Package 'deepnet'

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Type Package

Title Deep Learning Toolkit in R

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dbn.dnn.train

Training a Deep neural network with weights initialized by DBN

Description

Training a Deep neural network with weights initialized by DBN

Usage

```
dbn.dnn.train(x, y, hidden = c(1), activationfun = "sigm", learningrate = 0.8,
    momentum = 0.5, learningrate_scale = 1, output = "sigm", numepochs = 3,
    batchsize = 100, hidden_dropout = 0, visible_dropout = 0, cd = 1)
```

Arguments

x matrix of x values for examples

y vector or matrix of target values for examples

hidden vector for number of units of hidden layers. Default is c(10).

activation fun activation function of hidden unit.Can be "sigm", "linear" or "tanh".Default is

"sigm" for logistic function

learning rate for gradient descent. Default is 0.8. momentum momentum for gradient descent. Default is 0.5.

learningrate_scale

learning rate will be mutiplied by this scale after every iteration. Default is 1.

numepochs number of iteration for samples Default is 3.

batchsize size of mini-batch. Default is 100.

output function of output unit, can be "sigm", "linear" or "softmax". Default is "sigm".

hidden_dropout drop out fraction for hidden layer. Default is 0.

visible_dropout

drop out fraction for input layer Default is 0.

cd number of iteration for Gibbs sample of CD algorithm.

Author(s)

Xiao Rong

```
Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2))
Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1))
x <- matrix(c(Var1, Var2), nrow = 100, ncol = 2)
y <- c(rep(1, 50), rep(0, 50))
dnn <- dbn.dnn.train(x, y, hidden = c(5, 5))
## predict by dnn</pre>
```

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```
 \begin{split} & test\_Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2)) \\ & test\_Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1)) \\ & test\_x <- matrix(c(test\_Var1, test\_Var2), nrow = 100, ncol = 2) \\ & nn.test(dnn, test\_x, y) \end{split}
```

load.mnist

Load MNIST DataSet

Description

Load MNIST DataSet

Usage

```
load.mnist(dir)
```

Arguments

dir

dir of minst dataset

Value

mnist dataset train\$n number of train samples train\$x pix of every train sample image train\$y label of every train sample image train\$yy one-of-c vector of label of train sample image test\$n number of test samples test\$x pix of every test sample image test\$y label of every test sample image test\$yy one-of-c vector of label of test sample image

Author(s)

Xiao Rong

nn.predict

Predict new samples by Trainded NN

Description

Predict new samples by Trainded NN

Usage

```
nn.predict(nn, x)
```

Arguments

nn nerual network trained by function nn.train

x new samples to predict

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Value

return raw output value of neural network. For classification task, return the probability of a class

Author(s)

Xiao Rong

Examples

```
Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2))
Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1))
x <- matrix(c(Var1, Var2), nrow = 100, ncol = 2)
y <- c(rep(1, 50), rep(0, 50))
nn <- nn.train(x, y, hidden = c(5))
## predict by nn
test_Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2))
test_Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1))
test_x <- matrix(c(test_Var1, test_Var2), nrow = 100, ncol = 2)
yy <- nn.predict(nn, test_x)</pre>
```

nn.test

Test new samples by Trainded NN

Description

Test new samples by Trainded NN, return error rate for classification

Usage

```
nn.test(nn, x, y, t = 0.5)
```

Arguments

nn	nerual network trained by function nn.train
x	new samples to predict
У	new samples' label
t	threshold for classification. If nn.predict value >= t then label 1,else label 0

Value

error rate

Author(s)

Xiao Rong

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Examples

```
Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2))
Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1))
x <- matrix(c(Var1, Var2), nrow = 100, ncol = 2)
y <- c(rep(1, 50), rep(0, 50))
nn <- nn.train(x, y, hidden = c(5))
test_Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2))
test_Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1))
test_x <- matrix(c(test_Var1, test_Var2), nrow = 100, ncol = 2)
err <- nn.test(nn, test_x, y)</pre>
```

nn.train

Training Neural Network

Description

Training single or mutiple hidden layers neural network by BP

Usage

```
nn.train(x, y, initW = NULL, initB = NULL, hidden = c(10), activationfun = "sigm",
    learningrate = 0.8, momentum = 0.5, learningrate_scale = 1, output = "sigm",
    numepochs = 3, batchsize = 100, hidden_dropout = 0, visible_dropout = 0)
```

Arguments

matrix of x values for examples Х vector or matrix of target values for examples y initW initial weights. If missing chosen at random initB initial bias. If missing chosen at random hidden vector for number of units of hidden layers. Default is c(10). activation function of hidden unit.Can be "sigm", "linear" or "tanh".Default is activationfun "sigm" for logistic function learningrate learning rate for gradient descent. Default is 0.8. momentum momentum for gradient descent. Default is 0.5. learningrate_scale learning rate will be mutiplied by this scale after every iteration. Default is 1. numepochs number of iteration for samples Default is 3. batchsize size of mini-batch. Default is 100. function of output unit, can be "sigm", "linear" or "softmax". Default is "sigm". output hidden_dropout drop out fraction for hidden layer. Default is 0. visible_dropout drop out fraction for input layer Default is 0.

6 rbm.down

Author(s)

Xiao Rong

Examples

