Package 'Riemann'

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Type Package

Title Learning with Data on Riemannian Manifolds

Version 0.1.4

Description We provide a variety of algorithms for manifold-valued data, including Fréchet summaries, hypothesis testing, clustering, visualization, and other learning tasks. See Bhattacharya and Bhattacharya (2012) <doi:10.1017/CBO9781139094764> for general exposition to statistics on manifolds.

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acg

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Angular Central Gaussian Distribution

Description

For a hypersphere S^{p-1} in \mathbf{R}^p , Angular Central Gaussian (ACG) distribution $ACG_p(A)$ is defined via a density

$$f(x|A) = |A|^{-1/2} (x^{\top} A^{-1} x)^{-p/2}$$

with respect to the uniform measure on S^{p-1} and A is a symmetric positive-definite matrix. Since f(x|A) = f(-x|A), it can also be used as an axial distribution on real projective space, which is unit sphere modulo $\{+1,-1\}$. One constraint we follow is that f(x|A) = f(x|cA) for c>0 in that we use a normalized version for numerical stability by restricting tr(A) = p.

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Usage

```
dacg(datalist, A)
racg(n, A)
mle.acg(datalist, ...)
```

Arguments

datalist a list of length-p unit-norm vectors.

A a $(p \times p)$ symmetric positive-definite matrix.

In the number of samples to be generated.

... extra parameters for computations, including

maxiter maximum number of iterations to be run (default:50).

eps tolerance level for stopping criterion (default: 1e-5).

Value

dacg gives a vector of evaluated densities given samples. racg generates unit-norm vectors in \mathbf{R}^p wrapped in a list. mle.acg estimates the SPD matrix A.

References

Tyler DE (1987). "Statistical analysis for the angular central Gaussian distribution on the sphere." *Biometrika*, **74**(3), 579–589. ISSN 0006-3444, 1464-3510.

Mardia KV, Jupp PE (eds.) (1999). *Directional Statistics*, Wiley Series in Probability and Statistics. John Wiley & Sons, Inc., Hoboken, NJ, USA. ISBN 978-0-470-31697-9 978-0-471-95333-3.

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```
image(Amle1[,5:1], axes=FALSE, main="MLE with n=50")
image(Amle2[,5:1], axes=FALSE, main="MLE with n=100")
par(opar)
```

cities

Data: Populated Cities in the U.S.

Description

As of January 2006, there are 60 cities in the contiguous U.S. with population size larger than 300000. We extracted information of the cities from the data delivered by **maps** package. Variables coord and cartesian are two identical representations of locations, which can be mutually converted by sphere.convert.

Usage

```
data(cities)
```

Format

```
a named list containing  \begin{tabular}{ll} \textbf{names} & a length-60 \ vector \ of \ city \ names. \\ \textbf{coord} & a \ (60 \times 2) \ matrix \ of \ latitude \ and \ longitude. \\ \textbf{cartesian} & a \ (60 \times 3) \ matrix \ of \ cartesian \ coordinates \ on \ the \ unit \ sphere. \\ \textbf{population} & a \ length-60 \ vector \ of \ cities' \ populations. \\ \end{tabular}
```

See Also

```
wrap.sphere
```

```
## LOAD THE DATA AND WRAP AS RIEMOBJ
data(cities)
myriem = wrap.sphere(cities$cartesian)

## COMPUTE INTRINSIC/EXTRINSIC MEANS
intmean = as.vector(riem.mean(myriem, geometry="intrinsic")$mean)
extmean = as.vector(riem.mean(myriem, geometry="extrinsic")$mean)

## CONVERT TO GEOGRAPHIC COORDINATES (Lat/Lon)
geo.int = sphere.xyz2geo(intmean)
geo.ext = sphere.xyz2geo(extmean)
```

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density

S3 method for mixture model: evaluate density

Description

Compute density for a fitted mixture model.

Usage

```
density(object, newdata)
```

Arguments

object a fitted mixture model of riemmix class.

newdata data of n objects (vectors, matrices) that can be wrapped by one of wrap.*

functions in the Riemann package.

Value

a length-n vector of class labels.

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ERP

Data: EEG Covariances for Event-Related Potentials

Description

This dataset delivers 216 covariance matrices from EEG ERPs with 4 different known classes by types of sources. Among 60 channels, only 32 channels are taken and sample covariance matrix is computed for each participant. The data is taken from a Python library mne's sample data.

Usage

```
data(ERP)
```

Format

```
a named list containing
```

covariance an $(32 \times 32 \times 216)$ array of covariance matrices.

label a length-216 factor of 4 different classes.

See Also

```
wrap.spd
```

Examples

```
## LOAD THE DATA AND WRAP AS RIEMOBJ
data(ERP)
myriem = wrap.spd(ERP$covariance)
```

gorilla

Data: Gorilla Skull

Description

This is 29 male and 30 female gorillas' skull landmark data where each individual is represented as 8-ad/landmarks in 2 dimensions. This is a re-arranged version of the data from **shapes** package.

Usage

```
data(gorilla)
```

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Format

References

Dryden IL, Mardia KV (2016). *Statistical shape analysis with applications in R*, Wiley series in probability and statistics, Second edition edition. John Wiley & Sons, Chichester, UK; Hoboken, NJ. ISBN 978-1-119-07251-5 978-1-119-07250-8.

Reno PL, Meindl RS, McCollum MA, Lovejoy CO (2003). "Sexual dimorphism in Australopithecus afarensis was similar to that of modern humans." *Proceedings of the National Academy of Sciences*, 100(16):9404–9409.

See Also

```
wrap.landmark
```

Examples

grassmann.optmacg

Estimation of Distribution Algorithm with MACG Distribution

Description

For a function $f: Gr(k, p) \to \mathbf{R}$, find the minimizer and the attained minimum value with estimation of distribution algorithm using MACG distribution.

grassmann.optmacg 9

Usage

```
grassmann.optmacg(func, p, k, ...)
```

Arguments

func a function to be minimized.
p dimension parameter as in Gr(k,p).
k dimension parameter as in Gr(k,p).
... extra parameters including
n.start number of runs; algorithm is executed n. start times (default: 10).
maxiter maximum number of iterations for each run (default: 100).
popsize the number of samples generated at each step for stochastic search (default: 100).
ratio ratio in (0,1) where top ratio*popsize samples are chosen for parameter update (default: 0.25).
print.progress a logical; if TRUE, it prints each iteration (default: FALSE).

Value

a named list containing:

cost minimized function value.

solution a $(p \times k)$ matrix that attains the cost.

```
#
               Optimization for Eigen-Decomposition
# Given (5x5) covariance matrix S, eigendecomposition is can be
# considered as an optimization on Grassmann manifold. Here,
# we are trying to find top 3 eigenvalues and compare.
## PREPARE
A = cov(matrix(rnorm(100*5), ncol=5)) # define covariance
myfunc <- function(p){</pre>
                                    # cost function to minimize
  return(sum(-diag(t(p)%*%A%*%p)))
## SOLVE THE OPTIMIZATION PROBLEM
Aout = grassmann.optmacg(myfunc, p=5, k=3, popsize=100, n.start=30)
## COMPUTE EIGENVALUES
# 1. USE SOLUTIONS TO THE ABOVE OPTIMIZATION
       = Aout$solution
eig3sol = sort(diag(t(abase)%*%A%*%abase), decreasing=TRUE)
# 2. USE BASIC 'EIGEN' FUNCTION
```

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grassmann.runif

Generate Uniform Samples on Grassmann Manifold

Description

It generates n random samples from Grassmann manifold Gr(k, p).

Usage

```
grassmann.runif(n, k, p, type = c("list", "array", "riemdata"))
```

Arguments

```
n number of samples to be generated.

k dimension of the subspace.

p original dimension (of the ambient space).

type return type;

"list" a length-n list of (p \times k) basis of k-subspaces.

"array" a (p \times k \times n) 3D array whose slices are k-subspace basis.

"riemdata" a S3 object. See wrap. grassmann for more details.
```

Value

an object from one of the above by type option.

References

Chikuse Y (2003). *Statistics on Special Manifolds*, volume 174 of *Lecture Notes in Statistics*. Springer New York, New York, NY. ISBN 978-0-387-00160-9 978-0-387-21540-2.

See Also

```
stiefel.runif, wrap.grassmann
```

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Examples

```
#------
# Draw Samples on Grassmann Manifold
#------
# Multiple Return Types with 3 Observations of 5-dim subspaces in R^10
dat.list = grassmann.runif(n=3, k=5, p=10, type="list")
dat.arr3 = grassmann.runif(n=3, k=5, p=10, type="array")
dat.riem = grassmann.runif(n=3, k=5, p=10, type="riemdata")
```

grassmann.utest

Test of Uniformity on Grassmann Manifold

Description

Given the data on Grassmann manifold Gr(k, p), it tests whether the data is distributed uniformly.

Usage

```
grassmann.utest(grobj, method = c("Bing", "BingM"))
```

Arguments

grobj a S3 "riemdata" class of Grassmann-valued data.
method (case-insensitive) name of the test method containing

"Bing" Bingham statistic.

"BingM" modified Bingham statistic with better order of error.

Value

a (list) object of S3 class htest containing:

statistic a test statistic.

p.value p-value under H_0 .

alternative alternative hypothesis.

method name of the test.

data.name name(s) of provided sample data.

References

Chikuse Y (2003). *Statistics on Special Manifolds*, volume 174 of *Lecture Notes in Statistics*. Springer New York, New York, NY. ISBN 978-0-387-00160-9 978-0-387-21540-2.

Mardia KV, Jupp PE (eds.) (1999). *Directional Statistics*, Wiley Series in Probability and Statistics. John Wiley & Sons, Inc., Hoboken, NJ, USA. ISBN 978-0-470-31697-9 978-0-471-95333-3.

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See Also

```
wrap.grassmann
```

Examples

```
#-----
   Compare Bingham's original and modified versions of the test
# Test 1. sample uniformly from Gr(2,4)
# Test 2. use perturbed principal components from 'iris' data in R^4
         which is concentrated around a point to reject H0.
## Data Generation
# 1. uniform data
myobj1 = grassmann.runif(n=100, k=2, p=4)
# 2. perturbed principal components
data(iris)
irdat = list()
for (n in 1:100){
  tmpdata = iris[1:50,1:4] + matrix(rnorm(50*4,sd=0.5),ncol=4)
  irdat[[n]] = eigen(cov(tmpdata))$vectors[,1:2]
myobj2 = wrap.grassmann(irdat)
## Test 1 : uniform data
grassmann.utest(myobj1, method="Bing")
grassmann.utest(myobj1, method="BingM")
## Tests : iris data
grassmann.utest(myobj2, method="bINg") # method names are
grassmann.utest(myobj2, method="BiNgM") # CASE - INSENSITIVE !
```

hands

Data: Left Hands

Description

This dataset contains 10 shapes of 4 subjects's left hands where each shape is represented by 56 landmark points. For each person, first six shapes are equally spaced sequence from maximally to minimally spread fingures. The rest are arbitrarily chosen with two constraints; (1) the palm should face the support and (2) the contour should contain no crossins.

Usage

```
data(hands)
```

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Format

```
a named list containing {\bf data} \ \ {\rm an} \ (56\times 2\times 40) \ {\rm array} \ {\rm of} \ {\rm landmarks} \ {\rm for} \ 40 \ {\rm subjects}. {\bf person} \ \ {\rm alength} \ -40 \ {\rm vector} \ {\rm of} \ {\rm subject} \ {\rm indices}.
```

References

Stegmann M, Gomez D (2002) "A Brief Introduction to Statistical Shape Analysis." *Informatics and Mathematical Modelling, Technical University of Denmark, DTU.*

See Also

```
wrap.landmark
```

Examples

```
## LOAD THE DATA
data(hands)

## VISUALIZE 6 HANDS OF PERSON 1
opar <- par(no.readonly=TRUE)
par(mfrow=c(2,3))
for (i in 1:6){
    xx = hands$data[,1,i]
    yy = hands$data[,2,i]
    plot(xx,yy,"b", cex=0.9)
}
par(opar)</pre>
```

label

S3 method for mixture model: predict labels

Description

Given a fitted mixture model of K components, predict labels of observations accordingly.

Usage

```
label(object, newdata)
```

Arguments

object a fitted mixture model of riemmix class.

newdata data of n objects (vectors, matrices) that can be wrapped by one of wrap.*

functions in the Riemann package.

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Value

a length-n vector of class labels.

Examples

loglkd

S3 method for mixture model: log-likelihood

Description

Given a fitted mixture model f(x) and observations $x_1, \ldots, x_n \in \mathcal{M}$, compute the log-likelihood

$$L = \log \prod_{i=1}^{n} f(x_i) = \sum_{i=1}^{n} \log f(x_i)$$

•

Usage

```
loglkd(object, newdata)
```

Arguments

object a fitted mixture model of riemmix class.

newdata data of n objects (vectors, matrices) that can be wrapped by one of wrap.*

functions in the Riemann package.

Value

the log-likelihood.

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Examples

macg

Matrix Angular Central Gaussian Distribution

Description

For Stiefel and Grassmann manifolds St(r,p) and Gr(r,p), the matrix variant of ACG distribution is known as Matrix Angular Central Gaussian (MACG) distribution $MACG_{p,r}(\Sigma)$ with density

$$f(X|\Sigma) = |\Sigma|^{-r/2} |X^{\top} \Sigma^{-1} X|^{-p/2}$$

where Σ is a $(p \times p)$ symmetric positive-definite matrix. Similar to vector-variate ACG case, we follow a convention that $tr(\Sigma) = p$.

Usage

```
dmacg(datalist, Sigma)
rmacg(n, r, Sigma)
mle.macg(datalist, ...)
```

Arguments

datalist a list of $(p \times r)$ orthonormal matrices. Sigma a $(p \times p)$ symmetric positive-definite matrix. n the number of samples to be generated.

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r the number of basis.

extra parameters for computations, including
maxiter maximum number of iterations to be run (default:50).
eps tolerance level for stopping criterion (default: 1e-5).

Value

dmacg gives a vector of evaluated densities given samples. rmacg generates $(p \times r)$ orthonormal matrices wrapped in a list. mle.macg estimates the SPD matrix Σ .

References

Chikuse Y (1990). "The matrix angular central Gaussian distribution." *Journal of Multivariate Analysis*, **33**(2), 265–274. ISSN 0047259X.

Mardia KV, Jupp PE (eds.) (1999). *Directional Statistics*, Wiley Series in Probability and Statistics. John Wiley & Sons, Inc., Hoboken, NJ, USA. ISBN 978-0-470-31697-9 978-0-471-95333-3.

Kent JT, Ganeiber AM, Mardia KV (2013). "A new method to simulate the Bingham and related distributions in directional data analysis with applications." *arXiv:1310.8110*.

See Also

acg

```
-----
         Example with Matrix Angular Central Gaussian Distribution
# Given a fixed Sigma, generate samples and estimate Sigma via ML.
# ------
## GENERATE AND MLE in St(2,5)/Gr(2,5)
# Generate data
Strue = diag(5)
                           # true SPD matrix
sam1 = rmacg(n=50, r=2, Strue) # random samples
sam2 = rmacg(n=100, r=2, Strue) # random samples
# MLE
Smle1 = mle.macg(sam1)
Smle2 = mle.macg(sam2)
# Visualize
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,3), pty="s")
image(Strue[,5:1], axes=FALSE, main="true SPD")
image(Smle1[,5:1], axes=FALSE, main="MLE with n=50")
image(Smle2[,5:1], axes=FALSE, main="MLE with n=100")
par(opar)
```

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moSL

Finite Mixture of Spherical Laplace Distributions

Description

For n observations on a (p-1) sphere in \mathbf{R}^p , a finite mixture model is fitted whose components are spherical Laplace distributions via the following model

$$f(x; \{w_k, \mu_k, \sigma_k\}_{k=1}^K) = \sum_{k=1}^K w_k SL(x; \mu_k, \sigma_k)$$

with parameters w_k 's for component weights, μ_k 's for component locations, and σ_k 's for component scales.

Usage

```
moSL(
  data,
  k = 2,
  same.sigma = FALSE,
  variants = c("soft", "hard", "stochastic"),
  ...
)

