# Package 'RSNNS'

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**Title** Neural Networks using the Stuttgart Neural Network Simulator (SNNS)

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Type Package

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**Description** The Stuttgart Neural Network Simulator (SNNS) is a library containing many standard implementations of neural networks. This package wraps the SNNS functionality to make it available from within R. Using the 'RSNNS' low-level interface, all of the algorithmic functionality and flexibility of SNNS can be accessed. Furthermore, the package contains a convenient high-level interface, so that the most common neural network topologies and learning algorithms integrate seamlessly into R.

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URL https://github.com/cbergmeir/RSNNS

BugReports https://github.com/cbergmeir/RSNNS/issues

MailingList rsnns@googlegroups.com

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# Description

The Stuttgart Neural Network Simulator (SNNS) is a library containing many standard implementations of neural networks. This package wraps the SNNS functionality to make it available from within R.

#### **Details**

If you have problems using RSNNS, find a bug, or have suggestions, please do not write to the general R lists or contact the authors of the original SNNS software. Instead, you should: File an issue on github (bugs/suggestions), Ask your question on Stackoverflow under the tag RSNNS, or write to the mailing list (rsnns@googlegroups.com). If all that fails, then you can also contact the maintainer directly by email.

If you use the package, please cite the following work in your publications:

Bergmeir, C. and Benítez, J.M. (2012), Neural Networks in R Using the Stuttgart Neural Network Simulator: RSNNS. Journal of Statistical Software, 46(7), 1-26.

The package has a hierarchical architecture with three levels:

- RSNNS high-level api (rsnns)
- RSNNS low-level api (SnnsR)
- The api of our C++ port of SNNS (SnnsCLib)

Many demos for using both low-level and high-level api of the package are available. To get a list of them, type:

library(RSNNS)
demo()

It is a good idea to start with the demos of the high-level api (which is much more convenient to use). E.g., to access the iris classification demo type:

demo(iris)

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or for the laser regression demo type:

```
demo(laser)
```

As the high-level api is already quite powerful and flexible, you'll most probably normally end up using one of the functions: mlp, dlvq, rbf, rbfDDA, elman, jordan, som, art1, art2, artmap, or assoz, with some pre- and postprocessing. These S3 classes are all subclasses of rsnns.

You might also want to have a look at the original SNNS program and the SNNS User Manual 4.2, especially pp 67-87 for explications on all the parameters of the learning functions, and pp 145-215 for detailed (theoretical) explications of the methods and advice on their use. And, there is also the javaNNS, the successor of SNNS from the original authors. It makes the C core functionality available from a Java GUI.

Demos ending with "SnnsR" show the use of the low-level api. If you want to do special things with neural networks that are currently not implemented in the high-level api, you can see in this demos how to do it. Many demos are present both as high-level and low-level versions.

The low-level api consists mainly of the class SnnsR-class, which internally holds a pointer to a C++ object of the class SnnsCLib, i.e., an instance of the SNNS kernel. The class furthermore implements a calling mechanism for methods of the SnnsCLib object, so that they can be called conveniently using the "\$"-operator. This calling mechanism also allows for transparent masking of methods or extending the kernel with new methods from within R. See \$, SnnsR-method. R-functions that are added by RSNNS to the kernel are documented in this manual under topics beginning with SnnsRObject\$. Documentation of the original SNNS kernel user interface functions can be found in the SNNS User Manual 4.2 pp 290-314. A call to, e.g., the SNNS kernel function krui\_getNoOfUnits(...) can be done with SnnsRObject\$getNoOfUnits(...). However, a few functions were excluded from the wrapping for various reasons. Fur more details and other known issues see the file /inst/doc/KnownIssues.

Another nice tool is the NeuralNetTools package, that can be used to visualize and analyse the networks generated with RSNNS.

Most of the example data included in SNNS is also present in this package, see snnsData.

A comprehensive report with many examples showing the usage of RSNNS, developed by Seymour Shlien, is available here:

```
https://ifdo.ca/~seymour/R/
```

#### Author(s)

```
Christoph Bergmeir <c.bergmeir@decsai.ugr.es> and José M. Benítez <j.m.benitez@decsai.ugr.es> DiCITS Lab, Sci2s group, DECSAI, University of Granada. http://dicits.ugr.es, https://sci2s.ugr.es
```

#### References

Bergmeir, C. and Benítez, J.M. (2012), 'Neural Networks in R Using the Stuttgart Neural Network Simulator: RSNNS', Journal of Statistical Software, 46(7), 1-26.

General neural network literature:

Bishop, C. M. (2003), Neural networks for pattern recognition, University Press, Oxford.

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Haykin, S. S. (1999), Neural networks :a comprehensive foundation, Prentice Hall, Upper Saddle River, NJ.

Kriesel, D. (2007), A Brief Introduction to Neural Networks. http://www.dkriesel.com

Ripley, B. D. (2007), Pattern recognition and neural networks, Cambridge University Press, Cambridge.

Rojas, R. (1996), Neural networks: a systematic introduction, Springer-Verlag, Berlin.

Rumelhart, D. E.; Clelland, J. L. M. & Group, P. R. (1986), Parallel distributed processing :explorations in the microstructure of cognition, Mit, Cambridge, MA etc..

Literature on the original SNNS software:

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

javaNNS, the sucessor of the original SNNS with a Java GUI: https://github.com/mwri/javanns Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley.

Other resources:

A function to plot networks from the mlp function: https://beckmw.wordpress.com/2013/11/14/visualizing-neural-networks-in-r-update/

#### See Also

```
mlp, dlvq, rbf, rbfDDA, elman, jordan, som, art1, art2, artmap, assoz
```

 $analyze {\tt Classification} \ \ {\it Converts \ continuous \ outputs \ to \ class \ labels}$ 

## **Description**

This function converts the continuous outputs to binary outputs that can be used for classification. The two methods 402040, and winner-takes-all (WTA), are implemented as described in the SNNS User Manual 4.2.

## Usage

```
analyzeClassification(y, method = "WTA", l = 0, h = 0)
```

# Arguments

У	inputs
method	"WTA" or "402040"
1	lower bound, e.g. in 402040: 1=0.4
h	upper bound, e.g. in 402040: h=0.6

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#### **Details**

The following text is an edited citation from the SNNS User Manual 4.2 (pp 269):

**402040** A pattern is recognized as classified correctly, if (i) the output of exactly one output unit is >= h (ii) the teaching output of this unit is the maximum teaching output (> 0) of the pattern (iii) the output of all other output units is <= 1.

A pattern is recognized as classified incorrectly, if (i) and (iii) hold as above, but for (ii) holds that the teaching output is *not* the maximum teaching output of the pattern or there is no teaching output > 0.

A pattern is recognized as unclassified in all other cases.

The method derives its name from the commonly used default values l = 0.4, h = 0.6.

WTA A pattern is recognized as classified correctly, if (i) there is an output unit with the value greater than the output value of all other output units (this output value is supposed to be a) (ii) a > h (iii) the teaching output of this unit is the maximum teaching output of the pattern (> 0) (iv) the output of all other units is < a - 1.

A pattern is recognized as classified incorrectly, if (i), (ii), and (iv) hold as above, but for (iii) holds that the teaching output of this unit is *not* the maximum teaching output of the pattern or there is no teaching output > 0.

A pattern is recognized as unclassified in all other cases.

Commonly used default values for this method are: 1 = 0.0, h = 0.0.

#### Value

the position of the winning unit (i.e., the winning class), or zero, if no classification was done.

#### References

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

#### See Also

encodeClassLabels

art1

Create and train an art1 network

#### Description

Adaptive resonance theory (ART) networks perform clustering by finding prototypes. They are mainly designed to solve the stability/plasticity dilemma (which is one of the central problems in neural networks) in the following way: new input patterns may generate new prototypes (plasticity), but patterns already present in the net (represented by their prototypes) are only altered by similar new patterns, not by others (stability). ART1 is for binary inputs only, if you have real-valued input, use art2 instead.

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Learning in an ART network works as follows: A new input is intended to be classified according to the prototypes already present in the net. The similarity between the input and all prototypes is calculated. The most similar prototype is the *winner*. If the similarity between the input and the winner is high enough (defined by a *vigilance parameter*), the winner is adapted to make it more similar to the input. If similarity is not high enough, a new prototype is created. So, at most the winner is adapted, all other prototypes remain unchanged.

## Usage

```
art1(x, ...)
## Default S3 method:
art1(
  х,
 dimX,
 dimY,
  f2Units = nrow(x),
 maxit = 100,
  initFunc = "ART1_Weights",
  initFuncParams = c(1, 1),
  learnFunc = "ART1",
  learnFuncParams = c(0.9, 0, 0),
  updateFunc = "ART1_Stable",
  updateFuncParams = c(0),
  shufflePatterns = TRUE,
)
```

#### **Arguments**

```
a matrix with training inputs for the network
Х
                  additional function parameters (currently not used)
dimX
                  x dimension of inputs and outputs
dimY
                  y dimension of inputs and outputs
f2Units
                  controls the number of clusters assumed to be present
maxit
                  maximum of iterations to learn
initFunc
                  the initialization function to use
initFuncParams the parameters for the initialization function
learnFunc
                  the learning function to use
learnFuncParams
                  the parameters for the learning function
updateFunc
                  the update function to use
updateFuncParams
                  the parameters for the update function
shufflePatterns
                  should the patterns be shuffled?
```

art1

#### **Details**

The architecture of an ART network is the following: ART is based on the more general concept of *competitive learning*. The networks have two fully connected layers (in both directions), the input/comparison layer and the recognition layer. They propagate activation back and forth (resonance). The units in the recognition layer have lateral inhibition, so that they show a winner-takes-all behaviour, i.e., the unit that has the highest activation inhibits activation of other units, so that after a few cycles its activation will converge to one, whereas the other units activations converge to zero. ART stabilizes this general learning mechanism by the presence of some special units. For details refer to the referenced literature.

The default initialization function, ART1\_Weights, is the only one suitable for ART1 networks. It has two parameters, which are explained in the SNNS User Manual pp.189. A default of 1.0 for both is usually fine. The only learning function suitable for ART1 is ART1. Update functions are ART1\_Stable and ART1\_Synchronous. The difference between the two is that the first one updates until the network is in a stable state, and the latter one only performs one update step. Both the learning function and the update functions have one parameter, the vigilance parameter.

