Operating System

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CHAPTER-1

Introduction

Concepts of Operating System

Software:-

•Program is a collection of code/instruction.

•Software is a collection of program.

Hardware:-

•Physical device is a collection of computer system which is called Hardware.

Example: **Processor, RAM, Hard disk, I/O devices.**

Concepts of Operating System

Types of Software:-

• Software is divide into 3 types:

1. System software

2. Utility software

3. Application software

System Software

- The software which is used to perform all types of system level tasks of computer is called system software.

For example:

– Compiler

– Operating system

– Interpreter

– Linker

– Loader

Utility Software

- The software, which provide an additional meaning to the computer system.

For Example:-

– Calculator

– MS-paint

– Browser

– Notepad

– Media Player

Application Software

- The software which is created by users, using the different high level language and database system for any special purpose.

   For Example:-

   – Library Management system

   – Banking Software

   – Ticket Reservation system
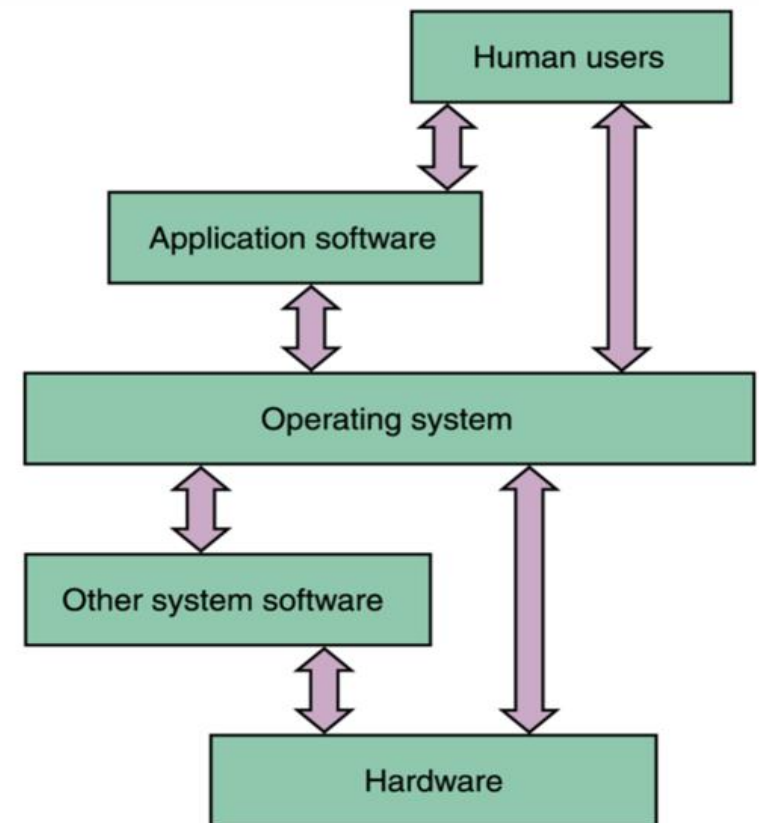
What is an Operating System?

- An operating system (OS) is a collection of system software that manages computer hardware resources and provides common services for computer programs.

OR

- A program that acts as an intermediary/interface between a user of a computer and the computer hardware.

What is an Operating System?

- Users and Processes access the Computer's resources through the Operating System

Operating System Approach[6]

Goals of an Operating System

- Simplify the execution of user programs and make solving user problems easier

- Use computer hardware efficiently

- Allow sharing of hardware and software resources.

- Make application software portable and flexible

- Provide isolation, security and protection among user programs

- Improve overall system reliability like Error confinement, Fault tolerance, Reconfiguration.

Generations of Operating Systems

- It's also known as history of Operating systems.

- Which can be divided in 4 generations

First Generation (1945-1955)
Vacuum Tubes & Plug boards

Second Generation (1955-1965)
Transistors & Batch Systems

Third Generation (1965-1980)
Integrated Circuits & Multi programming

Fourth Generation (1980-Current)
Personal Computers

The First Generation (1945-1955): Vacuum Tubes

- Digital computers were not constructed until the second world war.

- Calculating engines with mechanical relays were built at that time.

- However, the mechanical relays were very slow and were later replaced with vacuum tubes.

- These machines were enormous but were still very slow.

Vacuum Tubes Source: Google
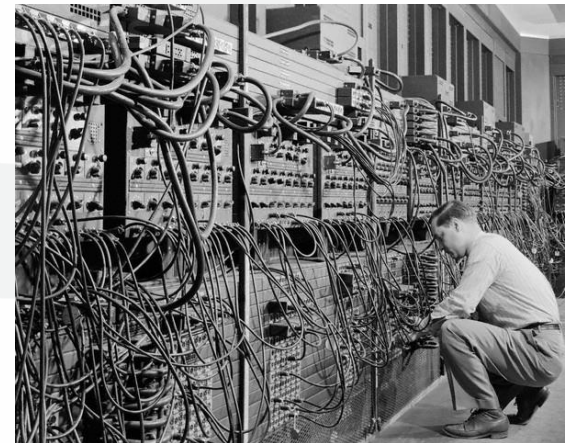
1940s computers Source: Google

The First Generation (1945-1955): Plugboards

•Programming languages were unknown and there were no operating systems so all the programming was done in machine language. All the problems were simple numerical calculations.

•By the 1950's punch cards were introduced and this improved the computer system. Instead of using plugboards, programs were written on cards and read into the system.

Plugboards Source: Google

The Second Generation(1955-1965)

Transistors & Batch Systems

- Transistors led to the development of the computer systems that could be manufactured and sold to paying customers. These machines were known as mainframes and were locked in air-conditioned computer rooms with staff to operate them.

- The Batch System was introduced to reduce the wasted time in the computer. A tray full of jobs was collected in the input room and read into the magnetic tape.

The Third Generation (1965-1980)

Integrated Circuits & Multiprogramming

- Until the 1960's, there were two types of computer systems i.e the scientific and the commercial computers. These were combined by IBM in the System/360. This used integrated circuits and provided a major price and performance advantage over the second generation systems.

- The third generation operating systems also introduced multiprogramming. This meant that the processor was not idle while a job was completing its I/O operation. Another job was scheduled on the processor so that its time would not be wasted.

The Fourth Generation (1980-Present)

Personal Computers

- Personal Computers were easy to create with the development of large-scale integrated circuits. These were chips containing thousands of transistors on a square centimetre of silicon.

- The advent of personal computers also led to the growth of networks. This created network operating systems and distributed operating systems. The users were aware of a network while using a network operating system and could log in to remote machines and copy files from one machine to another.

