

AUV

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Structure

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Electrical

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Software

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Why?

- Academic:
 - Educational Opportunities
 - Out-of-classroom Experience
- Reality Check:
 - Applying Classroom's Skill
 - Improve The



How?

- Mechanical Aspect:

- Outer Structure
- Inner Structure
- Camera Housing
- Motor Position

- Electrical Aspect:

- Design
- Battery

- Software Aspect:

- Original Setup
- Problems
- Solutions
- Programming

Mechanical Aspect:

- Inner Structure:

- Endoskeletal:

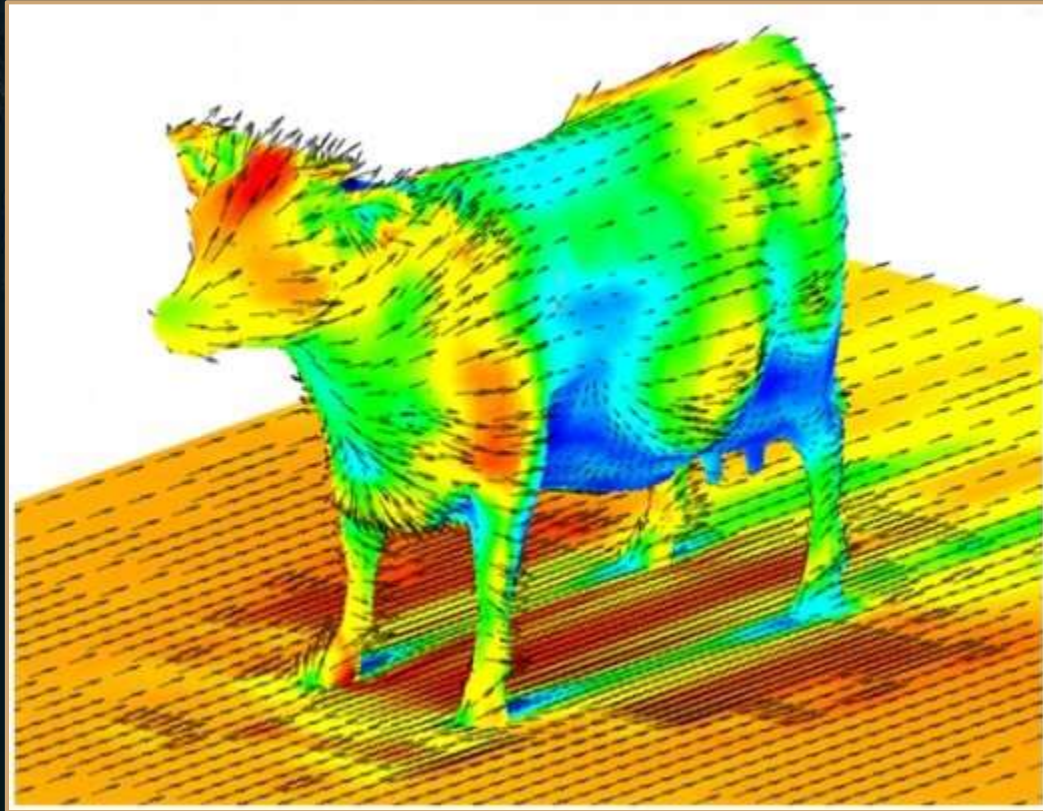
- Material:

- Aluminum 5052

- Inner Structure:

- Endoskeletal:

Mechanical Aspect:



Mechanical Aspect:

- Inner Structure:

- Endoskeletal:

- Material:

- Aluminum 5052
 - PLA Filament

- Manufacture:

- Water Jetting
 - 3-D Printing

- Inner Structure:

- Endoskeletal:

- Mounting:

- Velcro

- Outlet:

- Cable Penetrators 6 and 8 mm

- Accessibility

- 8 Pin Connector McCartney

Mechanical Aspect:

- Outer Structure:
 - 80 x 20 Aluminum
 - Weight
 - Modular
 - Purpose
 - Ratchet Strap:
 - Purpose
 - Manufacture
 - Motor Mounting Plate:
 - Material:
 - Aluminum 5052
 - Manufacture:
 - Water Jetting

- Outer Structure:
 - Pelican Case:
 - Material:
 - Polypropylene
 - Manufacture:
 - Injection Molding
 - Main Housing
 - Buoyancy
 - 30 lbs
 - CFD (Computational Fluid Dynamics)

Mechanical Aspect:

Animation:



Mechanical Aspect:

- Camera Housing:
 - Material:
 - Acrylic
 - Aluminum End Case (10 Holes)
 - Cable Penetrators
 - PLA Filament (Red and Black)
 - O rings
 - Manufacture:
 - 3D Printing

- Motor Position:



Electrical Aspect - Design:

- Kill Switch:

- Reed Switch
- MOSFET: max 30 Amps
- Optically Coupled Transistor

- Components:

