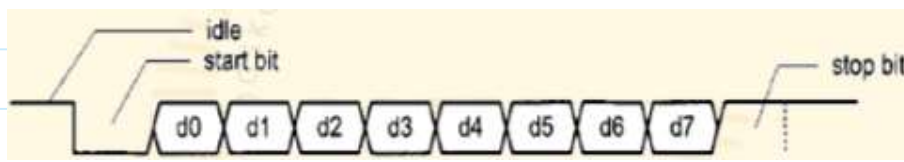


W03 - UART, the stop state

torsdag 7. mai 2020 08:13

1. In order to describe the behaviour of the modified circuit (that is "stop" state deleted altogether and "rx_done_tick<='1'" asserted immediately before leaving "data" state), I would first like to describe the operational workflow depicted in the ASMD chart for UART (RS-232). The ASDM chart can be found on p. 2 of this document



(an overview of start bit (logic 0), 8 data bits and stop bit (logic 1).)

STATE "IDLE"

The receiving subsystem is itself a finite state machine with datapath, so its behaviour can be represented by an ASMD chart as shown in the figure. The ASMD chart comprises only 4 states which are closely related to the RS-232 frame format (we're not using a parity bit in this case). **First state IDLE** is where the FSM remains after the stop bit while it is waiting for the next start bit('0') to occur. When that happens, the sampling ticks counter is reset to 0 ($S < -0$) and moves onto the next state; start.

STATE "START"

In the start state, the sampling tick is incremented until the sampling ticks counter reaches 7; middle point of the start bit. Then it resets the sampling ticks counter and the data bits counter and transitions to next state; data.

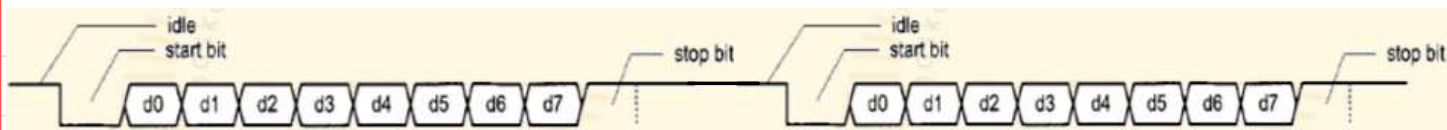
STATE "DATA"

Data state is remained until all data bits have been read. In the data state, we again increment the sampling ticks counter for every tick received from the baud generator, but now we wait until this counter reaches 15 instead of 7, since we want to go from the middle point of one data bit period to the middle point of the next data bit period. When the sampling ticks counter reaches 15, we know that it needs to be reset, and deserialize another bit.

Deserializing means to read the value that is present at the rX dataline and insert it into the deserializer register and check whether that is the last databit to be received. If not, then we must increment the databit counter and reenter the datastate until all databits have been read. In the middle of the bit period of last databit, the system-of-interest transitions to **stop state**.

