Vivian Nguyen

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Robotics Engineer | Data Scientist | EIT

EDUCATION

Fundamentals of Engineering Exam: FE Mechanical Tentative - 11/22/2019

Bachelor of Science: Mechanical Engineering

December 2019

Minor: Engineering Design Graphics

Southern Polytechnic College of Engineering and Engineering Technology

GPA 3.22

Kennesaw State University, Marietta, GA

SKILLS

- Robotics: ROS 1, Machine Vision, Perception, Sensor Fusion, Arduino, JETSON Embedded
- Data Science: Python, Machine Learning[TensorFlow/Keras, PyTorch, CuPy, CUDA acceleration], NumPy, Pandas
- Engineering: SolidWorks [CSWP, DT, FEA, CFD], AutoDesk Fusion 360, Additive Manufacturing
- Communication: Technical Communication
- **DevOps:** Linux Remote over SSH, 24/7 Server Administration
- Computer: Ubuntu BASH, Git Version Control, Microsoft Office
- **Soft Skills:** Problem Solving, Management, Public Speaking, Professional Communication, People Skills

WORK EXPERIENCE

Data Science Immersive Fellow

August 2020 - Present

General Assembly, Remote

• 480-hour immersive program to apply statistics, programming, data analytics, modeling and machine learning skills in different real-world contexts

Engineering Internship

June 2016 – December 2016

Global Power Products, Lawrenceville, GA

- Designed a manual power transfer switch rated to 400 Amps in accordance with ANSI (American National Standards Institute)
- Created a 3D part library from scratch to organize roughly 100 existing parts

RESEARCH EXPERIENCE

Undergraduate Research Assistant: Mechatronics Engineering

April 2018 -December 2019

Dr. Kevin McFall, Kennesaw State University, Marietta, GA

- Developed an end to end machine learning solution for an autonomous robot for active object detection and path planning
- Presented at NCUR 2019, Publication with JOSFR

TEAM & PROJECT EXPERIENCE

Lead Mechanical Engineer: KSU Autonomous Underwater Vehicle

August 2017 – May 2018

• Led the Engineering Design Process for 2017-2018 Competition Met design considerations and requirements for ROBOSUB

Lead Software Engineer: KSU Autonomous Underwater Vehicle

August 2016 – August 2017

• Led the Software Design Process for 2016-2017 Competition with design considerations for ROBOSUB

Software Team Member: KSU Autonomous Underwater Vehicle

May 2016 – August 2016

• Programmed an autonomous underwater vehicle

• Competed at San Diego SSC TRANSDEC Naval Base

Design Team Member: Human Powered Vehicle Competition Team

August 2014 - May 2015

- Designed, wrote technical paper, tested and documented
- Competed at University of Florida; 22/33 Eastern Conference

LEADERSHIP/AFFILIATIONS

Trumpet Section Leader – Kennesaw State University Marching Band

August 2016 – December 2017