In its current implementation, the network has two-dimensional input. The matrix x contains all (one dimensional) input patterns. Internally, every one of these patterns is converted to a two-dimensional pattern using parameters dimX and dimY. The parameter f2Units controls the number of units in the recognition layer, and therewith the maximal amount of clusters that are assumed to be present in the input patterns.

A detailed description of the theory and the parameters is available from the SNNS documentation and the other referenced literature.

## Value

an rsnns object. The fitted.values member of the object contains a list of two-dimensional activation patterns.

#### References

Carpenter, G. A. & Grossberg, S. (1987), 'A massively parallel architecture for a self-organizing neural pattern recognition machine', Comput. Vision Graph. Image Process. 37, 54–115.

Grossberg, S. (1988), Adaptive pattern classification and universal recoding. I.: parallel development and coding of neural feature detectors, MIT Press, Cambridge, MA, USA, chapter I, pp. 243–258.

Herrmann, K.-U. (1992), 'ART – Adaptive Resonance Theory – Architekturen, Implementierung und Anwendung', Master's thesis, IPVR, University of Stuttgart. (in German)

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

#### See Also

art2, artmap

10 art2

#### **Examples**

```
## Not run: demo(art1_letters)
## Not run: demo(art1_lettersSnnsR)

data(snnsData)
patterns <- snnsData$art1_letters.pat

inputMaps <- matrixToActMapList(patterns, nrow=7)
par(mfrow=c(3,3))
for (i in 1:9) plotActMap(inputMaps[[i]])

model <- art1(patterns, dimX=7, dimY=5)
encodeClassLabels(model$fitted.values)</pre>
```

art2

Create and train an art2 network

#### **Description**

ART2 is very similar to ART1, but for real-valued input. See art1 for more information. Opposed to the ART1 implementation, the ART2 implementation does not assume two-dimensional input.

# Usage

```
art2(x, ...)
## Default S3 method:
art2(
    x,
    f2Units = 5,
    maxit = 100,
    initFunc = "ART2_Weights",
    initFuncParams = c(0.9, 2),
    learnFunc = "ART2",
    learnFuncParams = c(0.98, 10, 10, 0.1, 0),
    updateFunc = "ART2_Stable",
    updateFuncParams = c(0.98, 10, 10, 0.1, 0),
    shufflePatterns = TRUE,
    ...
)
```

# Arguments

```
    a matrix with training inputs for the network
    additional function parameters (currently not used)
    controls the number of clusters assumed to be present
```

art2 11

maxit maximum of iterations to learn initFunc the initialization function to use

initFuncParams the parameters for the initialization function

learnFunc the learning function to use

learnFuncParams

the parameters for the learning function

updateFunc the update function to use

updateFuncParams

the parameters for the update function

shufflePatterns

should the patterns be shuffled?

#### **Details**

As comparison of real-valued vectors is more difficult than comparison of binary vectors, the comparison layer is more complex in ART2, and actually consists of three layers. With a more complex comparison layer, also other parts of the network enhance their complexity. In SNNS, this enhanced complexity is reflected by the presence of more parameters in initialization-, learning-, and update function.

In analogy to the implementation of ART1, there are one initialization function, one learning function and two update functions suitable for ART2. The learning and update functions have five parameters, the initialization function has two parameters. For details see the SNNS User Manual, p. 67 and pp. 192.

#### Value

an rsnns object. The fitted values member contains the activation patterns for all inputs.

#### References

Carpenter, G. A. & Grossberg, S. (1987), 'ART 2: self-organization of stable category recognition codes for analog input patterns', Appl. Opt. 26(23), 4919–4930.

Grossberg, S. (1988), Adaptive pattern classification and universal recoding. I.: parallel development and coding of neural feature detectors, MIT Press, Cambridge, MA, USA, chapter I, pp. 243–258.

Herrmann, K.-U. (1992), 'ART – Adaptive Resonance Theory – Architekturen, Implementierung und Anwendung', Master's thesis, IPVR, University of Stuttgart. (in German)

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

#### See Also

art1, artmap

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#### **Examples**

artmap

Create and train an artmap network

#### Description

An ARTMAP performs supervised learning. It consists of two coupled ART networks. In theory, these could be ART1, ART2, or others. However, in SNNS ARTMAP is implemented for ART1 only. So, this function is to be used with binary input. As explained in the description of art1, ART aims at solving the stability/plasticity dilemma. So the advantage of ARTMAP is that it is a supervised learning mechanism that guarantees stability.

## Usage

```
artmap(x, ...)
## Default S3 method:
artmap(
    x,
    nInputsTrain,
    nInputsTargets,
    nUnitsRecLayerTrain,
    nUnitsRecLayerTargets,
    maxit = 1,
    nRowInputsTargets = 1,
    nRowUnitsRecLayerTrain = 1,
    nRowUnitsRecLayerTrain = 1,
    nRowUnitsRecLayerTrain = 1,
    nRowUnitsRecLayerTargets = 1,
```

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```
initFunc = "ARTMAP_Weights",
initFuncParams = c(1, 1, 1, 1, 0),
learnFunc = "ARTMAP",
learnFuncParams = c(0.8, 1, 1, 0, 0),
updateFunc = "ARTMAP_Stable",
updateFuncParams = c(0.8, 1, 1, 0, 0),
shufflePatterns = TRUE,
...
)
```

#### **Arguments**

a matrix with training inputs and targets for the network Х additional function parameters (currently not used) the number of columns of the matrix that are training input nInputsTrain nInputsTargets the number of columns that are target values nUnitsRecLayerTrain number of units in the recognition layer of the training data ART network nUnitsRecLayerTargets number of units in the recognition layer of the target data ART network maximum of iterations to perform maxit nRowInputsTrain number of rows the training input units are to be organized in (only for visualization purposes of the net in the original SNNS software) nRowInputsTargets same, but for the target value input units nRowUnitsRecLayerTrain same, but for the recognition layer of the training data ART network nRowUnitsRecLayerTargets same, but for the recognition layer of the target data ART network initFunc the initialization function to use initFuncParams the parameters for the initialization function learnFunc the learning function to use learnFuncParams the parameters for the learning function updateFunc the update function to use updateFuncParams the parameters for the update function shufflePatterns should the patterns be shuffled?

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#### **Details**

See also the details section of art1. The two ART1 networks are connected by a *map field*. The input of the first ART1 network is the training input, the input of the second network are the target values, the teacher signals. The two networks are often called ARTa and ARTb, we call them here training data network and target data network.

In analogy to the ART1 and ART2 implementations, there are one initialization function, one learning function, and two update functions present that are suitable for ARTMAP. The parameters are basically as in ART1, but for two networks. The learning function and the update functions have 3 parameters, the vigilance parameters of the two ART1 networks and an additional vigilance parameter for inter ART reset control. The initialization function has four parameters, two for every ART1 network.

A detailed description of the theory and the parameters is available from the SNNS documentation and the other referenced literature.

#### Value

an rsnns object. The fitted.values member of the object contains a list of two-dimensional activation patterns.

#### References

Carpenter, G. A.; Grossberg, S. & Reynolds, J. H. (1991), 'ARTMAP: Supervised real-time learning and classification of nonstationary data by a self-organizing neural network', Neural Networks 4(5), 565–588.

Grossberg, S. (1988), Adaptive pattern classification and universal recoding. I.: parallel development and coding of neural feature detectors, MIT Press, Cambridge, MA, USA, chapter I, pp. 243–258.

Herrmann, K.-U. (1992), 'ART – Adaptive Resonance Theory – Architekturen, Implementierung und Anwendung', Master's thesis, IPVR, University of Stuttgart. (in German)

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

## See Also

```
art1, art2
```

#### **Examples**

```
## Not run: demo(artmap_letters)
## Not run: demo(artmap_lettersSnnsR)

data(snnsData)
trainData <- snnsData$artmap_train.pat
testData <- snnsData$artmap_test.pat</pre>
```

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assoz

Create and train an (auto-)associative memory

#### **Description**

The autoassociative memory performs clustering by finding a prototype to the given input. The implementation assumes two-dimensional input and output (cf. art1).

#### Usage

```
assoz(x, ...)
## Default S3 method:
assoz(
    X,
    dimX,
    dimY,
    maxit = 100,
    initFunc = "RM_Random_Weights",
    initFuncParams = c(1, -1),
    learnFunc = "RM_delta",
    learnFuncParams = c(0.01, 100, 0, 0, 0),
    updateFunc = "Auto_Synchronous",
    updateFuncParams = c(50),
    shufflePatterns = TRUE,
    ...
)
```

#### **Arguments**

```
a matrix with training inputs for the network
additional function parameters (currently not used)

dimX x dimension of inputs and outputs

dimY y dimension of inputs and outputs

maxit maximum of iterations to learn

initFunc the initialization function to use

initFuncParams the parameters for the initialization function

learnFunc the learning function to use
```

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```
learnFuncParams
the parameters for the learning function
updateFunc the update function to use
updateFuncParams
the parameters for the update function
shufflePatterns
should the patterns be shuffled?
```

#### **Details**

The default initialization and update functions are the only ones suitable for this kind of network. The update function takes one parameter, which is the number of iterations that will be performed. The default of 50 usually does not have to be modified. For learning, RM\_delta and Hebbian functions can be used, though the first one usually performs better.

A more detailed description of the theory and the parameters is available from the SNNS documentation and the other referenced literature.

#### Value

an rsnns object. The fitted values member contains the activation patterns for all inputs.

#### References

```
Palm, G. (1980), 'On associative memory', Biological Cybernetics 36, 19-31.
Rojas, R. (1996), Neural networks: a systematic introduction, Springer-Verlag, Berlin.
```

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

## See Also

```
art1, art2
```

#### **Examples**

```
## Not run: demo(assoz_letters)
## Not run: demo(assoz_lettersSnnsR)

data(snnsData)
patterns <- snnsData$art1_letters.pat

model <- assoz(patterns, dimX=7, dimY=5)

actMaps <- matrixToActMapList(model$fitted.values, nrow=7)

par(mfrow=c(3,3))
for (i in 1:9) plotActMap(actMaps[[i]])</pre>
```

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confusionMatrix

Computes a confusion matrix

## **Description**

The confusion matrix shows how many times a pattern with the real class x was classified as class y. A perfect method should result in a diagonal matrix. All values not on the diagonal are errors of the method.

