Package 'gomms'

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Title GLM-Based Ordination Method
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Description A zero-inflated quasi-Poisson factor model to display similarity between samples visually in a low (2 or 3) dimensional space.
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gomms-package GLM-Based Ordination Method

Description

preliminary analysis of similarity between samples in a low (2 or 3) dimensional display.

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Author(s)

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References

Sohn, M.B. and Li, H. (2017). A GLM-Based Latent Variable Ordination Method for Microbiome Samples (Submitted).

Examples

```
## Not run:
# load test data

data(gomms_test_data);
# estimate factor scores
cdat <- as.matrix(gomms_test_data[,-ncol(gomms_test_data)]);
rslt <- gomms(cdat);
# plot estimated factor scores
y <- as.matrix(gomms_test_data$group);
gomms.plot(rslt, y);
## End(Not run)</pre>
```

gomms

GLM-Based Ordination Method for Microbiome Samples

Description

estimate factor loadings and scores.

Usage

```
gomms(X, n.factors = 2, min.prop.nonzeros = 0.05, show.max.delta = FALSE)
```

Arguments

```
X raw count data.

n.factors number of factors. Default value is 2.

min.prop.nonzeros

minimum proportion of nonzeros allowed in analysis.

show.max.delta display the maximum different between jth and (j+1)th iterations.
```

Value

estimated factor scores.

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References

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gomms.plot

Plot Factor Loadings

Description

plot estimated factor loadings for each sample.

Usage

```
gomms.plot(X, Y, col.markers = NULL, pch.markers = NULL, ...)
```

Arguments

X two dimnsional matrix of factor scores.

Y one or two dimensional matrix of classification.

col.markers user specified colors for classification.

pch.markers user specified plot symbols for classification.
... optional graphical parameters to be passed.

gomms_test_data

Test Data

Description

70 samples and 83 features. The last column contains the population identification for each sample.

Usage

```
data(gomms_test_data)
```

Qqpois Qqpois

Qqpois	Probability of a Zero from a Zero State	

Description

estimate the probability of a zero from a zero state.

Usage

```
Qqpois(cdat, eta.hat, mu.hat, dispersion)
```

Arguments

cdat count Data.

eta. hat estimated proportion of zeros from a zero state.

mu.hat estimated mean count.

dispersion estimated values for dispersion.

Value

estimated probability of a zero from a zero state.

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