## S3 method for class 'moSL'
loglkd(object, newdata)

## S3 method for class 'moSL'
label(object, newdata)

## S3 method for class 'moSL'
density(object, newdata)
```

Arguments

data	data vectors in form of either an $(n \times p)$ matrix or a length- n list. See wrap. sphere for descriptions on supported input types.
k	the number of clusters (default: 2).
same.sigma	a logical; TRUE to use same scale parameter across all components, or \ensuremath{FALSE} otherwise.
variants	$type\ of\ the\ class\ assignment\ methods, one\ of\ "\verb soft" ,"hard", and\ "\verb stochastic" .$
	extra parameters including
	maxiter the maximum number of iterations (default: 50).
	eps stopping criterion for the EM algorithm (default: 1e-6).
	printer a logical; TRUE to show history of the algorithm, FALSE otherwise.

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object a fitted moSL model from the moSL function.

newdata data vectors in form of either an $(m \times p)$ matrix or a length-m list. See wrap. sphere

for descriptions on supported input types.

Value

a named list of S3 class riemmix containing

cluster a length-n vector of class labels (from 1:k).

loglkd log likelihood of the fitted model.

criteria a vector of information criteria.

parameters a list containing proportion, location, and scale. See the section for more details.

membership an $(n \times k)$ row-stochastic matrix of membership.

Parameters of the fitted model

A fitted model is characterized by three parameters. For k-mixture model on a (p-1) sphere in \mathbf{R}^p , (1) proportion is a length-k vector of component weight that sums to 1, (2) location is an $(k \times p)$ matrix whose rows are per-cluster locations, and (3) concentration is a length-k vector of scale parameters for each component.

Note on S3 methods

There are three S3 methods; loglkd, label, and density. Given a random sample of size m as newdata, (1) loglkd returns a scalar value of the computed log-likelihood, (2) label returns a length-m vector of cluster assignments, and (3) density evaluates densities of every observation according of the model fit.

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```
plot(embed2, col=k2$cluster, pch=19, main="K=2")
plot(embed2, col=k3$cluster, pch=19, main="K=3")
plot(embed2, col=k4$cluster, pch=19, main="K=4")
par(opar)

# ------ #

# USE S3 METHODS
# ------ #

# Use the same 'locations' data as new data
# (1) log-likelihood
newloglkd = round(loglkd(k3, locations), 5)
fitloglkd = round(k3$loglkd, 5)
print(paste0("Log-likelihood for K=3 fitted : ", fitloglkd))
print(paste0("Log-likelihood for K=3 predicted : ", newloglkd))

# (2) label
newlabel = label(k3, locations)

# (3) density
newdensity = density(k3, locations)
```

moSN

Finite Mixture of Spherical Normal Distributions

Description

For n observations on a (p-1) sphere in \mathbf{R}^p , a finite mixture model is fitted whose components are spherical normal distributions via the following model

$$f(x; \{w_k, \mu_k, \lambda_k\}_{k=1}^K) = \sum_{k=1}^K w_k SN(x; \mu_k, \lambda_k)$$

with parameters w_k 's for component weights, μ_k 's for component locations, and λ_k 's for component concentrations.

Usage

```
moSN(
   data,
   k = 2,
   same.lambda = FALSE,
   variants = c("soft", "hard", "stochastic"),
   ...
)

## S3 method for class 'moSN'
loglkd(object, newdata)
```

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```
## S3 method for class 'moSN'
label(object, newdata)
## S3 method for class 'moSN'
density(object, newdata)
```

Arguments

data vectors in form of either an $(n \times p)$ matrix or a length-n list. See wrap. sphere

for descriptions on supported input types.

k the number of clusters (default: 2).

same.lambda a logical; TRUE to use same concentration parameter across all components, or

FALSE otherwise.

variants type of the class assignment methods, one of "soft", "hard", and "stochastic".

... extra parameters including

maxiter the maximum number of iterations (default: 50). **eps** stopping criterion for the EM algorithm (default: 1e-6).

printer a logical; TRUE to show history of the algorithm, FALSE otherwise.

object a fitted moSN model from the moSN function.

newdata data vectors in form of either an $(m \times p)$ matrix or a length-m list. See wrap. sphere

for descriptions on supported input types.

Value

a named list of S3 class riemmix containing

cluster a length-n vector of class labels (from 1:k).

loglkd log likelihood of the fitted model.

criteria a vector of information criteria.

parameters a list containing proportion, center, and concentration. See the section for more details.

membership an $(n \times k)$ row-stochastic matrix of membership.

Parameters of the fitted model

A fitted model is characterized by three parameters. For k-mixture model on a (p-1) sphere in \mathbf{R}^p , (1) proportion is a length-k vector of component weight that sums to 1, (2) center is an $(k \times p)$ matrix whose rows are cluster centers, and (3) concentration is a length-k vector of concentration parameters for each component.

Note on S3 methods

There are three S3 methods; loglkd, label, and density. Given a random sample of size m as newdata, (1) loglkd returns a scalar value of the computed log-likelihood, (2) label returns a length-m vector of cluster assignments, and (3) density evaluates densities of every observation according of the model fit.

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References

You K, Suh C (2022). "Parameter Estimation and Model-Based Clustering with Spherical Normal Distribution on the Unit Hypersphere." *Computational Statistics* & *Data Analysis*, 107457. ISSN 01679473.

```
# ----- #
      FITTING THE MODEL
# ----- #
# Load the 'city' data and wrap as 'riemobj'
data(cities)
locations = cities$cartesian
embed2 = array(0,c(60,2))
for (i in 1:60){
  embed2[i,] = sphere.xyz2geo(locations[i,])
# Fit the model with different numbers of clusters
k2 = moSN(locations, k=2)
k3 = moSN(locations, k=3)
k4 = moSN(locations, k=4)
# Visualize
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,3))
plot(embed2, col=k2$cluster, pch=19, main="K=2")
plot(embed2, col=k3$cluster, pch=19, main="K=3")
plot(embed2, col=k4$cluster, pch=19, main="K=4")
par(opar)
# ----- #
               USE S3 METHODS
# ----- #
# Use the same 'locations' data as new data
# (1) log-likelihood
newloglkd = round(loglkd(k3, locations), 3)
print(paste0("Log-likelihood for K=3 model fit : ", newloglkd))
# (2) label
newlabel = label(k3, locations)
# (3) density
newdensity = density(k3, locations)
```

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Description

The 9 planets in our solar system are evolving the sun via their own orbits. This data provides normal vector of the orbital planes. Normal vectors are unit-norm vectors, so that they are thought to reside on 2-dimensional sphere.

Usage

```
data(orbital)
```

Format

an (9×3) matrix where each row is a normal vector for a planet.

See Also

```
wrap.sphere
```

Examples

```
## LOAD THE DATA AND WRAP AS RIEMOBJ
data(orbital)
myorb = wrap.sphere(orbital)

## VISUALIZE
mds2d = riem.mds(myorb)$embed
opar <- par(no.readonly=TRUE)
plot(mds2d, main="9 Planets", pch=19, xlab="x", ylab="y")
par(opar)</pre>
```

passiflora

Data: Passiflora Leaves

Description

Passiflora is a genus of about 550 species of flowering plants. This dataset contains 15 landmarks in 2 dimension of 3319 leaves of 40 species. Papers listed in the reference section analyzed the data and found 7 clusters.

Usage

```
data(passiflora)
```

Format

```
a named list containing data a 3d array of size (15 \times 2 \times 3319). species a length-3319 vector of 40 species factors. class a length-3319 vector of 7 cluster factors.
```

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References

Chitwood DH, Otoni WC (2017). "Divergent leaf shapes among Passiflora species arise from a shared juvenile morphology." *Plant Direct*, **1**(5), e00028. ISSN 24754455.

Chitwood DH, Otoni WC (2017). "Morphometric analysis of Passiflora leaves: the relationship between landmarks of the vasculature and elliptical Fourier descriptors of the blade." *GigaScience*, **6**(1). ISSN 2047-217X.

See Also

```
wrap.landmark
```

Examples

predict.m2skreg

Prediction for Manifold-to-Scalar Kernel Regression

Description

Given new observations $X_1, X_2, \dots, X_M \in \mathcal{M}$, plug in the data with respect to the fitted model for prediction.

Usage

```
## S3 method for class 'm2skreg'
predict(object, newdata, geometry = c("intrinsic", "extrinsic"), ...)
```

Arguments

```
object an object of m2skreg class. See riem.m2skreg for more details. newdata a S3 "riemdata" class for manifold-valued data corresponding to X_1, \ldots, X_M. geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry. ... further arguments passed to or from other methods.
```

Value

a length-M vector of predictted values.

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See Also

```
riem.m2skreg
```

Examples

```
Example on Sphere S^2
#
# X: equi-spaced points from (0,0,1) to (0,1,0)
\# y : sin(x) with perturbation
\# Our goal is to check whether the predict function works well
# by comparing the originally predicted values vs. those of the same data.
#-----
# GENERATE DATA
npts = 100
nlev = 0.25
thetas = seq(from=0, to=pi/2, length.out=npts)
Xstack = cbind(rep(0,npts), sin(thetas), cos(thetas))
Xriem = wrap.sphere(Xstack)
ytrue = sin(seq(from=0, to=2*pi, length.out=npts))
ynoise = ytrue + rnorm(npts, sd=nlev)
# FIT & PREDICT
obj_fit = riem.m2skreg(Xriem, ynoise, bandwidth=0.01)
yval_fits = obj_fit$ypred
yval_pred = predict(obj_fit, Xriem)
# VISUALIZE
xgrd <- 1:npts
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,2))
plot(xgrd, yval_fits, pch=19, cex=0.5, "b", xlab="", ylim=c(-2,2), main="original fit")
lines(xgrd, ytrue, col="red", lwd=1.5)
plot(xgrd, yval_pred, pch=19, cex=0.5, "b", xlab="", ylim=c(-2,2), main="from 'predict'")
lines(xgrd, ytrue, col="red", lwd=1.5)
par(opar)
```

riem.clrq

Competitive Learning Riemannian Quantization

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, perform clustering via Competitive Learning Riemannian Quantization (CLRQ). Originally, the algorithm is designed for finding voronoi cells that

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are used in domain quantization. Given the discrete measure of data, centers of the cells play a role of cluster centers and data are labeled accordingly based on the distance to voronoi centers. For an iterative update of centers, gradient descent algorithm adapted for the Riemannian manifold setting is used with the gain factor sequence

$$\gamma_t = \frac{a}{1 + b\sqrt{t}}$$

where two parameters a, b are represented by par.a and par.b. For initialization, we provide k-means++ and random seeding options as in k-means.

Usage

```
riem.clrq(riemobj, k = 2, init = c("plus", "random"), gain.a = 1, gain.b = 1)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data. k the number of clusters. init (case-insensitive) name of an initialization scheme. (default: "plus".) gain.a parameter a for gain factor sequence. gain.b parameter b for gain factor sequence.

Value

a named list containing

centers a 3d array where each slice along 3rd dimension is a matrix representation of class centers. **cluster** a length-N vector of class labels (from 1:k).

References

Le Brigant A, Puechmorel S (2019). "Quantization and clustering on Riemannian manifolds with an application to air traffic analysis." *Journal of Multivariate Analysis*, **173**, 685–703. ISSN 0047259X.

Bonnabel S (2013). "Stochastic Gradient Descent on Riemannian Manifolds." *IEEE Transactions on Automatic Control*, **58**(9), 2217–2229. ISSN 0018-9286, 1558-2523.

See Also

riem.kmeans

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```
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)
## CLRQ WITH K=2,3,4
clust2 = riem.clrq(myriem, k=2)
clust3 = riem.clrq(myriem, k=3)
clust4 = riem.clrq(myriem, k=4)
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(2,2), pty="s")
plot(mds2d, pch=19, main="true label", col=mylabs)
plot(mds2d, pch=19, main="K=2", col=clust2$cluster)
plot(mds2d, pch=19, main="K=3", col=clust3$cluster)
plot(mds2d, pch=19, main="K=4", col=clust4$cluster)
par(opar)
```

riem.coreset18B

Build Lightweight Coreset

Description

Given manifold-valued data $X_1, X_2, \dots, X_N \in \mathcal{M}$, this algorithm finds the coreset of size M that can be considered as a compressed representation according to the lightweight coreset construction scheme proposed by the reference below.

Usage

```
riem.coreset18B(
  riemobj,
  M = length(riemobj$data)/2,
  geometry = c("intrinsic", "extrinsic"),
```

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```
) ..
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

M the size of coreset (default: N/2).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

... extra parameters including

maxiter maximum number of iterations to be run (default:50).

eps tolerance level for stopping criterion (default: 1e-5).

Value

a named list containing

 ${f coreid}$ a length- ${\cal M}$ index vector of the coreset.

weight a length-M vector of weights for each element.

References

Bachem O, Lucic M, Krause A (2018). "Scalable k -Means Clustering via Lightweight Coresets." In *Proceedings of the 24th ACM SIGKDD International Conference on Knowledge Discovery* & *Data Mining*, 1119–1127. ISBN 978-1-4503-5552-0.

```
Example on Sphere : a dataset with three types
# * 10 perturbed data points near (1,0,0) on S^2 in R^3
# * 10 perturbed data points near (0,1,0) on S^2 in R^3
# * 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
```

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```
## MDS FOR VISUALIZATION
embed2 = riem.mds(myriem, ndim=2)$embed
## FIND CORESET OF SIZES 3, 6, 9
core1 = riem.coreset18B(myriem, M=3)
core2 = riem.coreset18B(myriem, M=6)
core3 = riem.coreset18B(myriem, M=9)
col1 = rep(1,30); col1[core1$coreid] = 2
col2 = rep(1,30); col2[core2$coreid] = 2
col3 = rep(1,30); col3[core3$coreid] = 2
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,3), pty="s")
plot(embed2, pch=19, col=col1, main="coreset size=3")
plot(embed2, pch=19, col=col2, main="coreset size=6")
plot(embed2, pch=19, col=col3, main="coreset size=9")
par(opar)
```

riem.distlp

Distance between Two Curves on Manifolds

Description

Given two curves $\gamma_1, \gamma_2 : I \to \mathcal{M}$, we are interested in measuring the discrepancy of two curves. Usually, data are given as discrete observations so we are offering several methods to perform the task. See the section below for detailed description.

Usage

```
riem.distlp(
  riemobj1,
  riemobj2,
  vect = NULL,
  geometry = c("intrinsic", "extrinsic"),
  ...
)
```

Arguments

```
riemobj1 a S3 "riemdata" class for N manifold-valued data along the curve.

riemobj2 a S3 "riemdata" class for N manifold-valued data along the curve.

vect a vector of domain values. If given Null (default), sequence 1:N is set.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.
```

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... extra parameters including **p** an exponent (default: 2).

Value

the distance value.

Default Method

Trapezoidal Approximation Assume $\gamma_1(t_i) = X_i$ and $\gamma_2(t_i) = Y_i$ for i = 1, 2, ..., N. In the Euclidean space, L_p distance between two scalar-valued functions is defined as

$$L_p^p(\gamma_1(x), \gamma_2(x)) = \int_{\mathcal{X}} |\gamma_1(x) - \gamma_2(x)|^p dx$$

. We extend this approach to manifold-valued curves

$$L_p^p(\gamma_1(t),\gamma_2(t)) = \int_{t \in I} d^p(\gamma_1(t),\gamma_2(t)) dt$$

where $d(\cdot, \cdot)$ is an intrinsic/extrinsic distance on manifolds. With the given representations, the above integral is approximated using trapezoidal rule.

```
#
                         Curves on Sphere
#
 curve1 : y = 0.5*cos(x) on the tangent space at (0,0,1)
# curve2 : y = 0.5*cos(x) on the tangent space at (0,0,1)
  curve3 : y = 0.5*sin(x) on the tangent space at (0,0,1)
# * distance between curve1 & curve2 should be close to 0.
# * distance between curve1 & curve3 should be large.
#-----
## GENERATION
vecx = seg(from=-0.9, to=0.9, length.out=50)
vecy1 = 0.5*cos(vecx) + rnorm(50, sd=0.05)
vecy2 = 0.5*cos(vecx) + rnorm(50, sd=0.05)
vecy3 = 0.5*sin(vecx) + rnorm(50, sd=0.05)
## WRAP AS RIEMOBJ
mat1 = cbind(vecx, vecy1, 1); mat1 = mat1/sqrt(rowSums(mat1^2))
mat2 = cbind(vecx, vecy2, 1); mat2 = mat2/sqrt(rowSums(mat2^2))
mat3 = cbind(vecx, vecy3, 1); mat3 = mat3/sqrt(rowSums(mat3^2))
rcurve1 = wrap.sphere(mat1)
rcurve2 = wrap.sphere(mat2)
rcurve3 = wrap.sphere(mat3)
## COMPUTE DISTANCES
riem.distlp(rcurve1, rcurve2, vect=vecx)
riem.distlp(rcurve1, rcurve3, vect=vecx)
```

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riem.dtw

Dynamic Time Warping Distance

Description

Given two time series - a query $X = (X_1, X_2, \dots, X_N)$ and a reference $Y = (Y_1, Y_2, \dots, Y_M)$, riem. dtw computes the most basic version of Dynamic Time Warping (DTW) distance between two series using a symmetric step pattern, meaning no window constraints and others at all. Although the scope of DTW in Euclidean space-valued objects is rich, it is scarce for manifold-valued curves. If you are interested in the topic, we refer to **dtw** package.