## Usage

```
confusionMatrix(targets, predictions)
```

#### **Arguments**

targets the known, correct target values

predictions the corresponding predictions of a method for the targets

#### **Details**

If the class labels are not already encoded, they are encoded using encodeClassLabels (with default values).

#### Value

the confusion matrix

decodeClassLabels

Decode class labels to a binary matrix

# **Description**

This method decodes class labels from a numerical or levels vector to a binary matrix, i.e., it converts the input vector to a binary matrix.

#### Usage

```
decodeClassLabels(x, valTrue = 1, valFalse = 0)
```

#### **Arguments**

x class label vectorvalTrue see Details paragraphvalFalse see Details paragraph

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#### **Details**

In the matrix, the value valTrue (e.g. 1) is present exactly in the column given by the value in the input vector, and the value valFalse (e.g. 0) in the other columns. The number of columns of the resulting matrix depends on the number of unique labels found in the vector. E.g. the input c(1, 3, 2, 3) will result in an output matrix with rows: 100 001 010 001

#### Value

a matrix containing the decoded class labels

#### Author(s)

The implementation is a slightly modified version of the function class.ind from the nnet package of Brian Ripley.

#### References

Venables, W. N. and Ripley, B. D. (2002), 'Modern Applied Statistics with S', Springer-Verlag.

#### **Examples**

```
decodeClassLabels(c(1,3,2,3))
decodeClassLabels(c("r","b","b","r", "g", "g"))
data(iris)
decodeClassLabels(iris[,5])
```

denormalizeData

Revert data normalization

## **Description**

Column-wise normalization of the input matrix is reverted, using the given parameters.

#### Usage

```
denormalizeData(x, normParams)
```

#### **Arguments**

x input data

normParams the parameters generated by an earlier call to normalizeData that will be used

for reverting normalization

#### **Details**

The input matrix is column-wise denormalized using the parameters given by normParams. E.g., if normParams contains mean and sd for every column, the values are multiplied by sd and the mean is added

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## Value

column-wise denormalized input

#### See Also

```
normalizeData, getNormParameters
```

## **Examples**

```
data(iris)
values <- normalizeData(iris[,1:4])
denormalizeData(values, getNormParameters(values))</pre>
```

dlvq

Create and train a dlvq network

#### **Description**

Dynamic learning vector quantization (DLVQ) networks are similar to self-organizing maps (SOM, som). But they perform supervised learning and lack a neighborhood relationship between the prototypes.

### Usage

```
dlvq(x, ...)
## Default S3 method:
dlvq(
    x,
    y,
    initFunc = "DLVQ_Weights",
    initFuncParams = c(1, -1),
    learnFunc = "Dynamic_LVQ",
    learnFuncParams = c(0.03, 0.03, 10),
    updateFunc = "Dynamic_LVQ",
    updateFuncParams = c(0),
    shufflePatterns = TRUE,
    ...
)
```

## Arguments

```
    a matrix with training inputs for the network
    additional function parameters (currently not used)
    the corresponding target values
    the initialization function to use
```

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initFuncParams the parameters for the initialization function

learnFunc the learning function to use

learnFuncParams

the parameters for the learning function

updateFunc the update function to use

updateFuncParams

the parameters for the update function

shufflePatterns

should the patterns be shuffled?

#### **Details**

The input data has to be normalized in order to use DLVQ.

Learning in DLVQ: For each class, a mean vector (prototype) is calculated and stored in a (newly generated) hidden unit. Then, the net is used to classify every pattern by using the nearest prototype. If a pattern gets misclassified as class y instead of class x, the prototype of class y is moved away from the pattern, and the prototype of class x is moved towards the pattern. This procedure is repeated iteratively until no more changes in classification take place. Then, new prototypes are introduced in the net per class as new hidden units, and initialized by the mean vector of misclassified patterns in that class.

Network architecture: The network only has one hidden layer, containing one unit for each prototype. The prototypes/hidden units are also called codebook vectors. Because SNNS generates the units automatically, and does not need their number to be specified in advance, the procedure is called *dynamic* LVQ in SNNS.

The default initialization, learning, and update functions are the only ones suitable for this kind of network. The three parameters of the learning function specify two learning rates (for the cases correctly/uncorrectly classified), and the number of cycles the net is trained before mean vectors are calculated.

A detailed description of the theory and the parameters is available, as always, from the SNNS documentation and the other referenced literature.

#### Value

an rsnns object. The fitted values member contains the activation patterns for all inputs.

#### References

Kohonen, T. (1988), Self-organization and associative memory, Vol. 8, Springer-Verlag.

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

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#### **Examples**

```
## Not run: demo(dlvq_ziff)
## Not run: demo(dlvq_ziffSnnsR)

data(snnsData)
dataset <- snnsData$dlvq_ziff_100.pat

inputs <- dataset[,inputColumns(dataset)]
outputs <- dataset[,outputColumns(dataset)]

model <- dlvq(inputs, outputs)

fitted(model) == outputs
mean(fitted(model) - outputs)</pre>
```

elman

Create and train an Elman network

# **Description**

Elman networks are partially recurrent networks and similar to Jordan networks (function jordan). For details, see explanations there.

#### Usage

```
elman(x, ...)
## Default S3 method:
elman(
  х,
 у,
 size = c(5),
 maxit = 100,
  initFunc = "JE_Weights",
  initFuncParams = c(1, -1, 0.3, 1, 0.5),
  learnFunc = "JE_BP",
  learnFuncParams = c(0.2),
  updateFunc = "JE_Order",
  updateFuncParams = c(0),
  shufflePatterns = FALSE,
  linOut = TRUE,
  outContext = FALSE,
  inputsTest = NULL,
  targetsTest = NULL,
)
```

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#### **Arguments**

x a matrix with training inputs for the network

... additional function parameters (currently not used)

y the corresponding targets values size number of units in the hidden layer(s)

maxit maximum of iterations to learn initFunc the initialization function to use

initFuncParams the parameters for the initialization function

learnFunc the learning function to use

learnFuncParams

the parameters for the learning function

updateFunc the update function to use

updateFuncParams

the parameters for the update function

shufflePatterns

should the patterns be shuffled?

linOut sets the activation function of the output units to linear or logistic

outContext if TRUE, the context units are also output units (untested)

inputsTest a matrix with inputs to test the network targetsTest the corresponding targets for the test input

#### Details

Learning in Elman networks: Same as in Jordan networks (see jordan).

Network architecture: The difference between Elman and Jordan networks is that in an Elman network the context units get input not from the output units, but from the hidden units. Furthermore, there is no direct feedback in the context units. In an Elman net, the number of context units and hidden units has to be the same. The main advantage of Elman nets is that the number of context units is not directly determined by the output dimension (as in Jordan nets), but by the number of hidden units, which is more flexible, as it is easy to add/remove hidden units, but not output units.

A detailed description of the theory and the parameters is available, as always, from the SNNS documentation and the other referenced literature.

#### Value

an rsnns object.

#### References

Elman, J. L. (1990), 'Finding structure in time', Cognitive Science 14(2), 179–211.

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

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#### See Also

```
jordan
```

## **Examples**

```
## Not run: demo(iris)
## Not run: demo(laser)
## Not run: demo(eight_elman)
## Not run: demo(eight_elmanSnnsR)
data(snnsData)
inputs <- snnsData$eight_016.pat[,inputColumns(snnsData$eight_016.pat)]</pre>
outputs <- snnsData$eight_016.pat[,outputColumns(snnsData$eight_016.pat)]</pre>
par(mfrow=c(1,2))
modelElman <- elman(inputs, outputs, size=8, learnFuncParams=c(0.1), maxit=1000)</pre>
modelElman
modelJordan <- jordan(inputs, outputs, size=8, learnFuncParams=c(0.1), maxit=1000)</pre>
modelJordan
plotIterativeError(modelElman)
plotIterativeError(modelJordan)
summary(modelElman)
summary(modelJordan)
```

encodeClassLabels

Encode a matrix of (decoded) class labels

## **Description**

Applies analyzeClassification row-wise to a matrix.

#### Usage

```
encodeClassLabels(x, method = "WTA", 1 = 0, h = 0)
```

#### **Arguments**

x	inputs
method	$see\ analyze {\tt Classification}$

1 idemh idem

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#### Value

a numeric vector, each number represents a different class. A zero means that no class was assigned to the pattern.

#### See Also

```
analyzeClassification
```

#### **Examples**

```
data(iris)
labels <- decodeClassLabels(iris[,5])
encodeClassLabels(labels)</pre>
```

exportToSnnsNetFile

Export the net to a file in the original SNNS file format

# Description

Export the net that is present in the rsnns object in the original (.net) SNNS file format.

#### Usage

```
exportToSnnsNetFile(object, filename, netname = "RSNNS_untitled")
```

## **Arguments**

object the rsnns object

filename path and filename to be written to

netname name that is given to the network in the file

 ${\tt extractNetInfo}$ 

Extract information from a network

#### **Description**

This function generates a list of data.frames containing the most important information that defines a network, in a format that is easy to use. To get the full definition in the original SNNS format, use summary.rsnns or exportToSnnsNetFile instead.

## Usage

```
extractNetInfo(object)
```

getNormParameters 25

# **Arguments**

object

the rsnns object

## **Details**

Internally, a call to SnnsRObject\$extractNetInfo is done, and the results of this call are returned.

#### Value

a list containing information extracted from the network (see SnnsRObject\$extractNetInfo).

## See Also

SnnsRObject\$extractNetInfo

getNormParameters

Get normalization parameters of the input data

# Description

Get the normalization parameters that are appended by normalizeData as attributes to the input data

## Usage

```
getNormParameters(x)
```

## **Arguments**

Χ

input data

# Details

This function is equivalent to calling attr(x, "normParams").

#### Value

the parameters generated by an earlier call to normalizeData

#### See Also

normalizeData, denormalizeData

getSnnsRDefine

Get a define of the SNNS kernel

# Description

Get a define of the SNNS kernel from a defines-list. All defines-lists present can be shown with RSNNS:::SnnsDefines.