Examples of Personal Computer Operating Systems

Microsoft Windows

- Microsoft created the Windows operating system in the mid-1980s.

- Most recent versions are Windows 10 (released in 2015), Windows 8 (2012), Windows 7 (2009), and Windows Vista (2007).

- Windows comes pre-loaded on most new PCs, which helps to make it the most popular operating system in the world.

Examples of Personal Computer Operating Systems

Microsoft Windows

Windows 10

Examples of Personal Computer Operating Systems

Mac OS

- Mac OS is a line of operating systems created by Apple.

- It comes preloaded on all new Macintosh computers, or Macs.

- Specific versions include El Capitan (released in 2015), Yosemite (2014), Mavericks (2013), Mountain Lion (2012), and Lion (2011).

Examples of Personal Computer Operating Systems

macOS

macOS Source: Google

Examples of Personal Computer Operating Systems

Linux

- Linux (pronounced LINN-ux) is a family of open-source operating systems, which means they can be modified and distributed by anyone around the world.

- The advantages of Linux are that it is free, and there are many different distributions or versions you can choose from.

Examples of Personal Computer Operating Systems

linux

Ubuntu OS Source: Google

Operating systems for mobile devices

- Mobile devices such as smartphones, tablets, and MP3 players are different from desktop and laptop computers, so they run operating systems that are designed specifically for mobile devices.

- Examples of mobile OS - Apple iOS and Google Android.

# Types of Operating Systems

- Simple Batch System

- Multiprogramming Batch System

- Multitasking system

- Multiprocessor System

- Distributed Operating System

- Real-time Operating System

SIMPLE BATCH SYSTEMS

- **No direct interaction** between user and computer.

- The user has to **submit a job** (written on cards or tape) to a computer operator.

- Then computer operator places a **batch of several jobs** on an input device.

SIMPLE BATCH SYSTEMS
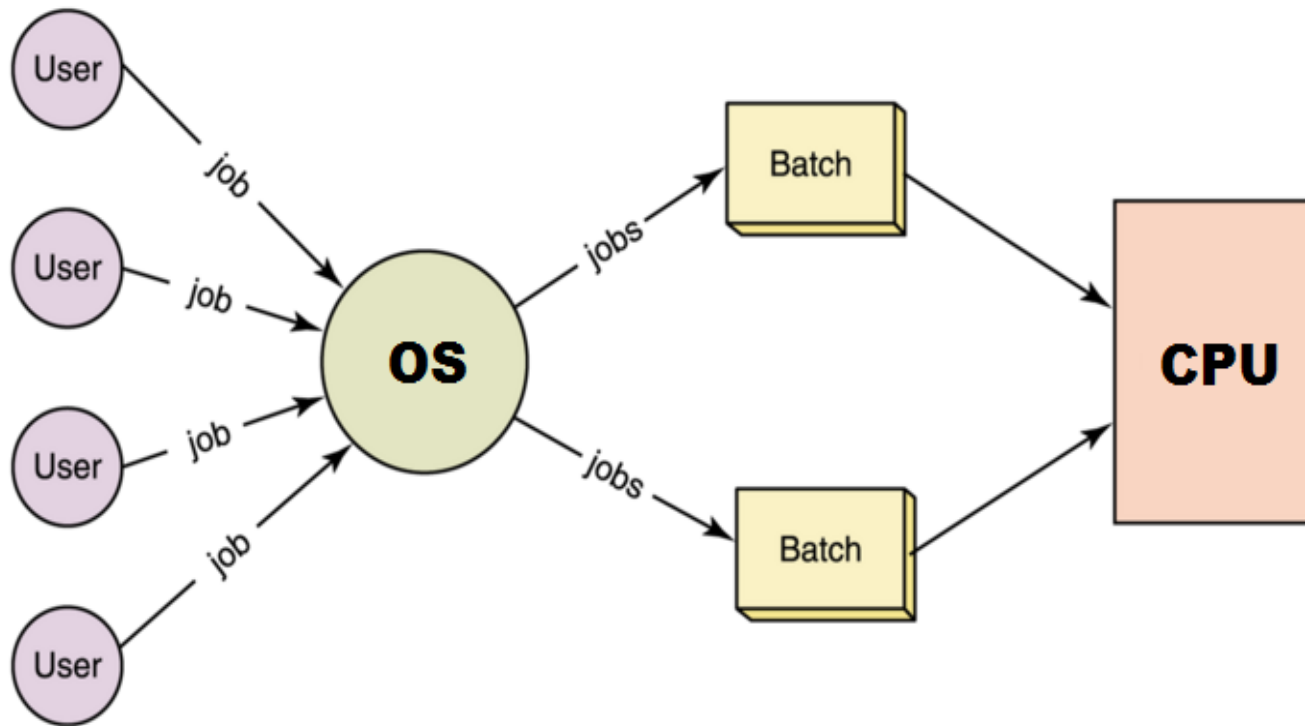
Batch OS ([Source](#))

SIMPLE BATCH SYSTEMS

Advantages

- Increased performance - next job start as the previous job finished.

- Suitable for executing large jobs that need little interaction

Disadvantages

- Zero interaction between user and computer.

- No mechanism to prioritize processes.

Multiprogramming Batch Operating System

- Several jobs are kept in main memory at the same time, and the CPU is multiplexed among them.
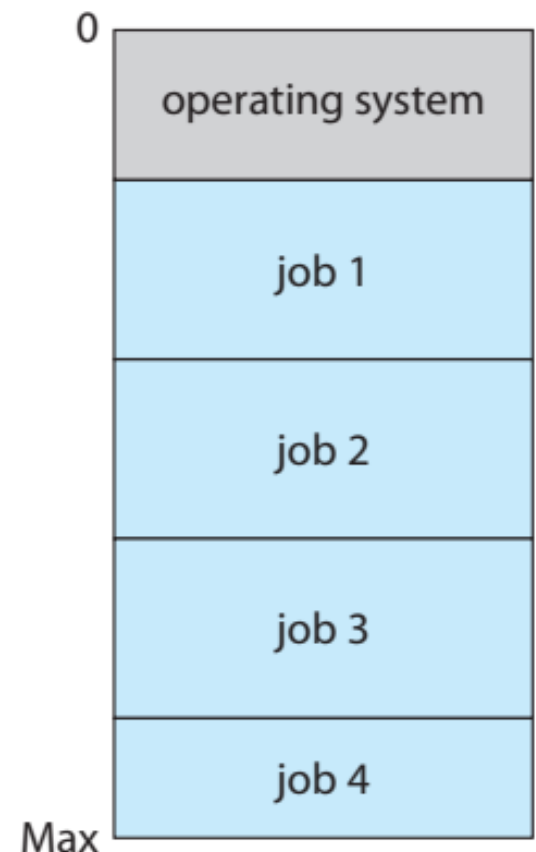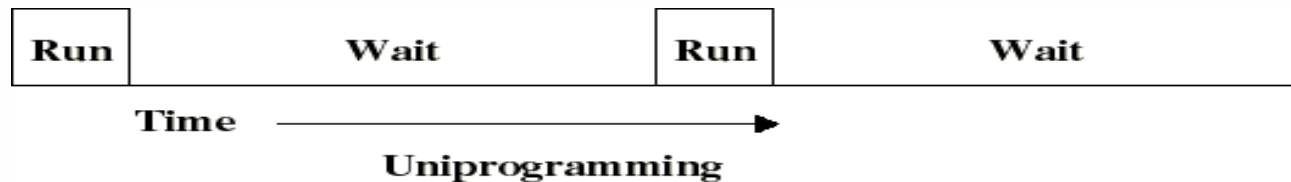

