Scala Inline

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Abstract. [1]

Keywords: Partial Evaluation

1 Introduction

```
def dot[V: Numeric](v1: Vector[V], v2: Vector[V]): V =
  (v1 zip v2).foldLeft(zero[V]){ case (prod, (cl, cr)) =>
    prod + cl * cr
}
```

 ${f Fig.\,1.}$ Function for computing the dot product over generic Numeric values.

2 Formalization $F_{i<:}$

```
Terms:
t ::=
                               identifier
     x, x
     (x:iT) \Rightarrow t
                                function
     t(t)
                                application
     \{\overline{x=t}\}
                                \operatorname{record}
                                selection
     t.x
     in line\ t
                               inlining request
     [X <: iT] \Rightarrow t
                                type abstraction
     t[iT]
                               type application
S, T, U ::=
                            Types:
     iS \Rightarrow jT
                                function type
     \{\overline{x:iS}\}
                                record type
     [X <: iS] \Rightarrow jT
                                universal type
                                top type
iT, jT, kT, lT ::=
                            Inlineable Types:
     T, dynamic T
                                dynamic type
     static\ T
                               static type
     in line\ T
                               must inline type
\Gamma ::=
                            Contexts:
                                empty context
     \Gamma, x : iT
                                term binding
     \Gamma, X <: iT
                                type binding
```

 $\mathbf{Fig.\,2.}\ \mathrm{Syntax}$

$$\frac{x:iT \in \Gamma}{\Gamma \vdash x:iT} \qquad (T-IDENT)$$

$$\frac{\Gamma, \ x:iT_1 \vdash t:jT_2}{\Gamma \vdash (x:iT_1) \Rightarrow t: static \ iT_1 \Rightarrow jT_2} \qquad (T-Func)$$

$$\frac{\Gamma \vdash t:iT}{\Gamma \vdash \{\overline{x=t}\}: static \ \{\overline{x}:iT\}\}} \qquad (T-Rec)$$

$$\frac{\Gamma \vdash t_1:i(jT_1 \Rightarrow kT_2) \quad \Gamma \vdash t_2:jT_2}{\Gamma \vdash t_1(t_2): (i \land j \land k)T_2} \qquad (T-App)$$

$$\frac{\Gamma \vdash t:i\{x=jT_1, \overline{y=kT_2}\}}{\Gamma \vdash t.x: (i \land j)T_1} \qquad (T-Sel)$$

$$\frac{\Gamma \vdash t: static \ T}{\Gamma \vdash inline \ t: inline \ T} \qquad (T-Inline)$$

$$\frac{\Gamma, \ X <: iT_1 \vdash t_2: jT_2}{\Gamma \vdash [X <: iT_1] \Rightarrow t_2: static[X <: iT_1] \Rightarrow jT_2} \qquad (T-TAbs)$$

$$\frac{\Gamma \vdash t_1: i([X <: jT_{11}] \Rightarrow kT_{12}) \quad \Gamma \vdash lT_2 <: jT_{11}}{\Gamma \vdash t_1[lT_2]: [X \mapsto lT_2](i \land k)T_{12}} \qquad (T-TApp)$$

$$\frac{\Gamma \vdash t: iS \quad \Gamma \vdash iS <: jT}{\Gamma \vdash t: jT} \qquad (T-Sub)$$

Fig. 3. typing $\Gamma \vdash t : iT$

$$\frac{\forall i.\ i <: dynamic}{} \qquad \qquad \text{(IS-Dynamic)} \\ \frac{\forall i \in \{static,\ inline\}.\ i <: static}{inline <: inline} \qquad \qquad \text{(IS-Static)} \\ \frac{inline <: inline}{} \qquad \qquad \text{(IS-Inline)}$$

Fig. 4. Inlinity Subtyping i <: j

$$\forall i, \ \forall j, \ i <: j. \ i \wedge j = j$$

Fig. 5. Inlinity Intersection $i \wedge j$

$$\frac{\Gamma \vdash S <: S}{\Gamma \vdash S <: U \quad \Gamma \vdash U <: T} \qquad \text{(S-Refl)}$$

$$\frac{\Gamma \vdash S <: U \quad \Gamma \vdash U <: T}{\Gamma \vdash S <: T} \qquad \text{(S-Top)}$$

$$\frac{X <: T \in \Gamma}{\Gamma \vdash X <: T} \qquad \text{(S-TVAR)}$$

$$\frac{\Gamma \vdash kT_1 <: iS_1 \quad \Gamma \vdash jS_2 <: lT_2}{\Gamma \vdash iS_1 \Rightarrow jS_2 <: kT_1 \Rightarrow lT_2} \qquad \text{(S-Arrow)}$$

$$\frac{\Gamma \vdash [X <: iU_1] \Rightarrow jS_2 <: kT_2}{\Gamma \vdash [X <: iU_1] \Rightarrow jS_2 <: [X <: iU_1] \Rightarrow kT_2} \qquad \text{(S-All)}$$

$$\frac{\{x_p : i_pT_p \stackrel{p \in 1 \dots n + m}{P} \} <: \{x_p : i_pT_p \stackrel{p \in 1 \dots n}{P} \}} \qquad \text{(S-RecWidth)}}{\{x_p : i_pS_p \stackrel{p \in 1 \dots n}{P} \} <: \{x_p : j_pT_p \stackrel{p \in 1 \dots n}{P} \}} \qquad \text{(S-RecDepth)}}$$

$$\frac{\{x_p : i_pS_p \stackrel{p \in 1 \dots n}{P} \} <: \{y_p : j_pT_p \stackrel{p \in 1 \dots n}{P} \}}{\{x_p : i_pS_p \stackrel{p \in 1 \dots n}{P} \}} <: \{y_p : j_pT_p \stackrel{p \in 1 \dots n}{P} \}} \qquad \text{(S-RecPerm)}}$$

$$\frac{i <: j \quad \Gamma \vdash S <: T}{\Gamma \vdash iS <: jT} \qquad \text{(S-Inline)}}$$

Fig. 6. Subtyping $\Gamma \vdash iS <: jT$

- 3 Translating Scala to the Core Calculus
- 4 Case Studies
- 5 Related Work
- 6 Conclusion

References

1. Eugene Burmako and Martin Odersky. Scala Macros, a Technical Report. In *Third International Valentin Turchin Workshop on Metacomputation*, 2012.