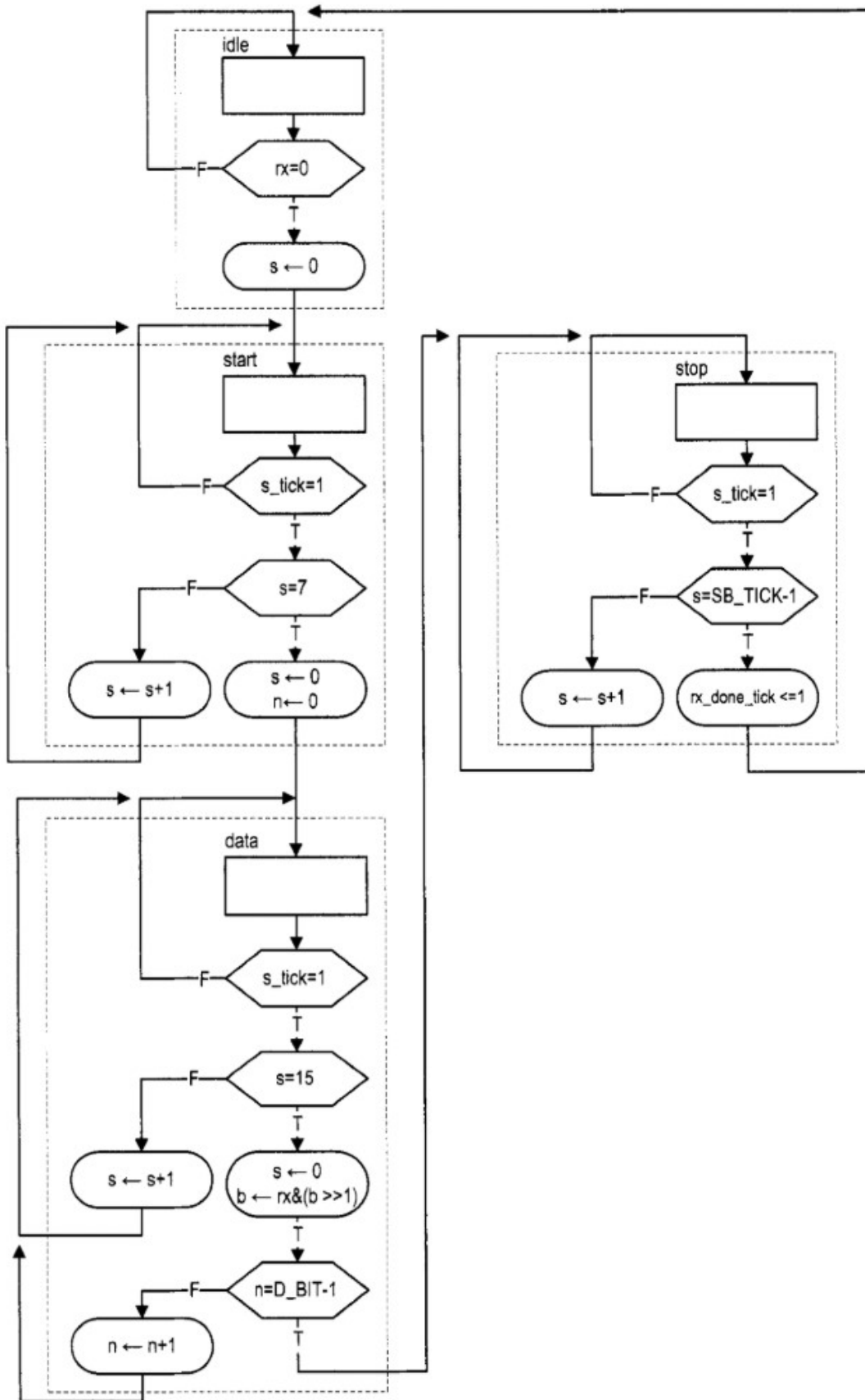
STATE "STOP"

In the stop state we again count the sampling ticks counter until reaching the middle point of the stopbit period. When that happens, we will assert the rx_done_tick to be equal to 1 for one clock cycle and restart the whole process. In other words the stop state provides a half bit period for the last databit to pass and another half bit period to reach to the middle-point of the stop bit. Then a "rx_done_tick" flag is set (logic 1). This means that the reception rightfully stops a half bit period after the last databit, which is enough time before a potential, next startbit can be received.