Usage

```
riem.dtw(riemobj1, riemobj2, geometry = c("intrinsic", "extrinsic"))
```

Arguments

riemobj1 a S3 "riemdata" class for M manifold-valued data along the curve. riemobj2 a S3 "riemdata" class for N manifold-valued data along the curve. geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

Value

the distance value.

```
#
                          Curves on Sphere
#
# curve1 : y = 0.5*cos(x) on the tangent space at (0,0,1)
#
  curve2 : y = 0.5*sin(x) on the tangent space at (0,0,1)
  we will generate two sets for curves of different sizes.
## GENERATION
clist = list()
for (i in 1:10){ # curve type 1
  vecx = seq(from=-0.9, to=0.9, length.out=sample(10:50, 1))
  vecy = 0.5*cos(vecx) + rnorm(length(vecx), sd=0.1)
  mats = cbind(vecx, vecy, 1)
  clist[[i]] = wrap.sphere(mats/sqrt(rowSums(mats^2)))
for (i in 1:10){ # curve type 2
  vecx = seq(from=-0.9, to=0.9, length.out=sample(10:50, 1))
  vecy = 0.5*sin(vecx) + rnorm(length(vecx), sd=0.1)
```

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```
mats = cbind(vecx, vecy, 1)
 clist[[i+10]] = wrap.sphere(mats/sqrt(rowSums(mats^2)))
}
## COMPUTE DISTANCES
outint = array(0,c(20,20))
outext = array(0,c(20,20))
for (i in 1:19){
 for (j in 2:20){
    outint[i,j] <- outint[j,i] <- riem.dtw(clist[[i]], clist[[j]],</pre>
                                             geometry="intrinsic")
   outext[i,j] <- outext[j,i] <- riem.dtw(clist[[i]], clist[[j]],</pre>
                                             geometry="extrinsic")
}
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,2), pty="s")
image(outint[,20:1], axes=FALSE, main="intrinsic DTW Distance")
image(outext[,20:1], axes=FALSE, main="extrinsic DTW Distance")
par(opar)
```

riem.fanova

Fréchet Analysis of Variance

Description

Given sets of manifold-valued data $X_{1:n_1}^{(1)}, X_{1:n_2}^{(2)}, \ldots, X_{1:n_m}^{(m)}$, performs analysis of variance to test equality of distributions. This means, small p-value implies that at least one of the equalities does not hold.

Usage

```
riem.fanova(..., maxiter = 50, eps = 1e-05)
riem.fanovaP(..., maxiter = 50, eps = 1e-05, nperm = 99)
```

Arguments

... S3 objects of riemdata class for manifold-valued data.

maxiter maximum number of iterations to be run.
eps tolerance level for stopping criterion.

nperm the number of permutations for resampling-based test.

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Value

```
a (list) object of S3 class htest containing: 

statistic a test statistic.

p.value p-value under H_0.

alternative alternative hypothesis.

method name of the test.

data.name name(s) of provided sample data.
```

References

Dubey P, Müller H (2019). "Fréchet analysis of variance for random objects." *Biometrika*, **106**(4), 803–821. ISSN 0006-3444, 1464-3510.

```
#-----
#
           Example on Sphere : Uniform Samples
#
# Each of 4 classes consists of 20 uniform samples from uniform
# density on 2-dimensional sphere S^2 in R^3.
## PREPARE DATA OF 4 CLASSES
ndata = 200
class1 = list()
class2 = list()
class3 = list()
class4 = list()
for (i in 1:ndata){
 tmpxy = matrix(rnorm(4*2, sd=0.1), ncol=2)
 tmpz = rep(1,4)
 tmp3d = cbind(tmpxy, tmpz)
 tmp = tmp3d/sqrt(rowSums(tmp3d^2))
 class1[[i]] = tmp[1,]
 class2[[i]] = tmp[2,]
 class3[[i]] = tmp[3,]
 class4[[i]] = tmp[4,]
obj1 = wrap.sphere(class1)
obj2 = wrap.sphere(class2)
obj3 = wrap.sphere(class3)
obj4 = wrap.sphere(class4)
## RUN THE ASYMPTOTIC TEST
riem.fanova(obj1, obj2, obj3, obj4)
## RUN THE PERMUTATION TEST WITH MANY PERMUTATIONS
riem.fanovaP(obj1, obj2, obj3, obj4, nperm=999)
```

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riem.hclust

Hierarchical Agglomerative Clustering

Description

Given N observations $X_1, X_2, \dots, X_M \in \mathcal{M}$, perform hierarchical agglomerative clustering with **fastcluster** package's implementation.

Usage

```
riem.hclust(
  riemobj,
  geometry = c("intrinsic", "extrinsic"),
  method = c("single", "complete", "average", "mcquitty", "ward.D", "ward.D2",
        "centroid", "median"),
  members = NULL
)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

method agglomeration method to be used. This must be one of "single", "complete", "average", "mcquitty", "ward.D", "ward.D2", "centroid" or "median".

members NULL or a vector whose length equals the number of observations. See hclust

for details.

Value

an object of class helust. See helust for details.

References

Müllner D (2013). "fastcluster: Fast Hierarchical, Agglomerative Clustering Routines for R and Python." *Journal of Statistical Software*, **53**(9). ISSN 1548-7660.

```
#-----
# Example on Sphere : a dataset with three types
#
# class 1 : 10 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 10 perturbed data points near (0,1,0) on S^2 in R^3
```

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```
# class 3 : 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
  tgt = c(1, stats::rnorm(2, sd=0.1))
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
  tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
  tgt = c(stats::rnorm(2, sd=0.1), 1)
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
## COMPUTE SINGLE AND COMPLETE LINKAGE
hc.sing <- riem.hclust(myriem, method="single")</pre>
hc.comp <- riem.hclust(myriem, method="complete")</pre>
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,2))
plot(hc.sing, main="single linkage")
plot(hc.comp, main="complete linkage")
par(opar)
```

riem.interp

Geodesic Interpolation

Description

Given 2 observations $X_1, X_2 \in \mathcal{M}$, find the interpolated point of a geodesic $\gamma(t)$ for $t \in (0,1)$ which assumes two endpoints $\gamma(0) = X_1$ and $\gamma(1) = X_2$.

Usage

```
riem.interp(riemobj, t = 0.5, geometry = c("intrinsic", "extrinsic"))
```

Arguments

riemobj a S3 "riemdata" class for 2 manifold-valued data where the first object is the

starting point.

t a scalar in (0,1) for which the interpolation is taken.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embed-

ded ("extrinsic") geometry.

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Value

an interpolated object in matrix representation on \mathcal{M} .

Examples

```
Geodesic Interpolation between (1,0) and (0,1) in S<sup>1</sup>
## PREPARE DATA
sp.start = c(1,0)
sp.end = c(0,1)
sp.data = wrap.sphere(rbind(sp.start, sp.end))
## FIND THE INTERPOLATED POINT AT "t=0.25"
mid.int = as.vector(riem.interp(sp.data, t=0.25, geometry="intrinsic"))
mid.ext = as.vector(riem.interp(sp.data, t=0.25, geometry="extrinsic"))
## VISUALIZE
# Prepare Lines and Points
thetas = seq(from=0, to=pi/2, length.out=100)
quarter = cbind(cos(thetas), sin(thetas))
pic.pts = rbind(sp.start, mid.int, mid.ext, sp.end)
pic.col = c("black","red","green","black")
# Draw
opar <- par(no.readonly=TRUE)</pre>
par(pty="s")
plot(quarter, main="two interpolated points at t=0.25",
     xlab="x", ylab="y", type="l")
points(pic.pts, col=pic.col, pch=19)
text(mid.int[1]-0.1, mid.int[2], "intrinsic", col="red")
text(mid.ext[1]-0.1, mid.ext[2], "extrinsic", col="green")
par(opar)
```

riem.interps

Geodesic Interpolation of Multiple Points

Description

Given 2 observations $X_1, X_2 \in \mathcal{M}$, find the interpolated points of a geodesic $\gamma(t)$ for $t \in (0,1)$ which assumes two endpoints $\gamma(0) = X_1$ and $\gamma(1) = X_2$.

Usage

```
riem.interps(
  riemobj,
  vect = c(0.25, 0.5, 0.75),
  geometry = c("intrinsic", "extrinsic")
)
```

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Arguments

riemobj a S3 "riemdata" class for 2 manifold-valued data where the first object is the starting point.

vect a length-T vector in (0,1) for which the interpolations are taken.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

Value

a 3d array where T slices along 3rd dimension are interpolated objects in matrix representation.

```
Geodesic Interpolation between (1,0) and (0,1) in S^1
## PREPARE DATA
sp.start = c(1,0)
sp.end = c(0,1)
sp.data = wrap.sphere(rbind(sp.start, sp.end))
## FIND THE INTERPOLATED POINT AT FOR t=0.1, 0.2, ..., 0.9.
myvect = seq(from=0.1, to=0.9, by=0.1)
geo.int = riem.interps(sp.data, vect=myvect, geometry="intrinsic")
geo.ext = riem.interps(sp.data, vect=myvect, geometry="extrinsic")
geo.int = matrix(geo.int, byrow=TRUE, ncol=2) # re-arrange for plotting
geo.ext = matrix(geo.ext, byrow=TRUE, ncol=2)
## VISUALIZE
# Prepare Lines and Points
thetas = seq(from=0, to=pi/2, length.out=100)
quarter = cbind(cos(thetas), sin(thetas))
pts.int = rbind(sp.start, geo.int, sp.end)
pts.ext = rbind(sp.start, geo.ext, sp.end)
col.int = c("black", rep("red",9), "black")
col.ext = c("black", rep("blue",9), "black")
# Draw
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,2), pty="s")
plot(quarter, main="intrinsic interpolation", # intrinsic geodesic
     xlab="x", ylab="y", type="l")
points(pts.int, col=col.int, pch=19)
for (i in 1:9){
  text(geo.int[i,1]*0.9, geo.int[i,2]*0.9,
       paste0(round(i/10,2)), col="red")
}
plot(quarter, main="extrinsic interpolation", # intrinsic geodesic
     xlab="x", ylab="y", type="l")
```

riem.isomap 37

```
points(pts.ext, col=col.ext, pch=19)
for (i in 1:9){
   text(geo.ext[i,1]*0.9, geo.ext[i,2]*0.9,
        paste0(round(i/10,2)), col="blue")
}
par(opar)
```

riem.isomap

Isometric Feature Mapping

Description

ISOMAP - isometric feature mapping - is a dimensionality reduction method to apply classical multidimensional scaling to the geodesic distance that is computed on a weighted nearest neighborhood graph. Nearest neighbor is defined by k-NN where two observations are said to be connected when they are mutually included in each other's nearest neighbor. Note that it is possible for geodesic distances to be Inf when nearest neighbor graph construction incurs separate connected components. When an extra parameter padding=TRUE, infinite distances are replaced by 2 times the maximal finite geodesic distance.

Usage

```
riem.isomap(
  riemobj,
  ndim = 2,
  nnbd = 5,
  geometry = c("intrinsic", "extrinsic"),
  ...
)
```

Arguments

```
riemobj a S3 "riemdata" class for N manifold-valued data.

ndim an integer-valued target dimension (default: 2).

nnbd the size of nearest neighborhood (default: 5).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

... extra parameters including

padding a logical; if TRUE, Inf-valued geodesic distances are replaced by 2

times the maximal geodesic distance in the data.
```

Value

```
a named list containing
```

```
embed an (N \times ndim) matrix whose rows are embedded observations.
```

38 riem.kmeans

References

Silva VD, Tenenbaum JB (2003). "Global Versus Local Methods in Nonlinear Dimensionality Reduction." In Becker S, Thrun S, Obermayer K (eds.), *Advances in Neural Information Processing Systems* 15, 721–728. MIT Press.

```
-----
#
          Example on Sphere : a dataset with three types
# 10 perturbed data points near (1,0,0) on S^2 in R^3
# 10 perturbed data points near (0,1,0) on S^2 in R^3
# 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)
## MDS AND ISOMAP WITH DIFFERENT NEIGHBORHOOD SIZE
mdss = riem.mds(myriem)$embed
iso1 = riem.isomap(myriem, nnbd=5)$embed
iso2 = riem.isomap(myriem, nnbd=10)$embed
## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,3), pty="s")
plot(mdss, col=mylabs, pch=19, main="MDS")
plot(iso1, col=mylabs, pch=19, main="ISOMAP:nnbd=5")
plot(iso2, col=mylabs, pch=19, main="ISOMAP:nnbd=10")
par(opar)
```

riem.kmeans 39

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, perform k-means clustering by minimizing withincluster sum of squares (WCSS). Since the problem is NP-hard and sensitive to the initialization, we provide an option with multiple starts and return the best result with respect to WCSS.

Usage

```
riem.kmeans(riemobj, k = 2, geometry = c("intrinsic", "extrinsic"), ...)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

k the number of clusters.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embed-

ded ("extrinsic") geometry.

... extra parameters including

algorithm (case-insensitive) name of an algorithm; "MacQueen" (default), or

"Lloyd".

init (case-insensitive) name of an initialization scheme; "plus" for k-means++

(default), or "random".

maxiter maximum number of iterations to be run (default:50).

nstart the number of random starts (default: 5).

Value

a named list containing

cluster a length-N vector of class labels (from 1:k).

means a 3d array where each slice along 3rd dimension is a matrix representation of class mean.

score within-cluster sum of squares (WCSS).

References

Lloyd S (1982). "Least squares quantization in PCM." *IEEE Transactions on Information Theory*, **28**(2), 129–137. ISSN 0018-9448.

MacQueen J (1967). "Some methods for classification and analysis of multivariate observations." In *Proceedings of the fifth berkeley symposium on mathematical statistics and probability, volume 1: Statistics*, 281–297.

See Also

riem.kmeanspp

40 riem.kmeans18B

Examples

```
______
          Example on Sphere : a dataset with three types
# class 1 : 10 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 10 perturbed data points near (0,1,0) on S^2 in R^3
# class 3 : 10 perturbed data points near (0,0,1) on S^2 in R^3
#-----
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)
## K-MEANS WITH K=2,3,4
clust2 = riem.kmeans(myriem, k=2)
clust3 = riem.kmeans(myriem, k=3)
clust4 = riem.kmeans(myriem, k=4)
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(2,2), pty="s")
plot(mds2d, pch=19, main="true label", col=mylabs)
plot(mds2d, pch=19, main="K=2", col=clust2$cluster)
plot(mds2d, pch=19, main="K=3", col=clust3$cluster)
plot(mds2d, pch=19, main="K=4", col=clust4$cluster)
par(opar)
```

riem.kmeans18B

K-Means Clustering with Lightweight Coreset

Description

The modified version of lightweight coreset for scalable k-means computation is applied for manifold-valued data $X_1, X_2, \ldots, X_N \in \mathcal{M}$. The smaller the set is, the faster the execution becomes with potentially larger quantization errors.

riem.kmeans18B 41

Usage

```
riem.kmeans18B(
  riemobj,
  k = 2,
  M = length(riemobj$data)/2,
  geometry = c("intrinsic", "extrinsic"),
  ...
)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

k the number of clusters.

M the size of coreset (default: N/2).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

... extra parameters including

maxiter maximum number of iterations to be run (default:50).

nstart the number of random starts (default: 5).

a named list containing

```
cluster a length-N vector of class labels (from 1:k).
```

means a 3d array where each slice along 3rd dimension is a matrix representation of class mean. **score** within-cluster sum of squares (WCSS).

References

Value

Bachem O, Lucic M, Krause A (2018). "Scalable k -Means Clustering via Lightweight Coresets." In *Proceedings of the 24th ACM SIGKDD International Conference on Knowledge Discovery* & *Data Mining*, 1119–1127. ISBN 978-1-4503-5552-0.

See Also

```
riem.coreset18B
```

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```
mydata = list()
for (i in 1:10){
  tgt = c(1, stats::rnorm(2, sd=0.1))
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 11:20){
  tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 21:30){
  tgt = c(stats::rnorm(2, sd=0.1), 1)
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)
## TRY DIFFERENT SIZES OF CORESET WITH K=4 FIXED
core1 = riem.kmeans18B(myriem, k=3, M=5)
core2 = riem.kmeans18B(myriem, k=3, M=10)
core3 = riem.kmeans18B(myriem, k=3, M=15)
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(2,2), pty="s")
plot(mds2d, pch=19, main="true label", col=mylabs)
plot(mds2d, pch=19, main="kmeans18B: M=5", col=core1$cluster)
plot(mds2d, pch=19, main="kmeans18B: M=10", col=core2$cluster)
plot(mds2d, pch=19, main="kmeans18B: M=15", col=core3$cluster)
par(opar)
```

riem.kmeanspp

K-Means++ Clustering

Description

Given N observations $X_1, X_2, \ldots, X_N \in \mathcal{M}$, perform k-means++ clustering algorithm using pairwise distances. The algorithm was originally designed as an efficient initialization method for k-means algorithm.

