

Date: Thursday, April 18, 2019

## Recap

### Method      Exploration / Exploitation      Optimal found?

A/B testing	100% Exploration	Yes — Through testing
Greedy	100% Exploitation	No — Local optimal
$\epsilon$ -greedy	Explore at rate $\epsilon$	Yes — eventually
Softmax	Explore at softmax Prob. rate	Yes — better @ ranking than $\epsilon$ -greedy

Note: Optimal mean or proportion

Note: So far, greedy,  $\epsilon$ -greedy, and softmax look at the mean/proportion at each round only!  
↳ There is no concern for variability or uncertainty of the reward.

- We can make optimization more efficient by accounting for the spread or variability of the reward distribution at each round.

- TWO methods: i) Upper confidence bound (UCB)  
ii) Probability matching / Bayesian Sampling

[ Slide is wrong, correction: ]

$$\text{UCB: } \arg \max_k \left( r_{kt} + \sqrt{\frac{2 \log(t)}{n_{kt}}} \right)$$

So for UCB, instead of just updating  $r_{kt}$  as in the previous methods, we now update  $r_{kt} + \sqrt{\frac{2 \log(t)}{n_{kt}}}$  at each round.

## UCB in Practice

for  $t = 1, \dots, T$

choose arm with  $\arg \max_k \left( r_{kt} + \sqrt{\frac{2 \log(t)}{n_{kt}}} \right)$

return arm with highest value

↳ This is greedy in nature, and can be made more efficient by relying on the entire distribution of rewards.

**Randomized probability matching:** reward of arm  $k$  up to time  $t$  (estimated)

Value of interest:  $P(r_{kt} \text{ is optimal})$

$$P(r_{kt} = \max_{j \in 1, \dots, K} \{r_{jt}\}) = P_{kt}$$

We allocate units to arm  $k$  with probability  $P_{kt}$ .

The probability we wrote up ( $P_{kt}$ ) can be thought of in the following way:

$R = (r_1, r_2, \dots, r_K) =$  True rewards for each arm

$\pi(R) =$  Prior distribution on  $R$

a) If  $r_j$  is a proportion, use a beta distribution (or uniform  $(0,1)$ )

Assume rewards are independent and each distributed as  $U(0,1)$ , then

$$\pi(R) = \prod_{j=1}^K 1 = 1$$

b) If  $r_j$  is continual, use a  $N(\mu_j, 1)$  distribution where  $\mu_j =$  the initialized reward for arm  $j$ .

$$\pi(R) = \prod_{j=1}^K \frac{1}{\sqrt{2\pi}} \exp \left\{ -\frac{(r_j - \mu_j)^2}{2} \right\}$$

(product of normals)

Data: The reward up to time  $t$ . That is  $r_{1t}, \dots, r_{kt}$

$f_t = (f_{1t}, \dots, f_{kt})$  ← estimated values up to round  $t$

Generating process:  $f(f_t | R)$  same as what is done in  $f$ -greedy.

$\begin{matrix} \text{rewards} \\ \text{up to time } t \end{matrix} \xrightarrow{\quad} f_t \quad \xleftarrow{\quad} \text{true rewards}$

Our value of interest can be thought of as the posterior distribution of  $R$  given the rewards up to time  $t$ :

$$(*) \quad P_{kt} = P(r_k = \max \{r_1, r_2, \dots, r_k\} | (r_{1t}, \dots, r_{kt}))$$

To get to  $(*)$  is by calculating

$$P(R | r_{1t}, \dots, r_{kt}) \propto \pi(R) f(r_{1t}, \dots, r_{kt} | R)$$

Once we get  $\pi(R | r_{1t}, \dots, r_{kt})$ , we can then simulate say 1000 times and calculate the proportion of times  $r_k$  was maximum as our value for  $P_{kt}$ .

1) rewards are proportions  $\rightarrow$  use Dirichlet-multinomial model  
(Dirichlet posterior)

2) rewards are continuous  $\rightarrow$  use normal-normal model  
(Normal Posterior)

For proportions:

Algorithm: Initialize and calculate rewards  
↳ Normalize to probabilities for  $t=1, 2, \dots, T$

Calculate Dirichlet posterior parameters  
for  $P_{1t}, \dots, P_{kt}$ .

Simulate 1000 samples from Dirichlet and calculate

$$P_{kt} = P(r_k \text{ is max at time } t)$$

Pull arms with probabilities  $P_{1t}, \dots, P_{kt}$  and update prob.

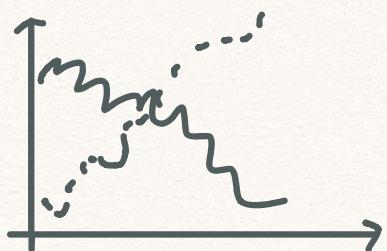
For continuous values:

Algorithm: Initialize and calculate reward) for  $t = 1, 2, \dots, T$   
Calculate Normal Posterior parameters for  
 $r_{1t}, \dots, r_{Kt}$ .  
Simulate 1000 samples from Normal and calculate  
 $P_{kt} = P(r_k \leq \max_{j \neq k} r_j)$   
Pull arms with probabilities  $P_{1t}, \dots, P_{Kt}$  and update prob.

$$\begin{aligned}\pi(r) &= \prod_{j=1}^K f(r_j) & x \sim U(0,1) & , \\ &= \prod_{j=1}^K 1 & f(x) = 1 & \end{aligned}$$


## RPM (Randomized Prob. Matching)

- has been found to be the most efficient (in terms of iterations needed) to identify the optimal condition.
- This is viewed by looking at the Optimality Probability plot.



--- is optimal and converges to 1  
— converges to 0