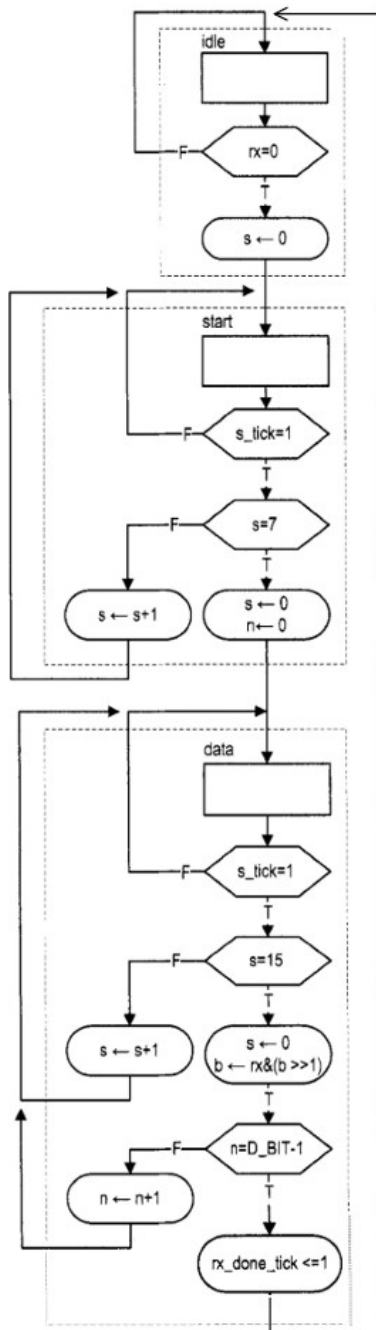
UART - ASMD chart

Friday, May 8, 2020 1:24 AM



Q1: Changing the ASMD chart

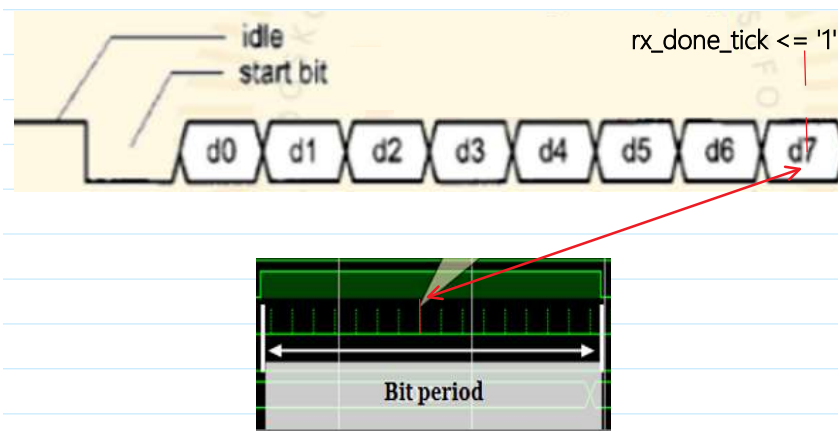
Friday, May 8, 2020 1:43 AM



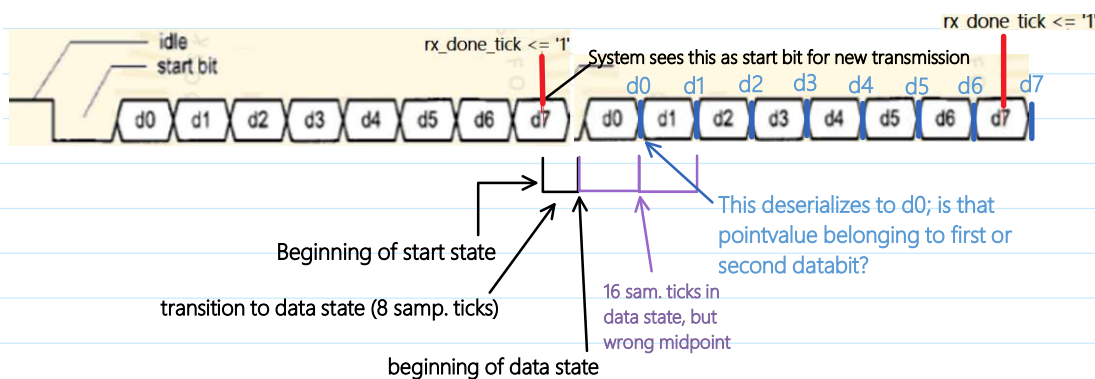
As can be seen from this figure, the "stop" state has been removed entirely, and the "rx_done_tick" flag has been set immediately before leaving "data" state.

This new operational workflow creates new problems;

- The "rx_done_tick" flag will be set while the reception is half bit period into the last databit. This is contradictory as the "rx_done_tick" flag is supposed to be set after reception is done.



