```
"""
```

Created on Tue Nov 12 04:40:55 2019

This code works only for square images

This contains code for P1 a,b,c

@author: Vivek Rathi

```
"""
```

```
import cv2
```

```
import numpy as np
```

```
#global variables
```

```
drawing = False # true if mouse is pressed
```

```
mode = True # if True, draw rectangle. Press 'e' to toggle to ellipse
```

```
ix,iy = -1,-1
```

```
sflag = True # if size of f_img & b_img is not same, s_flag sets to False
```

```
# draw function for GUI
```

```
def draw(event,x,y,flags,param):
```

```
    global ix,iy,lx,ly,drawing,m_shape
```

```
    if event == cv2.EVENT_LBUTTONDOWN:
```

```
        drawing = True
```

```
        ix,iy = x,y
```

```
#     elif event == cv2.EVENT_MOUSEMOVE:
```

```
#         if drawing == True:
```

```
#             cv2.ellipse(fore_img,((x-ix)//2,(y-iy)//2),((y-iy)//2,(x-ix)//2),0,0,360,(0,255,0),1)
```

```

elif event == cv2.EVENT_LBUTTONDOWN:
    drawing = False
    if mode == False:
        cv2.ellipse(f_imgcp,((ix+(x-ix)//2),(iy+(y-iy)//2)),(x-ix,y-iy),0,0,360,(0,0,0),1)
    else:
        cv2.rectangle(f_imgcp,(ix,iy),(x,y),(0,0,0),1)

    lx = x;
    ly = y;

```

#padding function- reflect type only

```

def padr(img,t,b,l,r):
    ir = img.shape[0]
    ic = img.shape[1]
    if len(img.shape) == 3:
        imgpad = np.zeros((ir+t+b,ic+l+r,3), dtype = 'float32')
    elif len(img.shape) == 2:
        imgpad = np.zeros((ir+t+b,ic+l+r), dtype = 'float32')
    imgpad[t:ir+b,l:ic+r] = img
    rows = imgpad.shape[0]
    cols = imgpad.shape[1]
    for i,j in zip(range(t-1,-1,-1),range(t,t+1,1)):
        imgpad[i,:] = imgpad[j,:]

    for i,j in zip(range(l-1,-1,-1),range(l,l+1,1)):
        imgpad[:,i] = imgpad[:,j]

    for i,j in zip(range(rows-b,rows,1),range(rows-b-1,rows-b-b-1,-1)):
        imgpad[i,:] = imgpad[j,:]

    for i,j in zip(range(cols-r,cols,1),range(cols-r-1,cols-l-l-1,-1)):
        imgpad[:,i] = imgpad[:,j]

```

```
return imgpad
```

```
# Convolution Function- odd kernel only
```

```
def conv(img,k):
```

```
    imgcopy = np.copy(img).astype('float32')
```

```
    t=b=l=r = k.shape[0]//2
```

```
    padimg = padr(img,t,b,l,r)
```

```
    if len(img.shape) == 3:
```

```
        B = np.zeros((k.shape[0],k.shape[1],3))
```

```
        k_shift = k.shape[0]
```

```
        r = padimg.shape[0]
```

```
        c = padimg.shape[1]
```

```
        for i in range(r-k_shift-1):
```

```
            for j in range(c-k_shift-1):
```

```
                B[:,0] = np.multiply(k,padimg[i:i+k_shift,j:j+k_shift,0])
```

```
                B[:,1] = np.multiply(k,padimg[i:i+k_shift,j:j+k_shift,1])
```

```
                B[:,2] = np.multiply(k,padimg[i:i+k_shift,j:j+k_shift,2])
```

```
                imgcopy[i,j,0] = np.sum(B[:,0])
```

```
                imgcopy[i,j,1] = np.sum(B[:,1])
```

```
                imgcopy[i,j,2] = np.sum(B[:,2])
```

```
    return imgcopy
```

```
    elif len(img.shape) == 2:
```

```
        B = np.zeros((k.shape[0],k.shape[1]))
```

```
        k_shift = k.shape[0]
```

```
        r = padimg.shape[0]
```

```
        c = padimg.shape[1]
```

```
        for i in range(r-k_shift):
```

```
            for j in range(c-k_shift):
```

```
                B = np.multiply(k,padimg[i:i+k_shift,j:j+k_shift])
```

```
                imgcopy[i,j] = np.sum(B)
```

```

    return imgcopy

# spread intensities to 0,255 for display
def spread_linear(img,uplimit):
    s = np.copy(img)
    ma = img.max()
    mi = img.min()
    if len(img.shape) == 3:
        for i in range(img.shape[0]):
            for j in range(img.shape[1]):
                s[i,j,:] = ((uplimit - 1)/(ma - mi)) * (img[i,j,:] - mi)
    return s.astype('uint8')
else:
    for i in range(img.shape[0]):
        for j in range(img.shape[1]):
            s[i,j] = ((uplimit - 1)/(ma - mi)) * (img[i,j] - mi)
    return s.astype('uint8')

# Downsamples the image using nearest neighbor interpolation
def downscale(img):
    old_r = img.shape[0]
    old_c = img.shape[1]
    new_r = (np.floor(img.shape[0]/ 2)).astype('int16')
    new_c = (np.floor(img.shape[1]/ 2)).astype('int16')

    r_r = new_r/old_r
    r_c = new_c/old_c

    R = (np.floor((np.arange(0,new_r,1))/r_r)).astype('int16')
    C = (np.floor((np.arange(0,new_c,1))/r_c)).astype('int16')

    dimg = img[R,:]
    dimg = dimg[:,C]