Usage

```
riem.kmeanspp(riemobj, k = 2, geometry = c("intrinsic", "extrinsic"))
```

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Arguments

```
riemobj a S3 "riemdata" class for N manifold-valued data. k the number of clusters. geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.
```

Value

a named list containing

```
centers a length-k vector of sampled centers' indices. cluster a length-N vector of class labels (from 1:k).
```

References

Arthur D, Vassilvitskii S (2007). "K-Means++: The advantages of careful seeding." In *Proceedings of the eighteenth annual ACM-SIAM symposium on discrete algorithms*, SODA '07, 1027–1035. ISBN 978-0-89871-624-5, Number of pages: 9 Place: New Orleans, Louisiana.

```
Example on Sphere : a dataset with three types
# class 1 : 10 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 10 perturbed data points near (0,1,0) on S^2 in R^3
# class 3 : 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)
## K-MEANS++ WITH K=2,3,4
clust2 = riem.kmeanspp(myriem, k=2)
clust3 = riem.kmeanspp(myriem, k=3)
clust4 = riem.kmeanspp(myriem, k=4)
```

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```
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed

## VISUALIZE
opar <- par(no.readonly=TRUE)
par(mfrow=c(2,2), pty="s")
plot(mds2d, pch=19, main="true label", col=mylabs)
plot(mds2d, pch=19, main="K=2", col=clust2$cluster)
plot(mds2d, pch=19, main="K=3", col=clust3$cluster)
plot(mds2d, pch=19, main="K=4", col=clust4$cluster)
par(opar)</pre>
```

riem.kmedoids

K-Medoids Clustering

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, perform k-medoids clustering using pairwise distances.

Usage

```
riem.kmedoids(riemobj, k = 2, geometry = c("intrinsic", "extrinsic"))
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

k the number of clusters.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embed-

ded ("extrinsic") geometry.

Value

```
a named list containing
```

```
medoids a length-k vector of medoids' indices. 
 cluster a length-N vector of class labels (from 1:k).
```

See Also

pam

riem.knn 45

Examples

```
._____
          Example on Sphere : a dataset with three types
\# class 1 : 10 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 10 perturbed data points near (0,1,0) on S^2 in R^3
# class 3 : 10 perturbed data points near (0,0,1) on S^2 in R^3
#-----
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)
## K-MEDOIDS WITH K=2,3,4
clust2 = riem.kmedoids(myriem, k=2)
clust3 = riem.kmedoids(myriem, k=3)
clust4 = riem.kmedoids(myriem, k=4)
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(2,2), pty="s")
plot(mds2d, pch=19, main="true label", col=mylabs)
plot(mds2d, pch=19, main="K=2", col=clust2$cluster)
plot(mds2d, pch=19, main="K=3", col=clust3$cluster)
plot(mds2d, pch=19, main="K=4", col=clust4$cluster)
par(opar)
```

riem.knn

Find K-Nearest Neighbors

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, riem.knn constructs k-nearest neighbors.

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Usage

```
riem.knn(riemobj, k = 2, geometry = c("intrinsic", "extrinsic"))
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data. k the number of neighbors to find. geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

Value

a named list containing

nn.idx an $(N \times k)$ neighborhood index matrix. **nn.dists** an $(N \times k)$ distances from a point to its neighbors.

```
Example on Sphere : a dataset with three types
\# * 10 perturbed data points near (1,0,0) on S^2 in R^3
# * 10 perturbed data points near (0,1,0) on S^2 in R^3
\# * 10 perturbed data points near (0,0,1) on S^2 in R^3
#-----
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
myriem = wrap.sphere(mydata)
mylabs = rep(c(2,3,4), each=10)
## K-NN CONSTRUCTION WITH K=5 & K=10
knn1 = riem.knn(myriem, k=5)
knn2 = riem.knn(myriem, k=10)
## MDS FOR VISUALIZATION
embed2 = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
```

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```
opar <- par(no.readonly=TRUE)
par(mfrow=c(1,2), pty="s")
plot(embed2, pch=19, main="knn with k=4", col=mylabs)
for (i in 1:30){
    for (j in 1:5){
        lines(embed2[c(i,knn1$nn.idx[i,j]),])
    }
}
plot(embed2, pch=19, main="knn with k=8", col=mylabs)
for (i in 1:30){
    for (j in 1:10){
        lines(embed2[c(i,knn2$nn.idx[i,j]),])
    }
}
par(opar)</pre>
```

riem.kpca

Kernel Principal Component Analysis

Description

Although the method of Kernel Principal Component Analysis (KPCA) was originally developed to visualize non-linearly distributed data in Euclidean space, we graft this to the case for manifolds where extrinsic geometry is explicitly available. The algorithm uses Gaussian kernel with

$$K(X_i, X_j) = \exp\left(-\frac{d^2(X_i, X_j)}{2\sigma^2}\right)$$

where σ is a bandwidth parameter and $d(\cdot, \cdot)$ is an extrinsic distance defined on a specific manifold.

Usage

```
riem.kpca(riemobj, ndim = 2, sigma = 1)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data. ndim an integer-valued target dimension (default: 2). sigma the bandwidth parameter (default: 1).

Value

a named list containing

embed an $(N \times ndim)$ matrix whose rows are embedded observations. **vars** a length-N vector of eigenvalues from kernelized covariance matrix. 48 riem.m2skreg

References

Schölkopf B, Smola A, Müller K (1997). "Kernel principal component analysis." In Goos G, Hartmanis J, van Leeuwen J, Gerstner W, Germond A, Hasler M, Nicoud J (eds.), *Artificial Neural Networks — ICANN'97*, volume 1327, 583–588. Springer Berlin Heidelberg, Berlin, Heidelberg. ISBN 978-3-540-63631-1 978-3-540-69620-9.

Examples

```
Example for Gorilla Skull Data : 'gorilla'
## PREPARE THE DATA
# Aggregate two classes into one set
data(gorilla)
mygorilla = array(0,c(8,2,59))
for (i in 1:29){
 mygorilla[,,i] = gorilla$male[,,i]
for (i in 30:59){
 mygorilla[,,i] = gorilla$female[,,i-29]
gor.riem = wrap.landmark(mygorilla)
gor.labs = c(rep("red",29), rep("blue",30))
## APPLY KPCA WITH DIFFERENT KERNEL BANDWIDTHS
kpca1 = riem.kpca(gor.riem, sigma=0.01)
kpca2 = riem.kpca(gor.riem, sigma=1)
kpca3 = riem.kpca(gor.riem, sigma=100)
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,3), pty="s")
plot(kpca1$embed, pch=19, col=gor.labs, main="sigma=1/100")
plot(kpca2$embed, pch=19, col=gor.labs, main="sigma=1")
plot(kpca3$embed, pch=19, col=gor.labs, main="sigma=100")
par(opar)
```

riem.m2skreg

Manifold-to-Scalar Kernel Regression

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$ and scalars $y_1, y_2, \dots, y_N \in \mathbf{R}$, perform the Nadaraya-Watson kernel regression by

$$\hat{m}_h(X) = \frac{\sum_{i=1}^n K\left(\frac{d(X,X_i)}{h}\right) y_i}{\sum_{i=1}^n K\left(\frac{d(X,X_i)}{h}\right)}$$

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where the Gaussian kernel is defined as

$$K(x) := \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$$

with the bandwidth parameter h > 0 that controls the degree of smoothness.

Usage

```
riem.m2skreg(
  riemobj,
  y,
  bandwidth = 0.5,
  geometry = c("intrinsic", "extrinsic")
)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data corresponding to X_1, \ldots, X_N . y a length-N vector of dependent variable values. bandwidth a nonnegative number that controls smoothness. geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

Value

a named list of S3 class m2skreg containing

ypred a length-N vector of smoothed responses.

bandwidth the bandwidth value that was originally provided, which is saved for future use.

inputs a list containing both riemobj and y for future use.

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```
# FIT WITH DIFFERENT BANDWIDTHS
fit1 = riem.m2skreg(Xriem, ynoise, bandwidth=0.001)
fit2 = riem.m2skreg(Xriem, ynoise, bandwidth=0.01)
fit3 = riem.m2skreg(Xriem, ynoise, bandwidth=0.1)

# VISUALIZE

xgrd <- 1:npts
opar <- par(no.readonly=TRUE)
par(mfrow=c(1,3))
plot(xgrd, fit1$ypred, pch=19, cex=0.5, "b", xlab="", ylim=c(-2,2), main="h=1e-3")
lines(xgrd, ytrue, col="red", lwd=1.5)
plot(xgrd, fit2$ypred, pch=19, cex=0.5, "b", xlab="", ylim=c(-2,2), main="h=1e-2")
lines(xgrd, ytrue, col="red", lwd=1.5)
plot(xgrd, fit3$ypred, pch=19, cex=0.5, "b", xlab="", ylim=c(-2,2), main="h=1e-1")
lines(xgrd, ytrue, col="red", lwd=1.5)
par(opar)</pre>
```

riem.m2skregCV

Manifold-to-Scalar Kernel Regression with K-Fold Cross Validation

Description

Manifold-to-Scalar Kernel Regression with K-Fold Cross Validation

Usage

```
riem.m2skregCV(
  riemobj,
  y,
  bandwidths = seq(from = 0.01, to = 1, length.out = 10),
  geometry = c("intrinsic", "extrinsic"),
  kfold = 5
)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data corresponding to X_1, \ldots, X_N .

y a length-N vector of dependent variable values.

bandwidths a vector of nonnegative numbers that control smoothness.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

kfold the number of folds for cross validation.

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Value

a named list of S3 class m2skreg containing

ypred a length-N vector of optimal smoothed responses.

bandwidth the optimal bandwidth value.

inputs a list containing both riemobj and y for future use.

errors a matrix whose columns are bandwidths values and corresponding errors measure in SSE.

```
Example on Sphere S^2
\# X : equi-spaced points from (0,0,1) to (0,1,0)
y : sin(x) with perturbation
# GENERATE DATA
set.seed(496)
npts = 100
nlev = 0.25
thetas = seq(from=0, to=pi/2, length.out=npts)
Xstack = cbind(rep(0,npts), sin(thetas), cos(thetas))
Xriem = wrap.sphere(Xstack)
ytrue = sin(seq(from=0, to=2*pi, length.out=npts))
ynoise = ytrue + rnorm(npts, sd=nlev)
# FIT WITH 5-FOLD CV
cv_band = (10^seq(from=-4, to=-1, length.out=200))
cv_fit = riem.m2skregCV(Xriem, ynoise, bandwidths=cv_band)
cv_err = cv_fit$errors
# VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,2))
plot(1:npts, cv_fit$ypred, pch=19, cex=0.5, "b", xlab="", main="optimal prediction")
lines(1:npts, ytrue, col="red", lwd=1.5)
plot(cv_err[,1], cv_err[,2], "b", pch=19, cex=0.5, main="5-fold CV errors",
     xlab="bandwidth", ylab="SSE")
abline(v=cv_fit$bandwidth, col="blue", lwd=1.5)
par(opar)
```

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Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, apply multidimensional scaling to get low-dimensional embedding in Euclidean space. Usually, ndim=2,3 are chosen for visualization.

Usage

```
riem.mds(riemobj, ndim = 2, geometry = c("intrinsic", "extrinsic"))
```

Arguments

```
riemobj a S3 "riemdata" class for N manifold-valued data.

ndim an integer-valued target dimension (default: 2).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.
```

Value

a named list containing

```
embed an (N \times ndim) matrix whose rows are embedded observations.

stress discrepancy between embedded and original distances as a measure of error.
```

References

Torgerson WS (1952). "Multidimensional scaling: I. Theory and method." *Psychometrika*, **17**(4), 401–419. ISSN 0033-3123, 1860-0980.

```
Example on Sphere : a dataset with three types
#
# 10 perturbed data points near (1,0,0) on S^2 in R^3
# 10 perturbed data points near (0,1,0) on S^2 in R^3
# 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
```

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```
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)

## MDS EMBEDDING WITH TWO GEOMETRIES
embed2int = riem.mds(myriem, geometry="intrinsic")$embed
embed2ext = riem.mds(myriem, geometry="extrinsic")$embed

## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,2), pty="s")
plot(embed2int, main="intrinsic MDS", ylim=c(-2,2), col=mylabs, pch=19)
plot(embed2ext, main="extrinsic MDS", ylim=c(-2,2), col=mylabs, pch=19)
par(opar)
```

riem.mean

Fréchet Mean and Variation

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, compute Fréchet mean and variation with respect to the geometry by minimizing

$$\min_{x} \sum_{n=1}^{N} w_n \rho^2(x, x_n), \quad x \in \mathcal{M}$$

where $\rho(x,y)$ is a distance for two points $x,y \in \mathcal{M}$. If non-uniform weights are given, normalized version of the mean is computed and if weight=NULL, it automatically sets equal weights ($w_i = 1/n$) for all observations.

Usage

```
riem.mean(riemobj, weight = NULL, geometry = c("intrinsic", "extrinsic"), ...)
```

Arguments

riemobj	a S3 "riemdata" class for N manifold-valued data.
weight	weight of observations; if NULL it assumes equal weights, or a nonnegative length- $\!N\!$ vector that sums to 1 should be given.
geometry	(case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.
	extra parameters including
	maxiter maximum number of iterations to be run (default:50).
	eps tolerance level for stopping criterion (default: 1e-5).

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Value

a named list containing

mean a mean matrix on \mathcal{M} .

variation sum of (weighted) squared distances.

Examples

```
Example on Sphere : points near (0,1) on S^1 in R^2
## GENERATE DATA
ndata = 50
mydat = array(0,c(ndata,2))
for (i in 1:ndata){
 tgt = c(stats::rnorm(1, sd=2), 1)
 mydat[i,] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydat)
## COMPUTE TWO MEANS
mean.int = as.vector(riem.mean(myriem, geometry="intrinsic")$mean)
mean.ext = as.vector(riem.mean(myriem, geometry="extrinsic")$mean)
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
plot(mydat[,1], mydat[,2], pch=19, xlim=c(-1.1,1.1), ylim=c(0,1.1),
     main="BLUE-extrinsic vs RED-intrinsic")
arrows(x0=0,y0=0,x1=mean.int[1],y1=mean.int[2],col="red")\\
arrows(x0=0,y0=0,x1=mean.ext[1],y1=mean.ext[2],col="blue")
par(opar)
```

riem.median

Fréchet Median and Variation

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, compute Fréchet median and variation with respect to the geometry by minimizing

$$\min_{x} \sum_{n=1}^{N} w_n \rho(x, x_n), \quad x \in \mathcal{M}$$

where $\rho(x,y)$ is a distance for two points $x,y\in\mathcal{M}$. If non-uniform weights are given, normalized version of the mean is computed and if weight=NULL, it automatically sets equal weights for all observations.

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Usage

```
riem.median(
  riemobj,
  weight = NULL,
  geometry = c("intrinsic", "extrinsic"),
  ...
)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

weight weight of observations; if NULL it assumes equal weights, or a nonnegative

length-N vector that sums to 1 should be given.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embed-

ded ("extrinsic") geometry.

... extra parameters including

maxiter maximum number of iterations to be run (default:50).

eps tolerance level for stopping criterion (default: 1e-5).