Furthermore, if the case of the last databit being a logical 0 and the "rx_done_tick" flag set as depicted in the ASMD chart, the "idle" state will see the last databit ('0') as a startbit for new reception (rx=0). This creates a cascading effect; the real d0 of next reception will be misinterpreted as a start bit and the deserialization of bitstream will be phased by 0.5 bit period, leading to problematic deserializing of datastream.



UART TOP MODULE (BAUDRATE GENERATOR+UART RX)

-- Listing 7.4

```
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity uart is
  generic(
    -- Default setting:
    -- 19,200 baud, 8 data bits, 1 stop bit, 2^2 FIFO
    DBIT: integer:=8;    -- # data bits
    SB_TICK: integer:=16; -- # ticks for stop bits, 16/24/32
                        -- for 1/1.5/2 stop bits
    DVSR: integer:= 163; -- baud rate divisor
                        -- DVSR = 50M/(16*baud rate)
    DVSR_BIT: integer:=8; -- # bits of DVSR
    FIFO_W: integer:=2   -- # addr bits of FIFO
                        -- # words in FIFO=2^FIFO_W
  );
  port(
    clk, reset: in std_logic;
    -- rd_uart, wr_uart: in std_logic;
    rx: in std_logic;
    -- w_data: in std_logic_vector(7 downto 0);
    -- tx_full, rx_empty: out std_logic;
    r_data: out std_logic_vector(7 downto 0)
    -- tx: out std_logic
  );
end uart;
```

```
architecture str_arch of uart is
  signal tick: std_logic;
  signal rx_done_tick: std_logic;
  -- signal tx_fifo_out: std_logic_vector(7 downto 0);
  signal rx_data_out: std_logic_vector(7 downto 0);
  -- signal tx_empty, tx_fifo_not_empty: std_logic;
  -- signal tx_done_tick: std_logic;
begin
```

```
  baud_gen_unit: entity work.mod_m_counter
    generic map(M=>DVSR, N=>DVSR_BIT)
    port map(clk=>clk, reset=>reset,
      q=>open, max_tick=>tick);
```

```
  uart_rx_unit: entity work.uart_rx(str_arch)
    generic map(DBIT=>DBIT, SB_TICK=>SB_TICK)
    port map(clk=>clk, reset=>reset, rx=>rx,
      s_tick=>tick, rx_done_tick=>rx_done_tick,
      dout=>rx_data_out);
```

```

--  uart_tx_unit: entity work. uart_tx(arch)
--    generic map(DBIT=>DBIT, SB_TICK=>SB_TICK)
--    port map(clk=>clk, reset=>reset,
--             tx_start=>tx_fifo_not_empty,
--             s_tick=>tick, din=>tx_fifo_out,
--             tx_done_tick=> tx_done_tick, tx=>tx);
--  tx_fifo_not_empty <= not tx_empty;

r_data <= rx_data_out;

end str_arch;

```

UART RX MODULE

-- Listing 7.1

```

library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity uart_rx is
  generic(
    DBIT: integer:=8;    -- # data bits
    SB_TICK: integer:=16 -- # ticks for stop bits
  );
  port(
    clk, reset: in std_logic;
    rx: in std_logic;
    s_tick: in std_logic;
    rx_done_tick: out std_logic;
    dout: out std_logic_vector(7 downto 0)
  );
end uart_rx ;

architecture arch of uart_rx is
  type state_type is (idle, start, data);
  signal state_reg, state_next: state_type;
  signal s_reg, s_next: unsigned(3 downto 0);
  signal n_reg, n_next: unsigned(2 downto 0);
  signal b_reg, b_next: std_logic_vector(7 downto 0);

begin

  -- FSM state & data registers
  process(clk,reset)
  begin
    if reset='1' then
      state_reg <= idle;
      s_reg <= (others=>'0');
      n_reg <= (others=>'0');
      b_reg <= (others=>'0');
    end if;
  end process;

