```
MC.CI = function(delta){
  n = length(delta)
  se = sqrt(1/n)*sd(delta)
  list(mean=mean(delta), CI=mean(delta)+c(-1,1)*se*1.96, se=se)
1 simple monte carlo
M=1000
x = matrix(rpois(25*M, 2), nrow = M, ncol = 25)
xbar = rowMeans(x)
deltax = (xbar-2)/(sqrt(2/25)) >= 1.645
# estimate of type 1 error rate
MC.CI(deltax)
## $mean
## [1] 0.061
##
## $CI
## [1] 0.04615873 0.07584127
##
## $se
## [1] 0.007572076
comment: easy to implement, but having the largest standard error and not very accurate
importance sampling
x = matrix(rpois(25*M, 2.4653), nrow = M, ncol = 25)
xbar = rowMeans(x)
deltax = (xbar-2)/(sqrt(2/25)) >= 1.645
dfx = dpois(x,2)
dgx = dpois(x, 2.4653)
fx=rep(1,M)
gx=rep(1,M)
for (j in 1:M){
 for(k in 1:25){
    fx[j]=dfx[j,k]*fx[j]
    gx[j]=dgx[j,k]*gx[j]
  }
}
deltax = (deltax*fx/gx)
MC.CI(deltax)
## $mean
## [1] 0.05462187
##
## $CI
```

```
## [1] 0.04957082 0.05967292
##
## $se
## [1] 0.002577068
```

comment: smallest standard error, useful when it's hard to sample nontrivial delta(x) from distribution of f(x), seems to overestimate the result for a bit

antithetic

```
hM = round(M/2)
x = matrix(runif(25*hM), nrow = hM, ncol = 25)
x1 = qpois(x, 2)
x2 = qpois(1-x,2)
x1bar = rowMeans(x1)
x2bar = rowMeans(x2)
deltax1 = (x1bar-2)/(sqrt(2/25)) >= 1.645
deltax2 = (x2bar-2)/(sqrt(2/25)) >= 1.645
deltax = (deltax1+deltax2)/2
MC.CI(deltax)
## $mean
## [1] 0.048
##
## $CI
## [1] 0.03507604 0.06092396
##
## $se
## [1] 0.006593858
```

merit: easy to implement (given when can generate x from its quantile), successfully decreased standard error by certain amount. overall, seems to produce accurate result (close to 0.05)

control variate

```
x = matrix(rpois(25*M, 2), nrow = M, ncol = 25)
xbar = rowMeans(x)
deltax = (xbar-2)/(sqrt(2/25)) >= 1.645

gx = rowSums(x)

cov.hat = sum((deltax-mean(deltax))*(gx-mean(gx))/(M*(M-1)))
var.hat = sum((gx-mean(gx))^2)/(M*(M-1))
vardelta.hat = sum((deltax-mean(deltax))^2)/(M*(M-1))
alpha = -cov.hat/var.hat

real.star=50

delta.cv = deltax + alpha*(gx-real.star)

var.cv = vardelta.hat+alpha^2*var.hat+2*cov.hat*alpha
```

```
theta.cv = mean(delta.cv)

theta.cv

## [1] 0.0620431

se = sqrt(var.cv)
 se

## [1] 0.006589048

theta.cv+c(1,-1)*se*1.96
```