Value

a named list containing

median a median matrix on \mathcal{M} .

variation sum of (weighted) distances.

```
Example on Sphere : points near (0,1) on S^1 in R^2
## GENERATE DATA
ndata = 50
mydat = array(0,c(ndata,2))
for (i in 1:ndata){
  tgt = c(stats::rnorm(1, sd=2), 1)
  mydat[i,] = tgt/sqrt(sum(tgt^2))
}
myriem = wrap.sphere(mydat)
## COMPUTE TWO MEANS
med.int = as.vector(riem.median(myriem, geometry="intrinsic")$median)
med.ext = as.vector(riem.median(myriem, geometry="extrinsic")$median)
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
plot(mydat[,1], mydat[,2], pch=19, xlim=c(-1.1,1.1), ylim=c(0,1.1),
     main="BLUE-extrinsic vs RED-intrinsic")
arrows(x0=0,y0=0,x1=med.int[1],y1=med.int[2],col="red")\\
```

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```
arrows(x0=0,y0=0,x1=med.ext[1],y1=med.ext[2],col="blue")

par(opar)
```

riem.nmshift

Nonlinear Mean Shift

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, perform clustering of the data based on the nonlinear mean shift algorithm. Gaussian kernel is used with the bandwidth h as of

$$G(x_i, x_j) \propto \exp\left(-\frac{\rho^2(x_i, x_j)}{h^2}\right)$$

where $\rho(x,y)$ is geodesic distance between two points $x,y\in\mathcal{M}$. Numerically, some of the limiting points that collapse into the same cluster are not exact. For such purpose, we require maxk parameter to search the optimal number of clusters based on k-medoids clustering algorithm in conjunction with silhouette criterion.

Usage

```
riem.nmshift(riemobj, h = 1, maxk = 5, maxiter = 50, eps = 1e-05)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

h bandwidth parameter. The larger the h is, the more blurring is applied.

maxk maximum number of clusters to determine the optimal number of clusters.

maxiter maximum number of iterations to be run.
eps tolerance level for stopping criterion.

Value

a named list containing

distance an $(N \times N)$ distance between modes corresponding to each data point.

cluster a length-N vector of class labels.

References

Subbarao R, Meer P (2009). "Nonlinear Mean Shift over Riemannian Manifolds." *International Journal of Computer Vision*, **84**(1), 1–20. ISSN 0920-5691, 1573-1405.

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```
-----
          Example on Sphere : a dataset with three types
\# class 1 : 10 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 10 perturbed data points near (0,1,0) on S^2 in R^3
# class 3 : 10 perturbed data points near (0,0,1) on S^2 in R^3
#-----
## GENERATE DATA
set.seed(496)
ndata = 10
mydata = list()
for (i in 1:ndata){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in (ndata+1):(2*ndata)){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in ((2*ndata)+1):(3*ndata)){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=ndata)
## RUN NONLINEAR MEANSHIFT FOR DIFFERENT 'h' VALUES
run1 = riem.nmshift(myriem, maxk=10, h=0.1)
run2 = riem.nmshift(myriem, maxk=10, h=1)
run3 = riem.nmshift(myriem, maxk=10, h=10)
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(2,3), pty="s")
plot(mds2d, pch=19, main="label : h=0.1", col=run1$cluster)
plot(mds2d, pch=19, main="label : h=1", col=run2$cluster)
plot(mds2d, pch=19, main="label : h=10", col=run3$cluster)
image(run1$distance[,30:1], axes=FALSE, main="distance : h=0.1")
image(run2$distance[,30:1], axes=FALSE, main="distance : h=1")
image(run3$distance[,30:1], axes=FALSE, main="distance : h=10")
par(opar)
```

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Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, compute pairwise distances.

Usage

```
riem.pdist(riemobj, geometry = c("intrinsic", "extrinsic"), as.dist = FALSE)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embed-

ded ("extrinsic") in geometry

as.dist logical; if TRUE, it returns dist object, else it returns a symmetric matrix.

Value

a S3 dist object or $(N \times N)$ symmetric matrix of pairwise distances according to as.dist parameter.

```
Example on Sphere : a dataset with two types
#
#
# group1 : perturbed data points near (0,0,1) on S^2 in R^3
\# group2 : perturbed data points near (1,0,0) on S^2 in R^3
#-----
## GENERATE DATA
mydata = list()
sdval = 0.1
for (i in 1:10){
 tgt = c(stats::rnorm(2, sd=sdval), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(1, stats::rnorm(2, sd=sdval))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
## COMPARE TWO DISTANCES
dint = riem.pdist(myriem, geometry="intrinsic", as.dist=FALSE)
dext = riem.pdist(myriem, geometry="extrinsic", as.dist=FALSE)
## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,2), pty="s")
image(dint[,nrow(dint):1], main="intrinsic", axes=FALSE)
image(dext[,nrow(dext):1], main="extrinsic", axes=FALSE)
par(opar)
```

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riem.pdist2

Compute Pairwise Distances for Two Sets of Data

Description

Given M observations $X_1, X_2, \dots, X_M \in \mathcal{M}$ and N observations $Y_1, Y_2, \dots, Y_N \in \mathcal{M}$, compute pairwise distances between two sets' elements.

Usage

```
riem.pdist2(riemobj1, riemobj2, geometry = c("intrinsic", "extrinsic"))
```

Arguments

```
riemobj1 a S3 "riemdata" class for M manifold-valued data.

riemobj2 a S3 "riemdata" class for N manifold-valued data.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.
```

Value

```
an (M \times N) matrix of distances.
```

```
Example on Sphere : a dataset with two types
  group1 : 10 perturbed data points near (0,0,1) on S^2 in R^3
  group2: 10 perturbed data points near (1,0,0) on S^2 in R^3
            10 perturbed data points near (0,1,0) on S^2 in R^3
            10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata1 = list()
mydata2 = list()
for (i in 1:10){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata1[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata2[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata2[[i]] = tgt/sqrt(sum(tgt^2))
}
```

riem.pga

```
for (i in 21:30){
   tgt = c(stats::rnorm(2, sd=0.1), 1)
   mydata2[[i]] = tgt/sqrt(sum(tgt^2))
}
myriem1 = wrap.sphere(mydata1)
myriem2 = wrap.sphere(mydata2)

## COMPARE TWO DISTANCES
dint = riem.pdist2(myriem1, myriem2, geometry="intrinsic")
dext = riem.pdist2(myriem1, myriem2, geometry="extrinsic")

## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,2))
image(dint[nrow(dint):1,], main="intrinsic", axes=FALSE)
image(dext[nrow(dext):1,], main="extrinsic", axes=FALSE)
par(opar)
```

riem.pga

Principal Geodesic Analysis

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, Principal Geodesic Analysis (PGA) finds a low-dimensional embedding by decomposing 2nd-order information in tangent space at an intrinsic mean of the data.

Usage

```
riem.pga(riemobj, ndim = 2)
```

Arguments

```
riemobj a S3 "riemdata" class for N manifold-valued data. ndim an integer-valued target dimension.
```

Value

```
a named list containing
```

```
center an intrinsic mean in a matrix representation form.

embed an (N \times ndim) matrix whose rows are embedded observations.
```

References

Fletcher PT, Lu C, Pizer SM, Joshi S (2004). "Principal Geodesic Analysis for the Study of Non-linear Statistics of Shape." *IEEE Transactions on Medical Imaging*, **23**(8), 995–1005. ISSN 0278-0062.

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Examples

```
#-----
         Example on Sphere : a dataset with three types
# 10 perturbed data points near (1,0,0) on S^2 in R^3
# 10 perturbed data points near (0,1,0) on S^2 in R^3
# 10 perturbed data points near (0,0,1) on S^2 in R^3
#-----
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)
## EMBEDDING WITH MDS AND PGA
embed2mds = riem.mds(myriem, ndim=2, geometry="intrinsic")$embed
embed2pga = riem.pga(myriem, ndim=2)$embed
## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,2), pty="s")
plot(embed2mds, main="Multidimensional Scaling", col=mylabs, pch=19)
plot(embed2pga, main="Principal Geodesic Analysis", col=mylabs, pch=19)
par(opar)
```

riem.phate

PHATE

Description

PHATE is a nonlinear manifold learning method that is specifically targeted at improving diffusion maps by incorporating data-adaptive kernel construction, detection of optimal time scale, and information-theoretic metric measures.

Usage

```
riem.phate(riemobj, ndim = 2, geometry = c("intrinsic", "extrinsic"), ...)
```

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Arguments

```
riemobj a S3 "riemdata" class for N manifold-valued data.
ndim an integer-valued target dimension (default: 2).
geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.
... extra parameters for PHATE including
nbdk size of nearest neighborhood (default: 5).
alpha decay parameter for Gaussian kernel exponent (default: 2).
potential type of potential distance transformation; "log" or "sqrt" (default: "log").
```

Value

a named list containing

embed an $(N \times ndim)$ matrix whose rows are embedded observations.

References

Moon KR, van Dijk D, Wang Z, Gigante S, Burkhardt DB, Chen WS, Yim K, van den Elzen A, Hirn MJ, Coifman RR, Ivanova NB, Wolf G, Krishnaswamy S (2019). "Visualizing Structure and Transitions in High-Dimensional Biological Data." *Nature Biotechnology*, **37**(12), 1482–1492. ISSN 1087-0156, 1546-1696.

```
Example on Sphere : a dataset with three types
# 10 perturbed data points near (1,0,0) on S^2 in R^3
# 10 perturbed data points near (0,1,0) on S^2 in R^3
# 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
```

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```
mylabs = rep(c(1,2,3), each=10)

## PHATE EMBEDDING WITH LOG & SQRT POTENTIAL
phate_log = riem.phate(myriem, potential="log")$embed
phate_sqrt = riem.phate(myriem, potential="sqrt")$embed
embed_mds = riem.mds(myriem)$embed

## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,3), pty="s")
plot(embed_mds, col=mylabs, pch=19, main="MDS")
plot(phate_log, col=mylabs, pch=19, main="PHATE+Log")
plot(phate_sqrt, col=mylabs, pch=19, main="PHATE+Sqrt")
par(opar)
```

riem.rmml

Riemannian Manifold Metric Learning

Description

Given N observations $X_1, X_2, \ldots, X_N \in \mathcal{M}$ and corresponding label information, riem.rmml computes pairwise distance of data under Riemannian Manifold Metric Learning (RMML) framework based on equivariant embedding. When the number of data points is not sufficient, an inverse of scatter matrix does not exist analytically so the small regularization parameter λ is recommended with default value of $\lambda=0.1$.

Usage

```
riem.rmml(riemobj, label, lambda = 0.1, as.dist = FALSE)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.
label a length-N vector of class labels. NA values are omitted.
lambda regularization parameter. If $\lambda \leq 0$, no regularization is applied.
as.dist logical; if TRUE, it returns dist object, else it returns a symmetric matrix.

Value

a S3 dist object or $(N \times N)$ symmetric matrix of pairwise distances according to as.dist parameter.

References

Zhu P, Cheng H, Hu Q, Wang Q, Zhang C (2018). "Towards Generalized and Efficient Metric Learning on Riemannian Manifold." In *Proceedings of the Twenty-Seventh International Joint Conference on Artificial Intelligence*, 3235–3241. ISBN 978-0-9992411-2-7.

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Examples

```
#
            Distance between Two Classes of SPD Matrices
# Class 1 : Empirical Covariance from Standard Normal Distribution
# Class 2 : Empirical Covariance from Perturbed 'iris' dataset
## DATA GENERATION
data(iris)
ndata = 10
mydata = list()
for (i in 1:ndata){
 mydata[[i]] = stats::cov(matrix(rnorm(100*4),ncol=4))
for (i in (ndata+1):(2*ndata)){
 tmpdata = as.matrix(iris[,1:4]) + matrix(rnorm(150*4,sd=0.5),ncol=4)
 mydata[[i]] = stats::cov(tmpdata)
myriem = wrap.spd(mydata)
mylabs = rep(c(1,2), each=ndata)
## COMPUTE GEODESIC AND RMML PAIRWISE DISTANCE
pdgeo = riem.pdist(myriem)
pdmdl = riem.rmml(myriem, label=mylabs)
## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,2), pty="s")
image(pdgeo[,(2*ndata):1], main="geodesic distance", axes=FALSE)
image(pdmdl[,(2*ndata):1], main="RMML distance", axes=FALSE)
par(opar)
```

riem.sammon

Sammon Mapping

Description

Given N observations $X_1, X_2, \ldots, X_N \in \mathcal{M}$, apply Sammon mapping, a non-linear dimensionality reduction method. Since the method depends only on the pairwise distances of the data, it can be adapted to the manifold-valued data.

Usage

```
riem.sammon(riemobj, ndim = 2, geometry = c("intrinsic", "extrinsic"), ...)
```

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Arguments

```
riemobj a S3 "riemdata" class for N manifold-valued data.

ndim an integer-valued target dimension (default: 2).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

... extra parameters including

maxiter maximum number of iterations to be run (default:50).

eps tolerance level for stopping criterion (default: 1e-5).
```

Value

a named list containing

embed an $(N \times ndim)$ matrix whose rows are embedded observations.

stress discrepancy between embedded and original distances as a measure of error.

References

Sammon JW (1969). "A Nonlinear Mapping for Data Structure Analysis." *IEEE Transactions on Computers*, **C-18**(5), 401–409. ISSN 0018-9340.

```
Example on Sphere : a dataset with three types
# 10 perturbed data points near (1,0,0) on S^2 in R^3
# 10 perturbed data points near (0,1,0) on S^2 in R^3
# 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=10)
## COMPARE SAMMON WITH MDS
embed2mds = riem.mds(myriem, ndim=2)$embed
embed2sam = riem.sammon(myriem, ndim=2)$embed
```

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```
## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,2), pty="s")
plot(embed2mds, col=mylabs, pch=19, main="MDS")
plot(embed2sam, col=mylabs, pch=19, main="Sammon mapping")
par(opar)
```

riem.sc05Z

Spectral Clustering by Zelnik-Manor and Perona (2005)

Description

Zelnik-Manor and Perona proposed a method to define a set of data-driven bandwidth parameters where σ_i is the distance from a point x_i to its nnbd-th nearest neighbor. Then the affinity matrix is defined as

$$A_{ij} = \exp(-d(x_i, d_j)^2 / \sigma_i \sigma_j)$$

and the standard spectral clustering of Ng, Jordan, and Weiss (riem. scNJW) is applied.

Usage

```
riem.sc05Z(riemobj, k = 2, nnbd = 7, geometry = c("intrinsic", "extrinsic"))
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

k the number of clusters (default: 2).

nnbd neighborhood size to define data-driven bandwidth parameter (default: 7).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embed-

ded ("extrinsic") geometry.

Value

a named list containing

cluster a length-N vector of class labels (from 1:k).

eigval eigenvalues of the graph laplacian's spectral decomposition.

embeds an $(N \times k)$ low-dimensional embedding.

References

Zelnik-manor L, Perona P (2005). "Self-Tuning Spectral Clustering." In Saul LK, Weiss Y, Bottou L (eds.), *Advances in Neural Information Processing Systems 17*, 1601–1608. MIT Press.

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Examples

```
______
          Example on Sphere : a dataset with three types
# class 1 : 10 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 10 perturbed data points near (0,1,0) on S^2 in R^3
# class 3 : 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
    = rep(c(1,2,3), each=10)
## CLUSTERING WITH DIFFERENT K VALUES
cl2 = riem.sc05Z(myriem, k=2)$cluster
cl3 = riem.sc05Z(myriem, k=3)$cluster
cl4 = riem.sc05Z(myriem, k=4)$cluster
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,4), pty="s")
plot(mds2d, col=lab, pch=19, main="true label")
plot(mds2d, col=cl2, pch=19, main="riem.sc05Z: k=2")
plot(mds2d, col=cl3, pch=19, main="riem.sc05Z: k=3")
plot(mds2d, col=cl4, pch=19, main="riem.sc05Z: k=4")
par(opar)
```

riem.scNJW

Spectral Clustering by Ng, Jordan, and Weiss (2002)

Description

The version of Ng, Jordan, and Weiss first constructs the affinity matrix

$$A_{ij} = \exp(-d(x_i, d_j)^2 / \sigma^2)$$

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where σ is a common bandwidth parameter and performs k-means clustering on the row-space of eigenvectors for the symmetric graph laplacian matrix

$$L = D^{-1/2}(D - A)D^{-1/2}$$

.