```

```

elsif (clk'event and clk='1') then
    state_reg <= state_next;
    s_reg <= s_next;
    n_reg <= n_next;
    b_reg <= b_next;
end if;
end process;

-- next-state logic & data path functional units/routing
process(state_reg,s_reg,n_reg,b_reg,s_tick,rx)
begin
    state_next <= state_reg;
    s_next <= s_reg;
    n_next <= n_reg;
    b_next <= b_reg;
    rx_done_tick <='0';

    case state_reg is
        when idle =>
            if rx='0' then
                state_next <= start;
                s_next <= (others=>'0');
            end if;

        when start =>
            if (s_tick = '1') then
                if s_reg=7 then
                    state_next <= data;
                    s_next <= (others=>'0');
                    n_next <= (others=>'0');
                else
                    s_next <= s_reg + 1;
                end if;
            end if;

        when data =>
            if (s_tick = '1') then
                if s_reg=15 then
                    s_next <= (others=>'0');
                    b_next <= rx & b_reg(7 downto 1) ;

                    if n_reg=(DBIT-1) then
                        rx_done_tick <= '1';
                        state_next <= idle ;
                    else
                        n_next <= n_reg + 1;
                    end if;
                else
                    s_next <= s_reg + 1;
                end if;
            end if;
        end if;
    end case;
end process;

```

```

--      when stop =>
--          if (s_tick = '1') then
--              if s_reg=(SB_TICK-1) then
--                  state_next <= idle;
--                  rx_done_tick <='1';
--              else
--                  s_next <= s_reg + 1;
--              end if;
--          end if;
--      end case;
end process;
dout <= b_reg;
end arch;

```

BAUDRATE GENERATOR

-- Listing 4.11

```

library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity mod_m_counter is
    generic(
        N: integer := 8;    -- number of bits
        M: integer := 163    -- mod-M
    );
    port(
        clk, reset: in std_logic;
        max_tick: out std_logic;
        q: out std_logic_vector(N-1 downto 0)
    );
end mod_m_counter;

architecture arch of mod_m_counter is
    signal r_reg: unsigned(N-1 downto 0);
    signal r_next: unsigned(N-1 downto 0);
begin
    -- register
    process(clk,reset)
    begin
        if (reset='1') then
            r_reg <= (others=>'0');
        elsif (clk'event and clk='1') then
            r_reg <= r_next;
        end if;
    end process;
    -- next-state logic
    r_next <= (others=>'0') when r_reg=(M-1) else
        r_reg + 1;
end arch;

```



```

-- output logic
q <= std_logic_vector(r_reg);
max_tick <= '1' when r_reg=(M-1) else '0';

end arch;

```

UART TOP MODULE TESTBENCH

```

-- Company:
-- Engineer:
--
-- Create Date: 05/08/2020 03:44:45 AM
-- Design Name:
-- Module Name: uart_tb - Behavioral
-- Project Name:
-- Target Devices:
-- Tool Versions:
-- Description:
--
-- Dependencies:
--
-- Revision:
-- Revision 0.01 - File Created
-- Additional Comments:
--

```

```

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

```

```

-- Uncomment the following library declaration if using
-- arithmetic functions with Signed or Unsigned values
--use IEEE.NUMERIC_STD.ALL;

```

```

-- Uncomment the following library declaration if instantiating
-- any Xilinx leaf cells in this code.
--library UNISIM;
--use UNISIM.VComponents.all;

```

```

entity uart_tb is
-- Port ( );
end uart_tb;

```

```

architecture Behavioral of uart_tb is

```

```

-- Signals
signal clk, reset, rx : std_logic;