```

```

return dimg

# Upsamples the image using nearest neighbor interpolation
def upscale(img,n_img):
    old_r = img.shape[0]
    old_c = img.shape[1]

    new_r = n_img.shape[0]
    new_c = n_img.shape[1]

    r_r = new_r/old_r
    r_c = new_c/old_c

    R = (np.floor((np.arange(0,new_r,1))/r_r)).astype('int16')
    C = (np.floor((np.arange(0,new_c,1))/r_c)).astype('int16')

    uimg = img[R,:]
    uimg = uimg[:,C]

    return uimg

# creates pyramid with images of decreasing size
def pyrdown(img):
    c_gaus = conv(img,k)
    return downscale(c_gaus)

# creates pyramid with images of increasing size
def pyrup(img,n_img):
    uimg = upscale(img,n_img)
    c_lap = conv(uimg,k)
    return c_lap

```

```
# creates Gaussian and Laplacian Pyramids
```

```
def ComputePyr(img, layers):
```

```
    global num_l, k
```

```
    num_l = 1
```

```
    shape = img.shape[0]
```

```
    for i in range(layers-1):
```

```
        if (shape//2 < 5):
```

```
            print("Sorry! We can only have maximum layers of %d " % num_l)
```

```
            layers = num_l
```

```
            break
```

```
        else:
```

```
            shape = shape // 2
```

```
            num_l += 1
```

```
#Gaussian Kernel
```

```
x = cv2.getGaussianKernel(5, 2)
```

```
k = x*x.T
```

```
#Gaussian Pyramid
```

```
G = img.copy().astype('float32')
```

```
gpA = [G]
```

```
for i in range(layers-1):
```

```
    G = pyrdown(G)
```

```
    gpA.append(G)
```

```
#Laplacian Pyramid
```

```
lpA = [gpA[layers-1]]
```

```
for i in range(layers-1, 0, -1):
```

```
    GE = pyrup(gpA[i], gpA[i-1])
```

```
    L = np.subtract(gpA[i-1], GE)
```

```
    lpA.append(L)
```

```
return gpA, lpA
```

```
# creates gaussian pyramid for mask
```

```
def mask_gpyr(mask, layers):
```

```
    G_M = np.copy(mask).astype('float32')
```

```
    gpM = [G_M]
```

```
    for i in range(layers-1):
```

```
        G_M = pyrdown(G_M)
```

```
        gpM.append(G_M)
```

```
    gpM.reverse()
```

```
    return gpM
```

```
# blends images to return blended image
```

```
def laplacian_blend(LA, LB, GM, layers):
```

```
    LS = []
```

```
    for la, lb, mask in zip(LA, LB, GM):
```

```
        ls = la * mask + lb * (1 - mask)
```

```
        LS.append(np.float32(ls))
```

```
    lap_bl = LS[0]
```

```
    for i in range(1, layers):
```

```
        lap_bl = pyrup(lap_bl, LS[i])
```

```
        lap_bl = cv2.add(lap_bl, LS[i])
