

Data: Thursday, October 25, 2018.

RECAP

- Strict vs. weak stationarity
- Mean function $\mu(t) = \text{IE}[\gamma_t]$
- Covariance function $\gamma(t, t+h) = \text{Cov}(\gamma_t, \gamma_{t+h})$

For a (weak) stationary time series, the covariance function simplifies to:

$\gamma(h)$ does not depend on t .

This function is specifically referred to as an **autocovariance function**.

In this context, we define the **autocorrelation function** to be

$$\begin{aligned}\rho(h) &= \text{Corr}(\gamma_t, \gamma_{t+h}), \\ &= \frac{\text{Cov}(\gamma_t, \gamma_{t+h})}{\sqrt{\text{Var}(\gamma_t)} \sqrt{\text{Var}(\gamma_{t+h})}}, \\ &= \frac{\text{Cov}(\gamma_t, \gamma_{t+h})}{\sqrt{\text{Cov}(\gamma_t, \gamma_t)} \sqrt{\text{Cov}(\gamma_{t+h}, \gamma_{t+h})}}, \\ &= \frac{\gamma(h)}{\gamma(0)}.\end{aligned}$$

PROPERTIES:

1. $\gamma(0) \geq 0 \Leftrightarrow \text{Var}[\gamma_t] \geq 0$
2. $|\gamma(h)| \leq \gamma(0) \Leftrightarrow \frac{|\gamma(h)|}{\gamma(0)} = |\rho(h)| \leq 1$
3. $\gamma(h) = \gamma(-h)$, $\rho(h) = \rho(-h)$
Even functions

$\text{Corr}(\gamma_1, \gamma_5) \approx \text{Corr}(\gamma_5, \gamma_2)$
 → We usually want to forecast to the future

Recall that for MA(1) model

$$\gamma(h) = \begin{cases} \sigma^2(1+\theta^2) & \text{if } h=0 \\ \sigma^2 \theta & \text{if } h=\pm 1 \\ 0 & \text{otherwise} \end{cases}$$

Noting that $\gamma(0) = \sigma^2(1+\theta^2)$

$$\rho(h) = \begin{cases} 1 & \text{if } h=0 \\ \theta/(1+\theta^2) & \text{if } h=\pm 1 \\ 0 & \text{otherwise} \end{cases}$$

You would expect a spike at 1

By looking at an ACF plot, that behaves like that, you could modeling using MA(1).

Example:

First order autoregression AR(1)

A times series $\{y_t\} \sim AR(1)$ behaves according to the following relationship:

$$y_t = \phi y_{t-1} + \varepsilon_t$$

where $|\phi| < 1$ and $\{\varepsilon_t\} \sim WN(0, \sigma^2)$

(?) and ε_t and y_s are uncorrelated for $s < t$.

This makes
AR(1)
stationary

Derive the autocovariance function of h and autocorrelation of n . ($\gamma(h)$ and $\rho(h)$).

$$\begin{aligned} \cdot \quad \text{IE}[y_t] &= \text{IE}[\phi y_{t-1} + \varepsilon_t] \\ &= \phi \text{IE}[y_{t-1}] + \text{IE}[\overset{0}{\varepsilon_t}] \\ \therefore \quad \text{IE}[y_t] &= \phi \text{IE}[y_{t-1}] \\ \kappa &= \phi \kappa \quad \text{because } \{y_t\} \text{ is stationary} \\ \Rightarrow \kappa &= 0 \\ \therefore \quad \kappa &= 0 \quad \text{since } \phi \neq 1. \end{aligned}$$

$$\begin{aligned} \cdot \quad \underline{\gamma(h)} &= \text{Cov}(y_t, y_{t+h}) \\ &= \text{IE}[y_t y_{t+h}] - \text{IE}[y_t] \text{IE}[y_{t+h}] \\ &= \text{IE}[y_t (\phi y_{t+h-1} + \varepsilon_{t+h})] \\ &= \text{IE}[\theta y_{t+h-1} y_t + \varepsilon_{t+h} y_t] \\ &= \theta \text{IE}[y_t y_{t+h-1}] + \text{IE}[y_t \overset{0}{\varepsilon_{t+h}}] \\ &= \theta \gamma(h-1) \end{aligned}$$

$$\begin{aligned}
 &= \Theta^2 \gamma(h-2) \\
 &= \Theta^3 \gamma(h-3) \\
 &\vdots \\
 &= \Theta^h \gamma(0)
 \end{aligned}$$

• $\gamma(0) = \text{Var}(Y_t)$

$$\begin{aligned}
 &= \text{Cov}(Y_t, Y_t) \\
 &= \mathbb{E}[Y_t^2] - \mathbb{E}[Y_t]^2 \\
 &= \mathbb{E}[(\phi Y_{t-1} + \varepsilon_t)^2] \\
 &= \mathbb{E}[\phi^2 Y_{t-1}^2 + 2\phi Y_{t-1} \varepsilon_t + \varepsilon_t^2] \\
 &= \phi^2 \mathbb{E}[Y_{t-1}^2] + 2\phi \mathbb{E}[Y_{t-1} \varepsilon_t] + \mathbb{E}[\varepsilon_t^2] \\
 &= \phi^2 \gamma(0) + 0 + \sigma^2 \\
 &= \phi^2 \gamma(0) + \sigma^2 \\
 \Rightarrow \gamma(0) &= \frac{\sigma^2}{1-\phi^2}
 \end{aligned}$$

Therefore, $\gamma(h) = \frac{\phi^h \sigma^2}{1-\phi^2}$ for $h \in \mathbb{Z}$.

$$\rho(h) = \frac{\gamma(h)}{\gamma(0)} = \frac{\gamma(h)}{\gamma(0)} = \phi^{|h|} \text{ for } h \in \mathbb{Z}.$$

Exponentially smaller as h increases.

Whereas we have calculated ACF's from specified models, typically we observe actual data and calculate sample estimates of the quantities.

Given an observed time series $\{y_t\} = \{y_1, y_2, \dots, y_n\}$

- Mean function:

$$\bar{y} = \frac{1}{n} \sum_{t=1}^n y_t = \hat{\mu}$$

- Sample autocovariance function:

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-h} (y_t - \bar{y})(y_{t+h} - \bar{y})$$

\downarrow
bias but required for non-negative

- Sample autocorrelation function:

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}$$

The sample ACF can be used to check for "uncorrelatedness" in a time series. This is achieved by comparing $\hat{\rho}(h)$ values to a threshold, which, if exceeded, indicates significant correlation.

— — — These thresholds rely on the asymptotic distribution $\tilde{\rho}(h)$.

For large n , $\tilde{\rho}(h) \sim N(0, \frac{1}{n})$

if the time series is uncorrelated.

The threshold is really a 95% confidence interval for $\rho(h)$ and is given by

$$\pm \frac{1.96}{\sqrt{n}}.$$

thus $\hat{\rho}(h) \notin [-\frac{1.96}{\sqrt{n}}, \frac{1.96}{\sqrt{n}}]$ is indicative of significant correlation.