```

```

signal r_data : std_logic_vector( 7 downto 0);

constant clk_period : time := 20ns; -- 50MHz <--> 20ns period
constant bit_period : time := 52083.3333ns; -- 1 / baud rate (baud rate is actually a frequency (bits/second)), baudrate= 19200 b/s
constant clks_per_bit: integer := 2604; -- clk freq/baudrate = how many clocks per bit
constant max_tick_period : time := 3255.20833ns; -- 307200 ticks/s <--> period = 1/307200

begin

-- Unit under test:
  uut: entity work.uart
    port map(
      clk => clk,
      reset => reset,
      rx => rx,
      -- w_data => w_data,
      -- tx_full => tx_full,
      -- rx_empty => rx_empty,
      r_data => r_data
      -- tx => tx,
      -- rd_uart => rd_uart,
      --wr_uart => wr_uart
    );

-- Clock process
clk_process: process
begin
  clk <= '0';
  wait for clk_period/2;
  clk<= '1';
  wait for clk_period/2;
end process;

-- Stimulus process
stim_process : process
begin
  -- Resetting for two clock periods; 20ns.
  reset <= '1';
  wait for bit_period;
  reset <= '0';

  -- We want to send in a 10-bit stream to rx, in which first bit is startbit ('0'),
  -- following 8 bits are databits (last databit is a 0), and 10th bit is stop bit.
  -- I choose 0-11010110-1.

  rx <= '0';      -- STARTBIT
  wait for bit_period;

```

```
rx <= '1';      -- D0  
wait for bit_period;
```

```
rx <= '1';      -- D1  
wait for bit_period;
```

```
rx <= '0';      -- D2  
wait for bit_period;
```

```
rx <= '1';      -- D3  
wait for bit_period;
```

```
rx <= '0';      -- D4  
wait for bit_period;
```

```
rx <= '1';      -- D5  
wait for bit_period;
```

```
rx <= '1';      -- D6  
wait for bit_period;
```

```
rx <= '0';      -- D7  
wait for bit_period;
```

```
rx <= '1';      -- STOPBIT  
wait for bit_period;
```

-----FIRST RECEPTION DONE, SECOND RECEPTION STARTS-----

```
rx <= '0';      -- STARTBIT  
wait for bit_period;
```

```
rx <= '1';      -- D0  
wait for bit_period;
```

```
rx <= '1';      -- D1  
wait for bit_period;
```

```
rx <= '0';      -- D2  
wait for bit_period;
```

```
rx <= '1';      -- D3  
wait for bit_period;
```

```
rx <= '0';      -- D4  
wait for bit_period;
```

```
rx <= '1';      -- D5  
wait for bit_period;
```

```
rx <= '1';      -- D6  
wait for bit_period;
```

```
rx <= '0';      -- D7
wait for bit_period;

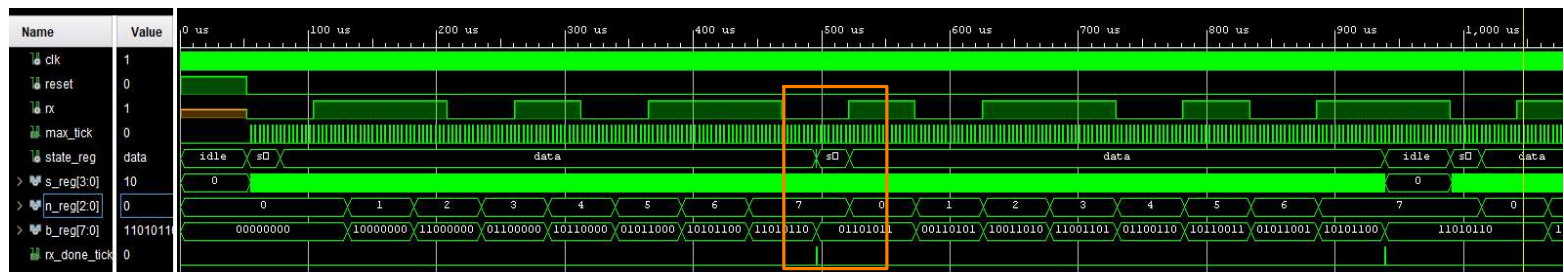
rx <= '1';      -- STOPBIT
wait for bit_period;

end process;

end Behavioral;
```

Q2: Screenshot of testbench

Friday, May 8, 2020 3:20 AM



As predicted [earlier](#), the system interprets the last **databit** as a beginning of the start state which results in wrongful deserialization of the input datastream. Note how a zero is cascaded to b_reg (digits shifted to the right) at 520μs, when it is supposed to be a 1 (as seen during the correct first reception).