```
Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2))
Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1))
x <- matrix(c(Var1, Var2), nrow = 100, ncol = 2)
y <- c(rep(1, 50), rep(0, 50))
nn <- nn.train(x, y, hidden = c(5))</pre>
```

rbm.down

Generate visible vector by hidden units states

Description

Generate visible vector by hidden units states

Usage

```
rbm.down(rbm, h)
```

Arguments

rbm an rbm object trained by function train.rbm

h hidden units states

Value

generated visible vector

Author(s)

Xiao Rong

```
Var1 <- c(rep(1, 50), rep(0, 50))
Var2 <- c(rep(0, 50), rep(1, 50))
x3 <- matrix(c(Var1, Var2), nrow = 100, ncol = 2)
r1 <- rbm.train(x3, 3, numepochs = 20, cd = 10)
h <- c(0.2, 0.8, 0.1)
v <- rbm.down(r1, h)</pre>
```

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rbm.train

Training a RBM(restricted Boltzmann Machine)

Description

Training a RBM(restricted Boltzmann Machine)

Usage

```
rbm.train(x, hidden, numepochs = 3, batchsize = 100, learningrate = 0.8,
   learningrate_scale = 1, momentum = 0.5, visible_type = "bin", hidden_type = "bin",
   cd = 1)
```

Arguments

x matrix of x values for examples

hidden number of hidden units

visible_type activation function of input unit.Only support "sigm" now

hidden_type activation function of hidden unit.Only support "sigm" now

learning rate for gradient descent. Default is 0.8.

momentum momentum for gradient descent. Default is 0.5.

learningrate_scale

learning rate will be mutiplied by this scale after every iteration. Default is 1.

numepochs number of iteration for samples Default is 3.

batchsize size of mini-batch. Default is 100.

cd number of iteration for Gibbs sample of CD algorithm.

Author(s)

Xiao Rong

```
Var1 <- c(rep(1, 50), rep(0, 50))
Var2 <- c(rep(0, 50), rep(1, 50))
x3 <- matrix(c(Var1, Var2), nrow = 100, ncol = 2)
r1 <- rbm.train(x3, 10, numepochs = 20, cd = 10)</pre>
```

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rbm.up

Infer hidden units state by visible units

Description

Infer hidden units states by visible units

Usage

```
rbm.up(rbm, v)
```

Arguments

rbm an rbm object trained by function train.rbm v visible units states

Value

hidden units states

Author(s)

Xiao Rong

Examples

```
Var1 <- c(rep(1, 50), rep(0, 50))
Var2 <- c(rep(0, 50), rep(1, 50))
x3 <- matrix(c(Var1, Var2), nrow = 100, ncol = 2)
r1 <- rbm.train(x3, 3, numepochs = 20, cd = 10)
v <- c(0.2, 0.8)
h <- rbm.up(r1, v)</pre>
```

sae.dnn.train

Training a Deep neural network with weights initialized by Stacked AutoEncoder

Description

Training a Deep neural network with weights initialized by Stacked AutoEncoder

Usage

```
sae.dnn.train(x, y, hidden = c(1), activationfun = "sigm", learningrate = 0.8,
   momentum = 0.5, learningrate_scale = 1, output = "sigm", sae_output = "linear",
   numepochs = 3, batchsize = 100, hidden_dropout = 0, visible_dropout = 0)
```

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Arguments

x matrix of x values for examples

y vector or matrix of target values for examples

hidden vector for number of units of hidden layers. Default is c(10).

activation function of hidden unit. Can be "sigm", "linear" or "tanh". Default is

"sigm" for logistic function

learning rate for gradient descent. Default is 0.8. momentum for gradient descent. Default is 0.5.

learningrate_scale

learning rate will be mutiplied by this scale after every iteration. Default is 1.

numepochs number of iteration for samples Default is 3.

batchsize size of mini-batch. Default is 100.

output function of output unit, can be "sigm", "linear" or "softmax". Default is "sigm". sae_output function of autoencoder output unit, can be "sigm", "linear" or "softmax". De-

fault is "linear".

hidden_dropout drop out fraction for hidden layer. Default is 0.

visible_dropout

drop out fraction for input layer Default is 0.

Author(s)

Xiao Rong

```
Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2))
Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1))
x <- matrix(c(Var1, Var2), nrow = 100, ncol = 2)
y <- c(rep(1, 50), rep(0, 50))
dnn <- sae.dnn.train(x, y, hidden = c(5, 5))
## predict by dnn
test_Var1 <- c(rnorm(50, 1, 0.5), rnorm(50, -0.6, 0.2))
test_Var2 <- c(rnorm(50, -0.8, 0.2), rnorm(50, 2, 1))
test_x <- matrix(c(test_Var1, test_Var2), nrow = 100, ncol = 2)
nn.test(dnn, test_x, y)</pre>
```

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