## Usage

```
getSnnsRDefine(defList, defValue)
```

## **Arguments**

defList the defines-list from which to get the define from

defValue the value in the list

#### Value

a string with the name of the define

#### See Also

resolveSnnsRDefine

# **Examples**

```
getSnnsRDefine("topologicalUnitTypes",3)
getSnnsRDefine("errorCodes",-50)
```

 ${\tt getSnnsRFunctionTable} \quad \textit{Get SnnsR function table}$ 

# **Description**

Get the function table of available SNNS functions.

## Usage

```
getSnnsRFunctionTable()
```

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## Value

a data.frame with columns:

name of the function

type the type of the function (learning, init, update,...)
#inParams the number of input parameters of the function
#outParams the number of output parameters of the function

inputColumns

Get the columns that are inputs

## **Description**

This function extracts all columns from a matrix whose column names begin with "in". The example data of this package follows this naming convention.

## Usage

```
inputColumns(patterns)
```

## **Arguments**

patterns

matrix or data.frame containing the patterns

jordan

Create and train a Jordan network

# Description

Jordan networks are partially recurrent networks and similar to Elman networks (see elman). Partially recurrent networks are useful when working with time series data. I.e., when the output of the network not only should depend on the current pattern, but also on the patterns presented before.

#### Usage

```
jordan(x, ...)
## Default S3 method:
jordan(
    x,
    y,
    size = c(5),
    maxit = 100,
    initFunc = "JE_Weights",
```

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```
initFuncParams = c(1, -1, 0.3, 1, 0.5),
learnFunc = "JE_BP",
learnFuncParams = c(0.2),
updateFunc = "JE_Order",
updateFuncParams = c(0),
shufflePatterns = FALSE,
linOut = TRUE,
inputsTest = NULL,
targetsTest = NULL,
...
)
```

#### Arguments

x a matrix with training inputs for the network

. . . additional function parameters (currently not used)

y the corresponding targets values

size number of units in the hidden layer(s)

maxit maximum of iterations to learn initFunc the initialization function to use

initFuncParams the parameters for the initialization function

learnFunc the learning function to use

learnFuncParams

the parameters for the learning function

updateFunc the update function to use

updateFuncParams

the parameters for the update function

shufflePatterns

should the patterns be shuffled?

linOut sets the activation function of the output units to linear or logistic

inputsTest a matrix with inputs to test the network targetsTest the corresponding targets for the test input

#### **Details**

Learning on Jordan networks: Backpropagation algorithms for feed-forward networks can be adapted for their use with this type of networks. In SNNS, there exist adapted versions of several backpropagation-type algorithms for Jordan and Elman networks.

Network architecture: A Jordan network can be seen as a feed-forward network with additional context units in the input layer. These context units take input from themselves (direct feedback), and from the output units. The context units save the current state of the net. In a Jordan net, the number of context units and output units has to be the same.

Initialization of Jordan and Elman nets should be done with the default init function JE\_Weights, which has five parameters. The first two parameters define an interval from which the forward

jordan 29

connections are randomly chosen. The third parameter gives the self-excitation weights of the context units. The fourth parameter gives the weights of context units between them, and the fifth parameter gives the initial activation of context units.

Learning functions are JE\_BP, JE\_BP\_Momentum, JE\_Quickprop, and JE\_Rprop, which are all adapted versions of their standard-procedure counterparts. Update functions that can be used are JE\_Order and JE\_Special.

A detailed description of the theory and the parameters is available, as always, from the SNNS documentation and the other referenced literature.

#### Value

an rsnns object.

#### References

Jordan, M. I. (1986), 'Serial Order: A Parallel, Distributed Processing Approach', Advances in Connectionist Theory Speech 121(ICS-8604), 471-495.

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

#### See Also

elman

# **Examples**

matrixToActMapList

```
plotRegressionError(patterns$targetsTrain, modelJordan$fitted.values)
plotRegressionError(patterns$targetsTest, modelJordan$fittedTestValues)
hist(modelJordan$fitted.values - patterns$targetsTrain, col="lightblue")

plot(inputs, type="1")
plot(inputs[1:100], type="1")
lines(outputs[1:100], col="red")
lines(modelJordan$fitted.values[1:100], col="green")
```

matrixToActMapList

Convert matrix of activations to activation map list

#### **Description**

Organize a matrix containing 1d vectors of network activations as 2d maps.

## Usage

```
matrixToActMapList(m, nrow = 0, ncol = 0)
```

## Arguments

m	the matrix containing one activation pattern in every row
nrow	number of rows the resulting matrices will have
ncol	number of columns the resulting matrices will have

## Details

The input to this function is a matrix containing in each row an activation pattern/output of a neural network. This function uses vectorToActMap to reorganize the matrix to a list of matrices, whereby each row of the input matrix is converted to a matrix in the output list.

# Value

a list containing the activation map matrices

#### See Also

vectorToActMap plotActMap

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mlp

Create and train a multi-layer perceptron (MLP)

#### Description

This function creates a multilayer perceptron (MLP) and trains it. MLPs are fully connected feed-forward networks, and probably the most common network architecture in use. Training is usually performed by error backpropagation or a related procedure.

There are a lot of different learning functions present in SNNS that can be used together with this function, e.g., Std\_Backpropagation, BackpropBatch, BackpropChunk, BackpropMomentum, BackpropWeightDecay, Rprop, Quickprop, SCG (scaled conjugate gradient), ...

## Usage

```
mlp(x, ...)
## Default S3 method:
mlp(
  Х,
 у,
  size = c(5),
 maxit = 100,
  initFunc = "Randomize_Weights",
  initFuncParams = c(-0.3, 0.3),
  learnFunc = "Std_Backpropagation",
  learnFuncParams = c(0.2, 0),
  updateFunc = "Topological_Order",
  updateFuncParams = c(0),
  hiddenActFunc = "Act_Logistic",
  shufflePatterns = TRUE,
  linOut = FALSE,
  outputActFunc = if (linOut) "Act_Identity" else "Act_Logistic",
  inputsTest = NULL,
  targetsTest = NULL,
  pruneFunc = NULL,
  pruneFuncParams = NULL,
)
```

#### **Arguments**

```
x a matrix with training inputs for the network
... additional function parameters (currently not used)
y the corresponding targets values
size number of units in the hidden layer(s)
```

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maxit maximum of iterations to learn initFunc the initialization function to use

initFuncParams the parameters for the initialization function

learnFunc the learning function to use

learnFuncParams

the parameters for the learning function

updateFunc the update function to use

updateFuncParams

the parameters for the update function

hiddenActFunc the activation function of all hidden units

shufflePatterns

should the patterns be shuffled?

linOut sets the activation function of the output units to linear or logistic (ignored if

outputActFunc is given)

outputActFunc the activation function of all output units inputsTest a matrix with inputs to test the network targetsTest the corresponding targets for the test input

pruneFunc the pruning function to use

pruneFuncParams

the parameters for the pruning function. Unlike the other functions, these have to be given in a named list. See the pruning demos for further explanation.

#### **Details**

Std\_Backpropagation, BackpropBatch, e.g., have two parameters, the learning rate and the maximum output difference. The learning rate is usually a value between 0.1 and 1. It specifies the gradient descent step width. The maximum difference defines, how much difference between output and target value is treated as zero error, and not backpropagated. This parameter is used to prevent overtraining. For a complete list of the parameters of all the learning functions, see the SNNS User Manual, pp. 67.

The defaults that are set for initialization and update functions usually don't have to be changed.

#### Value

an rsnns object.

#### References

Rosenblatt, F. (1958), 'The perceptron: A probabilistic model for information storage and organization in the brain', Psychological Review 65(6), 386–408.

Rumelhart, D. E.; Clelland, J. L. M. & Group, P. R. (1986), Parallel distributed processing :explorations in the microstructure of cognition, Mit, Cambridge, MA etc.

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

normalizeData 33

#### **Examples**

```
## Not run: demo(iris)
## Not run: demo(laser)
## Not run: demo(encoderSnnsCLib)
data(iris)
#shuffle the vector
iris <- iris[sample(1:nrow(iris),length(1:nrow(iris))),1:ncol(iris)]</pre>
irisValues <- iris[,1:4]</pre>
irisTargets <- decodeClassLabels(iris[,5])</pre>
#irisTargets <- decodeClassLabels(iris[,5], valTrue=0.9, valFalse=0.1)</pre>
iris <- splitForTrainingAndTest(irisValues, irisTargets, ratio=0.15)</pre>
iris <- normTrainingAndTestSet(iris)</pre>
model <- mlp(iris$inputsTrain, iris$targetsTrain, size=5, learnFuncParams=c(0.1),</pre>
              maxit=50, inputsTest=iris$inputsTest, targetsTest=iris$targetsTest)
summary(model)
model
weightMatrix(model)
extractNetInfo(model)
par(mfrow=c(2,2))
plotIterativeError(model)
predictions <- predict(model,iris$inputsTest)</pre>
plotRegressionError(predictions[,2], iris$targetsTest[,2])
confusionMatrix(iris$targetsTrain,fitted.values(model))
confusionMatrix(iris$targetsTest,predictions)
plotROC(fitted.values(model)[,2], iris$targetsTrain[,2])
plotROC(predictions[,2], iris$targetsTest[,2])
#confusion matrix with 402040-method
confusionMatrix(iris$targetsTrain, encodeClassLabels(fitted.values(model),
                                                          method="402040", l=0.4, h=0.6))
```

normalizeData

Data normalization

## **Description**

The input matrix is column-wise normalized.

#### Usage

```
normalizeData(x, type = "norm")
```

## **Arguments**

x input data

type **either** type string specifying the type of normalization. Implemented are "0\_1",

"center", and "norm"

or attribute list of a former call to this method to apply e.g. normalization of

the training data to the test data

#### **Details**

The parameter type specifies, how normalization takes place:

**0\_1** values are normalized to the [0,1]-interval. The minimum in the data is mapped to zero, the maximum to one.

**center** the data is centered, i.e. the mean is substracted

**norm** the data is normalized to mean zero, variance one

#### Value

column-wise normalized input. The normalization parameters that were used for the normalization are present as attributes of the output. They can be obtained with getNormParameters.

#### See Also

denormalizeData, getNormParameters

normTrainingAndTestSet

Function to normalize training and test set

#### **Description**

Normalize training and test set as obtained by splitForTrainingAndTest in the following way: The inputsTrain member is normalized using normalizeData with the parameters given in type. The normalization parameters obtained during this normalization are then used to normalize the inputsTest member. if dontNormTargets is not set, then the targets are normalized in the same way. In classification problems, normalizing the targets normally makes no sense. For regression, normalizing also the targets is usually a good idea. The default is to not normalize targets values.

## Usage