```

```
    return np.clip(lap_bl, 0, 255).astype('uint8')
```

```
# creates mask of foreground image
```

```
def create_mask(img, x1, y1, x2, y2):
```

```
    mask = np.zeros((img.shape)).astype('float32')
```

```
    if mode == False:
```

```
        mask = cv2.ellipse(mask, ((ix+(lx-ix)//2), (iy+(ly-iy)//2)), (lx-ix, ly-iy), 0, 0, 360, (1, 1, 1), -1)
```

```
    else:
```

```
#    mask[y1+1:y2, x1+1:x2] = 1
```



```

        mask=cv2.rectangle(mask,(ix,iy),(lx,ly),(1,1,1),-1)

    return mask

# aligns f_img to b_img
def align(b_img,f_img,r,c):
    # global s_flag
    # s_flag = False

    a_img = np.zeros(b_img.shape)
    a_img[r:f_img.shape[0]+r,c:f_img.shape[1]+c] = f_img
    return a_img.astype('uint8')

#Start Code here

#read image-
b_img = cv2.imread('P3_BG_2.png',1)
f_img = cv2.imread('P3_FG_2.png',1)

# validation for aligning
if (b_img.shape[0] > f_img.shape[0]):
    # global s_flag
    # s_flag = False

    n_f_img = align(b_img,f_img,50,35) # this rows & columns need to be done manually
    f_img = np.copy(n_f_img)
    f_imgcp = np.copy(n_f_img)
else:
    f_imgcp = np.copy(f_img)

# display for GUI
cv2.namedWindow('FOREGROUND IMAGE',cv2.WINDOW_NORMAL)
cv2.setMouseCallback('FOREGROUND IMAGE',draw)

while(1):
    cv2.imshow('FOREGROUND IMAGE',f_imgcp)

```

```

k = cv2.waitKey(1) & 0xFF
if k == ord('e'): # ellipse
    mode = not mode
elif k == 27:
    cv2.destroyAllWindows()
    break

# mask creation
mask = create_mask(f_imgcp,ix,iy,lx,ly)

# display images
cv2.namedWindow('FOREGROUND IMAGE', cv2.WINDOW_NORMAL)
cv2.imshow('FOREGROUND IMAGE',f_img)
cv2.namedWindow('MASK', cv2.WINDOW_NORMAL)
cv2.imshow('MASK',mask)
cv2.namedWindow('BACKGROUND IMAGE', cv2.WINDOW_NORMAL)
cv2.imshow('BACKGROUND IMAGE',b_img)
cv2.waitKey(0)
cv2.destroyAllWindows()

# compute pyramids- here you can enter layers as per requirement
GPA,LPA = ComputePyr(f_img,10)
GPB,LPB = ComputePyr(b_img,10)
GPM = mask_gpyr(mask,len(GPA))
final = laplacian_blend(LPA,LPB,GPM,len(GPA))

# display images
cv2.namedWindow('FOREGROUND IMAGE', cv2.WINDOW_NORMAL)
cv2.imshow('FOREGROUND IMAGE',f_imgcp)
cv2.namedWindow('MASK', cv2.WINDOW_NORMAL)
cv2.imshow('MASK',mask)
cv2.namedWindow('BACKGROUND IMAGE', cv2.WINDOW_NORMAL)

```

```
cv2.imshow('BACKGROUND IMAGE',b_img)

cv2.namedWindow('BLENDED IMAGE', cv2.WINDOW_NORMAL)

cv2.imshow('BLENDED IMAGE',final)

cv2.waitKey(0)

cv2.destroyAllWindows()
```

