# Package 'InvariantCausalPrediction'

October 12, 2022

Type Package

Title Invariant Causal Prediction

Version 0.8			
<b>Date</b> 2019-10-10			
Author Nicolai Meinshausen			
Depends glmnet, mboost			
Maintainer Nicolai Meinshausen <meinshausen@stat.math.ethz.ch></meinshausen@stat.math.ethz.ch>			
<b>Description</b> Confidence intervals for causal effects, using data collected in different experimental or environmental conditions. Hidden variables can be included in the model with a more experimental version.			
License GPL			
NeedsCompilation no			
Repository CRAN			
<b>Date/Publication</b> 2019-11-10 11:40:02 UTC			
R topics documented:			
InvariantCausalPrediction-package2hiddenICP2ICP5plot.InvariantCausalPrediction10summary.InvariantCausalPrediction11			
Index 12			

2 hiddenICP

InvariantCausalPrediction-package

Invariant causal prediction

#### **Description**

Confidence intervals for causal prediction in a regression setting. An experimental version is also available for classification.

#### **Details**

Package: InvariantCausalPrediction

Type: Package
Version: 0.6-1
Date: 2016-05-02
License: GPL

Confidence intervals can be computed with function ICP, both for regression and binary classification. print, plot and summary methods are available.

#### Author(s)

Nicolai Meinshausen <meinshausen@stat.math.ethz.ch>

Maintainer: Nicolai Meinshausen <meinshausen@stat.math.ethz.ch>

hiddenICP

Invariant Causal Prediction with hidden variables

#### **Description**

Confidence intervals for causal effects in a regression setting with possible confounders.

# Usage

```
hiddenICP(X, Y, ExpInd, alpha = 0.1, mode = "asymptotic", intercept=FALSE)
```

# Arguments

X A matrix (or data frame) with the predictor variables for all experimental settings

Y The response or target variable of interest. Can be numeric for regression or a factor with two levels for binary classification.

hiddenICP 3

ExpInd Indicator of the experiment or the intervention type an observation belongs to.

Can be a numeric vector of the same length as Y with K unique entries if there are K different experiments (for example entry 1 for all observational data and entry 2 for intervention data). Can also be a list, where each element of the list contains the indices of all observations that belong to the corresponding grouping in the data (for example two elements: first element is a vector that contains indices of observations that are observational data and second element is a vector that contains indices of all observations that are of interventional

type).

alpha The level of the test procedure. Use the default alpha=0.1 to obtain 90% confi-

dence intervals.

mode Currently only mode "asymptotic" is implemented; the argument is thus in the

current version without effect.

intercept Boolean variable; if TRUE, an intercept is added to the design matrix (but coeffi-

cients are returned without intercept term).

#### Value

A list with elements

betahat The point estimator for the causal effects

maximinCoefficients

The value in the confidence interval for each variable effects that is closest to 0.

Is hence non-zero for variables with significant effects.

ConfInt The matrix with confidence intervals for the causal coefficient of all variables.

First row is the upper bound and second row the lower bound.

pvalues The p-values of all variables.

colnames The column-names of the predictor variables.

alpha The chosen level.

#### Author(s)

Nicolai Meinshausen <meinshausen@stat.math.ethz.ch>

#### References

none yet.

#### See Also

ICP for reconstructing the parents of a variable under arbitrary interventions on all other variables (but no hidden variables). See package "backShift" for constructing point estimates of causal cyclic models in the presence of hidden variables (again under shift interventions).