```
normTrainingAndTestSet(x, dontNormTargets = TRUE, type = "norm")
```

outputColumns 35

# Arguments

#### Value

a named list with the same elements as splitForTrainingAndTest, but with normalized values. The normalization parameters are appended to each member of the list as attributes, as in normalizeData.

#### See Also

```
splitForTrainingAndTest, normalizeData, denormalizeData, getNormParameters
```

#### **Examples**

```
data(iris)
#shuffle the vector
iris <- iris[sample(1:nrow(iris),length(1:nrow(iris))),1:ncol(iris)]
irisValues <- iris[,1:4]
irisTargets <- decodeClassLabels(iris[,5])
iris <- splitForTrainingAndTest(irisValues, irisTargets, ratio=0.15)
normTrainingAndTestSet(iris)</pre>
```

outputColumns

Get the columns that are targets

## **Description**

This function extracts all columns from a matrix whose column names begin with "out". The example data of this package follows this naming convention.

## Usage

```
outputColumns(patterns)
```

#### **Arguments**

patterns

matrix or data.frame containing the patterns

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plotActMap

Plot activation map

# Description

Plot an activation map as a heatmap.

# Usage

```
plotActMap(x, ...)
```

## **Arguments**

the input data matrix

... parameters passed to image

#### See Also

vectorToActMap matrixToActMapList

plotIterativeError

Plot iterative errors of an rsnns object

# **Description**

Plot the iterative training and test error of the net of this rsnns object.

# Usage

```
plotIterativeError(object, ...)
## S3 method for class 'rsnns'
plotIterativeError(object, ...)
```

# Arguments

object a rsnns object

... parameters passed to plot

#### **Details**

Plots (if present) the class members IterativeFitError (as black line) and IterativeTestError (as red line).

plotRegressionError 37

 $\verb"plotRegressionError"$ 

Plot a regression error plot

# Description

The plot shows target values on the x-axis and fitted/predicted values on the y-axis. The optimal fit would yield a line through zero with gradient one. This optimal line is shown in black color. A linear fit to the actual data is shown in red color.

# Usage

```
plotRegressionError(targets, fits, ...)
```

# Arguments

targets the target values

fits the values predicted/fitted by the model

... parameters passed to plot

plotROC

Plot a ROC curve

# **Description**

This function plots a receiver operating characteristic (ROC) curve.

# Usage

```
plotROC(T, D, ...)
```

# Arguments

T predictions

D targets

... parameters passed to plot

### Author(s)

Code is taken from R news Volume 4/1, June 2004.

#### References

R news Volume 4/1, June 2004

print.rsnns

predict.rsnns

Generic predict function for rsnns object

# Description

Predict values using the given network.

# Usage

```
## S3 method for class 'rsnns'
predict(object, newdata, ...)
```

# Arguments

object the rsnns object

newdata the new input data which is used for prediction

... additional function parameters (currently not used)

# Value

the predicted values

print.rsnns

Generic print function for rsnns objects

# **Description**

Print out some characteristics of an rsnns object.

# Usage

```
## S3 method for class 'rsnns'
print(x, ...)
```

# **Arguments**

x the rsnns object

. . . additional function parameters (currently not used)

rbf 39

rbf

Create and train a radial basis function (RBF) network

### **Description**

The use of an RBF network is similar to that of an mlp. The idea of radial basis function networks comes from function interpolation theory. The RBF performs a linear combination of n basis functions that are radially symmetric around a center/prototype.

# Usage

```
rbf(x, ...)
## Default S3 method:
rbf(
  Х,
 у,
  size = c(5),
 maxit = 100,
  initFunc = "RBF_Weights",
  initFuncParams = c(0, 1, 0, 0.02, 0.04),
  learnFunc = "RadialBasisLearning",
  learnFuncParams = c(1e-05, 0, 1e-05, 0.1, 0.8),
  updateFunc = "Topological_Order",
  updateFuncParams = c(0),
  shufflePatterns = TRUE,
  linOut = TRUE,
  inputsTest = NULL,
  targetsTest = NULL,
)
```

### **Arguments**

```
a matrix with training inputs for the network

additional function parameters (currently not used)

the corresponding targets values

number of units in the hidden layer(s)

maxit

maximum of iterations to learn

initFunc

the initialization function to use

initFuncParams

the parameters for the initialization function

learnFunc

the learning function to use
```

the parameters for the learning function

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updateFunc the update function to use

updateFuncParams

the parameters for the update function

shufflePatterns

should the patterns be shuffled?

linOut sets the activation function of the output units to linear or logistic

inputsTest a matrix with inputs to test the network targetsTest the corresponding targets for the test input

#### **Details**

RBF networks are feed-forward networks with one hidden layer. Their activation is not sigmoid (as in MLP), but radially symmetric (often gaussian). Thereby, information is represented locally in the network (in contrast to MLP, where it is globally represented). Advantages of RBF networks in comparison to MLPs are mainly, that the networks are more interpretable, training ought to be easier and faster, and the network only activates in areas of the feature space where it was actually trained, and has therewith the possibility to indicate that it "just doesn't know".

Initialization of an RBF network can be difficult and require prior knowledge. Before use of this function, you might want to read pp 172-183 of the SNNS User Manual 4.2. The initialization is performed in the current implementation by a call to RBF\_Weights\_Kohonen(0,0,0,0,0) and a successive call to the given initFunc (usually RBF\_Weights). If this initialization doesn't fit your needs, you should use the RSNNS low-level interface to implement your own one. Have a look then at the demos/examples. Also, we note that depending on whether linear or logistic output is chosen, the initialization parameters have to be different (normally  $c(0,1,\ldots)$ ) for linear and  $c(-4,4,\ldots)$  for logistic output).

### Value

an rsnns object.

#### References

Poggio, T. & Girosi, F. (1989), 'A Theory of Networks for Approximation and Learning' (A.I. Memo No.1140, C.B.I.P. Paper No. 31), Technical report, MIT ARTIFICIAL INTELLIGENCE LABORATORY.

Vogt, M. (1992), 'Implementierung und Anwendung von Generalized Radial Basis Functions in einem Simulator neuronaler Netze', Master's thesis, IPVR, University of Stuttgart. (in German)

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

# **Examples**

```
## Not run: demo(rbf_irisSnnsR)
## Not run: demo(rbf_sin)
## Not run: demo(rbf_sinSnnsR)
```

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rbfDDA

Create and train an RBF network with the DDA algorithm

# Description

Create and train an RBF network with the dynamic decay adjustment (DDA) algorithm. This type of network can only be used for classification. The training typically begins with an empty network, i.e., a network only consisting of input and output units, and adds new units successively. It is a lot easier to use than normal RBF, because it only requires two quite uncritical parameters.

### Usage

```
rbfDDA(x, ...)
## Default S3 method:
rbfDDA(
    x,
    y,
    maxit = 1,
    initFunc = "Randomize_Weights",
    initFuncParams = c(-0.3, 0.3),
    learnFunc = "RBF-DDA",
    learnFuncParams = c(0.4, 0.2, 5),
    updateFunc = "Topological_Order",
    updateFuncParams = c(0),
    shufflePatterns = TRUE,
    linOut = FALSE,
    ...
)
```

### **Arguments**

x a matrix with training inputs for the network

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... additional function parameters (currently not used)

y the corresponding targets values maxit maximum of iterations to learn initFunc the initialization function to use

initFuncParams the parameters for the initialization function

learnFunc the learning function to use

learnFuncParams

the parameters for the learning function

updateFunc the update function to use

updateFuncParams

the parameters for the update function

shufflePatterns

should the patterns be shuffled?

linOut sets the activation function of the output units to linear or logistic

#### **Details**

The default functions do not have to be altered. The learning function RBF-DDA has three parameters: a positive threshold, and a negative threshold, that controls adding units to the network, and a parameter for display purposes in the original SNNS. This parameter has no effect in RSNNS. See p 74 of the original SNNS User Manual for details.

# Value

an rsnns object.

#### References

Berthold, M. R. & Diamond, J. (1995), Boosting the Performance of RBF Networks with Dynamic Decay Adjustment, in 'Advances in Neural Information Processing Systems', MIT Press, , pp. 521–528.

Hudak, M. (1993), 'RCE classifiers: theory and practice', Cybernetics and Systems 23(5), 483–515. Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

# **Examples**

```
## Not run: demo(iris)
## Not run: demo(rbfDDA_spiralsSnnsR)

data(iris)
iris <- iris[sample(1:nrow(iris),length(1:nrow(iris))),1:ncol(iris)]
irisValues <- iris[,1:4]
irisTargets <- decodeClassLabels(iris[,5])
iris <- splitForTrainingAndTest(irisValues, irisTargets, ratio=0.15)</pre>
```

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```
iris <- normTrainingAndTestSet(iris)

model <- rbfDDA(iris$inputsTrain, iris$targetsTrain)
summary(model)
plotIterativeError(model)</pre>
```

readPatFile

Load data from a pat file

# Description

This function generates an SnnsR-class object, loads the given .pat file there as a pattern set and then extracts the patterns to a matrix, using SnnsRObject\$extractPatterns.

# Usage

```
readPatFile(filename)
```

# Arguments

filename

the name of the .pat file

#### Value

a matrix containing the data loaded from the .pat file.

readResFile

Rudimentary parser for res files.

# Description

This function contains a rudimentary parser for SNNS .res files. It is completely implemented in R and doesn't make use of SNNS functionality.

### Usage

```
readResFile(filename)
```

# Arguments

filename

the name of the .res file

#### Value

a matrix containing the predicted values that were found in the .res file

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resolveSnnsRDefine

Resolve a define of the SNNS kernel

# Description

Resolve a define of the SNNS kernel using a defines-list. All defines-lists present can be shown with RSNNS:::SnnsDefines.