Memory layout for a multiprogramming system[1]
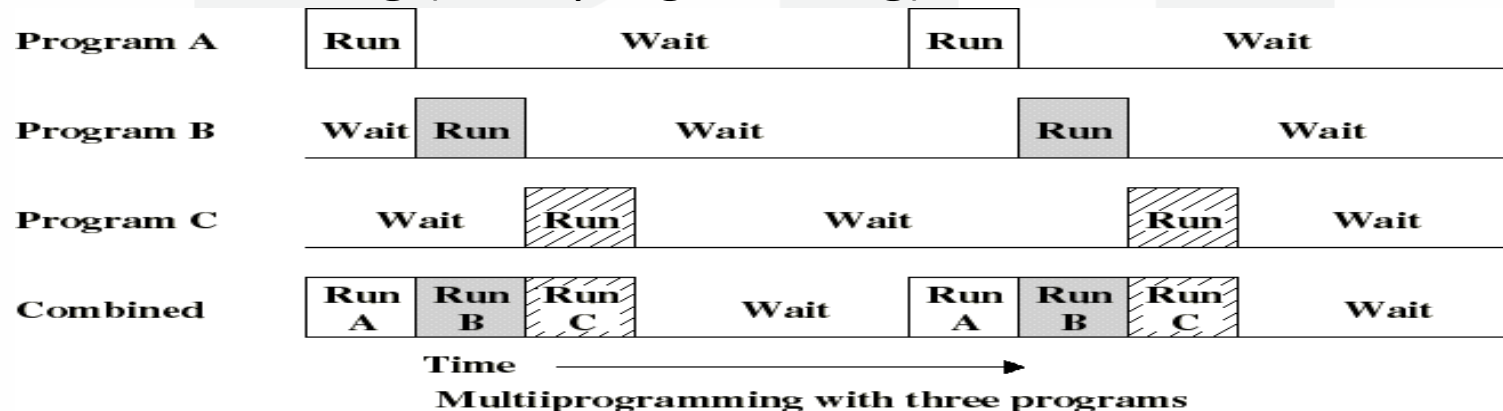
Multiprogramming Batch Operating System

•Multiprogramming increases CPU utilization

•Multiple jobs are loaded into main memory and one is selected from pool for execution by CPU

•If at some point program in progress requires service of a peripheral device, the control of CPU is given to next job which is in main memory

•So, CPU is always executing some program instead of waiting.

Multiprogramming Batch Operating System

- CPU usage is poor when only one program is present in memory

Run	Wait	Run	Wait

Time ⟶

Uniprogramming

- If memory can hold several programs, then CPU can switch to another one whenever a program is awaiting for an I/O to complete This is multitasking (multiprogramming)

Program A	Run	Wait	Run	Wait
Program B	Wait Run	Wait	Run	Wait
Program C	Wait Run	Wait	Run	Wait
Combined	Run A Run B Run C	Wait	Run A Run B Run C	Wait

Time ⟶

Multiprogramming with three programs

Multiprogramming (Source)

Multiprogramming Batch Operating System

Effects of Multiprogramming

	Uniprogramming	Multiprogramming
Processor use	17%	33%
Memory use	30%	67%
Disk use	33%	67%
Printer use	33%	67%
Elapsed time	30 min.	15 min.
Throughput rate	6 jobs/hr	12 jobs/hr
Mean response time	18 min.	10 min.

Effects of Multiprogramming (Source)

Multiprogramming Batch Operating System

Advantages

- High CPU utilization, so CPU never sits idle, if there are jobs available
- Many programs are allotted CPU almost simultaneously.
- Provides better resource utilization (Memory, I/O, CPU)
- More then one process can be executed simultaneously by user.

Disadvantages

- CPU scheduling is required.
- Memory management is required, to accommodate many jobs in memory
- Multiprogramming does not support interaction with users

Multitasking/Time Sharing System(TSS)

- Multiprogramming does not support interaction with users, TSS extends multiprogramming to handle multiple interactive jobs

- TSS uses CPU scheduling & multiprogramming to provide economical interactive systems of two or more users.

- Each user is given a time-slice for executing his job in Round-Robin Fashion (Every process will be given equal amount of CPU one by one in sequence). Job continues until the time slice ends.

- The CPU is multiplexed among several jobs that are kept in main memory.

Multitasking/Time Sharing System(TSS)

- TSS allows more frequent context switches from one user to the next (when time-slice of particular process ends it switches to the next for given time slice duration)

- This gives each user the impression that the entire computer is dedicated to his use only, whereas actually one computer is being shared among many users.

Multitasking/Time Sharing System(TSS)

Advantages

- Provides Quick Response

- Reduces CPU idle time

Disadvantages

- Security & Integrity of user's program & data is needed.

- If lots of users & applications are running then it may hang up the system. So, high configuration of hardware is required.

Multiprocessor/Parallel System

- **Multiprocessor systems** with more than one CPU works in close communication.

- **Tightly coupled system** – processors share memory and I/O devices, bus, system and communication usually takes place through the shared memory.

Multiprocessor/Parallel System

- A multiprocessor system comprises of **several processors** that share a **common physical memory**.

- Multiprocessor system delivers **higher computing power and speed.**

- In multiprocessor system all processors function under **single operating system.**

Multiprocessor/Parallel System

Advantages

- **Increased throughput:** No. of jobs executed per unit time increased as there are more no. of processors.