OUTPUTS

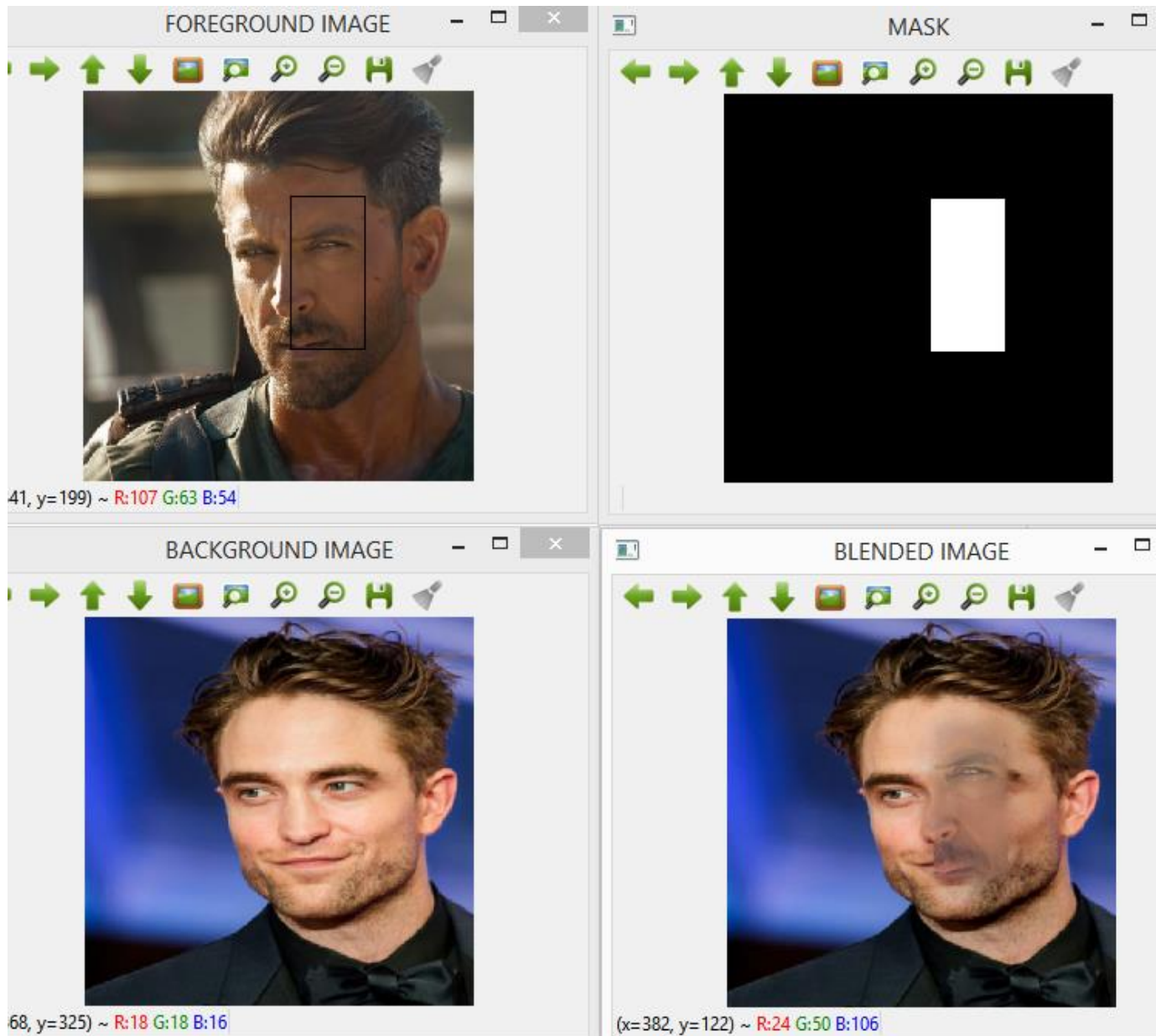
LAYERS VALIDATION

```
12
13 # compute pyramids- here you can enter layers as per requirement
14 GPA, LPA = ComputePyr(f_imgcp, 10)
15 GPB, LPB = ComputePyr(b_img, 10)
16 GPM = mask_gpyr(mask, len(GPA))
17 final = laplacian_blend(LPA, LPB, GPM, len(GPA))
18
19 # display images
20 cv2.namedWindow('FOREGROUND IMAGE', cv2.WINDOW_NORMAL)
21 cv2.imshow('FOREGROUND IMAGE', f_imgcp)
```