# Usage

```
resolveSnnsRDefine(defList, def)
```

# **Arguments**

defList the defines-list from which to resolve the define from

def the name of the define

### Value

the value of the define

### See Also

getSnnsRDefine

# **Examples**

```
resolveSnnsRDefine("topologicalUnitTypes","UNIT_HIDDEN")
```

rsnnsObjectFactory

Object factory for generating rsnns objects

# Description

The object factory generates an rsnns object and initializes its member variables with the values given as parameters. Furthermore, it generates an object of SnnsR-class. Later, this information is to be used to train the network.

rsnnsObjectFactory 45

### Usage

```
rsnnsObjectFactory(
   subclass,
   nInputs,
   maxit,
   initFunc,
   initFuncParams,
   learnFunc,
   learnFuncParams,
   updateFunc,
   updateFunc,
   updateFuncParams,
   shufflePatterns = TRUE,
   computeIterativeError = TRUE,
   pruneFuncParams = NULL
)
```

# **Arguments**

subclass the subclass of rsnns to generate (vector of strings) the number of inputs the network will have nInputs maximum of iterations to learn maxit the initialization function to use initFunc initFuncParams the parameters for the initialization function learnFunc the learning function to use learnFuncParams the parameters for the learning function updateFunc the update function to use updateFuncParams the parameters for the update function shufflePatterns should the patterns be shuffled? computeIterativeError should the error be computed in every iteration? pruneFunc the pruning function to use

the parameters for the pruning function. Unlike the other functions, these have to be given in a named list. See the pruning demos for further explanation.

### **Details**

pruneFuncParams

The typical procedure implemented in rsnns subclasses is the following:

- generate the rsnns object with this object factory
- · generate the network according to the architecture needed

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• train the network (with train)

In every rsnns object, the iterative error is the summed squared error (SSE) of all patterns. If the SSE is computed on the test set, then it is weighted to take care of the different amount of patterns in the sets.

#### Value

a partly initialized rsnns object

# See Also

```
mlp, dlvq, rbf, rbfDDA, elman, jordan, som, art1, art2, artmap, assoz
```

savePatFile

Save data to a pat file

# **Description**

This function generates an SnnsR-class object, loads the given data there as a pattern set and then uses the functionality of SNNS to save the data as a .pat file.

# Usage

```
savePatFile(inputs, targets, filename)
```

# **Arguments**

inputs a matrix with input values targets a matrix with target values filename the name of the .pat file

setSnnsRSeedValue

DEPRECATED, Set the SnnsR seed value

### **Description**

DEPRECATED, now just calls R's set.seed(), that should be used instead.

# Usage

```
setSnnsRSeedValue(seed)
```

### Arguments

seed

the seed to use. If 0, a seed based on the system time is generated.

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snnsData

Example data of the package

# **Description**

This is data from the original SNNS examples directory ported to R and stored as one list. The function readPatFile was used to parse all pattern files (.pat) from the original SNNS examples directory. Due to limitations of that function, pattern files containing patterns with variable size were omitted.

#### **Examples**

data(snnsData)
names(snnsData)

SnnsR-class

The main class of the package

# **Description**

An S4 class that is the main class of RSNNS. Each instance of this class contains a pointer to a C++ object of type SnnsCLib, i.e. an instance of the SNNS kernel.

### **Details**

The only slot variables holds an environment with all member variables. Currently, there are two members (constructed by the object factory):

**snnsCLibPointer** A pointer to the corresponding C++ object **serialization** a serialization of the C++ object, in SNNS .net format

The member variables are not directly present as slots but wrapped in an environment to allow for changing the serialization (by call by reference).

An object of this class is used internally by all the models in the package. The object is always accessible by model\$snnsObject\$...

To make full use of the SNNS functionalities, you might want to use this class directly. Always use the object factory SnnsRObjectFactory to construct an object, and the calling mechanism \$ to call functions. Through the calling mechanism, many functions of SnnsCLib are present that are not documented here, but in the SNNS User Manual. So, if you choose to use the low-level interface, it is highly recommended to have a look at the demos and at the SNNS User Manual.

#### References

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

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### See Also

### \$, SnnsRObjectFactory

# **Examples**

```
## Not run: demo(encoderSnnsCLib)
## Not run: demo(art1_lettersSnnsR)
## Not run: demo(art2_tetraSnnsR)
## Not run: demo(artmap_lettersSnnsR)
## Not run: demo(eight_elmanSnnsR)
## Not run: demo(rbf_irisSnnsR)
## Not run: demo(rbf_sinSnnsR)
## Not run: demo(rbfDDA_spiralsSnnsR)
## Not run: demo(som_cubeSnnsR)
#This is the demo eight_elmanSnnsR
#Here, we train an Elman network
#and save a trained and an untrained version
#to disk, as well as the used training data
basePath <- ("./")
data(snnsData)
inputs <- snnsData$eight_016.pat[,inputColumns(snnsData$eight_016.pat)]</pre>
outputs <- snnsData$eight_016.pat[,outputColumns(snnsData$eight_016.pat)]
snnsObject <- SnnsRObjectFactory()</pre>
snnsObject$setLearnFunc('JE_BP')
snnsObject$setUpdateFunc('JE_Order')
snnsObject$setUnitDefaults(1,0,1,0,1,'Act_Logistic','Out_Identity')
snnsObject$elman_createNet(c(2,8,2),c(1,1,1),FALSE)
patset <- snnsObject$createPatSet(inputs, outputs)</pre>
snnsObject$setCurrPatSet(patset$set_no)
snnsObjectinitializeNet(c(1.0, -1.0, 0.3, 1.0, 0.5))
snnsObject$shufflePatterns(TRUE)
snnsObject$DefTrainSubPat()
## Not run: snnsObject$saveNet(paste(basePath,"eight_elmanSnnsR_untrained.net",sep=""),
                                           "eight_elmanSnnsR_untrained")
## End(Not run)
parameters <- c(0.2, 0, 0, 0, 0)
maxit <- 1000
error <- vector()
```

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SnnsRObjectFactory

SnnsR object factory

### **Description**

Object factory to create a new object of type SnnsR-class.

# Usage

```
SnnsRObjectFactory(x = NULL)
```

# **Arguments**

Х

(optional) object of class SnnsR-class, to be deep-copied

#### **Details**

This function creates a new object of class SnnsR-class, initializes its only slot variables with a new environment, generates a new C++ object of class SnnsCLib, and an empty object serialization.

### See Also

```
$, SnnsR-class
```

### **Examples**

```
mySnnsObject <- SnnsRObjectFactory()
mySnnsObject$setLearnFunc('Quickprop')
mySnnsObject$setUpdateFunc('Topological_Order')</pre>
```

SnnsRObjectMethodCaller

Method caller for SnnsR objects

# **Description**

Enable calling of C++ functions as methods of SnnsR-class objects.

### Usage

```
## S4 method for signature 'SnnsR'
x$name
```

# **Arguments**

x object of class SnnsR-class

name function to call

#### **Details**

This function makes methods of SnnsR\_\_ and SnnsCLib\_\_ accessible via "\$". If no SnnsR\_\_ method is present, then the according SnnsCLib\_\_ method is called. This enables a very flexible method handling. To mask a method from SnnsCLib, e.g. to do some parameter checking or postprocessing, only a method with the same name, but beginning with SnnsR\_\_ has to be present in R. See e.g. SnnsRObject\$initializeNet for such an implementation.

Error handling is also done within the method caller. If the result of a function is a list with a member err, then SnnsCLib\_error is called to use the SNNS kernel function to get the corresponding error message code and an R warning is thrown containing this message.

Furthermore, a serialization mechanism is implemented which all models present in the package use to be able to be saved and loaded by R's normal save/load mechanism (as RData files).

The completely trained object can be serialized with

```
s <- snnsObject$serializeNet("RSNNS_untitled")
snnsObject@variables$serialization <- s$serialization</pre>
```

For the models implemented, this is done in SnnsRObject\$train. If the S4 object is then saved and loaded, the calling mechanism will notice on the next use of a function that the pointer to the C++ SnnsCLib object is nil, and if a serialization is present, the object is restored from this serialization before the method is called.

SnnsRObject\$createNet Create a layered network

# **Description**

This function creates a layered network in the given SnnsR object. This is an SnnsR low-level function. You may want to have a look at SnnsR-class to find out how to properly use it.

# Usage

```
## S4 method for signature 'SnnsR'
createNet(unitsPerLayer, fullyConnectedFeedForward = TRUE, iNames = NULL, oNames = NULL)
```

# **Arguments**

unitsPerLayer a vector of integers that represents the number of units in each layer, including

input and output layer

 $fully {\tt Connected Feed Forward}$ 

if TRUE, the network is fully connected as a feed-forward network. If FALSE, no

connections are created

iNames names of input units

oNames names of output units

# See Also

```
SnnsR-class
```

# **Examples**

```
obj1 <- SnnsRObjectFactory()
obj1$createNet(c(2,2), FALSE)
obj1$getUnitDefinitions()

obj2 <- SnnsRObjectFactory()
obj2$createNet(c(8,5,5,2), TRUE)
obj2$getUnitDefinitions()</pre>
```

SnnsRObject\$createPatSet

Create a pattern set

# Description

SnnsR low-level function to create a pattern set in the SNNS kernel from the values given, so that they are available in the SNNS kernel for use.

# Usage

```
## S4 method for signature 'SnnsR'
createPatSet(inputs, targets)
```

# **Arguments**

inputs the input values targets the target values

### Value

a list with elements err and set\_no. The latter one identifies the pattern set within the SnnsR-class object

SnnsRObject\$extractNetInfo

Get characteristics of the network.

# Description

The returned list has three members:

- infoHeader general information about the network
- unitDefinitions information about the units
- fullWeightMatrix weight matrix of the connections

#### **Usage**

```
## S4 method for signature 'SnnsR'
extractNetInfo()
```

# Value

a list of data frames containing information extracted from the network.

SnnsRObject\$extractPatterns

Extract the current pattern set to a matrix

# Description

SnnsR low-level function that extracts all patterns of the current pattern set and returns them as a matrix. Columns are named with the prefix "in" or "out", respectively.