- **Economical:** Buying one system with 3 CPU is cheaper than 3 systems with 3 different CPUs. The processors can share peripherals, cabinets and power supplies.

- **Increased reliability:** The failure of one processor will not stop the system, it functions with other available processors.

Real Time System

- A real-time operating system (RTOS) promises a certain capability within a specified time constraint.

- It is defined as an operating system known to give maximum time for each of the critical operations that it performs, like OS calls and interrupt handling.

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Real Time System

Hard real-time system

- The Real-Time Operating system which guarantees the **maximum time for critical operations** and complete them **on time** are referred to as Hard Real-Time Operating Systems.

- If the system fails to meet the deadline even once the system is considered to have Failed.

- E.g. Defence applications, nuclear system etc. Missing deadlines creates hazards.

Real Time System

Soft real-time system

- The critical task will get priority over other tasks, but **no assurity of completing it in a defined time**. These systems are referred to as Soft Real-Time Operating Systems.

- It is less restrictive type of OS. even if the system fails to meet the deadline, the system is not considered to have failed. In this case the results of the requests are not worthless.

- E.g. Audio-Video streaming etc.

Distributed System

- Distribute the computation among several physical processors.

- Distributed OS is an OS that runs on several machines and it controls the resources of several machines.

- Loosely coupled system – each processor has its own local memory; processors communicate with one another through various communications lines, such as high-speed buses or telephone lines.
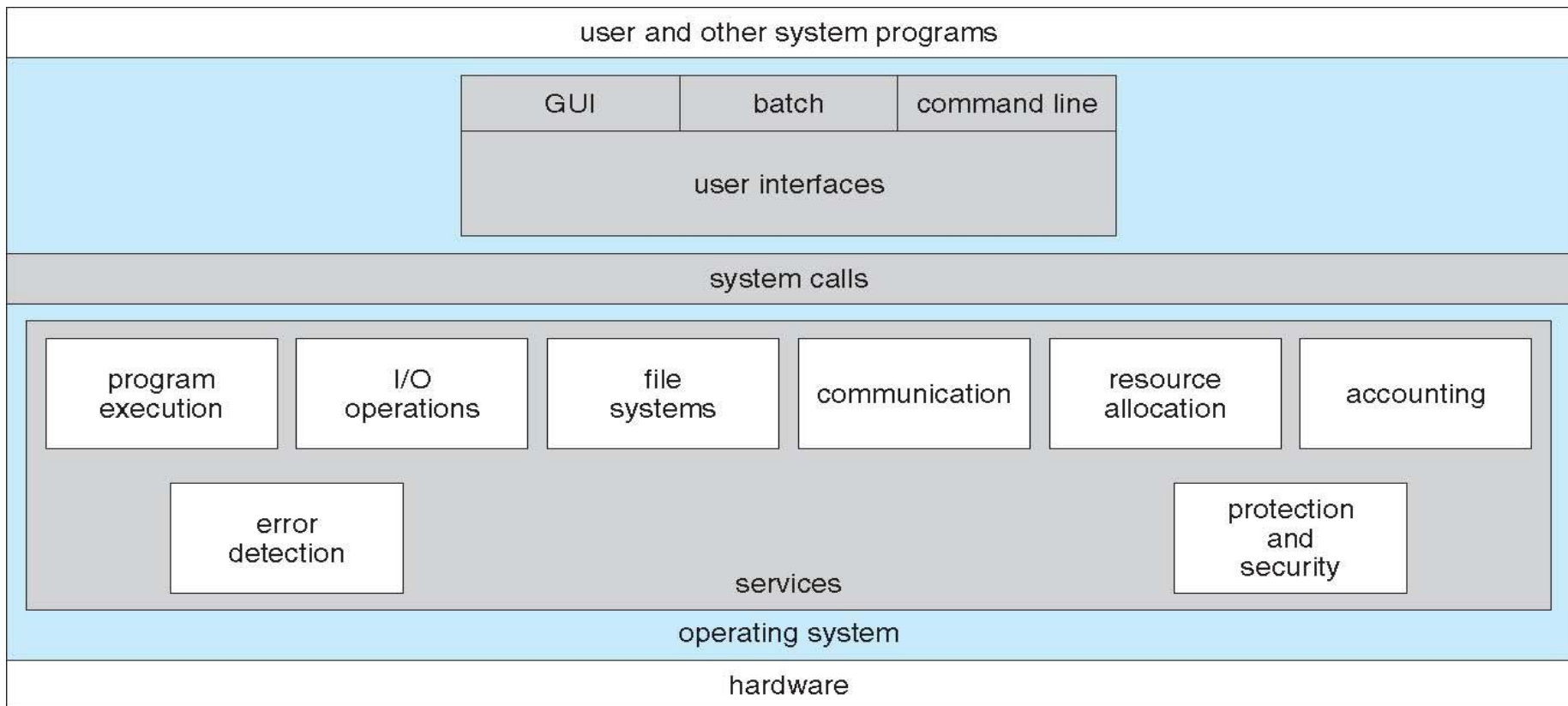
Distributed System