4 hiddenICP

#### **Examples**

```
###### 1st example:
###### Simulate data with interventions
     set.seed(1)
   ## sample size n
     n <- 2000
   ## 4 predictor variables
     p <- 4
   ## simulate as independent Gaussian variables
     X <- matrix(rnorm(n*p),nrow=n)</pre>
   ## divide data into observational (ExpInd=1) and interventional (ExpInd=2)
     ExpInd <- c(rep(1,n/2),rep(2,n/2))
   ## for interventional data (ExpInd==2): change distribution
     nI <- sum(ExpInd==2)
     X[ExpInd==2,] <- X[ExpInd==2,] + matrix( 5*rt( nI*p,df=3),ncol=p)</pre>
     ## add hidden variables
     W \leftarrow rnorm(n) * 5
     X \leftarrow X + outer(W, rep(1,4))
     ## first two variables are the causal predictors of Y
     beta <- c(1,1,0,0)
   ## response variable Y
     Y <- as.numeric(X%*%beta - 2*W + rnorm(n))
####### Compute "hidden Invariant Causal Prediction" Confidence Intervals
     icp <- hiddenICP(X,Y,ExpInd,alpha=0.01)</pre>
     print(icp)
###### Print point estimates and points in the confidence interval closest to \emptyset
     print(icp$betahat)
     print(icp$maximinCoefficients)
     cat("true coefficients are:", beta)
#### compare with coefficients from a linear model
     cat("coefficients from linear model:")
     print(summary(lm(Y \sim X-1)))
###### 2nd example:
####### Simulate model X -> Y -> Z with hidden variables, trying to
###### estimate causal effects from (X,Z) on Y
     set.seed(1)
   ## sample size n
     n <- 10000
   ## simulate as independent Gaussian variables
     W <- rnorm(n)</pre>
     noiseX <- rnorm(n)</pre>
```

```
noiseY <- rnorm(n)</pre>
     noiseZ <- rnorm(n)</pre>
   ## divide data into observational (ExpInd=1) and interventional (ExpInd=2)
     ExpInd <- c(rep(1,n/2),rep(2,n/2))
     noiseX[ which(ExpInd==2)] <- noiseX[ which(ExpInd==2)] * 5
     noiseZ[ which(ExpInd==2)] <- noiseZ[ which(ExpInd==2)] * 3</pre>
   ## simulate equilibrium data
     beta <- -0.5
     alpha <- 0.9
     X <- noiseX + 3*W
     Y <- beta* X + noiseY + 3*W
     Z <- alpha*Y + noiseZ
###### Compute "Invariant Causal Prediction" Confidence Intervals
     icp <- hiddenICP(cbind(X,Z),Y,ExpInd,alpha=0.1)</pre>
     print(icp)
###### Print/plot/show summary of output (truth here is (beta,0))
     print(signif(icp$betahat,3))
     print(signif(icp$maximinCoefficients,3))
     cat("true coefficients are:", beta,0)
#### compare with coefficients from a linear model
     cat("coefficients from linear model:")
     print(summary(lm(Y \sim X + Z -1)))
```

ICP

Invariant Causal Prediction

#### **Description**

Confidence intervals for causal effects in a regression setting.

#### Usage

# **Arguments**

Χ A matrix (or data frame) with the predictor variables for all experimental settings

Υ The response or target variable of interest. Can be numeric for regression or a

factor with two levels for binary classification.

ExpInd Indicator of the experiment or the intervention type an observation belongs to.

> Can be a numeric vector of the same length as Y with K unique entries if there are K different experiments (for example entry 1 for all observational data and entry 2 for intervention data). Can also be a list, where each element of the list contains the indices of all observations that belong to the corresponding grouping in the data (for example two elements: first element is a vector that contains indices of observations that are observational data and second element is a vector that contains indices of all observations that are of interventional

type).

alpha Determines coverage of the confidence regions. alpha is the probability of

non-coverage, so the default of 0.01 produces 99% confidence intervals. If no model has a p-value of at least alpha, the model assumptions seem violated and

modelReject will return TRUE.

Use "exact" for an exact test in a regression setting, especially if sample size is

small. However, this test is computationally demanding if sample size is high. The default "normal" tests for a shift in mean and variance of the residuals between different populations/environments. Using "correlation" tests additionally for vanishing correlation between predictor variables and residuals in each environment. Other options are "ranks" that uses a rank-based alternative and "ks" for a Kolmogorov-Smirnov test to detect differences in the distributions of the residuals between different environments. It is also possible to supply a function of the form function(x,z) that takes samples x and z of two populations as arguments and whose return value is the p-value for the null hypothesis that

the two underlying distribution are identical.

selection The method for pre-selection of variables to save computational resources. Can

> use "all" for no pre-selection (which guarantees coverage but might take longer to compute), "boosting" for a boosting-type, "lasso" for Lasso cross-validated or "stability" for a stability-selection-type pre-selection. Default is "all" if p does

not exceed 10 and "boosting" otherwise.

maxNoVariables The maximal number of variables to pre-select (choosing smaller values saves

computational resources but increases approximation error).

The maximal size of sets of variables considered in the procedure (same com-

ment as for maxNoVariables).

maxNoObs The maximal number of observations used for the "exact" test (same comment

as for maxNoVariables).

showAcceptedSets

If TRUE, print out information about accepted sets of variables.

showCompletion If TRUE, print out information about progress of computation.

stopIfEmpty If TRUE, the procedure will stop computing confidence intervals if the empty set

has been accepted (and hence no variable can have a signicificant causal effect).

test

maxNoVariablesSimult

Setting to TRUE will save computational time in these cases, but means that the confidence intervals lose their coverage properties for values different to 0.

gof If no set of variables (including the empty set) leads to a p-value larger than the

goodness-of-fit cutoff gof, the whole model will be rejected. If the model is correct, this will happen with a probability of gof and this option protects again making statements when the model is obviously not suitable for the data.