### Usage

```
## S4 method for signature 'SnnsR'
extractPatterns()
```

#### Value

a matrix containing the patterns of the currently loaded patern set.

SnnsRObject\$getAllHiddenUnits

Get all hidden units of the net

# **Description**

SnnsR low-level function to get all units from the net with the ttype "UNIT\_HIDDEN". This function calls SnnsR0bject\$getAllUnitsTType with the parameter "UNIT\_HIDDEN".

# Usage

```
## S4 method for signature 'SnnsR'
getAllHiddenUnits()
```

### Value

a vector with integer numbers identifying the units.

#### See Also

SnnsRObject\$getAllUnitsTType

SnnsRObject\$getAllInputUnits

Get all input units of the net

# Description

SnnsR low-level function to get all units from the net with the ttype "UNIT\_INPUT". This function calls SnnsR0bject\$getAllUnitsTType with the parameter "UNIT\_INPUT".

### Usage

```
## S4 method for signature 'SnnsR'
getAllInputUnits()
```

### Value

a vector with integer numbers identifying the units.

### See Also

SnnsRObject\$getAllUnitsTType

SnnsRObject\$getAllOutputUnits

Get all output units of the net.

# Description

SnnsR low-level function to get all units from the net with the ttype "UNIT\_OUTPUT". This function calls SnnsRObject\$getAllUnitsTType with the parameter "UNIT\_OUTPUT".

# Usage

```
## S4 method for signature 'SnnsR'
getAllOutputUnits()
```

### Value

a vector with integer numbers identifying the units.

# See Also

SnnsRObject\$getAllUnitsTType

SnnsRObject\$getAllUnits

Get all units present in the net.

### **Description**

Get all units present in the net.

# Usage

```
## S4 method for signature 'SnnsR'
getAllUnits()
```

#### Value

a vector with integer numbers identifying the units.

SnnsRObject\$getAllUnitsTType

Get all units in the net of a certain ttype.

# Description

SnnsR low-level function to get all units in the net of a certain ttype. Possible ttype defined by SNNS are, among others: "UNIT\_OUTPUT", "UNIT\_INPUT", and "UNIT\_HIDDEN". For a full list, call RSNNS:::SnnsDefines\$topologicalUnitTypes As this is an SnnsR low-level function, you may want to have a look at SnnsR-class to find out how to properly use it.

# Usage

```
## S4 method for signature 'SnnsR'
getAllUnitsTType(ttype)
```

# Arguments

ttype

a string containing the ttype.

### Value

a vector with integer numbers identifying the units.

#### See Also

Snns RObject \$get All Output Units, Snns RObject \$get All Input Units, Snns RObject \$get All Hidden Units All Input Units, Snns RObject \$get All Hidden Units All Input Units, Snns RObject \$get All Hidden Units All Input Units, Snns RObject \$get All Hidden Units All Input Units, Snns RObject \$get All Hidden Units All Input Units, Snns RObject \$get All Hidden Units All Input Units, Snns RObject \$get All Input Units, Snns RObject \$get All Hidden Units All Input Units, Snns RObject \$get All Input Units, Snns Robject All Input Units, Snns

SnnsRObject\$getCompleteWeightMatrix

Get the complete weight matrix.

# **Description**

Get a weight matrix containing all weights of all neurons present in the net.

### Usage

```
## S4 method for signature 'SnnsR'
getCompleteWeightMatrix(setDimNames)
```

# **Arguments**

setDimNames

indicates, whether names of units are extracted and set as row/col names in the weight matrix

#### Value

the complete weight matrix

SnnsRObject\$getInfoHeader

Get an info header of the network.

# Description

Get an info header of the network.

# Usage

```
## S4 method for signature 'SnnsR'
getInfoHeader()
```

### Value

a data frame containing some general characteristics of the network.

SnnsRObject\$getSiteDefinitions

Get the sites definitions of the network.

# Description

Get the sites definitions of the network.

# Usage

```
## S4 method for signature 'SnnsR'
getSiteDefinitions()
```

### Value

a data frame containing information about all sites present in the network.

SnnsRObject\$getTypeDefinitions

Get the FType definitions of the network.

# Description

Get the FType definitions of the network.

# Usage

```
## S4 method for signature 'SnnsR'
getTypeDefinitions()
```

# Value

a data frame containing information about FType units present in the network.

SnnsRObject\$getUnitDefinitions

Get the unit definitions of the network.

# Description

Get the unit definitions of the network.

# Usage

```
## S4 method for signature 'SnnsR'
getUnitDefinitions()
```

### Value

a data frame containing information about all units present in the network.

SnnsRObject\$getUnitsByName

Find all units whose name begins with a given prefix.

# **Description**

Find all units whose name begins with a given prefix.

# Usage

```
## S4 method for signature 'SnnsR'
getUnitsByName(prefix)
```

# **Arguments**

prefix

a prefix that the names of the units to find have.

# Value

a vector with integer numbers identifying the units.

SnnsRObject\$getWeightMatrix

Get the weight matrix between two sets of units

# **Description**

SnnsR low-level function to get the weight matrix between two sets of units.

### Usage

```
## S4 method for signature 'SnnsR'
getWeightMatrix(unitsSource, unitsTarget, setDimNames)
```

### **Arguments**

unitsSource a vector with numbers identifying the source units unitsTarget a vector with numbers identifying the target units

setDimNames indicates, whether names of units are extracted and set as row/col names in the

weight matrix

### Value

the weight matrix between the two sets of neurons

#### See Also

SnnsRObject\$getAllUnitsTType

SnnsRObject\$initializeNet

Initialize the network

#### **Description**

This SnnsR low-level function masks the SNNS kernel function of the same name to allow for both giving the initialization function directly in the call or to use the one that is currently set.

# Usage

```
## S4 method for signature 'SnnsR'
initializeNet(parameterInArray, initFunc)
```

### **Arguments**

parameterInArray

the parameters of the initialization function

initFunc the name of the initialization function

SnnsRObject\$predictCurrPatSet

Predict values with a trained net

# Description

SnnsR low-level function to predict values with a trained net.

### Usage

```
## S4 method for signature 'SnnsR'
predictCurrPatSet(outputMethod="reg_class", updateFuncParams=c(0.0))
```

### **Arguments**

```
outputMethod is passed to SnnsRObject$whereAreResults updateFuncParams parameters\ passed\ to\ the\ networks\ update\ function
```

#### **Details**

This function has to be used embedded in a step of loading and afterwards removing the patterns into the SnnsR-class object. As SNNS only supports 2 pattern sets in parallel, removing unneeded pattern sets is quite important.

### Value

the predicted values

SnnsRObject\$resetRSNNS

Reset the SnnsR object.

# **Description**

SnnsR low-level function to delete all pattern sets and delete the current net in the SnnsR-class object.

# Usage

```
## S4 method for signature 'SnnsR'
resetRSNNS()
```

SnnsRObject\$setTTypeUnitsActFunc

Set the activation function for all units of a certain ttype.

# **Description**

The function uses the function SnnsRObject\$getAllUnitsTType to find all units of a certain ttype, and sets the activation function of all these units to the given activation function.

### Usage

```
## S4 method for signature 'SnnsR'
setTTypeUnitsActFunc(ttype, act_func)
```

### **Arguments**

ttype a string containing the ttype.

act\_func the name of the activation function to set.

#### See Also

```
SnnsRObject$getAllUnitsTType
```

# **Examples**

```
## Not run: SnnsRObject$setTTypeUnitsActFunc("UNIT_HIDDEN", "Act_Logistic")
```

SnnsRObject\$setUnitDefaults

Set the unit defaults

# Description

This SnnsR low-level function masks the SNNS kernel function of the same name to allow both for giving the parameters directly or as a vector. If the second parameter, bias, is missing, it is assumed that the first parameter should be interpreted as a vector containing all parameters.

# Usage

```
## S4 method for signature 'SnnsR'
setUnitDefaults(act, bias, st, subnet_no, layer_no, act_func, out_func)
```

# **Arguments**

act	same as SNNS kernel function
bias	idem
st	idem
subnet_no	idem
layer_no	idem
act_func	idem
out_func	idem

 ${\it Snns} {\it RObject\$somPredictComponentMaps} \\ {\it Calculate the som component maps}$ 

# Description

SnnsR low-level function to calculate the som component maps.

# Usage

```
## S4 method for signature 'SnnsR'
somPredictComponentMaps(updateFuncParams=c(0.0, 0.0, 1.0))
```

# Arguments

updateFuncParams

parameters passed to the networks update function

# Value

a matrix containing all componant maps as 1d vectors

### See Also

som

SnnsRObject\$somPredictCurrPatSetWinners

Get most of the relevant results from a som

# **Description**

SnnsR low-level function to get most of the relevant results from a SOM.

### Usage

```
## S4 method for signature 'SnnsR'
somPredictCurrPatSetWinners(updateFuncParams=c(0.0, 0.0, 1.0),
saveWinnersPerPattern=TRUE, targets=NULL)
```

#### **Arguments**

updateFuncParams

parameters passed to the networks update function

saveWinnersPerPattern

should a list with the winners for every pattern be saved?

targets optional target classes of the patterns

### Value

a list with three elements:

nWinnersPerUnit

For each unit, the amount of patterns where this unit won is given. So, this is a 1d vector representing the normal version of the som.

winnersPerPattern

a vector where for each pattern the number of the winning unit is given. This is an intermediary result that normally won't be saved.

labeledUnits

a matrix which — if the targets parameter is given — contains for each unit (rows) and each class present in the targets (columns), the amount of patterns of the class where the unit has won. From the labeledUnits, the labeledMap can be computed, e.g. by voting of the class labels for the final label of the unit.

#### See Also

som

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SnnsRObject\$somPredictCurrPatSetWinnersSpanTree

Get the spanning tree of the SOM

# **Description**

SnnsR low-level function to get the spanning tree of the SOM, This function calls directly the corresponding SNNS kernel function (the only one available for SOM). Advantage are faster computation, disadvantage is somewhat limited information in the output.

### Usage

```
## S4 method for signature 'SnnsR'
somPredictCurrPatSetWinnersSpanTree()
```

#### Value

the spanning tree, which is the som, showing for each unit a number identifying the last pattern for which this unit won. (We note that, also if there are more than one patterns, only the last one is saved)

#### See Also

som

SnnsRObject\$train

Train a network and test it in every training iteration

### **Description**

SnnsR low-level function to train a network and test it in every training iteration.