Distributed OS (Source)
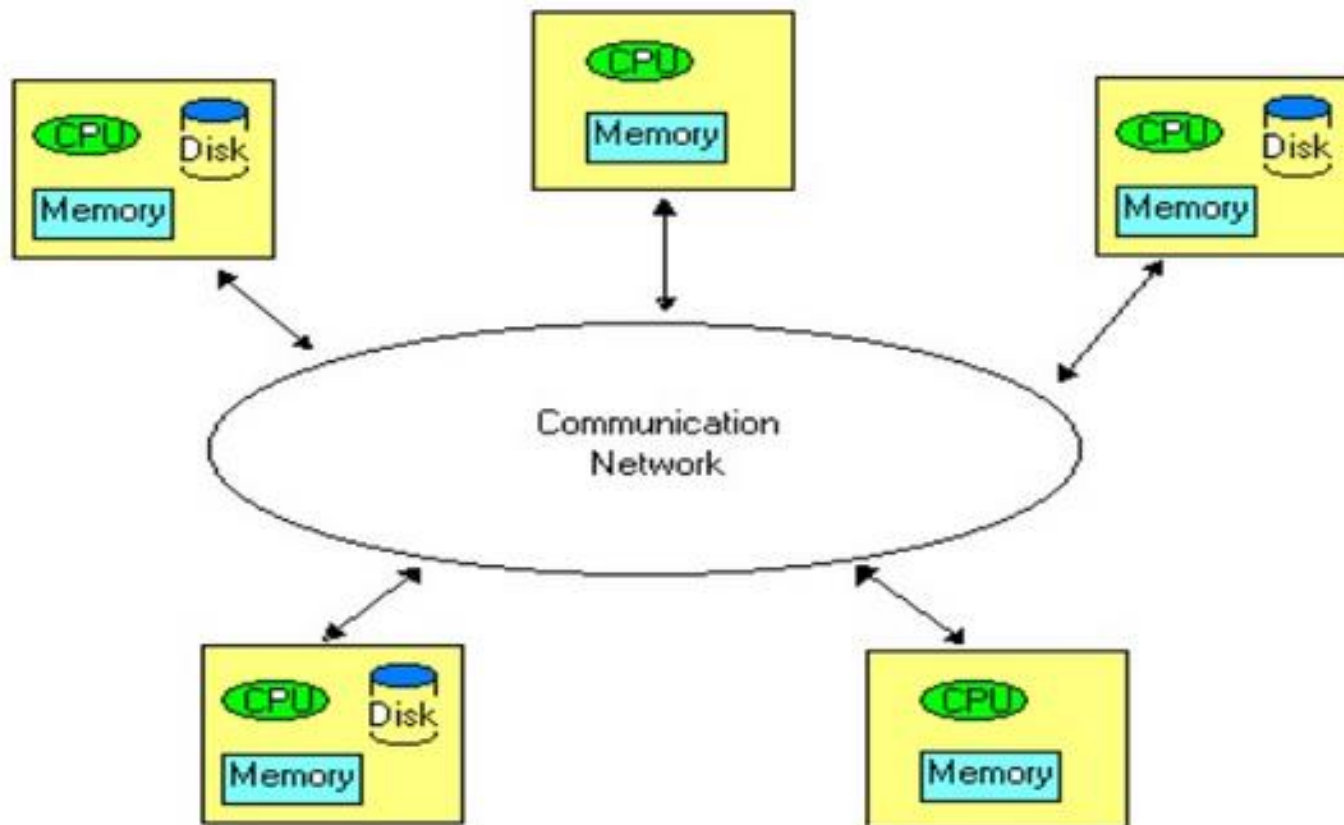
Distributed System

Advantages

- Resources Sharing

- Computation speed up due to load sharing . So, Short response time and higher throughput.

- Higher Reliability: Degree of tolerance against failure

- Incremental Growth : to extend functionality of a system by simply adding additional resources to the system

Operating System Services

user and other system programs		
GUI	batch	command line
user interfaces		

system calls

program execution	I/O operations	file systems	communication	resource allocation	accounting

error detection				protection and security

services

operating system

hardware

A view of operating system services[1]

Operating System Services

- **User Interface:** Almost all operating systems have a user interface (UI). Varies between Command-Line (CLI), Graphics User Interface (GUI), Batch Interfaces

- **Program execution:** The system must be able to load a program into memory and to run that program, must be able to end execution, either normally or abnormally (indicating error)

- **I/O operations:** A running program may require I/O, which may involve a file or an I/O device, user programs cannot execute I/O operations directly, the operating system must provide some means to do I/O.

Operating System Services

- *File-system manipulation:* Programs need to read and write files and directories, create and delete them, search them, list file Information, permission management; allow or deny access to files/directories based on file ownership.

- *Communications:* Exchange of information between processes executing either on the same computer or on different systems tied together by a network. Implemented via shared memory or message passing.

Operating System Services

- *Error detection* – OS needs to be constantly aware of possible errors

- May occur in the CPU and memory hardware, in I/O devices, in user program

- For each type of error, OS should take the appropriate action to ensure correct and consistent computing

- Debugging facilities can greatly enhance the user's and programmer's abilities to efficiently use the system

Some Additional OS Services

- *Resource allocation:* When multiple users or multiple jobs running concurrently, resources must be allocated to each of them. Many types of resources - Some (such as CPU cycles, main memory, and file storage) may have special allocation code, others (such as I/O devices) may have general request and release code.

- *Accounting:* To keep track of which users use how much and what kinds of computer resources. Used for accounting or usage statistics.

Some Additional OS Services

- *Protection* involves ensuring that all access to system resources is controlled

- *Security* of the system from outsiders requires user authentication (by password), extends to defending external I/O devices (eg. Modems, network adapter from invalid access attempts .

- *Protection and security:* The owners of information stored in a multiuser or networked computer system may want to control use of that information, concurrent processes should not interfere with each other.
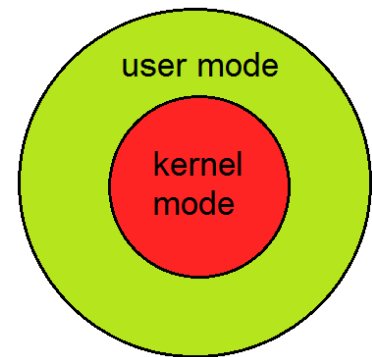
System Calls

- System call is a request made by user program in order to get the service of an operating system.

- When a program in user mode requires access to RAM or a hardware resource, it must ask the kernel to provide access to that resource. This is done via something called a system call.

System Calls

Kernel Mode

- When CPU is in kernel mode, the code being executed can access any memory address and any hardware resource.

- Hence kernel mode is a very privileged and powerful mode.

- If a program crashes in kernel mode, the entire system will be halted.

OS modes ([Source](#))

System Calls

User Mode

- When CPU is in user mode, the programs don't have direct access to memory and hardware resources.

- In user mode, if any program crashes, only that particular program is halted. That means the system will be in a safe state even if a program in user mode crashes.

- Hence, most programs in an OS run in user mode.
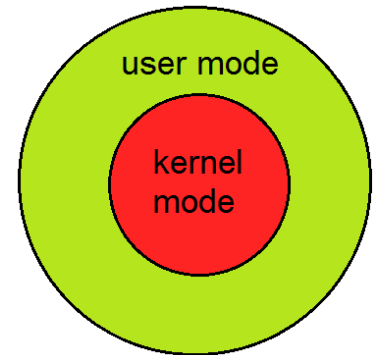
OS modes ([Source](#))

System Calls For Process Management

Process management

Call	Description
pid = fork( )	Create a child process identical to the parent
pid = waitpid(pid, &statloc, options)	Wait for a child to terminate
s = execve(name, argv, environp)	Replace a process' core image
exit(status)	Terminate process execution and return status

System Call[3]