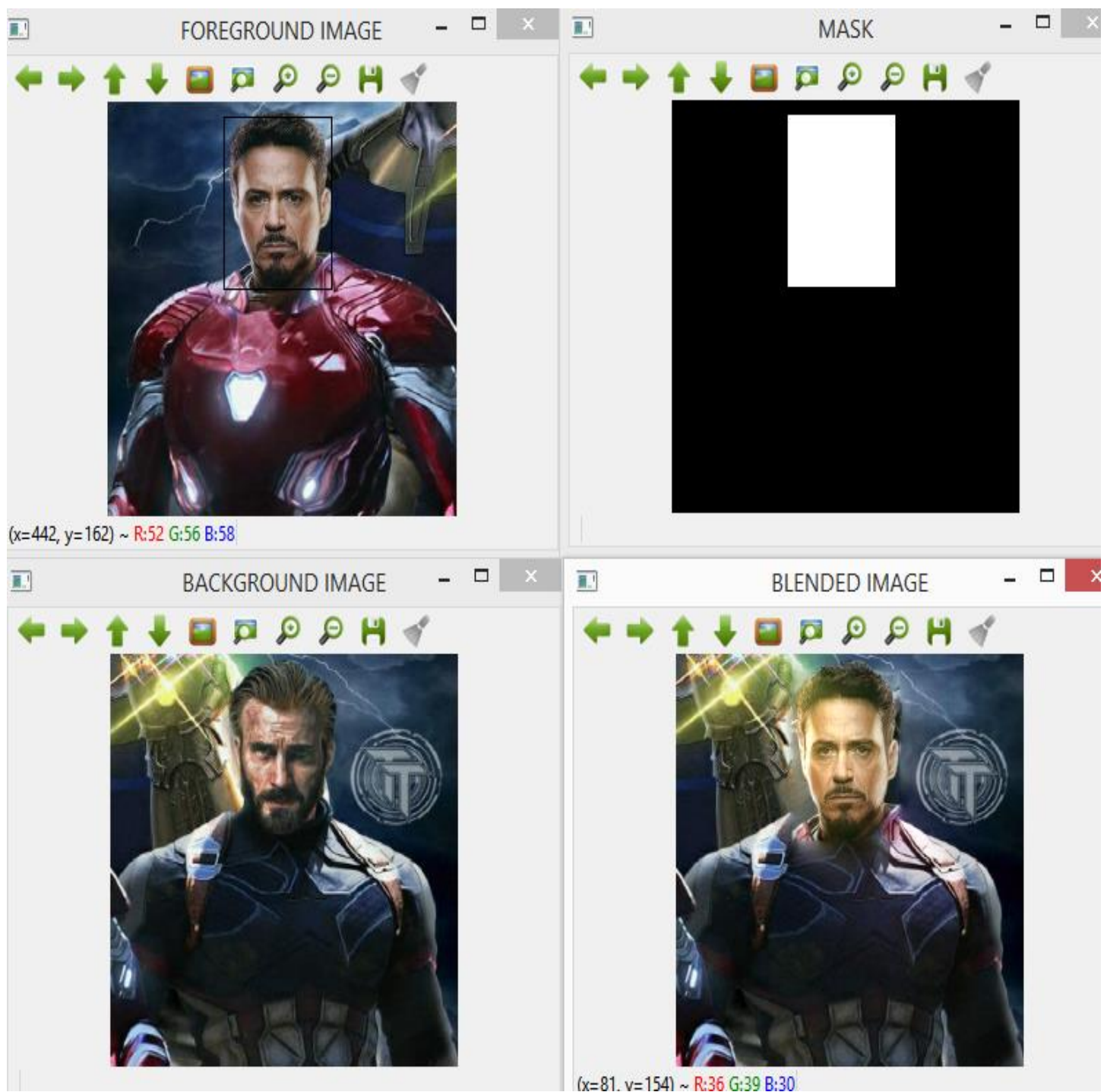
In [3]:

```
In [3]: runfile('D:/NCSTATE/ECE558/OpenCV/
Project03/untitled1.py', wdir='D:/NCSTATE/ECE558/
OpenCV/Project03')
Sorry! We can only have maximum layers of 7
```

1.



2.



3.

