Package 'DNNSIM'

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Type Package	
Title Single-Index Neural Network for Skewed Heavy-Tailed Data	
Version 0.1.1	
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Description Provides a deep neural network model with a monotonic increasing single index function tailored for periodontal disease studies. The residuals are assumed to follow a skewed T distribution, a skewed normal distribution, or a normal distribution. More details can be found at Liu, Huang, and Bai (2024) <doi:10.1016 j.csda.2024.108012="">.</doi:10.1016>	-
License GPL (>= 3)	
Encoding UTF-8	
RdMacros Rdpack	
SystemRequirements Python (>= 3.8.0); PyTorch (https://pytorch.org/); NumPy (https://numpy.org/); SciPy (https://scipy.org/); sklearn (https://scikit-learn.org/stable/);	
RoxygenNote 7.3.2	
Imports reticulate (>= 1.37.0), stats (>= 4.3.0), Rdpack (>= 2.6)	
NeedsCompilation no	
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data_simulation	Simulate data for the DNN-SIM model

Description

Simulate data for the DNN-SIM model

Usage

```
data_simulation(n, beta, w, sigma, delta, seed)
```

Arguments

```
n an integer. The sample size.

beta a vector. The covariate coefficients.

w a number between 0 and 1. The skewness parameter.

sigma a number larger than 0. The standard deviation parameter.

delta a number larger than 0. The degree of freedom parameter.

seed an integer. The random seed.
```

Details

This is a simple data generation function for a simulation study. All elements of the design matrix X follow a uniform distribution from -3.0 and 3.0 independently and identically. The true g function is the standard logistic function.

Value

a dataframe of the simulated response variable y and the design matrix X.

References

Liu Q, Huang X, Bai R (2024). "Bayesian Modal Regression Based on Mixture Distributions." *Computational Statistics & Analysis*, 108012. doi:10.1016/j.csda.2024.108012.

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DNNSIM

The 'DNNSIM' package.

Description

Provides a deep neural network model with a monotonic increasing single index function tailored for periodontal disease studies. The residuals are assumed to follow a skewed T distribution, a skewed normal distribution, or a normal distribution. More details can be found at Liu, Huang, and Bai (2024) doi:10.1016/j.csda.2024.108012.

Value

This is the summary page. No return value.

Author(s)

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DNN_model

Define and train the DNN-SIM model

Description

Define and train the DNN-SIM model

Usage

```
DNN_model(
   formula,
   data,
   model,
   num_epochs,
   verbatim = TRUE,
   CV = FALSE,
   CV_K = 10,
   bootstrap = FALSE,
   bootstrap_B = 1000,
```

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```
bootstrap_num_epochs = 100,
U_new = FALSE,
U_min = -4,
U_max = 4,
random_state = 100
)
```

Arguments

formula an object of class "formula" (or one that can be coerced to that class): a symbolic

description of the model to be fitted.

data a data frame.

model the model type. It must be be one of "N-GX-D", "SN-GX-D", "ST-GX-D", "N-

GX-B", "SN-GX-B", "ST-GX-B", "N-FX", "SN-FX", "ST-FX".

num_epochs an integer. The number of complete passes through the training dataset.

verbatim TRUE/FALSE.If verbatim is TRUE, then log information from training the DNN-

SIM model will be printed.

CV TRUE/FALSE. Whether use the cross-validation to measure the prediction ac-

curacy.

CV_K an integer. The number of folders K-folder cross-validation.

bootstrap TRUE/FALSE. Whether use the bootstrap method to quantify the uncertainty.

The bootstrap option ONLY works for the "ST-GX-D" model.

bootstrap_B an integer. The number of bootstrap iteration.

bootstrap_num_epochs

an integer. The number of complete passes through the training dataset in the

bootstrap procedure.

U_new TRUE/FALSE. Whether use self defined U for the estimation of single index

function, g(U).

U_min a numeric value. The minimum of the self defined U.
U_max a numeric value. The maximum of the self defined U.

random_state an integer. The random seed for initiating the neural network.

Details

The DNNSIM model is defined as:

$$Y = g(\mathbf{X}\boldsymbol{\beta}) + e.$$

The residuals e follow a skewed T distribution, skewed normal distribution, or normal distribution. The single index function g is assumed to be a monotonic increasing function.

Value

A list consisting of the point estimation, g function estimation (optional), cross-validation results (optional) and bootstrap results(optional).

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References

Liu Q, Huang X, Bai R (2024). "Bayesian Modal Regression Based on Mixture Distributions." *Computational Statistics & Analysis*, 108012. doi:10.1016/j.csda.2024.108012.

Examples

```
# check python module dependencies
if (reticulate::py_module_available("torch") &
    reticulate::py_module_available("numpy") &
    reticulate::py_module_available("sklearn") &
   reticulate::py_module_available("scipy")) {
 # set the random seed
 set.seed(100)
 # simulate some data
 df1 <- data_simulation(n=100,beta=c(1,1,1),w=0.3,</pre>
                         sigma=0.1,delta=10.0,seed=100)
 # the cross-validation and bootstrap takes a long time
 DNN_model_output <- DNN_model(y \sim X1 + X2 + X3 - 1,
                                data = df1,
                                model = "ST-GX-D",
                                num_epochs = 5,
                                verbatim = FALSE,
                                CV = TRUE,
                                CV_K = 2,
                                bootstrap = TRUE,
                                bootstrap_B = 2,
                                bootstrap_num_epochs = 5,
                                U_new = TRUE,
                                U_{\min} = -4.0,
                                U_max = 4.0
 print(DNN_model_output)
}
```

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```