

Simulation

Assignment 2

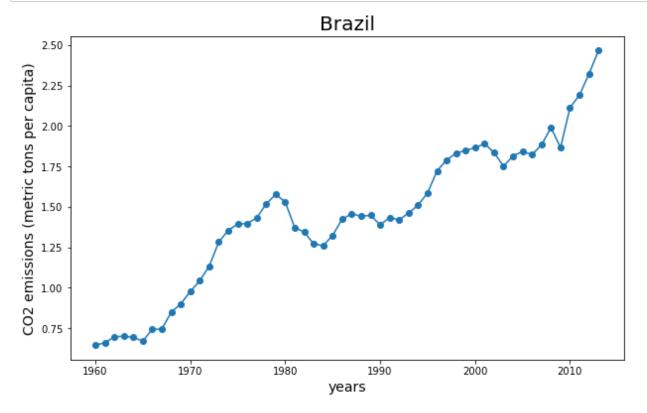
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Date: Saturday, February 18th, 2016

```
In [1]: it=0
        import csv
        with open('Data.csv') as f:
            reader = csv.reader(f)
            for row in reader:
                if it==4:
                     fieldnames = row
                 if it>4:
                     if row[1]=='BRA': #Change here country
                         usa = row
                     if row[1]=='RUS':
                         rus = row
                 it = it+1
        fieldnames_rus=fieldnames[36:]
        fieldnames_rus=fieldnames[:-4]
        fieldnames_rus=fieldnames_rus[36:]
        rus=rus[36:]
        rus=rus[:-4]
        usa=usa[4:]
        usa=usa[:-4]
        fieldnames=fieldnames[4:]
        fieldnames=fieldnames[:-4]
```

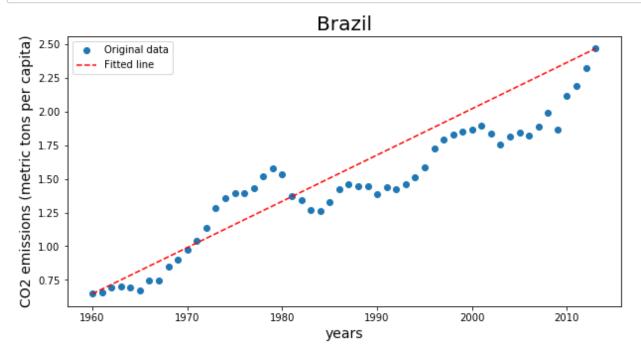
```
In [2]: %matplotlib inline
    import matplotlib as mpl
    import matplotlib.pyplot as plt
    mpl.rc("figure", figsize=(10, 6))
    plt.plot(fieldnames,usa,'o-')
    #plt.plot(fieldnames_rus,rus)
    plt.title('Brazil', fontsize=20)
    plt.xlabel('years', fontsize=14)
    plt.ylabel('CO2 emissions (metric tons per capita)', fontsize=14)
    plt.show()
```



1. Data

1. (5 Points) Fit a straight line passing through the endpoints;

```
In [3]: mpl.rc("figure", figsize=(10, 5))
   plt.plot(fieldnames,usa, 'o',label='Original data')
   plt.plot([fieldnames[0],fieldnames[len(fieldnames)-1]],[usa[0],usa[len
        (usa)-1]],'--', color='r',label='Fitted line')
   plt.title('Brazil', fontsize=20)
   plt.xlabel('years', fontsize=14)
   plt.ylabel('CO2 emissions (metric tons per capita)', fontsize=14)
   plt.legend()
   plt.show()
```

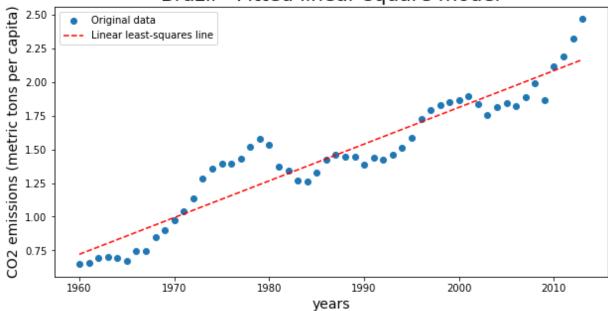


2.- (15 Points) Fit a linear least-squares model. Find the maximum error in magnitude in the first case. Predict the year in which the CO2 level may exceed 3 metric tons per capita.

```
In [4]: import numpy as np
x = np.asarray(fieldnames, dtype=float)
y = np.asarray(usa, dtype=float)
A = np.vstack([x, np.ones(len(x))]).T
m, c = np.linalg.lstsq(A, y)[0]
```

```
In [5]: plt.plot(fieldnames,usa, 'o',label='Original data')
   plt.plot(x, m*x + c, 'r--', label='Linear least-squares line')
   y_2 = m*x + c
   plt.title('Brazil - Fitted linear-square model', fontsize=20)
   plt.xlabel('years', fontsize=14)
   plt.ylabel('CO2 emissions (metric tons per capita)', fontsize=14)
   plt.legend()
   plt.show()
```