System Calls For File Management

File management

Call	Description
fd = open(file, how, ...)	Open a file for reading, writing or both
s = close(fd)	Close an open file
n = read(fd, buffer, nbytes)	Read data from a file into a buffer
n = write(fd, buffer, nbytes)	Write data from a buffer into a file
position = lseek(fd, offset, whence)	Move the file pointer
s = stat(name, &buf)	Get a file's status information

System Call[3]

System Calls For Directory Management

Directory and file system management

| Call	Description
s = mkdir(name, mode)	Create a new directory
s = rmdir(name)	Remove an empty directory
s = link(name1, name2)	Create a new entry, name2, pointing to name1
s = unlink(name)	Remove a directory entry
s = mount(special, name, flag)	Mount a file system
s = umount(special)	Unmount a file system

System Call[3]

System Calls For Miscellaneous Tasks

Miscellaneous

| Call	Description
s = chdir(dirname)	Change the working directory
s = chmod(name, mode)	Change a file's protection bits
s = kill(pid, signal)	Send a signal to a process
seconds = time(&seconds)	Get the elapsed time since Jan. 1, 1970

System Call[3]

Operating System layered structure
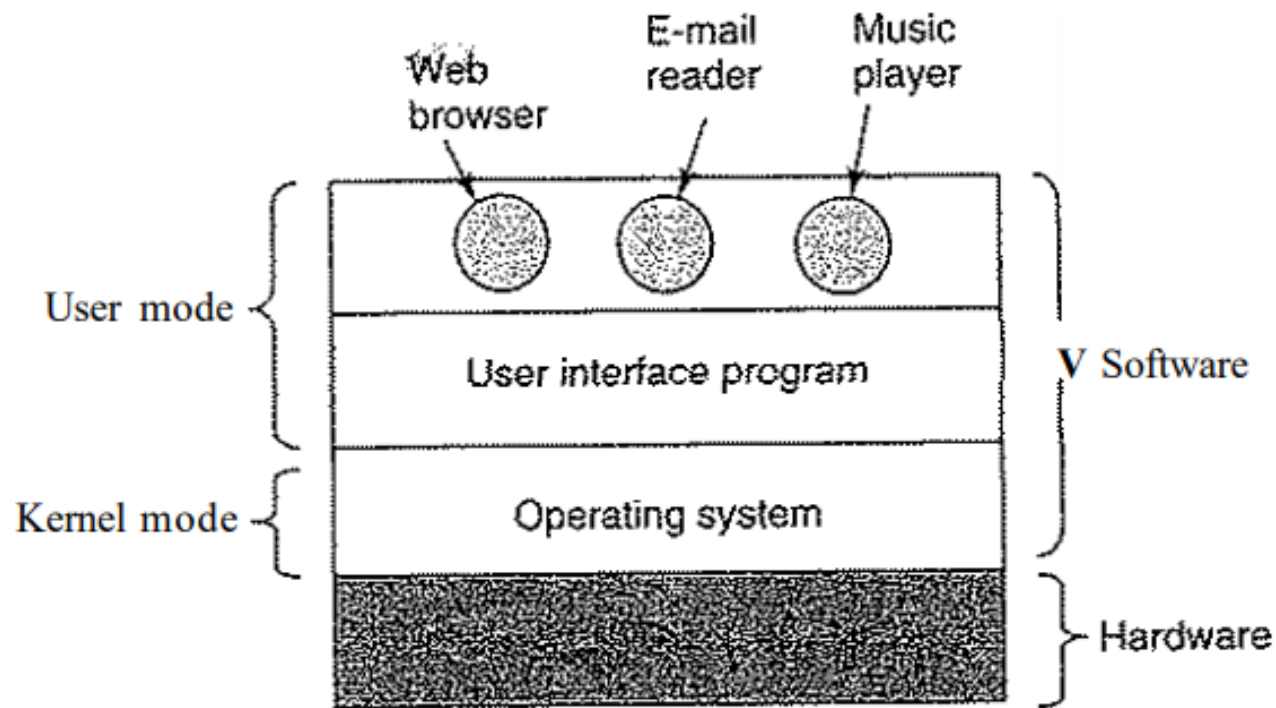
Where the operating system fits in[3]

Operating System layered structure

- With the layered approach, the bottom layer is the hardware, while the highest layer is the user interface.

- Advantage is simplicity of construction and debugging.

- The main difficulty is defining the various layers.

- The main disadvantage is that the OS tends to be less efficient than other implementations

Operating System Layers (Source)
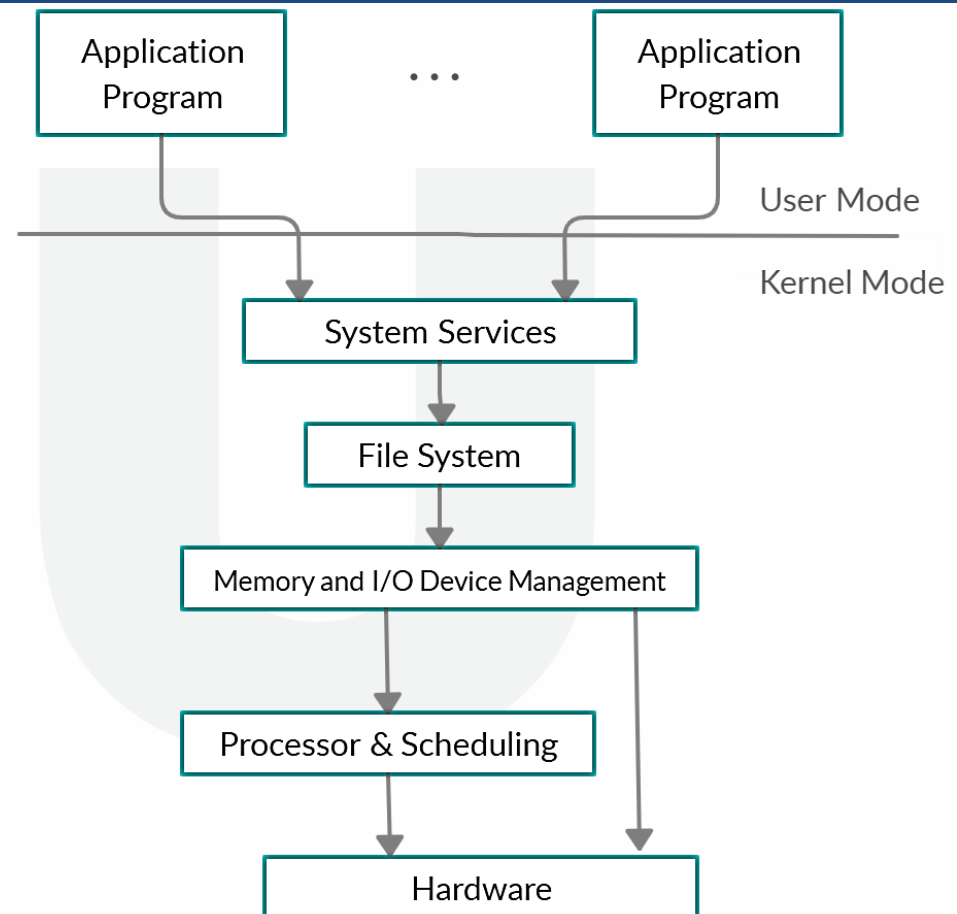
Operating System Structure - Components

- Process Management

- Main Memory Management

- File Management

- I/O System Management

- Secondary Management

- Networking

- Protection System

- Command-Interpreter System

Process Management

- A process is a program in execution. A process needs certain resources, including CPU time, memory, files, and I/O devices, to accomplish its task.