Usage

```
riem.scNJW(riemobj, k = 2, sigma = 1, geometry = c("intrinsic", "extrinsic"))
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

k the number of clusters (default: 2).

sigma bandwidth parameter (default: 1).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

Value

a named list containing

```
cluster a length-N vector of class labels (from 1:k).

eigval eigenvalues of the graph laplacian's spectral decomposition.

embeds an (N \times k) low-dimensional embedding.
```

References

Ng AY, Jordan MI, Weiss Y (2002). "On Spectral Clustering: Analysis and an Algorithm." In Dietterich TG, Becker S, Ghahramani Z (eds.), *Advances in Neural Information Processing Systems* 14, 849–856. MIT Press.

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```
mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
  tgt = c(stats::rnorm(2, sd=0.1), 1)
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
       = rep(c(1,2,3), each=10)
## CLUSTERING WITH DIFFERENT K VALUES
cl2 = riem.scNJW(myriem, k=2)$cluster
cl3 = riem.scNJW(myriem, k=3)$cluster
cl4 = riem.scNJW(myriem, k=4)$cluster
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,4), pty="s")
plot(mds2d, col=lab, pch=19, main="true label")
plot(mds2d, col=cl2, pch=19, main="riem.scNJW: k=2")
plot(mds2d, col=cl3, pch=19, main="riem.scNJW: k=3")
plot(mds2d, col=cl4, pch=19, main="riem.scNJW: k=4")
par(opar)
```

riem.scSM

Spectral Clustering by Shi and Malik (2000)

Description

The version of Shi and Malik first constructs the affinity matrix

$$A_{ij} = \exp(-d(x_i, d_j)^2 / \sigma^2)$$

where σ is a common bandwidth parameter and performs k-means clustering on the row-space of eigenvectors for the random-walk graph laplacian matrix

$$L = D^{-1}(D - A)$$

٠

Usage

```
riem.scSM(riemobj, k = 2, sigma = 1, geometry = c("intrinsic", "extrinsic"))
```

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Arguments

```
riemobj a S3 "riemdata" class for N manifold-valued data.

k the number of clusters (default: 2).

sigma bandwidth parameter (default: 1).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.
```

Value

```
a named list containing
```

```
cluster a length-N vector of class labels (from 1:k). eigval eigenvalues of the graph laplacian's spectral decomposition. embeds an (N \times k) low-dimensional embedding.
```

References

Shi J, Malik J (2000). "Normalized Cuts and Image Segmentation." *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 22(8):888–905.

```
Example on Sphere : a dataset with three types
# class 1 : 10 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 10 perturbed data points near (0,1,0) on S^2 in R^3
# class 3 : 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
  tgt = c(1, stats::rnorm(2, sd=0.1))
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
  tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
  tgt = c(stats::rnorm(2, sd=0.1), 1)
  mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
      = rep(c(1,2,3), each=10)
## CLUSTERING WITH DIFFERENT K VALUES
cl2 = riem.scSM(myriem, k=2)$cluster
cl3 = riem.scSM(myriem, k=3)$cluster
cl4 = riem.scSM(myriem, k=4)$cluster
```

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```
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed

## VISUALIZE
opar <- par(no.readonly=TRUE)
par(mfrow=c(1,4), pty="s")
plot(mds2d, col=lab, pch=19, main="true label")
plot(mds2d, col=cl2, pch=19, main="riem.scSM: k=2")
plot(mds2d, col=cl3, pch=19, main="riem.scSM: k=3")
plot(mds2d, col=cl4, pch=19, main="riem.scSM: k=4")
par(opar)</pre>
```

riem.scUL

Spectral Clustering with Unnormalized Laplacian

Description

The version of Shi and Malik first constructs the affinity matrix

$$A_{ij} = \exp(-d(x_i, d_j)^2 / \sigma^2)$$

where σ is a common bandwidth parameter and performs k-means clustering on the row-space of eigenvectors for the unnormalized graph laplacian matrix

$$L = D - A$$

•

Usage

```
riem.scUL(riemobj, k = 2, sigma = 1, geometry = c("intrinsic", "extrinsic"))
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

k the number of clusters (default: 2). sigma bandwidth parameter (default: 1).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embed-

ded ("extrinsic") geometry.

Value

a named list containing

cluster a length-N vector of class labels (from 1:k).

eigval eigenvalues of the graph laplacian's spectral decomposition.

embeds an $(N \times k)$ low-dimensional embedding.

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References

von Luxburg U (2007). "A Tutorial on Spectral Clustering." Statistics and Computing, 17(4):395-416.

```
#-----
          Example on Sphere : a dataset with three types
# class 1 : 10 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 10 perturbed data points near (0,1,0) on S^2 in R^3
# class 3 : 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:10){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 11:20){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:30){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
myriem = wrap.sphere(mydata)
     = rep(c(1,2,3), each=10)
## CLUSTERING WITH DIFFERENT K VALUES
cl2 = riem.scUL(myriem, k=2)$cluster
cl3 = riem.scUL(myriem, k=3)$cluster
cl4 = riem.scUL(myriem, k=4)$cluster
## MDS FOR VISUALIZATION
mds2d = riem.mds(myriem, ndim=2)$embed
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,4), pty="s")
plot(mds2d, col=lab, pch=19, main="true label")
plot(mds2d, col=cl2, pch=19, main="riem.scUL: k=2")
plot(mds2d, col=cl3, pch=19, main="riem.scUL: k=3")
plot(mds2d, col=cl4, pch=19, main="riem.scUL: k=4")
par(opar)
```

riem.seb 73

Description

Given N observations $X_1, X_2, \dots, X_N \in \mathcal{M}$, find the smallest enclosing ball.

Usage

```
riem.seb(riemobj, method = c("aa2013"), ...)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

method (case-insensitive) name of the algorithm to be used as follows;

"aa2013" Arnaudon and Nielsen (2013).

... extra parameters including

maxiter maximum number of iterations to be run (default:50).

eps tolerance level for stopping criterion (default: 1e-5).

Value

a named list containing

center a matrix on \mathcal{M} that minimizes the radius. **radius** the minimal radius with respect to the center.

References

Bâdoiu M, Clarkson KL (2003). "Smaller core-sets for balls." In *Proceedings of the fourteenth annual ACM-SIAM symposium on discrete algorithms*, SODA '03, 801–802. ISBN 0-89871-538-5.

Arnaudon M, Nielsen F (2013). "On approximating the Riemannian 1-center." *Computational Geometry*, **46**(1), 93–104. ISSN 09257721.

```
# Euclidean Example : samples from Standard Normal in R^2
#------
## GENERATE 25 OBSERVATIONS FROM N(0,I)
ndata = 25
mymats = array(0,c(ndata, 2))
mydata = list()
for (i in 1:ndata){
   mydata[[i]] = stats::rnorm(2)
   mymats[i,] = mydata[[i]]
}
myriem = wrap.euclidean(mydata)

## COMPUTE
sebobj = riem.seb(myriem)
center = as.vector(sebobj$center)
radius = sebobj$radius
```

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riem.test2bg14

Two-Sample Test modified from Biswas and Ghosh (2014)

Description

Given M observations $X_1, X_2, \dots, X_M \in \mathcal{M}$ and N observations $Y_1, Y_2, \dots, Y_N \in \mathcal{M}$, perform the permutation test of equal distribution

$$H_0: \mathcal{P}_X = \mathcal{P}_Y$$

by the method from Biswas and Ghosh (2014). The method, originally proposed for Euclidean-valued data, is adapted to the general Riemannian manifold with intrinsic/extrinsic distance.

Usage

```
riem.test2bg14(riemobj1, riemobj2, geometry = c("intrinsic", "extrinsic"), ...)
```

Arguments

riemobj1 a S3 "riemdata" class for M manifold-valued data.

riemobj2 a S3 "riemdata" class for N manifold-valued data.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

... extra parameters including

nperm the number of permutations (default: 999).

riem.test2bg14 75

Value

```
a (list) object of S3 class htest containing: 

statistic a test statistic.

p.value p-value under H_0.

alternative alternative hypothesis.

method name of the test.

data.name name(s) of provided sample data.
```

References

Biswas M, Ghosh AK (2014). "A nonparametric two-sample test applicable to high dimensional data." *Journal of Multivariate Analysis*, **123**, 160–171. ISSN 0047259X.

You K, Park H (2020). "Re-visiting Riemannian geometry of symmetric positive definite matrices for the analysis of functional connectivity." *NeuroImage*, 117464. ISSN 10538119.

```
Example on Sphere : a dataset with two types
# class 1 : 20 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 30 perturbed data points near (0,1,0) on S^2 in R^3
## GENERATE DATA
mydata1 = list()
mydata2 = list()
for (i in 1:20){
  tgt = c(1, stats::rnorm(2, sd=0.1))
  mydata1[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 1:20){
  tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
  mydata2[[i]] = tgt/sqrt(sum(tgt^2))
}
myriem1 = wrap.sphere(mydata1)
myriem2 = wrap.sphere(mydata2)
## PERFORM PERMUTATION TEST
# it is expected to return a very small number.
riem.test2bg14(myriem1, myriem2, nperm=999)
## Not run:
## CHECK WITH EMPIRICAL TYPE-1 ERROR
set.seed(777)
ntest = 1000
pvals = rep(0, ntest)
```

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```
for (i in 1:ntest){
    X = cbind(matrix(rnorm(30*2, sd=0.1),ncol=2), rep(1,30))
    Y = cbind(matrix(rnorm(30*2, sd=0.1),ncol=2), rep(1,30))
    Xnorm = X/sqrt(rowSums(X^2))
    Ynorm = Y/sqrt(rowSums(Y^2))

    Xriem = wrap.sphere(Xnorm)
    Yriem = wrap.sphere(Ynorm)
    pvals[i] = riem.test2bg14(Xriem, Yriem, nperm=999)$p.value
}

emperr = round(sum((pvals <= 0.05))/ntest, 5)
print(paste0("* EMPIRICAL TYPE-1 ERROR=", emperr))

## End(Not run)</pre>
```

riem.test2wass

Two-Sample Test with Wasserstein Metric

Description

Given M observations $X_1, X_2, \ldots, X_M \in \mathcal{M}$ and N observations $Y_1, Y_2, \ldots, Y_N \in \mathcal{M}$, permutation test based on the Wasserstein metric (see riem.wasserstein for more details) is applied to test whether two distributions are same or not, i.e.,

$$H_0: \mathcal{P}_X = \mathcal{P}_Y$$

with Wasserstein metric W_p being the measure of discrepancy between two samples.

Usage

```
riem.test2wass(
  riemobj1,
  riemobj2,
  p = 2,
  geometry = c("intrinsic", "extrinsic"),
  ...
)
```

Arguments

```
riemobj1 a S3 "riemdata" class for M manifold-valued data.

riemobj2 a S3 "riemdata" class for N manifold-valued data.

p an exponent for Wasserstein distance \mathcal{W}_p (default: 2).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

... extra parameters including
```

riem.test2wass 77

nperm the number of permutations (default: 999).use.smooth a logical; TRUE to use a smoothed Wasserstein distance, FALSE otherwise.

Value

```
a (list) object of S3 class htest containing: 

statistic a test statistic.

p.value p-value under H_0.

alternative alternative hypothesis.

method name of the test.

data.name name(s) of provided sample data.
```

```
Example on Sphere : a dataset with two types
# class 1 : 20 perturbed data points near (1,0,0) on S^2 in R^3
# class 2 : 30 perturbed data points near (0,1,0) on S^2 in R^3
## GENERATE DATA
mydata1 = list()
mydata2 = list()
for (i in 1:20){
  tgt = c(1, stats::rnorm(2, sd=0.1))
  mydata1[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 1:20){
  tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
  mydata2[[i]] = tgt/sqrt(sum(tgt^2))
myriem1 = wrap.sphere(mydata1)
myriem2 = wrap.sphere(mydata2)
## PERFORM PERMUTATION TEST
# it is expected to return a very small number, but
# small number of 'nperm' may not give a reasonable p-value.
riem.test2wass(myriem1, myriem2, nperm=99, use.smooth=FALSE)
## Not run:
## CHECK WITH EMPIRICAL TYPE-1 ERROR
set.seed(777)
ntest = 1000
pvals = rep(0,ntest)
for (i in 1:ntest){
  X = cbind(matrix(rnorm(30*2, sd=0.1), ncol=2), rep(1,30))
```

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```
Y = cbind(matrix(rnorm(30*2, sd=0.1),ncol=2), rep(1,30))
Xnorm = X/sqrt(rowSums(X^2))
Ynorm = Y/sqrt(rowSums(Y^2))

Xriem = wrap.sphere(Xnorm)
Yriem = wrap.sphere(Ynorm)
pvals[i] = riem.test2wass(Xriem, Yriem, nperm=999)$p.value
print(paste0("iteration ",i,"/",ntest," complete.."))
}

emperr = round(sum((pvals <= 0.05))/ntest, 5)
print(paste0("* EMPIRICAL TYPE-1 ERROR=", emperr))

## End(Not run)</pre>
```

riem.tsne

t-distributed Stochastic Neighbor Embedding

Description

Given N observations $X_1, X_2, \ldots, X_N \in \mathcal{M}$, t-SNE mimicks the pattern of probability distributions over pairs of manifold-valued objects on low-dimensional target embedding space by minimizing Kullback-Leibler divergence.

Usage

```
riem.tsne(riemobj, ndim = 2, geometry = c("intrinsic", "extrinsic"), ...)
```

Arguments

riemobj a S3 "riemdata" class for N manifold-valued data.

ndim an integer-valued target dimension.

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embed-

ded ("extrinsic") geometry.

... extra parameters for Rtsne algorithm from **Rtsne** package, such as perplexity,

momentum, and others.

Value

a named list containing

embed an $(N \times ndim)$ matrix whose rows are embedded observations.

stress discrepancy between embedded and original distances as a measure of error.

riem.wasserstein 79

Examples

```
-----
#
          Example on Sphere : a dataset with three types
# 10 perturbed data points near (1,0,0) on S^2 in R^3
# 10 perturbed data points near (0,1,0) on S^2 in R^3
# 10 perturbed data points near (0,0,1) on S^2 in R^3
## GENERATE DATA
mydata = list()
for (i in 1:20){
 tgt = c(1, stats::rnorm(2, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
for (i in 21:40){
 tgt = c(rnorm(1, sd=0.1), 1, rnorm(1, sd=0.1))
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
}
for (i in 41:60){
 tgt = c(stats::rnorm(2, sd=0.1), 1)
 mydata[[i]] = tgt/sqrt(sum(tgt^2))
myriem = wrap.sphere(mydata)
mylabs = rep(c(1,2,3), each=20)
## RUN THE ALGORITHM IN TWO GEOMETRIES
embed2int = riem.tsne(myriem, ndim=2, geometry="intrinsic", perplexity=mypx)
embed2ext = riem.tsne(myriem, ndim=2, geometry="extrinsic", perplexity=mypx)
## VISUALIZE
opar = par(no.readonly=TRUE)
par(mfrow=c(1,2), pty="s")
plot(embed2int$embed, main="intrinsic t-SNE", col=mylabs, pch=19)
plot(embed2ext$embed, main="extrinsic t-SNE", col=mylabs, pch=19)
par(opar)
```

riem.wasserstein

Wasserstein Distance between Empirical Measures

Description

Given two empirical measures μ, ν consisting of M and N observations, p-Wasserstein distance for $p \geq 1$ between two empirical measures is defined as

$$\mathcal{W}_p(\mu,\nu) = \left(\inf_{\gamma \in \Gamma(\mu,\nu)} \int_{\mathcal{M} \times \mathcal{M}} d(x,y)^p d\gamma(x,y)\right)^{1/p}$$

where $\Gamma(\mu, \nu)$ denotes the collection of all measures/couplings on $\mathcal{M} \times \mathcal{M}$ whose marginals are μ and ν on the first and second factors, respectively.

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Usage

```
riem.wasserstein(
  riemobj1,
  riemobj2,
  p = 2,
  geometry = c("intrinsic", "extrinsic"),
  ...
)
```

Arguments

```
riemobj1 a S3 "riemdata" class for M manifold-valued data, which are atoms of \mu.

riemobj2 a S3 "riemdata" class for N manifold-valued data, which are atoms of \nu.

p an exponent for Wasserstein distance \mathcal{W}_p (default: 2).

geometry (case-insensitive) name of geometry; either geodesic ("intrinsic") or embedded ("extrinsic") geometry.

... extra parameters including

weight1 a length-M weight vector for \mu; if NULL (default), uniform weight is set.

weight2 a length-N weight vector for \nu; if NULL (default), uniform weight is set.
```

Value

a named list containing

distance $\mathcal{W}_{\sqrt{}}$ distance between two empirical measures.

plan an $(M \times N)$ matrix whose rowSums and columnSums are weight1 and weight2 respectively.

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```
myriem1 = wrap.sphere(mydata1)
myriem2 = wrap.sphere(mydata2)
## COMPUTE p-WASSERSTEIN DISTANCES
dist1 = riem.wasserstein(myriem1, myriem2, p=1)
dist2 = riem.wasserstein(myriem1, myriem2, p=2)
dist5 = riem.wasserstein(myriem1, myriem2, p=5)
pm1 = paste0("p=1: dist=",round(dist1$distance,3))
pm2 = paste0("p=2: dist=",round(dist2$distance,3))
pm5 = paste0("p=5: dist=",round(dist5$distance,3))
## VISUALIZE TRANSPORT PLAN AND DISTANCE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,3))
image(dist1$plan, axes=FALSE, main=pm1)
image(dist2$plan, axes=FALSE, main=pm2)
image(dist5$plan, axes=FALSE, main=pm5)
par(opar)
```

rmvnorm

Generate Random Samples from Multivariate Normal Distribution

Description

In \mathbb{R}^p , random samples are drawn

$$X_1, X_2, \ldots, X_n \sim \mathcal{N}(\mu, \Sigma)$$

where $\mu \in \mathbf{R}^p$ is a mean vector and $\Sigma \in \mathrm{SPD}(p)$ is a positive definite covariance matrix.