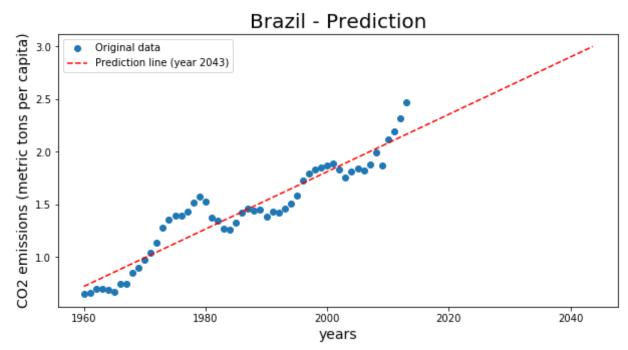
Using a linear least-square model, the maximum error in magnitude is 0.33881662634055765, and it

```
In [6]: error = np.absolute(y-y_2)
    print(max(error))
    print(fieldnames[np.argmax(error)])

0.338816626341
    1979

In [7]: slope = (y_2[len(y_2)-1]-y_2[0])/(x[len(x)-1]-x[0])
    var = ((3-y_2[0])/(slope))+x[0]
    var
```

Out[7]: 2043.6336215957022



The year in which the CO2 level may exceed 3 metric tons per capita in Brazil is 2043.



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2. Mathematical Preliminaries

• (5 Points) Is the following time-varying function positive definite?

$$V(t, x_1, x_2) = t(x_1^2 + x_2^2) + 4x_1x_2 \sin t$$

Solution:

A function $V: \mathbb{R}^n \to \mathbb{R}$ is positive definite if:

- V(z) = 0 iff z = 0
- $V(z) > 0 \ \forall z, z \neq 0$
 - 1. V(t, 0, 0) = 0
 - 2. $V(t, x_1, x_2) \ge V(x_1, x_2) \ \forall x \ne 0$. From the numerical approach below, we can conclude that there is no such function.

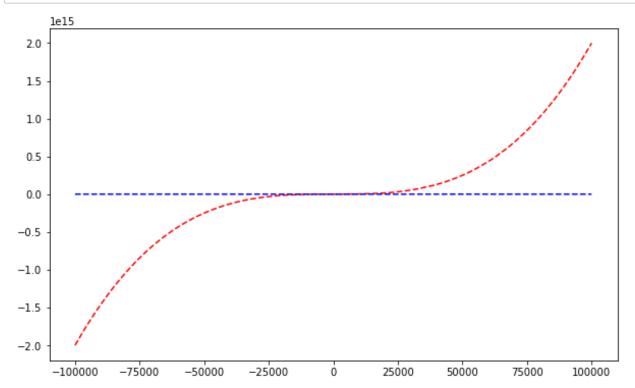
Therefore V(t, x, y) is positive semidefinite.

```
In [1]: import numpy as np
x = np.arange(-99999,99999)
y = np.arange(-99999,99999)
w = np.arange(-99999,99999)
```

In [2]:
$$z = w*(x**2 + y**2) + 4*x*y*np.sin(w)$$

 $z^2 = (x**2 + y**2) + 4*x*y$

```
In [3]: %matplotlib inline
    import matplotlib as mpl
    import matplotlib.pyplot as plt
    mpl.rc("figure", figsize=(10, 6))
    plt.plot(x,z,'--', color='r')
    plt.plot(x,z2,'--', color='b')
    plt.show()
```



• (10 Points) Test the stability of the zero solution for the following system:

$$x'_{1} = -x_{1}^{3} + x_{1}^{4}$$

 $x'_{2} = x_{1}^{4} + x_{2}^{3}$

Solution:

Let us solve this problem using Krasovskii's method:

$$J(X) = \begin{pmatrix} -3x_1^2 + 4x_1^3 & 0\\ 4x_1^3 & 3x_2^2 \end{pmatrix}$$

$$J^{T}(X) = \begin{pmatrix} -3x_1^2 + 4x_1^3 & 4x_1^3 \\ 0 & 3x_2^2 \end{pmatrix}$$

$$M(x_1, x_2) = J(X) + J^T(X) = \begin{pmatrix} -6x_1^2 + 8x_1^3 & 4x_1^3 \\ 4x_1^3 & 6x_2^2 \end{pmatrix}$$

 $M(x_1, x_2)$ is negative definite, therefore $V^*(x)$ is negative as well. By theorem shown in class, then we can affirm the zero solution is asymptocally stable.

• (15 points) Test the linear stability of the zero solution $x_1(t) = 0$, $x_2(t) = 0$ in the Lotka-Volterra population model, i.e.,

$$x'_1 = ax_1 + x_1x_2$$

 $x'_2 = -bx_2 + x_1x_2$,

for your favorite pair of integers (a, b).

Solution:

Let us choose a = 7 and b = 13.

Now, let us set the following equations in order to be able to obtain the critical points:

$$x'_1 = 7x_1 + x_1x_2 = 0$$

$$x'_2 = -13x_2 + x_1x_2 = 0$$

Critical point in 0,0

Out[4]: [(0, 0)]

Let us find the linearized system about (0,0)

$$x' = Ax$$
, where $A = \begin{pmatrix} 7 & 0 \\ 0 & -13 \end{pmatrix}$

```
In [5]: from sympy import *
   init_printing(use_unicode=True)
   M = Matrix([[7,0], [0,-13]])
   M.eigenvals()
```

Out[5]: $\{-13:1, 7:1\}$

Therefore (0,0) is a saddle point, therefore unestable.