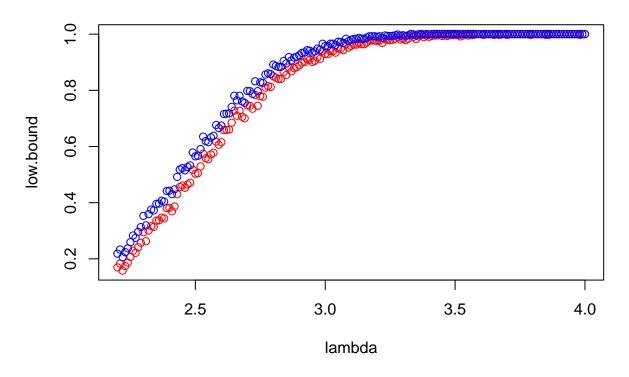
## ## [1] 0.07495763 0.04912857

effect of variance reduction is slightly better than antithetic sampling, most complicated to implement in these four cases.

```
# simple MC
lambda = seq(2.2,4,0.01)
low.bound=c()
up.bound=c()

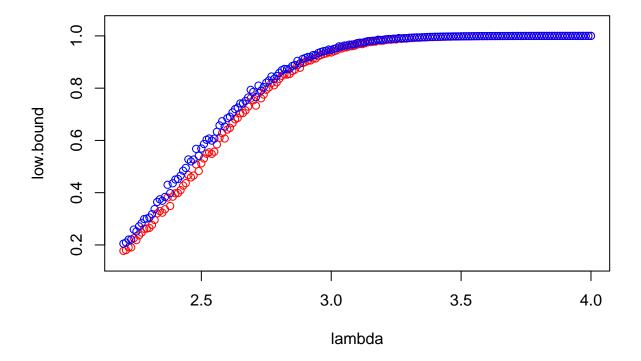
for (i in lambda){
    x = matrix(rpois(25*M, i), nrow = M, ncol = 25)
    xbar = rowMeans(x)
    deltax = (xbar-2)/(sqrt(2/25)) >= 1.645
    low.bound=c(low.bound, MC.CI(deltax)$CI[1])
    up.bound=c(up.bound, MC.CI(deltax)$CI[2])
}

plot(lambda, low.bound, col='red')
points(lambda, up.bound, col='blue')
```



```
#importance sampling
low.bound=c()
up.bound=c()
for (i in lambda){
  newlambda = 2.4653
  x = matrix(rpois(25*M, newlambda), nrow = M, ncol = 25)
  xbar = rowMeans(x)
  fx = rep(0,nrow(x))
  gx = rep(0,nrow(x))
  # if lambda>2.4653, we cannot sample acceptation well with f(x)
  if(i>2.4653){
    deltax = (xbar-2)/(sqrt(2/25)) \le 1.645
    dfx=dpois(x ,i)
    for (j in 1:nrow(x)){
      fx[j]=prod(dfx[j,])
    dgx=dpois(x , newlambda)
    for (j in 1:nrow(x)){
      gx[j]=prod(dgx[j,])
    }
    ipx = deltax*fx/gx
    ipx = 1-ipx
  # if lambda<2.4653, we cannot sample rejection well with f(x)
    deltax = (xbar-2)/(sqrt(2/25)) >= 1.645
    dfx=dpois(x ,i)
```

```
for (j in 1:nrow(x)){
    fx[j]=prod(dfx[j,])
}
dgx=dpois(x , newlambda)
for (j in 1:nrow(x)){
    gx[j]=prod(dgx[j,])
}
ipx = deltax*fx/gx
}
low.bound=c(low.bound, MC.CI(ipx)$CI[1])
up.bound=c(up.bound, MC.CI(ipx)$CI[2])
}
plot(lambda, low.bound, col='red', ylim = extendrange(c(low.bound, up.bound)))
points(lambda, up.bound, col='blue')
```



again simple montecarlo is easiest to implement, but yields largest CI and roughest curve. But it works. importance sampling yields smoothest curve, and shortest confidence interval especially when lambda > 2.5, when it's hard to sample delta(x)

```
# antithetic
low.bound=c()
up.bound=c()

for (i in lambda){
   hM = round(M/2)
   x = matrix(runif(25*hM), nrow = hM, ncol = 25)
```

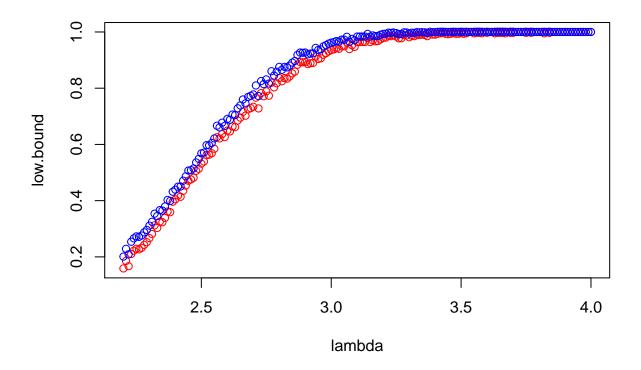
```
x1 = qpois(x,i)
x2 = qpois(1-x,i)
x1bar = rowMeans(x1)
x2bar = rowMeans(x2)

deltax1 = (x1bar-2)/(sqrt(2/25)) >= 1.645
deltax2 = (x2bar-2)/(sqrt(2/25)) >= 1.645

deltax = (deltax1+deltax2)/2

#concatenate 2 groups of data
low.bound=c(low.bound, MC.CI(deltax)$CI[1])
up.bound=c(up.bound, MC.CI(deltax)$CI[2])
}

plot(lambda, low.bound, col='red')
points(lambda, up.bound, col='rblue')
```



```
# control variate
low.bound=c()
up.bound=c()

for (i in lambda){
    x = matrix(rpois(25*M, i), nrow = M, ncol = 25)
    xbar = rowMeans(x)
    deltax = (xbar-2)/(sqrt(2/25)) >= 1.645
```

```
gx = rowSums(x)

cov.hat = sum((deltax-mean(deltax))*(gx-mean(gx))/(M*(M-1)))
var.hat = sum((gx-mean(gx))^2)/(M*(M-1))
vardelta.hat = sum((deltax-mean(deltax))^2)/(M*(M-1))

alpha = -cov.hat/var.hat

real.star=25*i

delta.cv = deltax + alpha*(gx-real.star)

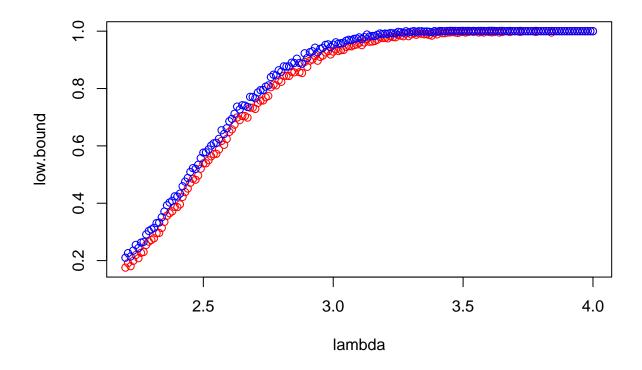
var.cv = vardelta.hat+alpha^2*var.hat+2*cov.hat*alpha

theta.cv = mean(delta.cv)

theta.cv = theta.cv+c(-1,1)*sqrt(var.cv)*1.96

low.bound=c(low.bound, CIs[1])
 up.bound=c(up.bound, CIs[2])
}

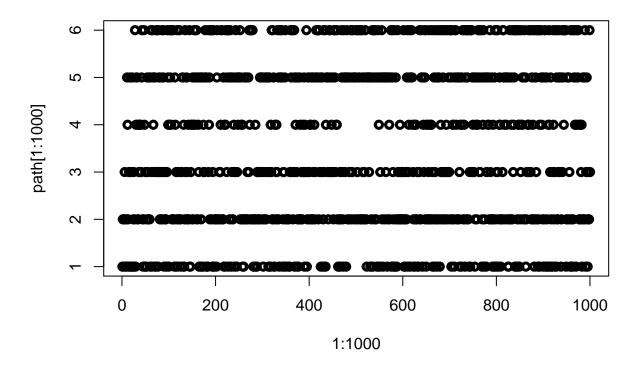
plot(lambda, low.bound, col='red')
points(lambda, up.bound, col='blue')
```