Usage

```
rmvnorm(n = 1, mu, sigma)
```

Arguments

n the number of samples to be generated.

mu mean vector.

sigma covariance matrix.

Value

either (1) a length-p vector (n = 1) or (2) an $(n \times p)$ matrix where rows are random samples.

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Examples

```
Generate Random Data and Compare with Empirical Covariances
# In R^5 with zero mean and diagonal covariance,
# generate 100 and 200 observations and compute MLE covariance.
#-----
## GENERATE DATA
mymu = rep(0,5)
mysig = diag(5)
## MLE FOR COVARIANCE
smat1 = stats::cov(rmvnorm(n=100, mymu, mysig))
smat2 = stats::cov(rmvnorm(n=200, mymu, mysig))
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,3), pty="s")
image(mysig[,5:1], axes=FALSE, main="true covariance")
image(smat1[,5:1], axes=FALSE, main="empirical cov with n=100")
image(smat2[,5:1], axes=FALSE, main="empirical cov with n=200")
par(opar)
```

spd.geometry

Supported Geometries on SPD Manifold

Description

SPD manifold is a well-studied space in that there have been many geometries proposed on the space. For special functions on under SPD category, this function finds whether there exists a matching name that is currently supported in **Riemann**. If there is none, it will return an error message.

Usage

```
spd.geometry(geometry)
```

Arguments

geometry

name of supported geometries, including

AIRM Affine-Invariant Riemannian Metric.

LERM Log-Euclidean Riemannian Metric.

Jeffrey Jeffrey's divergence.

Stein Stein's metric.

Wasserstein 2-Wasserstein geometry.

spd.pdist 83

Value

a matching name in lower-case.

Examples

```
# it just returns a small-letter string.
mygeom = spd.geometry("stein")
```

spd.pdist

Pairwise Distance on SPD Manifold

Description

Given N observations X_1, X_2, \dots, X_N in SPD manifold, compute pairwise distances among observations.

Usage

```
spd.pdist(spdobj, geometry, as.dist = FALSE)
```

Arguments

spdobj a S3 "riemdata" class of SPD-valued data.

geometry name of the geometry to be used. See spd.geometry for supported geometries.

as.dist logical; if TRUE, it returns a dist object. Else, it returns a symmetric matrix.

Value

a S3 dist object or $(N \times N)$ symmetric matrix of pairwise distances according to as . dist parameter.

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```
randmat = cbind(sin(randvec), cos(randvec), sin(randvec)*cos(randvec))
 spd_mats[,,j] = stats::cov(randmat + matrix(rnorm(50*3, sd=0.1), ncol=3))
}
## WRAP IT AS SPD OBJECT
spd_obj = wrap.spd(spd_mats)
## COMPUTE PAIRWISE DISTANCES
# Geometries are case-insensitive.
pdA = spd.pdist(spd_obj, "airM")
pdL = spd.pdist(spd_obj, "lErm")
pdJ = spd.pdist(spd_obj, "Jeffrey")
pdS = spd.pdist(spd_obj, "stEin")
pdW = spd.pdist(spd_obj, "wasserstein")
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(2,3), pty="s")
image(pdA, axes=FALSE, main="AIRM")
image(pdL, axes=FALSE, main="LERM")
image(pdJ, axes=FALSE, main="Jeffrey")
image(pdS, axes=FALSE, main="Stein")
image(pdW, axes=FALSE, main="Wasserstein")
par(opar)
```

spd.wassbary

Wasserstein Barycenter of SPD Matrices

Description

Given N observations X_1, X_2, \dots, X_N in SPD manifold, compute the L_2 -Wasserstein barycenter that minimizes

$$\sum_{n=1}^{N} \lambda_i \mathcal{W}_2(N(X), N(X_i))^2$$

where N(X) denotes the zero-mean Gaussian measure with covariance X.

Usage

```
spd.wassbary(spdobj, weight = NULL, method = c("RU02", "AE16"), ...)
```

Arguments

spdobj a S3 "riemdata" class of SPD-valued data of $(p \times p)$ matrices.

weight weight of observations; if NULL it assumes equal weights, or a nonnegative

length-N vector that sums to 1 should be given.

method name of the algorithm to be used; one of the "RU02", "AE16".

sphere.convert 85

extra parameters including
maxiter maximum number of iterations to be run (default:20).
abstol tolerance level for stopping criterion (default: 1e-8).

Value

a $(p \times p)$ Wasserstein barycenter matrix.

Examples

```
______
        Covariances from standard multivariate Gaussians.
## GENERATE DATA
ndata = 20
pdim = 10
mydat = array(0,c(pdim,pdim,ndata))
for (i in 1:ndata){
 mydat[,,i] = stats::cov(matrix(rnorm(100*pdim), ncol=pdim))
myriem = wrap.spd(mydat)
## COMPUTE BY DIFFERENT ALGORITHMS
baryRU <- spd.wassbary(myriem, method="RU02")</pre>
baryAE <- spd.wassbary(myriem, method="AE16")</pre>
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,3), pty="s")
image(diag(pdim), axes=FALSE, main="True Covariance")
image(baryRU, axes=FALSE, main="by RU02")
image(baryAE, axes=FALSE, main="by AE16")
par(opar)
```

sphere.convert

Convert between Cartesian Coordinates and Geographic Coordinates

Description

In geospatial data analysis, it is common to consider locations on the Earth as data. These locations, usually provided by latitude and longitude, are not directly applicable for spherical data analysis. We provide two functions - sphere.geo2xyz and sphere.xyz2geo - that convert geographic coordinates in longitude/latitude into a unit-norm vector on S^2 , and vice versa. As a convention, latitude and longitude are represented as *decimal degrees*.

86 sphere.runif

Usage

```
sphere.geo2xyz(lat, lon)
sphere.xyz2geo(xyz)
```

Arguments

lat latitude (in decimal degrees). lon longitude (in decimal degrees). xyz a unit-norm vector in S^2 .

Value

transformed data.

Examples

```
## EXAMPLE DATA WITH POPULATED US CITIES
data(cities)

## SELECT ALBUQUERQUE
geo = cities$coord[1,]
xyz = cities$cartesian[1,]

## CHECK TWO INPUT TYPES AND THEIR CONVERSIONS
sphere.geo2xyz(geo[1], geo[2])
sphere.xyz2geo(xyz)
```

sphere.runif

Generate Uniform Samples on Sphere

Description

It generates n random samples from S^{p-1} . For convenient usage of users, we provide a number of options in terms of the return type.

Usage

```
sphere.runif(n, p, type = c("list", "matrix", "riemdata"))
```

Arguments

n number of samples to be generated. p original dimension (of the ambient space). type return type;
"list" a length-n list of length-p vectors.
"matrix" a $(n \times p)$ where rows are unit vectors.
"riemdata" a S3 object. See wrap. sphere for more details (Default).

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Value

an object from one of the above by type option.

References

Chikuse Y (2003). *Statistics on Special Manifolds*, volume 174 of *Lecture Notes in Statistics*. Springer New York, New York, NY. ISBN 978-0-387-00160-9 978-0-387-21540-2.

See Also

```
wrap.sphere
```

Examples

sphere.utest

Test of Uniformity on Sphere

Description

Given N observations $\{X_1, X_2, ..., X_M\}$ on S^{p-1} , it tests whether the data is distributed uniformly on the sphere.

Usage

```
sphere.utest(spobj, method = c("Rayleigh", "RayleighM"))
```

Arguments

spobj a S3 "riemdata" class for N Sphere-valued data.

method (case-insensitive) name of the test method containing

"Rayleigh" original Rayleigh statistic.

"RayleighM" modified Rayleigh statistic with better order of error.

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Value

```
a (list) object of S3 class htest containing:
```

statistic a test statistic.

p.value p-value under H_0 .

alternative alternative hypothesis.

method name of the test.

data.name name(s) of provided sample data.

References

Chikuse Y (2003). *Statistics on Special Manifolds*, volume 174 of *Lecture Notes in Statistics*. Springer New York, New York, NY. ISBN 978-0-387-00160-9 978-0-387-21540-2.

Mardia KV, Jupp PE (eds.) (1999). *Directional Statistics*, Wiley Series in Probability and Statistics. John Wiley & Sons, Inc., Hoboken, NJ, USA. ISBN 978-0-470-31697-9 978-0-471-95333-3.

See Also

```
wrap.sphere
```

Examples

```
#------
# Compare Rayleigh's original and modified versions of the test
#-------
# Data Generation
myobj = sphere.runif(n=100, p=5, type="riemdata")

# Compare 2 versions : Original vs Modified Rayleigh
sphere.utest(myobj, method="rayleigh")
sphere.utest(myobj, method="rayleighm")
```

splaplace

Spherical Laplace Distribution

Description

This is a collection of tools for learning with spherical Laplace (SL) distribution on a (p-1)-dimensional sphere in \mathbf{R}^p including sampling, density evaluation, and maximum likelihood estimation of the parameters. The SL distribution is characterized by the following density function,

$$f_{SL}(x; \mu, \sigma) = \frac{1}{C(\sigma)} \exp\left(-\frac{d(x, \mu)}{\sigma}\right)$$

for location and scale parameters μ and σ respectively.

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Usage

```
dsplaplace(data, mu, sigma, log = FALSE)
rsplaplace(n, mu, sigma)
mle.splaplace(data, method = c("DE", "Optimize", "Newton"), ...)
```

Arguments

data	data vectors in form of either an $(n \times p)$ matrix or a length- n list. See wrap. sphere for descriptions on supported input types.
mu	a length- p unit-norm vector of location.
sigma	a scale parameter that is positive.
log	a logical; TRUE to return log-density, FALSE for densities without logarithm applied.
n	the number of samples to be generated.
method	an algorithm name for concentration parameter estimation. It should be one of "Newton", "Optimize", and "DE" (case-sensitive).
	extra parameters for computations, including
	maxiter maximum number of iterations to be run (default:50).
	eps tolerance level for stopping criterion (default: 1e-6).
	<pre>use.exact a logical to use exact (TRUE) or approximate (FALSE) updating rules (default: FALSE).</pre>

Value

dsplaplace gives a vector of evaluated densities given samples. rsplaplace generates unit-norm vectors in \mathbf{R}^p wrapped in a list. mle.splaplace computes MLEs and returns a list containing estimates of location (mu) and scale (sigma) parameters.

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```
idseq = seq(from=50, to=1000, by=10)
nseq = length(idseq)
hist.mu = rep(0, nseq)
hist.sig = rep(0, nseq)
for (i in 1:nseq){
  small.data = big.data[1:idseq[i]]
                                                 # data subsetting
  small.MLE = mle.splaplace(small.data)
                                                 # compute MLE
  hist.mu[i] = acos(sum(small.MLE$mu*true.mu)) # difference in mu
  hist.sig[i] = small.MLE$sigma
}
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,2))
plot(idseq, hist.mu, "b", pch=19, cex=0.5,
     main="difference in location", xlab="sample size")
plot(idseq, hist.sig, "b", pch=19, cex=0.5,
     main="scale parameter", xlab="sample size")
abline(h=true.sig, lwd=2, col="red")
par(opar)
```

spnorm

Spherical Normal Distribution

Description

We provide tools for an isotropic spherical normal (SN) distributions on a (p-1)-sphere in \mathbf{R}^p for sampling, density evaluation, and maximum likelihood estimation of the parameters where the density is defined as

$$f_{SN}(x; \mu, \lambda) = \frac{1}{Z(\lambda)} \exp\left(-\frac{\lambda}{2}d^2(x, \mu)\right)$$

for location and concentration parameters μ and λ respectively and the normalizing constant $Z(\lambda)$.

Usage

```
dspnorm(data, mu, lambda, log = FALSE)
rspnorm(n, mu, lambda)
mle.spnorm(data, method = c("Newton", "Halley", "Optimize", "DE"), ...)
```

spnorm 91

Arguments

data	data vectors in form of either an $(n \times p)$ matrix or a length- n list. See wrap. sphere for descriptions on supported input types.
mu	a length- p unit-norm vector of location.
lambda	a concentration parameter that is positive.
log	a logical; TRUE to return log-density, FALSE for densities without logarithm applied.
n	the number of samples to be generated.
method	an algorithm name for concentration parameter estimation. It should be one of "Newton", "Halley", "Optimize", and "DE" (case sensitive).
	extra parameters for computations, including
	maxiter maximum number of iterations to be run (default:50).
	eps tolerance level for stopping criterion (default: 1e-5).

Value

dspnorm gives a vector of evaluated densities given samples. rspnorm generates unit-norm vectors in \mathbf{R}^p wrapped in a list. mle.spnorm computes MLEs and returns a list containing estimates of location (mu) and concentration (lambda) parameters.

References

Hauberg S (2018). "Directional Statistics with the Spherical Normal Distribution." In 2018 21st International Conference on Information Fusion (FUSION), 704–711. ISBN 978-0-9964527-6-2.

You K, Suh C (2022). "Parameter Estimation and Model-Based Clustering with Spherical Normal Distribution on the Unit Hypersphere." *Computational Statistics* & *Data Analysis*, 107457. ISSN 01679473.

92 stiefel.optSA

```
hist.mu = rep(0, nseq)
hist.lbd = rep(0, nseq)
for (i in 1:nseq){
  small.data = big.data[1:idseq[i]]
                                             # data subsetting
  small.MLE = mle.spnorm(small.data) # compute MLE
  hist.mu[i] = acos(sum(small.MLE$mu*true.mu)) # difference in mu
  hist.lbd[i] = small.MLE$lambda
}
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
par(mfrow=c(1,2))
plot(idseq, hist.mu, "b", pch=19, cex=0.5, main="difference in location")
plot(idseq, hist.lbd, "b", pch=19, cex=0.5, main="concentration param")
abline(h=true.lbd, lwd=2, col="red")
par(opar)
```

stiefel.optSA

Simulated Annealing on Stiefel Manifold

Description

Simulated Annealing is a black-box, derivative-free optimization algorithm that iterates via stochastic search in the neighborhood of current position. stiefel.optSA solves the following problem

$$\min_{X} f(X), \quad X \in St(p,k)$$

without any other auxiliary information such as gradient or hessian involved.

Usage

```
stiefel.optSA(func, p, k, ...)
```

Arguments

	func	a function to be <i>minimized</i> .	
	p	dimension parameter as in $St(k, p)$.	
	k	dimension parameter as in $St(k, p)$.	
	extra parameters for SA algorithm including		
n.start number of runs; algorithm is executed n.start times (def		n.start number of runs; algorithm is executed n.start times (default: 5).	
		stepsize size of random walk on each component (default: 0.1).	
		maxiter maximum number of iterations for each run (default: 100).	

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cooling triplet for cooling schedule. See the section for the usage. **init.val** if NULL, starts from a random point. Otherwise, a Stiefel matrix of size (p,k) should be provided for fixed starting point. **print.progress** a logical; if TRUE, it prints each iteration.

Value

```
a named list containing: 

cost minimized function value. 

solution a (p \times k) matrix that attains the cost. 

accfreq frequency of acceptance moves.
```

```
#
               Optimization for Eigen-Decomposition
#
# Given (5x5) covariance matrix S, eigendecomposition is indeed
# an optimization problem cast on the stiefel manifold. Here,
# we are trying to find top 3 eigenvalues and compare.
#-----
## PREPARE
set.seed(121)
                                   # set seed
A = cov(matrix(rnorm(100*5), ncol=5)) # define covariance
myfunc <- function(p){</pre>
                                    # cost function to minimize
 return(sum(-diag(t(p)%*%A%*%p)))
## SOLVE THE OPTIMIZATION PROBLEM
Aout = stiefel.optSA(myfunc, p=5, k=3, n.start=40, maxiter=200)
## COMPUTE EIGENVALUES
# 1. USE SOLUTIONS TO THE ABOVE OPTIMIZATION
abase = Aout$solution
eig3sol = sort(diag(t(abase)%*%A%*%abase), decreasing=TRUE)
# 2. USE BASIC 'EIGEN' FUNCTION
eig3dec = sort(eigen(A)$values, decreasing=TRUE)[1:3]
## VISUALIZE
opar <- par(no.readonly=TRUE)</pre>
yran = c(min(min(eig3sol),min(eig3dec))*0.95,
        max(max(eig3sol), max(eig3dec))*1.05)
plot(1:3, eig3sol, type="b", col="red", pch=19, ylim=yran,
    xlab="index", ylab="eigenvalue", main="compare top 3 eigenvalues")
lines(1:3, eig3dec, type="b", col="blue", pch=19)
legend(1, 1, legend=c("optimization","decomposition"), col=c("red","blue"),
      lty=rep(1,2), pch=19)
par(opar)
```

94 stiefel.runif

stiefel.runif

Generate Uniform Samples on Stiefel Manifold

Description

It generates n random samples from Stiefel manifold St(k, p).