- The operating system is responsible for the following activities in connection with process management.
    - Process creation and deletion.
    - process suspension and resumption.
    - Deadlock handling
    - Provision of mechanisms for:
    - process synchronization
    - process communication

Memory Management

- Memory is a large array of words or bytes, each with its own address. It is a repository of quickly accessible data shared by the CPU and I/O devices.

- Main memory is a volatile storage device. It loses its contents in the case of system failure.

- The operating system is responsible for the following activities in connections with memory management:

  - Keep track of which parts of memory are currently being used and by whom.

  - Decide which processes to load when memory space becomes available.

  - Allocate and deallocate memory space as needed.

File Management

- A file is a collection of related information defined by its creator. Commonly, files represent programs (both source and object forms) and data.

- The operating system is responsible for the following activities in connections with file management:

  – File creation and deletion.

  – Directory creation and deletion.

  – Support of primitives for manipulating files and directories.

  – Mapping files onto secondary storage.

  – File backup on stable (nonvolatile) storage media.

I/O System Management

- The I/O system consists of:
    - A buffer-caching system
    - A general device-driver interface
    - Drivers for specific hardware devices

Secondary-Storage Management

- Since main memory (primary storage) is volatile and too small to accommodate all data and programs permanently, the computer system must provide secondary storage to back up main memory.

- Most modern computer systems use disks as the principle on-line storage medium, for both programs and data.

- OS is responsible for the following activities with disk management:
  – Free space management
  – Storage allocation
  – Disk scheduling

Networking

- A distributed system is a collection processors that do not share memory or a clock. Each processor has its own local memory.

- The processors in the system are connected through a communication network. Communication takes place using a protocol. A distributed system provides user access to various system resources.

- Access to a shared resource allows:
    - Computation speed-up
    - Increased data availability
    - Enhanced reliability

Protection

- Protection refers to a mechanism for controlling access by programs, processes, or users to both system and user resources.

- The protection mechanism must:
  - Distinguish between authorized and unauthorized usage.
  - Specify the controls to be imposed.
  - Provide a means of enforcement.
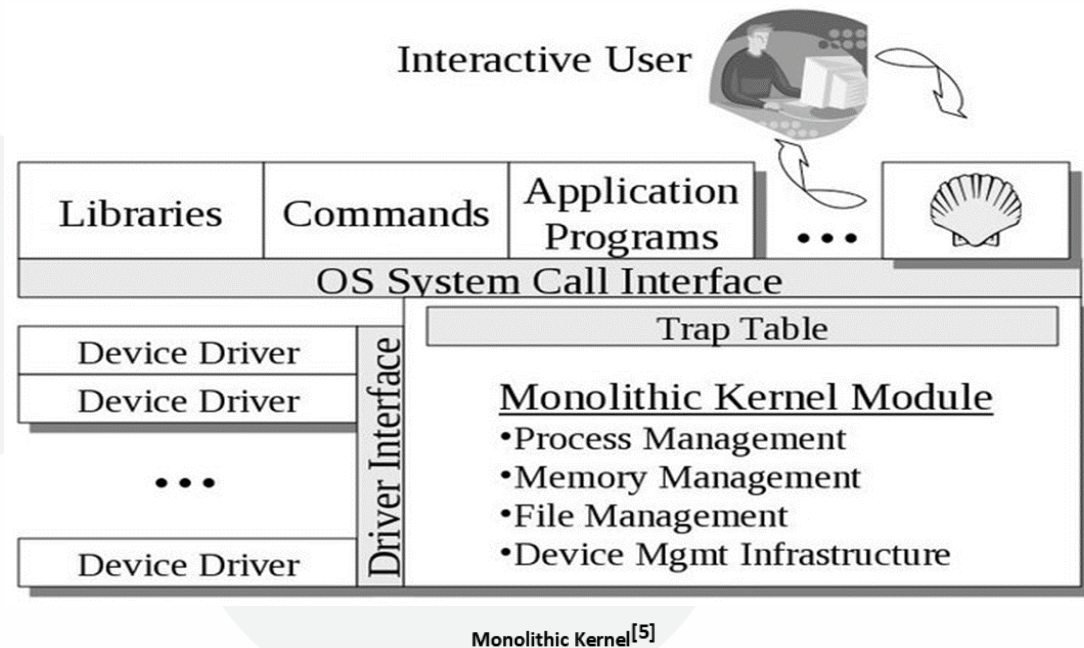
Command-Interpreter System

- The program that reads and interprets control statements is called variously:
    - command-line interpreter
    - shell (in UNIX)