#### Value

A list with elements

ConfInt The matrix with confidence intervals for the causal coefficient of all variables.

First row is the upper bound and second row the lower bound.

maximinCoefficients

The value in the confidence interval closest to 0. Is hence non-zero for variables

with significant effects.

colnames The names of the variables (replaced with generic "Variable 1" etc. if not avail-

able).

factor Logical indicating whether the response is a factor or not.

dimX The dimensions of the matrix with predictor variables.

Coeff A list which contains for all variables the vector with point-estimates among all

accepted sets where the variable was part of the set.

CoeffVar Same as Coeff but with the standard deviation of the point-estimate.

modelReject Logical indicating if the whole model was rejected (the p-value of the best fitting

model is too low).

acceptedSets A list with one element per accepted set. For each accepted model the list entry

is a vector that contains the indices of the variables in the accepted set.

usedvariables The pre-selected variables if not all variables are used for the analysis; otherwise

all variables.

pvalues The p-values of all variables.

stopIfEmpty A boolean value indicating whether computations stop as soon as intersection of

accepted sets is empty.

noEnv The number of distinct environments.
gof The goodness-of-fit cutoff gof used.

bestModel The largest p-value across all tested sets of variables.

#### Author(s)

Nicolai Meinshausen <meinshausen@stat.math.ethz.ch>

#### References

Jonas Peters, Peter Buhlmann, Nicolai Meinshausen (2015):

Causal inference using invariant prediction: identification and confidence intervals

arxiv preprint http://arxiv.org/abs/1501.01332

#### See Also

hiddenICP for reconstructing the parents of a variable in the presence of hidden variables (but assuming shift/additive interventions), which also allows construction of confidence intervals for the causal coefficients. See package "backShift" for constructing point estimates of causal cyclic models in the presence of hidden variables (again under shift interventions).

#### **Examples**

```
###### 1st example:
###### Simulate data with interventions
set.seed(1)
   ## sample size n
     n <- 4000
   ## 5 predictor variables
     p <- 5
   ## simulate as independent Gaussian variables
     X <- matrix(rnorm(n*p),nrow=n)</pre>
   ## divide data into observational (ExpInd=1) and interventional (ExpInd=2)
     ExpInd <- c(rep(1,n/2),rep(2,n/2))
   ## for interventional data (ExpInd==2): change distribution
     X[ExpInd=2,] \leftarrow sweep(X[ExpInd=2,],2, 5*rnorm(p), FUN="*")
   ## first two variables are the causal predictors of Y
     beta <- c(1,1,rep(0,p-2))
   ## response variable Y
     Y <- as.numeric(X%*%beta + rnorm(n))
  ## optinal: make last variable a child of Y (so last variable is non-causal for Y)
     X[,p] <- 0.3*Y + rnorm(n)
###### Compute "Invariant Causal Prediction" Confidence Intervals
     icp <- ICP(X,Y,ExpInd)</pre>
###### Print/plot/show summary of output
     print(icp)
     plot(icp)
#### compare with linear model
     cat("\n compare with linear model \n")
     print(summary(lm(Y~X)))
###### 2nd example:
###### Simulate a DAG where X1 -> Y, Y -> X2 and Y -> X3
###### noise interventions on second half of data on X1
###### structure of DAG (at Y -> X2) is changing under interventions
    n1 <- 400
    n2 <- 500
    ExpInd <- c(rep(1,n1), rep(2,n2))
  ## index for observational (ExpInd=1) and intervention data (ExpInd=2)
    X1 <- c(rnorm(n1), 2 * rnorm(n2) + 1)
    Y \leftarrow 0.5 * X1 + 0.2 * rnorm(n1 + n2)
```

```
X2 <- c(1.5 * Y[1:n1]
                              + 0.4 * rnorm(n1),
           -0.3 * Y[(n1+1):n2] + 0.4 * rnorm(n2))
    X3 < -0.4 * Y
                               + 0.2 * rnorm(n1 + n2)
    X \leftarrow cbind(X1, X2, X3)
### Compute "Invariant Causal Prediction" Confidence Intervals
 ## use a rank-based test to detect shift in distribution of residuals
    icp <- ICP(X, Y, ExpInd,test="ranks")</pre>
 ## use a Kolmogorov-Smirnov test to detect shift in distribution of residuals
    icp <- ICP(X, Y, ExpInd,test="ks")</pre>
 ## can also supply test as a function
 ## here chosen to be equivalent to option "ks" above
    icp <- ICP(X, Y, ExpInd,test=function(x,z) ks.test(x,z)$p.val)</pre>
## use a test based on normal approximations
     icp <- ICP(X, Y, ExpInd, test="normal")</pre>
### Print/plot/show summary of output
    print(icp)
    plot(icp)
#### compare with linear model
    cat("\n compare with linear model \n")
    print(summary(lm(Y~X)))
## Not run:
###### 3rd example:
###### College Distance data
    library(AER)
    data("CollegeDistance")
    CD <- CollegeDistance
 ## define two experimental settings by
 ## distance to closest 4-year college
    ExpInd <- list()</pre>
    ExpInd[[1]] <- which(CD$distance < quantile(CD$distance,0.5))</pre>
    ExpInd[[2]] <- which(CD$distance >= quantile(CD$distance,0.5))
 ## target variable is binary (did education lead at least to BA degree?)
    Y <- as.factor(CD$education>=16)
 ## use these predictors
    X <- CD[,c("gender","ethnicity","score","fcollege","mcollege","home",</pre>
       "urban", "unemp", "wage", "tuition", "income", "region")]
 ## searching all subsets (use selection="lasso" or selection="stability"
        to select a subset of subsets to search)
 ## with selection="all" the function will take several minutes
   icp <- ICP(X,Y,ExpInd,selection="all",alpha=0.1)</pre>
```

```
## Print/plot/show summary of output
    print(icp)
    summary(icp)
    plot(icp)

## End(Not run)
```