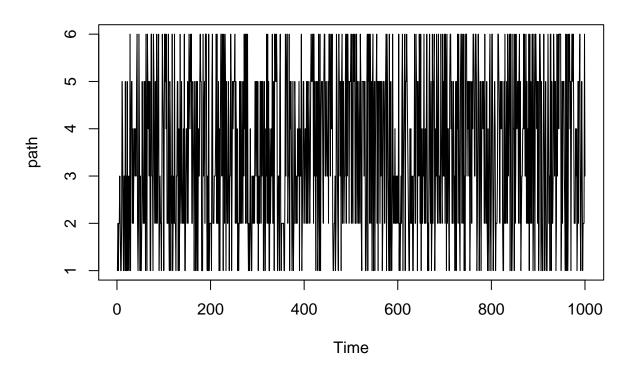
###

Control variance has slightly smaller CI and smoother curve than antithetic. They work better than simple montecarlo, worse than importance sampling when lambda is large. When lambda is small, they work better than importance sampling.

```
P=diag(c(0.5,0.5,0.25,0.25,0.5,0.5))
P[1,2]=P[6,5]=0.5
P[2,1]=P[2,3]=P[5,4]=P[5,6]=0.25
P[3,1]=P[3,2]=P[3,4]=P[4,6]=P[4,5]=P[4,3]=0.25
##
        [,1] [,2] [,3] [,4] [,5] [,6]
## [1,] 0.50 0.50 0.00 0.00 0.00 0.00
## [2,] 0.25 0.50 0.25 0.00 0.00 0.00
## [3,] 0.25 0.25 0.25 0.25 0.00 0.00
## [4,] 0.00 0.00 0.25 0.25 0.25 0.25
## [5,] 0.00 0.00 0.00 0.25 0.50 0.25
## [6,] 0.00 0.00 0.00 0.00 0.50 0.50
getrand.state=function(x){
  ret=-1
  r=runif(1)
 temp=0
  for(sta in 1:length(x)){
    temp=temp+x[sta]
    if (r <= temp){</pre>
      ret = sta
      break
    }
  }
 ret
}
x=c(1,rep(0,5))
path=rep(0,1000)
for (i in 1:1000){
 path[i]=getrand.state(x)
  x = t(P) %% x
}
plot(1:1000, path[1:1000], lwd=3)
```



ts.plot(path)



```
#relative frequency
table(path)/1000
## path
     1
            2
                   3
                         4
                               5
                                     6
## 0.152 0.226 0.141 0.096 0.212 0.173
# we guess stationary distribution is c(1/6,2/9,1/9,1/9,2/9,1/6)
t(P)%*%c(1/6,2/9,1/9,1/9,2/9,1/6)
##
            [,1]
## [1,] 0.1666667
## [2,] 0.2222222
## [3,] 0.1111111
## [4,] 0.1111111
## [5,] 0.2222222
```

## [6,] 0.1666667