- Its function is to get and execute the next command statement.
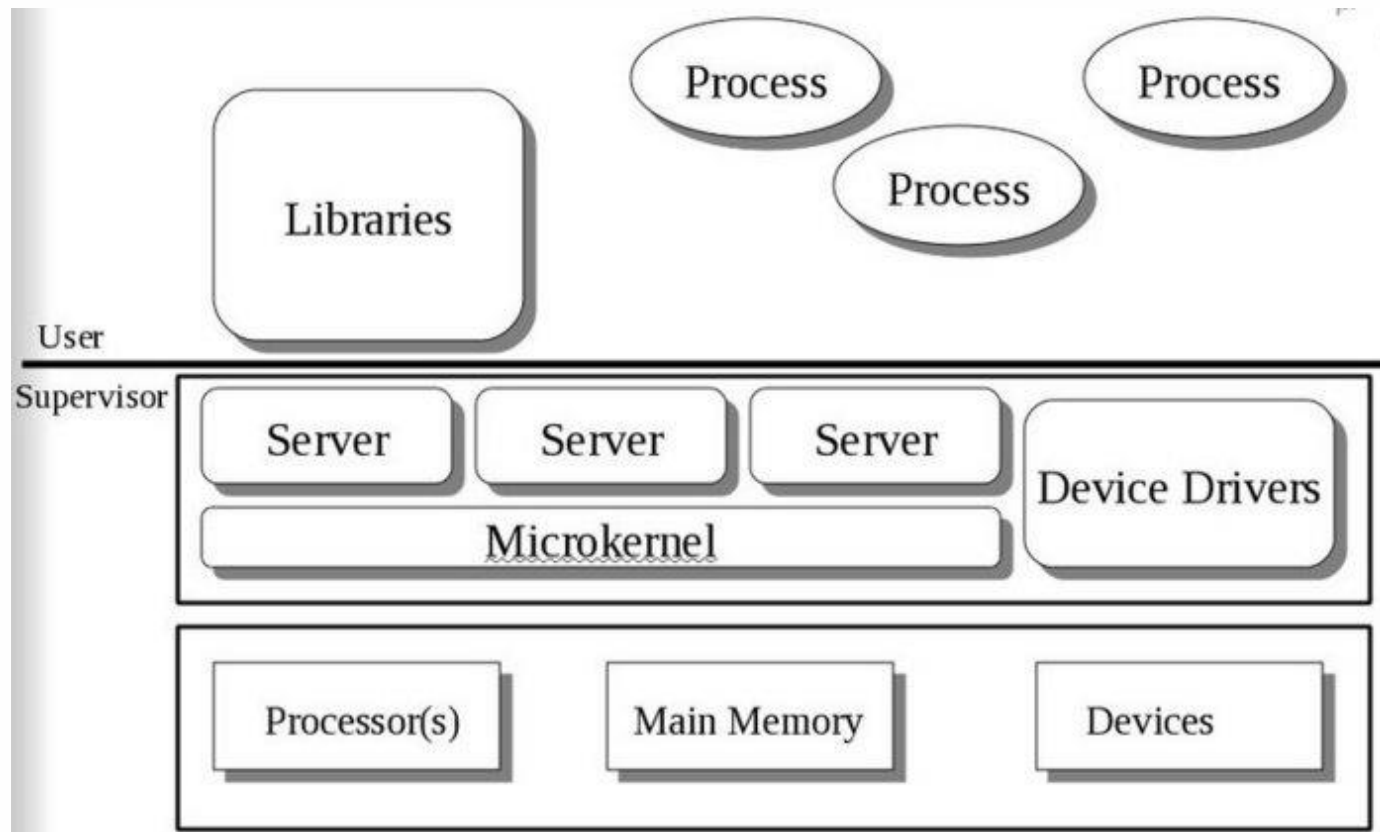
Monolithic Approach

- Functionality of the OS is activated with simple function calls within the kernel, Monolithic kernel is one large program.

- Device drivers are loaded into the running kernel and become part of the kernel.

Interactive User

| Libraries | Commands | Application Programs |

OS System Call Interface

Device Driver
Device Driver

• • •

Device Driver

Driver Interface

Trap Table

Monolithic Kernel Module
- Process Management
- Memory Management
- File Management
- Device Mgmt Infrastructure

Monolithic Kernel[5]

Monolithic Approach

- Microkernel structures the OS by removing all unnecessary parts of the kernel and implement them as system and user level programs.

- They offers minimal process and memory management, and a communications facility.

- Communication between components is done by message passing.

Monolithic Approach

Microkernel Approach[5]

Monolithic Approach

Advantage

- Operating system can be easily extended

- Kernel is smaller, so very few changes are required in it.

- It offers more security and reliability.

Disadvantage

- It has poor performance due to increased system overhead of message passing.

Virtual Machine

- Virtual machine does abstract the hardware of a single computer (the CPU, Memory, Disk drives, Network Interface Cards, and so forth) **into several different execution** environments and thereby **creating the illusion** that each separate execution environment is running its own PC/environment.
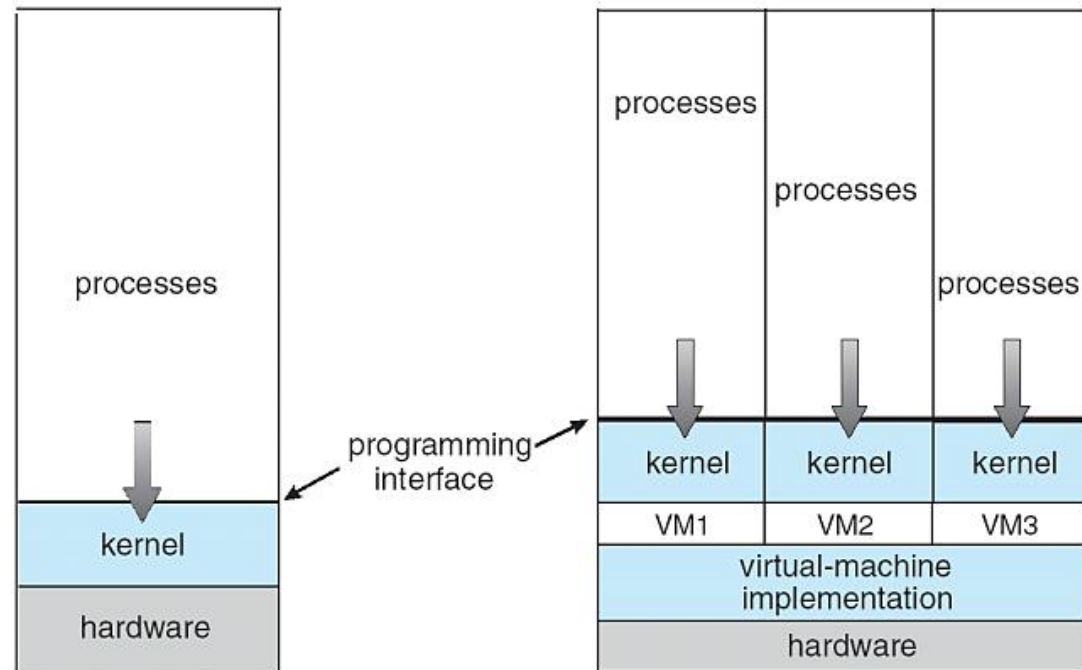
Non−Virtual Machine & Virtual Machine[1]

Virtual Machine

- Virtual Machine(VM) is also known as a guest machine, which is created within another computing environment known as a "host".

- Multiple VM can be present within a single host at one time.

References

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DIGITAL LEARNING CONTENT

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