plot.InvariantCausalPrediction

 $Plots\ of\ "Invariant Causal Prediction"\ objects$ 

# Description

Plots confidence intervals for invariant causal prediction (output of ICP function)

#### Usage

# **Arguments**

X	Object of class "InvariantCausalPrediction", as generated by function ICP.
maxshow	Maximal number of variables to show confidence intervals for
col1	Colour of confidence intervals generated by accepted sets of variables (defaults to light red).
col2	Colour of point-estimates generated by accepted sets of variables (defaults to light red).
col3	Colour of confidence intervals generated by procedure (defaults to blue).
mar	Margins for the figure (might need to be adjusted to allow for long variable names.
lwd	Scaling of the width of the lines used for individual confidence intervals.
• • •	Additional inputs to generic plot function (not used).

#### Value

Does not return an object.

# Author(s)

Nicolai Meinshausen <meinshausen@stat.math.ethz.ch>

#### References

```
Jonas Peters, Peter Buhlmann, Nicolai Meinshausen (2015):
Causal inference using invariant prediction: identification and confidence intervals arxiv preprint http://arxiv.org/abs/1501.01332
```

#### See Also

**ICP** 

```
summary.InvariantCausalPrediction
Summary of "InvariantCausalPrediction" objects
```

#### **Description**

Prints confidence intervals for invariant causal prediction (output of ICP function)

#### Usage

```
## S3 method for class 'InvariantCausalPrediction'
summary(object, maxshow = 50, ...)
```

## **Arguments**

object Object of class "InvariantCausalPrediction", as generated by function ICP.

Maximal number of variables to show in the summary.

Additional inputs to generic summary function (not used).

#### Value

Does not return an object.

#### Author(s)

Nicolai Meinshausen <meinshausen@stat.math.ethz.ch>

# References

```
Jonas Peters, Peter Buhlmann, Nicolai Meinshausen (2015):
Causal inference using invariant prediction: identification and confidence intervals arxiv preprint http://arxiv.org/abs/1501.01332
```

#### See Also

ICP

# **Index**

```
* Causality
    hiddenICP, 2
    ICP, 5
    plot.InvariantCausalPrediction, 10
    summary.InvariantCausalPrediction,
* Classification
    ICP, 5
    \verb"plot.InvariantCausalPrediction", \\ 10
    summary.InvariantCausalPrediction,
* Hidden Variables
    hiddenICP, 2
* Regression
    hiddenICP, 2
    ICP, 5
    plot.InvariantCausalPrediction, 10
    summary.InvariantCausalPrediction,
        11
hiddenICP, 2, 8
ICP, 3, 5, 10, 11
InvariantCausalPrediction
        (InvariantCausalPrediction-package),
InvariantCausalPrediction-package, 2
plot.InvariantCausalPrediction, 10
summary.InvariantCausalPrediction, 11
```