#### Usage

```
## S4 method for signature 'SnnsR'
train(inputsTrain, targetsTrain=NULL,
    initFunc="Randomize_Weights", initFuncParams=c(1.0, -1.0),
    learnFunc="Std_Backpropagation", learnFuncParams=c(0.2, 0),
    updateFunc="Topological_Order", updateFuncParams=c(0.0),
    outputMethod="reg_class", maxit=100, shufflePatterns=TRUE,
    computeError=TRUE, inputsTest=NULL, targetsTest=NULL,
    pruneFunc=NULL, pruneFuncParams=NULL)
```

SnnsRObject\$train 65

### **Arguments**

inputsTrain a matrix with inputs for the network

targetsTrain the corresponding targets

initFunc the initialization function to use

initFuncParams the parameters for the initialization function

learnFunc the learning function to use

learnFuncParams

the parameters for the learning function

updateFunc the update function to use

updateFuncParams

the parameters for the update function

outputMethod the output method of the net

maxit maximum of iterations to learn

shufflePatterns

should the patterns be shuffled?

computeError should the error be computed in every iteration?

inputsTest a matrix with inputs to test the network

targetsTest the corresponding targets for the test input

pruneFunc the pruning function to use

pruneFuncParams

the parameters for the pruning function. Unlike the other functions, these have to be given in a named list. See the pruning demos for further explanation.

#### Value

a list containing:

fitValues the fitted values, i.e. outputs of the training inputs

IterativeFitError

The SSE in every iteration/epoch on the training set

testValues the predicted values, i.e. outputs of the test inputs

IterativeTestError

The SSE in every iteration/epoch on the test set

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SnnsRObject\$whereAreResults

Get a list of output units of a net

### **Description**

SnnsR low-level function to get a list of output units of a net.

#### Usage

```
## S4 method for signature 'SnnsR'
whereAreResults(outputMethod="output")
```

#### **Arguments**

```
outputMethod a string defining the output method of the net. Possible values are: "art1", "art2", "artmap", "assoz", "som", "output".
```

#### **Details**

Depending on the network architecture, output is present in hidden units, in output units, etc. In some network types, the output units have a certain name prefix in SNNS. This function finds the output units according to certain network types. The type is specified by outputMethod. If the given outputMethod is unknown, the function defaults to "output".

#### Value

a list of numbers identifying the units

som

Create and train a self-organizing map (SOM)

### Description

This function creates and trains a self-organizing map (SOM). SOMs are neural networks with one hidden layer. The network structure is similar to LVQ, but the method is unsupervised and uses a notion of neighborhood between the units. The general idea is that the map develops by itself a notion of similarity among the input and represents this as spatial nearness on the map. Every hidden unit represents a prototype. The goal of learning is to distribute the prototypes in the feature space such that the (probability density of the) input is represented well. SOMs are usually built with 1d, 2d quadratic, 2d hexagonal, or 3d neighborhood, so that they can be visualized straightforwardly. The SOM implemented in SNNS has a 2d quadratic neighborhood.

As the computation of this function might be slow if many patterns are involved, much of its output is made switchable (see comments on return values).

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### Usage

```
som(x, ...)
## Default S3 method:
som(
  х,
 mapX = 16,
 mapY = 16,
 maxit = 100,
  initFuncParams = c(1, -1),
  learnFuncParams = c(0.5, mapX/2, 0.8, 0.8, mapX),
  updateFuncParams = c(0, 0, 1),
  shufflePatterns = TRUE,
  calculateMap = TRUE,
  calculateActMaps = FALSE,
  calculateSpanningTree = FALSE,
  saveWinnersPerPattern = FALSE,
  targets = NULL,
)
```

### **Arguments**

```
a matrix with training inputs for the network
                  additional function parameters (currently not used)
                  the x dimension of the som
mapX
mapY
                  the y dimension of the som
maxit
                  maximum of iterations to learn
initFuncParams the parameters for the initialization function
learnFuncParams
                  the parameters for the learning function
updateFuncParams
                  the parameters for the update function
shufflePatterns
                  should the patterns be shuffled?
calculateMap
                  should the som be calculated?
calculateActMaps
                  should the activation maps be calculated?
{\tt calculateSpanningTree}
                  should the SNNS kernel algorithm for generating a spanning tree be applied?
saveWinnersPerPattern
                  should a list with the winners for every pattern be saved?
targets
                  optional target classes of the patterns
```

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#### **Details**

Internally, this function uses the initialization function Kohonen\_Weights\_v3.2, the learning function Kohonen, and the update function Kohonen\_Order of SNNS.

#### Value

an rsnns object. Depending on which calculation flags are switched on, the som generates some special members:

map the som. For each unit, the amount of patterns where this unit won is given.

componentMaps a map for every input component, showing where in the map this component

leads to high activation.

actMaps a list containing for each pattern its activation map, i.e. all unit activations.

The actMaps are an intermediary result, from which all other results can be

computed. This list can be very long, so normally it won't be saved.

winnersPerPattern

a vector where for each pattern the number of the winning unit is given. Also,

an intermediary result that normally won't be saved.

labeledUnits a matrix which - if the targets parameter is given - contains for each unit

(rows) and each class present in the targets (columns), the amount of patterns of the class where the unit has won. From the labeledUnits, the labeledMap can be computed, e.g. by voting of the class labels for the final label of the unit.

labeledMap a labeled som that is computed from labeledUnits using decodeClassLabels.

spanningTree the result of the original SNNS function to calculate the map. For each unit,

the last pattern where this unit won is present. As the other results are more informative, the spanning tree is only interesting, if the other functions are too

slow or if the original SNNS implementation is needed.

#### References

Kohonen, T. (1988), Self-organization and associative memory, Vol. 8, Springer-Verlag.

Zell, A. et al. (1998), 'SNNS Stuttgart Neural Network Simulator User Manual, Version 4.2', IPVR, University of Stuttgart and WSI, University of Tübingen. https://www.ra.cs.uni-tuebingen.de/SNNS/welcome.html

Zell, A. (1994), Simulation Neuronaler Netze, Addison-Wesley. (in German)

# **Examples**

 ${\tt splitForTrainingAndTest}$ 

Function to split data into training and test set

### **Description**

Split the input and target values to a training and a test set. Test set is taken from the end of the data. If the data is to be shuffled, this should be done before calling this function.

### Usage

```
splitForTrainingAndTest(x, y, ratio = 0.15)
```

# **Arguments**

x inputsy targets

ratio ratio of training and test sets (default: 15% of the data is used for testing)

#### Value

a named list with the following elements:

inputsTrain a matrix containing the training inputs
targetsTrain a matrix containing the training targets
inputsTest a matrix containing the test inputs
targetsTest a matrix containing the test targets

70 summary.rsnns

### **Examples**

```
data(iris)
#shuffle the vector
iris <- iris[sample(1:nrow(iris),length(1:nrow(iris))),1:ncol(iris)]
irisValues <- iris[,1:4]
irisTargets <- decodeClassLabels(iris[,5])
splitForTrainingAndTest(irisValues, irisTargets, ratio=0.15)</pre>
```

summary.rsnns

Generic summary function for rsnns objects

# **Description**

Prints out a summary of the network. The printed information can be either all information of the network in the original SNNS file format, or the information given by extractNetInfo. This behaviour is controlled with the parameter origSnnsFormat.

# Usage

```
## S3 method for class 'rsnns'
summary(object, origSnnsFormat = TRUE, ...)
```

# **Arguments**

```
object the rsnns object
origSnnsFormat show data in SNNS's original format in which networks are saved, or show output of extractNetInfo
... additional function parameters (currently not used)
```

# Value

Either the contents of the .net file that SNNS would generate from the object, as a string. Or the output of extractNetInfo.

# See Also

```
extractNetInfo
```

toNumericClassLabels 71

toNumericClassLabels Convert a vector (of class labels) to a numeric vector

### **Description**

This function converts a vector (of class labels) to a numeric vector.

# Usage

```
toNumericClassLabels(x)
```

# **Arguments**

x inputs

# Value

the vector converted to a numeric vector

# **Examples**

```
data(iris)
toNumericClassLabels(iris[,5])
```

train

Internal generic train function for rsnns objects

# **Description**

The function calls SnnsRObject\$train and saves the result in the current rsnns object. This function is used internally by the models (e.g. mlp) for training. Unless you are not about to implement a new model on the S3 layer you most probably don't want to use this function.

# Usage

```
train(object, ...)

## S3 method for class 'rsnns'
train(
  object,
  inputsTrain,
  targetsTrain = NULL,
  inputsTest = NULL,
  targetsTest = NULL,
  serializeTrainedObject = TRUE,
  ...
)
```

72 vectorToActMap

### **Arguments**

object the rsnns object

... additional function parameters (currently not used)

inputsTrain training input
targetsTrain training targets
inputsTest test input
targetsTest test targets
serializeTrainedObject

parameter passed to SnnsRObject\$train

#### Value

an rsnns object, to which the results of training have been added.

vectorToActMap Convert a

Convert a vector to an activation map

# **Description**

Organize network activation as 2d map.

# Usage

```
vectorToActMap(v, nrow = 0, ncol = 0)
```

### **Arguments**

v the vector containing the activation pattern
nrow number of rows the resulting matrices will have
ncol number of columns the resulting matrices will have

### **Details**

The input to this function is a vector containing in each row an activation pattern/output of a neural network. This function reorganizes the vector to a matrix. Normally, only the number of rows nrow will be used.

#### Value

a matrix containing the 2d reorganized input

### See Also

matrixToActMapList plotActMap

weightMatrix 73

weightMatrix

Function to extract the weight matrix of an rsnns object

# Description

 $The function \ calls \ SnnsRObject \$getCompleteWeightMatrix \ and \ returns \ its \ result.$ 

# Usage

```
weightMatrix(object, ...)
## S3 method for class 'rsnns'
weightMatrix(object, ...)
```

# Arguments

```
object the rsnns object
... additional function parameters (currently not used)
```

# Value

a matrix with all weights from all neurons present in the net.

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