Usage

```
stiefel.runif(n, k, p, type = c("list", "array", "riemdata"))
```

Arguments

```
n number of samples to be generated.

k dimension of the frame.

p original dimension (of the ambient space).

type return type;

"list" a length-n list of (p \times k) basis of k-frames.

"array" a (n \times k \times n) 3D array whose slices are k frame basis
```

"array" a $(p \times k \times n)$ 3D array whose slices are k-frame basis.

"riemdata" a S3 object. See wrap.stiefel for more details.

Value

an object from one of the above by type option.

References

Chikuse Y (2003). *Statistics on Special Manifolds*, volume 174 of *Lecture Notes in Statistics*. Springer New York, New York, NY. ISBN 978-0-387-00160-9 978-0-387-21540-2.

See Also

```
wrap.stiefel
```

```
#------
# Draw Samples on Stiefel Manifold
#
# Try Different Return Types with 3 Observations of 5-frames in R^10
#-----
# GENERATION
dat.list = stiefel.runif(n=3, k=5, p=10, type="list")
dat.arr3 = stiefel.runif(n=3, k=5, p=10, type="array")
dat.riem = stiefel.runif(n=3, k=5, p=10, type="riemdata")
```

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stiefel.utest

Test of Uniformity on Stiefel Manifold

Description

Given the data on Stiefel manifold St(k, p), it tests whether the data is distributed uniformly.

Usage

```
stiefel.utest(stobj, method = c("Rayleigh", "RayleighM"))
```

Arguments

stobj a S3 "riemdata" class for N Stiefel-valued data.

method (case-insensitive) name of the test method containing

"Rayleigh" original Rayleigh statistic.

"RayleighM" modified Rayleigh statistic with better order of error.

Value

a (list) object of S3 class htest containing:

statistic a test statistic.

p.value p-value under H_0 .

alternative alternative hypothesis.

method name of the test.

data.name name(s) of provided sample data.

References

Chikuse Y (2003). *Statistics on Special Manifolds*, volume 174 of *Lecture Notes in Statistics*. Springer New York, New York, NY. ISBN 978-0-387-00160-9 978-0-387-21540-2.

Mardia KV, Jupp PE (eds.) (1999). *Directional Statistics*, Wiley Series in Probability and Statistics. John Wiley & Sons, Inc., Hoboken, NJ, USA. ISBN 978-0-470-31697-9 978-0-471-95333-3.

See Also

wrap.stiefel

96 wrap.correlation

Examples

```
._____
   Compare Rayleigh's original and modified versions of the test
# Test 1. sample uniformly from St(2,4)
# Test 2. use perturbed principal components from 'iris' data in R^4
        which is concentrated around a point to reject H0.
-
#------
## DATA GENERATION
# 1. uniform data
myobj1 = stiefel.runif(n=100, k=2, p=4)
# 2. perturbed principal components
data(iris)
irdat = list()
for (n in 1:100){
  tmpdata = iris[1:50,1:4] + matrix(rnorm(50*4,sd=0.5),ncol=4)
  irdat[[n]] = eigen(cov(tmpdata))$vectors[,1:2]
myobj2 = wrap.stiefel(irdat)
## TEST
# 1. uniform data
stiefel.utest(myobj1, method="Rayleigh")
stiefel.utest(myobj1, method="RayleighM")
# 2. concentrated data
stiefel.utest(myobj2, method="rayleIgh") # method names are
stiefel.utest(myobj2, method="raYleiGhM") # CASE - INSENSITIVE !
```

wrap.correlation

Prepare Data on Correlation Manifold

Description

The collection of correlation matrices is considered as a subset (and quotient) of the well-known SPD manifold. In our package, it is defined as

$$\mathcal{C}^p_{++} = \{X \in \mathbf{R}^{p \times p} \mid X^\top = X, \ \mathrm{rank}(X) = p, \ \mathrm{diag}(X) = 1\}$$

where the rank condition means it is strictly positive definite. Please note that the geometry involving semi-definite correlation matrices is not the objective here.

Usage

```
wrap.correlation(input)
```

wrap.euclidean 97

Arguments

input

correlation data matrices to be wrapped as riemdata class. Following inputs are considered,

array an $(p \times p \times n)$ array where each slice along 3rd dimension is a correlation matrix

list a length-n list whose elements are $(p \times p)$ correlation matrices.

Value

```
a named riemdata S3 object containing 
data a list of (p \times p) correlation matrices. 
size size of each correlation matrix. 
name name of the manifold of interests, "correlation"
```

Examples

```
#------
# Checker for Two Types of Inputs
#
# 5 observations; empirical correlation of normal observations.
#-------
# Data Generation
d1 = array(0,c(3,3,5))
d2 = list()
for (i in 1:5){
   dat = matrix(rnorm(10*3),ncol=3)
   d1[,,i] = stats::cor(dat)
   d2[[i]] = d1[,,i]
}
# Run
test1 = wrap.correlation(d1)
test2 = wrap.correlation(d2)
```

wrap.euclidean

Prepare Data on Euclidean Space

Description

Euclidean space \mathbb{R}^p is the most common space for data analysis, which can be considered as a Riemannian manifold with flat metric. Since the space of matrices is isomorphic to Euclidean space after vectorization, we consider the inputs as p-dimensional vectors.

Usage

```
wrap.euclidean(input)
```

98 wrap.grassmann

Arguments

input

data vectors to be wrapped as riemdata class. Following inputs are considered, **matrix** an $(n \times p)$ matrix of row observations. **list** a length-n list whose elements are length-n vectors.

Value

```
a named riemdata S3 object containing  \begin{tabular}{ll} \bf data & a list of $(p \times 1)$ matrices in ${\bf R}^p$. \\ \bf size & dimension of the ambient space. \\ \bf name & name of the manifold of interests, "euclidean" \\ \end{tabular}
```

Examples

wrap.grassmann

Prepare Data on Grassmann Manifold

Description

Grassmann manifold Gr(k,p) is the set of k-planes, or k-dimensional subspaces in R^p , which means that for a given matrix $Y \in \mathbf{R}p \times k$, the column space SPAN(Y) is an element in Grassmann manifold. We use a convention that each element in Gr(k,p) is represented as an orthonormal basis (ONB) $X \in \mathbf{R}^{p \times k}$ where

$$X^{\top}X = I_k$$
.

If not provided in such a form, this wrapper takes a QR decomposition of the given data to recover a corresponding ONB.

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Usage

```
wrap.grassmann(input)
```

Arguments

input

data matrices to be wrapped as riemdata class. Following inputs are considered, **array** an $(p \times k \times n)$ array where each slice along 3rd dimension is a k-subspace basis in dimension p.

list a length-n list whose elements are $(p \times k)$ basis for k-subspace.

Value

a named riemdata S3 object containing

data a list of k-subspace basis matrices.

size size of each k-subspace basis matrix.

name name of the manifold of interests, "grassmann"

Examples

```
#
                  Checker for Two Types of Inputs
#
#
  Generate 5 observations in Gr(2,4)
#-
  Generation
d1 = array(0, c(4, 2, 5))
d2 = list()
for (i in 1:5){
 d1[,,i] = matrix(rnorm(4*2), ncol=2)
 d2[[i]] = d1[,,i]
}
# Run
test1 = wrap.grassmann(d1)
test2 = wrap.grassmann(d2)
```

wrap.landmark

Wrap Landmark Data on Shape Space

Description

One of the frameworks used in shape space is to represent the data as landmarks. Each shape is a point set of k points in \mathbf{R}^p where each point is a labeled object. We consider general landmarks in $p=2,3,\ldots$ Note that when p>2, it is stratified space but we assume singularities do not exist or are omitted. The wrapper takes translation and scaling out from the data to make it *preshape* (centered, unit-norm). Also, for convenience, orthogonal Procrustes analysis is applied with the first observation being the reference so that all the other data are rotated to match the shape of the first.

100 wrap.multinomial

Usage

```
wrap.landmark(input)
```

Arguments

input

data matrices to be wrapped as riemdata class. Following inputs are considered,

array a $(k \times p \times n)$ array where each slice along 3rd dimension is a k-ad in \mathbf{R}^p .

list a length-n list whose elements are k-ads.

Value

a named riemdata S3 object containing

data a list of preshapes in \mathbb{R}^p .

size size of each preshape.

name name of the manifold of interests, "landmark"

References

Dryden IL, Mardia KV (2016). *Statistical shape analysis with applications in R*, Wiley series in probability and statistics, Second edition edition. John Wiley & Sons, Chichester, UK; Hoboken, NJ. ISBN 978-1-119-07251-5 978-1-119-07250-8.

Examples

```
## USE 'GORILLA' DATA
data(gorilla)
riemobj = wrap.landmark(gorilla$male)
```

wrap.multinomial

Prepare Data on Multinomial Manifold

Description

Multinomial manifold is referred to the data that is nonnegative and sums to 1. Also known as probability simplex or positive orthant, we denote (p-1) simplex in \mathbb{R}^p by

$$\Delta^{p-1} = \{ x \in \mathbf{R}^p \mid \sum_{i=1}^p x_i = 1, x_i > 0 \}$$

in that data are positive L_1 unit-norm vectors. In wrap.multinomial, normalization is applied when each data point is not on the simplex, but if vectors contain values not in (0,1), it returns errors.

wrap.rotation 101

Usage

```
wrap.multinomial(input)
```

Arguments

input

data vectors to be wrapped as riemdata class. Following inputs are considered,

matrix an $(n \times p)$ matrix of row observations.

list a length-n list whose elements are length-p vectors.

Value

```
a named riemdata S3 object containing
```

```
data a list of (p \times 1) matrices in \Delta^{p-1}.
```

size dimension of the ambient space.

name name of the manifold of interests, "multinomial"

Examples

wrap.rotation

Prepare Data on Rotation Group

Description

Rotation group, also known as special orthogonal group, is a Riemannian manifold

$$SO(p) = \{ Q \in \mathbf{R}^{p \times p} \mid Q^{\top}Q = I, \det(Q) = 1 \}$$

where the name originates from an observation that when p=2,3 these matrices are rotation of shapes/configurations.

102 wrap.spd

Usage

```
wrap.rotation(input)
```

Arguments

input

data matrices to be wrapped as riemdata class. Following inputs are considered,

array a $(p \times p \times n)$ array where each slice along 3rd dimension is a rotation matrix.

list a length-n list whose elements are $(p \times p)$ rotation matrices.

Value

```
a named riemdata S3 object containing
```

data a list of $(p \times p)$ rotation matrices.

size size of each rotation matrix.

name name of the manifold of interests, "rotation"

Examples

wrap.spd

Prepare Data on Symmetric Positive-Definite (SPD) Manifold

Description

The collection of symmetric positive-definite matrices is a well-known example of matrix manifold. It is defined as

$$\mathcal{S}^p_{++} = \{ X \in \mathbf{R}^{p \times p} \mid X^\top = X, \ \operatorname{rank}(X) = p \}$$

where the rank condition means it is strictly positive definite. Please note that the geometry involving semi-definite matrices is considered in wrap. spdk.

wrap.spdk 103

Usage

```
wrap.spd(input)
```

Arguments

input

SPD data matrices to be wrapped as riemdata class. Following inputs are considered,

array an $(p \times p \times n)$ array where each slice along 3rd dimension is a SPD matrix

list a length-n list whose elements are $(p \times p)$ SPD matrices.

Value

```
a named riemdata S3 object containing 
data a list of (p \times p) SPD matrices. 
size size of each SPD matrix. 
name name of the manifold of interests, "spd"
```

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Description

When $(p \times p)$ SPD matrices are of fixed-rank k < p, they form a geometric structure represented by $(p \times k)$ matrices,

$$SPD(k, p) = \{X \in \mathbf{R}^{(p \times p)} \mid YY^{\top} = X, \operatorname{rank}(X) = k\}$$

It's key difference from S_{++}^p is that all matrices should be of fixed rank k where k is usually smaller than p. Inputs are given as $(p \times p)$ matrices with specified k and wrap. spdk automatically decomposes input square matrices into rank-k representation matrices.

Usage

```
wrap.spdk(input, k)
```

Arguments

input

data matrices to be wrapped as riemdata class. Following inputs are considered,

array a $(p \times p \times n)$ array where each slice along 3rd dimension is a rank-k matrix.

list a length-n list whose elements are $(p \times p)$ matrices of rank-k.

k

rank of the SPD matrices.

Value

a named riemdata S3 object containing

data a list of $(p \times k)$ representation of the corresponding rank-k SPSD matrices.

size size of each representation matrix.

name name of the manifold of interests, "spdk"

References

Journée M, Bach F, Absil P, Sepulchre R (2010). "Low-rank optimization on the cone of positive semidefinite matrices." *SIAM Journal on Optimization*, **20**(5), 2327–2351.

wrap.sphere 105

```
# Run
test1 = wrap.spdk(d1, k=2)
test2 = wrap.spdk(d2, k=2)
```

wrap.sphere

Prepare Data on Sphere

Description

The unit hypersphere (sphere, for short) is one of the most fundamental curved space in studying geometry. Precisely, we denote (p-1) sphere in \mathbf{R}^p by

$$S^{p-1} = \{ x \in \mathbf{R}^p \mid x^{\top} x = ||x||^2 = 1 \}$$

where vectors are of unit norm. In wrap. sphere, normalization is applied when each data point is not on the unit sphere.

Usage

```
wrap.sphere(input)
```

Arguments

input

data vectors to be wrapped as riemdata class. Following inputs are considered, $\mathbf{matrix}\$ an $(n\times p)$ matrix of row observations of unit norm.

 ${f list}$ a length-n list whose elements are length-p vectors of unit norm.

Value

```
a named riemdata S3 object containing \mbox{\bf data} \ \mbox{ a list of } (p\times 1) \mbox{ matrices in } \mathcal{S}^{p-1}. \mbox{\bf size dimension of the ambient space.} \mbox{\bf name name of the manifold of interests, "sphere"}
```

```
# Checker for Two Types of Inputs

# Generate 5 observations in S^2 embedded in R^3.

#------
## DATA GENERATION
d1 = array(0,c(5,3))
d2 = list()
for (i in 1:5){
```

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```
single = stats::rnorm(3)
d1[i,] = single
d2[[i]] = single
}
## RUN
test1 = wrap.sphere(d1)
test2 = wrap.sphere(d2)
```

wrap.stiefel

Prepare Data on (Compact) Stiefel Manifold

Description

Stiefel manifold St(k, p) is the set of k-frames in \mathbb{R}^p , which is indeed a Riemannian manifold. For usage in **Riemann** package, each data point is represented as a matrix by the convention

$$St(k,p) = \{ X \in \mathbf{R}^{p \times k} \mid X^{\top} X = I_k \}$$

which means that columns are orthonormal. When the provided matrix is not an orthonormal basis as above, wrap.stiefel applies orthogonalization to extract valid basis information.

Usage

```
wrap.stiefel(input)
```

Arguments

input

data matrices to be wrapped as riemdata class. Following inputs are considered, array a $(p \times k \times n)$ array where each slice along 3rd dimension is a k-frame. list a length-n list whose elements are $(p \times k)$ k-frames.

Value

```
a named riemdata S3 object containing
```

data a list of k-frame orthonormal matrices.

size size of each k-frame basis matrix.

name name of the manifold of interests, "stiefel"

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```
#------
# Checker for Two Types of Inputs
#
# Generate 5 observations in St(2,4)
#------
# Data Generation by QR Decomposition
d1 = array(0,c(4,2,5))
d2 = list()
for (i in 1:5){
    d1[,,i] = qr.Q(qr(matrix(rnorm(4*2),ncol=2)))
    d2[[i]] = d1[,,i]
}
# Run
test1 = wrap.stiefel(d1)
test2 = wrap.stiefel(d2)
```

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