- 7 Kill Switch Modules
- 1 Arduino

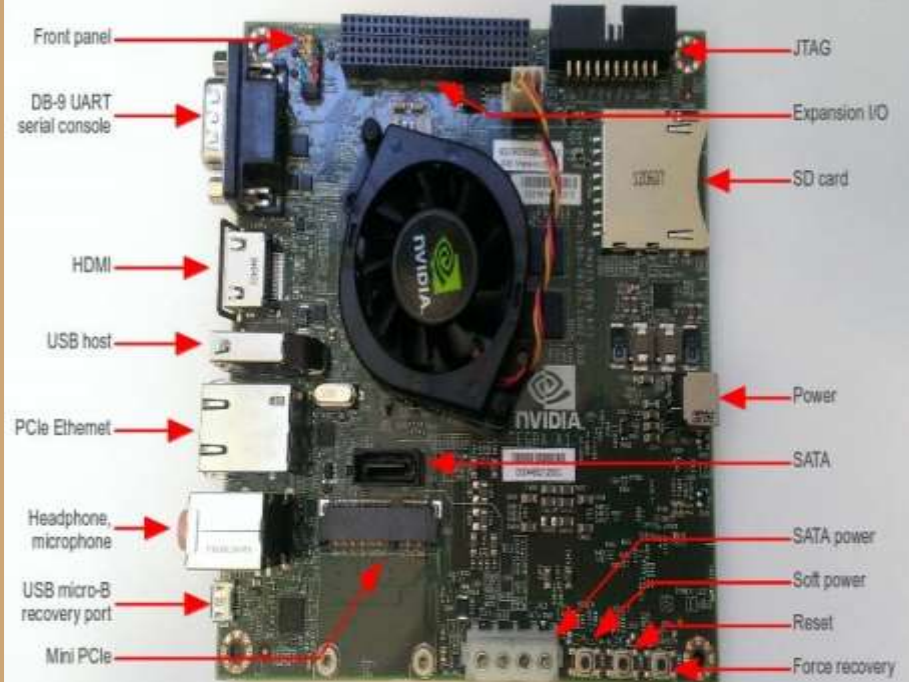
Electrical Aspect:

- Battery:
 - Brand: Mulistar Turnigy
 - Rating: 10000mAh at 10C
 - Number Count: 7 Batterys Total
 - Connectors: XT-90



Software Aspect:

- Original Setup:
 - Jetson TK
 - Pixhawk
 - Linux:
 - Ubuntu
 - Mavros
 - Zed Camera



Software Aspect:

- Problems:

- Pixhawk:
 - Communication
- Jetson:
 - Bricked
- Zed Camera
 - Crashing



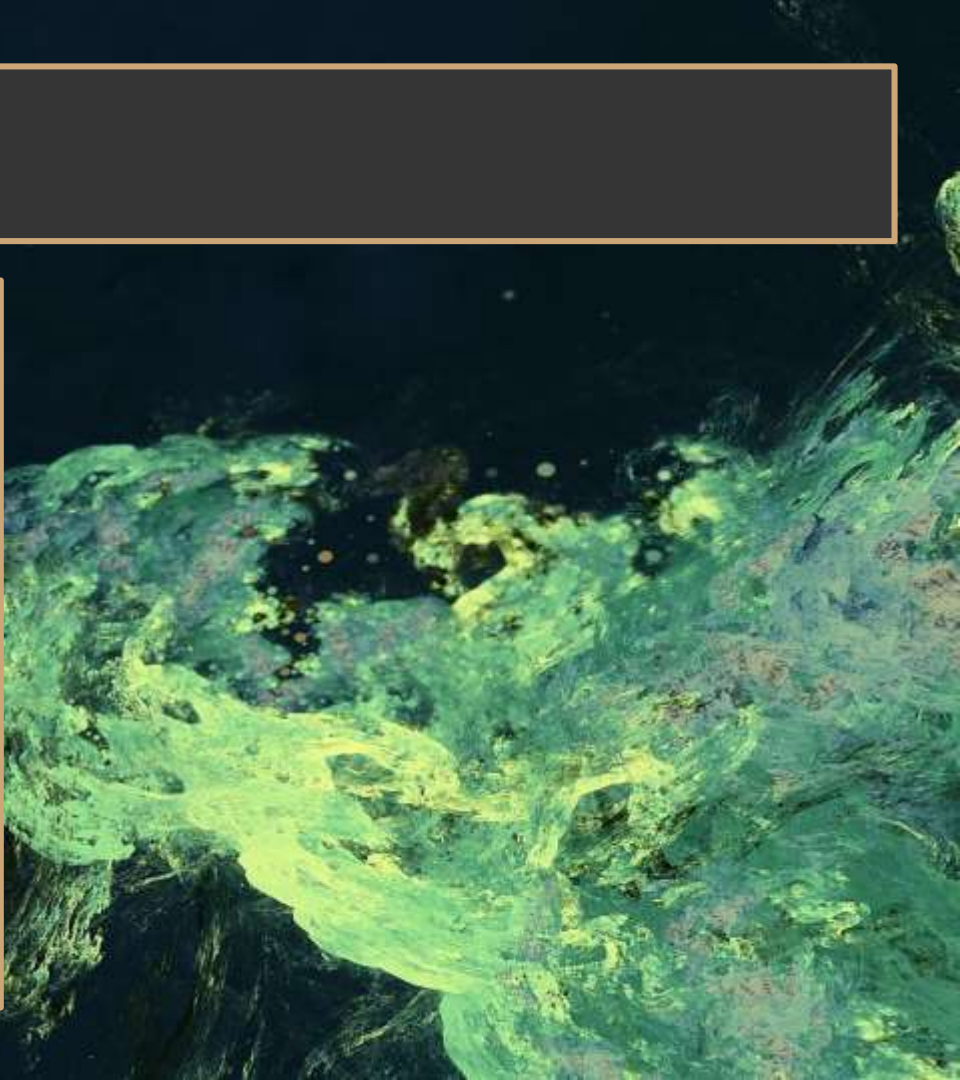
- Solution:

- USB Camera
- Pixhawk
- ODroid



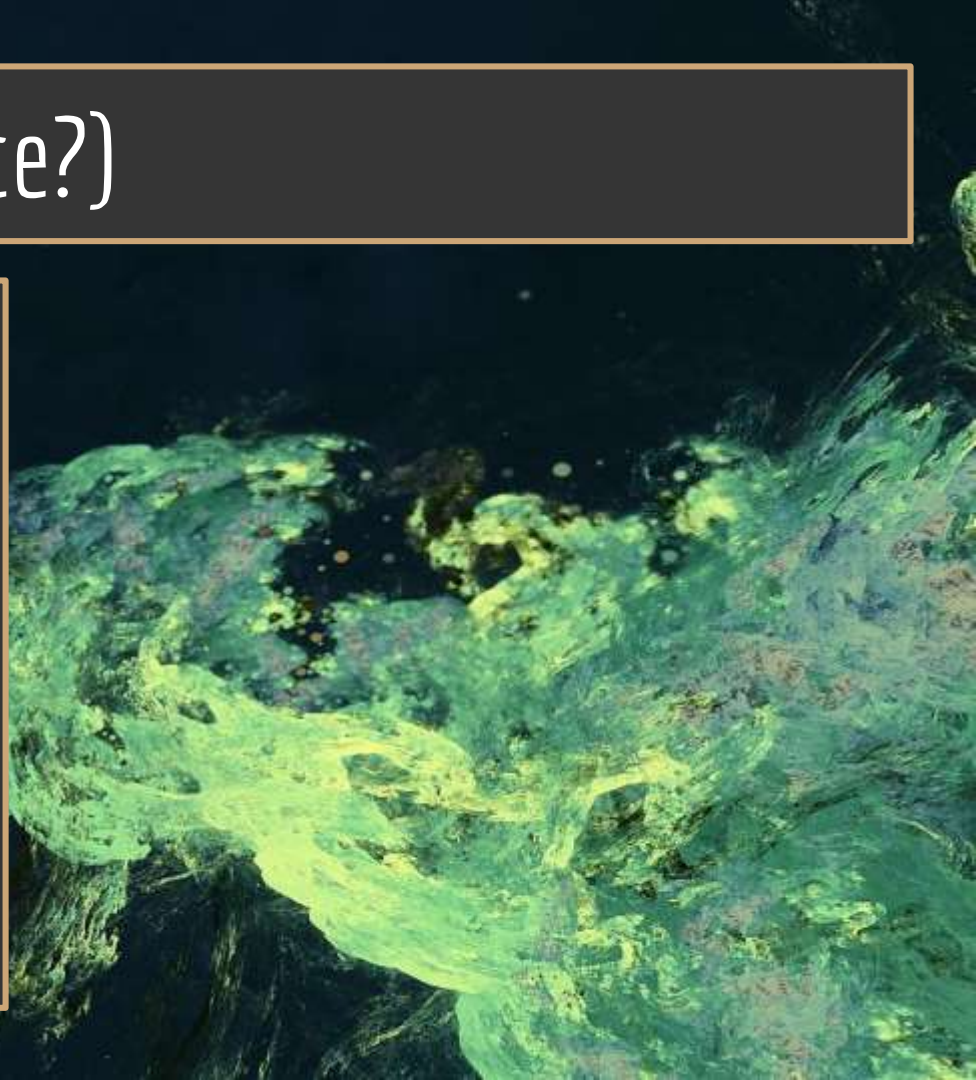
Software Aspect:

- Programming:
 - Language
 - C++
 - Gate Location
 - Color Calibration
 - Color Recognition via C++
 - USB Camera
 - Time & Weather
 - Movement Test
 - Tethered Connection



What? (What is this device?)

- Naming:
 - Cthulhu
- Function:
 - Complete the Obstacle Course
 - Receive Maximum Point
 - BE A BOSS!



Who? (Who is using the device?)