

# Package ‘stdbscan’

January 27, 2026

**Title** Spatio-Temporal DBSCAN Clustering

**Version** 0.1.0

**Description** Implements the ST-DBSCAN (spatio-temporal density-based spatial clustering of applications with noise) clustering algorithm for detecting spatially and temporally dense regions in point data, with a fast C++ backend via 'Rcpp'. Birant and Kut (2007) <[doi:10.1016/j.datak.2006.01.013](https://doi.org/10.1016/j.datak.2006.01.013)>.

**License** GPL (>= 3)

**Depends** R (>= 3.5.0)

**Encoding** UTF-8

**RoxygenNote** 7.3.3

**URL** <https://github.com/MiboraMinima/stdbscan/>,  
<https://miboraminima.github.io/stdbscan/>

**BugReports** <https://github.com/MiboraMinima/stdbscan/issues/>

**LinkingTo** Rcpp

**Imports** Rcpp

**Suggests** knitr, rmarkdown, readr, testthat, ggplot2, lubridate,  
plotly, covr, MetBrewer

**VignetteBuilder** knitr

**LazyData** true

**NeedsCompilation** yes

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**Repository** CRAN

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## Contents

geolife_traj . . . . .	2
st_dbSCAN . . . . .	3

**geolife\_traj***GPS pings from the GeoLife GPS Trajectories dataset***Description**

Extraction of the GeoLife GPS Trajectories dataset. The selected trajectory id is 000-20081023025304.

Data manipulation applied to the raw data :

- Conversion to EPSG:4586
- Manual selection of the pings
- Selection of relevant variables

**Usage**

```
geolife_traj
```

**Format**

A `data.frame` with one row per ping and the following columns:

- `date` (chr): The date
- `time` (chr): The time
- `x` (dbl): Longitude (EPSG:4586)
- `y` (dbl): Latitude (EPSG:4586)

**Source**

<https://www.microsoft.com/en-us/download/details.aspx?id=52367>

**Examples**

```
data(geolife_traj)
head(geolife_traj)
```

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st_dbSCAN	<i>Spatio-Temporal DBSCAN</i>
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## Description

Perform **ST-DBSCAN** clustering on points with spatial and temporal coordinates. This algorithm identifies clusters of points that are close both in space and time.

## Usage

```
st_dbSCAN(x, y, t, eps_spatial, eps_temporal, min_pts)
```

## Arguments

x	Numeric vector of x-coordinates (spatial).
y	Numeric vector of y-coordinates (spatial).
t	Numeric vector of time values. t is expected to represent elapsed time since a common origin (e.g. c(0, 6, 10)).
eps_spatial	Numeric. The spatial radius threshold. Points closer than this in space may belong to the same cluster.
eps_temporal	Numeric. The temporal threshold. Points closer than this in time may belong to the same cluster.
min_pts	Integer. Minimum number of points required to form a core point (standard DBSCAN parameter).

## Details

ST-DBSCAN extends classical DBSCAN by incorporating a temporal constraint. Two points are considered neighbors if they are within eps\_spatial in space **and** within eps\_temporal in time. Clusters are expanded from core points recursively following the DBSCAN algorithm.

This function is implemented in C++ via Rcpp for performance.

## Value

An integer vector of length `length(x)` with cluster assignments:

- -1: noise point
- >=1: cluster ID

## References

Birant, D., & Kut, A. (2007). ST-DBSCAN: An algorithm for clustering spatial-temporal data. *Data & Knowledge Engineering*, 60(1), 208–221. <https://doi.org/10.1016/j.datak.2006.01.013>

**Examples**

```
data(geolife_traj)

geolife_traj$date_time <- as.POSIXct(
  paste(geolife_traj$date, geolife_traj$time),
  format = "%Y-%m-%d %H:%M:%S",
  tz = "GMT"
)

geolife_traj$t <- as.numeric(
  geolife_traj$date_time - min(geolife_traj$date_time)
)

st_dbscan(
  x = geolife_traj$x,
  y = geolife_traj$y,
  t = geolife_traj$t,
  eps_spatial = 3, # meters
  eps_temporal = 30, # seconds
  min_pts = 3
)
```

# Index

\* **datasets**

geolife\_traj, [2](#)

geolife\_traj, [2](#)

st\_dbSCAN, [3](#)