Package 'smoothtail'

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Description Given independent and identically distributed observations X(1),, X(n) from a Generalized Pareto distribution with shape parameter gamma in [-1,0], offers several estimates to compute estimates of gamma. The estimates are based on the principle of replacing the order statistics by quantiles of a distribution function based on a logconcave density function. This procedure is justified by the fact that the GPD density is logconcave for gamma in [-1,0].
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<pre>URL http://www.kasparrufibach.ch, www.maths.usyd.edu.au/ut/people?who=S_Mueller</pre>
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smoothtail-package

Smooth Estimation of GPD Shape Parameter

Description

Given independent and identically distributed observations $X_1 < \ldots < X_n$ from a Generalized Pareto distribution with shape parameter $\gamma \in [-1,0]$, offers three methods to compute estimates of γ . The estimates are based on the principle of replacing the order statistics $X_{(1)}, \ldots, X_{(n)}$ of the sample by quantiles $\hat{X}_{(1)}, \ldots, \hat{X}_{(n)}$ of the distribution function \hat{F}_n based on the log-concave density estimator \hat{f}_n . This procedure is justified by the fact that the GPD density is log-concave for $\gamma \in [-1,0]$.

Details

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Type: Package
Version: 2.0.5
Date: 2016-07-12
License: GPL (>=2)

Use this package to estimate the shape parameter γ of a Generalized Pareto Distribution (GPD). In extreme value theory, γ is denoted tail index. We offer three new estimators, all based on the fact that the density function of the GPD is log-concave if $\gamma \in [-1,0]$, see Mueller and Rufibach (2009). The functions for estimation of the tail index are:

```
pickands
falk
falkMVUE
generalizedPick
```

This package depends on the package **logcondens** for estimation of a log-concave density: all the above functions take as first argument a dlc object as generated by logConDens in **logcondens**.

Additionally, functions for density, distribution function, quantile function and random number generation for a GPD with location parameter 0, shape parameter γ and scale parameter σ are provided:

dgpd pgpd qgpd rgpd.

Let us shortly clarify what we mean with log-concave density estimation. Suppose we are given an ordered sample $Y_1 < \ldots < Y_n$ of i.i.d. random variables having density function f, where $f = \exp \varphi$ for a concave function $\varphi : [-\infty, \infty) \to R$. Following the development in Duembgen and Rufibach (2009), it is then possible to get an estimator $\hat{f}_n = \exp \hat{\varphi}_n$ of f via the maximizer $\hat{\varphi}_n$ of

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$$L(\varphi) = \sum_{i=1}^{n} \varphi(Y_i) - \int \exp \varphi(t) dt$$

over all concave functions φ . It turns out that $\hat{\varphi}_n$ is piecewise linear, with knots only at (some of the) observation points. Therefore, the infinite-dimensional optimization problem of finding the function $\hat{\varphi}_n$ boils down to a finite dimensional problem of finding the vector $(\hat{\varphi}_n(Y_1), \dots, \hat{\varphi}(Y_n))$. How to solve this problem is described in Rufibach (2006, 2007) and in a more general setting in Duembgen, Huesler, and Rufibach (2010). The distribution function based on \hat{f}_n is defined as

$$\hat{F}_n(x) = \int_{Y_1}^x \hat{f}_n(t)dt$$

for x a real number. The definition of \hat{F}_n is justified by the fact that $\hat{F}_n(Y_1) = 0$.

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Duembgen, L., Huesler, A. and Rufibach, K. (2010) Active set and EM algorithms for log-concave densities based on complete and censored data. Technical report 61, IMSV, Univ. of Bern, available at http://arxiv.org/abs/0707.4643.

Mueller, S. and Rufibach K. (2009). Smooth tail index estimation. *J. Stat. Comput. Simul.*, **79**, 1155–1167.

Mueller, S. and Rufibach K. (2008). On the max-domain of attraction of distributions with log-concave densities. *Statist. Probab. Lett.*, **78**, 1440–1444.

Rufibach K. (2006) *Log-concave Density Estimation and Bump Hunting for i.i.d. Observations*. PhD Thesis, University of Bern, Switzerland and Georg-August University of Goettingen, Germany, 2006.

Available at http://www.zb.unibe.ch/download/eldiss/06rufibach_k.pdf.

Rufibach, K. (2007) Computing maximum likelihood estimators of a log-concave density function. *J. Stat. Comput. Simul.*, **77**, 561–574.

See Also

Package logcondens.

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Examples

```
# generate ordered random sample from GPD
set.seed(1977)
n <- 20
gam < - -0.75
x <- rgpd(n, gam)
# compute known endpoint
omega <- -1 / gam
# estimate log-concave density, i.e. generate dlc object
est <- logConDens(x, smoothed = FALSE, print = FALSE, gam = NULL, xs = NULL)
# plot distribution functions
s \leftarrow seq(0.01, max(x), by = 0.01)
plot(0, 0, type = 'n', ylim = c(0, 1), xlim = range(c(x, s))); rug(x)
lines(s, pgpd(s, gam), type = 'l', col = 2)
lines(x, 1:n / n, type = 's', col = 3)
lines(x, est$Fhat, type = 'l', col = 4)
legend(1, 0.4, c('true', 'empirical', 'estimated'), col = c(2 : 4), lty = 1)
# compute tail index estimators for all sensible indices k
falk.logcon <- falk(est)</pre>
falkMVUE.logcon <- falkMVUE(est, omega)</pre>
pick.logcon <- pickands(est)</pre>
genPick.logcon <- generalizedPick(est, c = 0.75, gam0 = -1/3)
# plot smoothed and unsmoothed estimators versus number of order statistics
plot(0, 0, type = 'n', xlim = c(0,n), ylim = c(-1, 0.2))
lines(1:n, pick.logcon[, 2], col = 1); lines(1:n, pick.logcon[, 3], col = 1, lty = 2)
lines(1:n, falk.logcon[, 2], col = 2); lines(1:n, falk.logcon[, 3], col = 2, lty = 2)
lines(1:n, falkMVUE.logcon[,2], col = 3); lines(1:n, falkMVUE.logcon[,3], col = 3,
   1ty = 2
lines(1:n, genPick.logcon[, 2], col = 4); lines(1:n, genPick.logcon[, 3], col = 4,
   1ty = 2
abline(h = gam, lty = 3)
legend(11, 0.2, c("Pickands", "Falk", "Falk MVUE", "Generalized Pickands'"),
   1ty = 1, col = 1:8
```

falk

Compute original and smoothed version of Falk's estimator

Description

Given an ordered sample of either exceedances or upper order statistics which is to be modeled using a GPD, this function provides Falk's estimator of the shape parameter $\gamma \in [-1, 0]$. Precisely,

$$\hat{\gamma}_{\text{Falk}} = \hat{\gamma}_{\text{Falk}}(k, n) = \frac{1}{k - 1} \sum_{j=2}^{k} \log \left(\frac{X_{(n)} - H^{-1}((n - j + 1)/n)}{X_{(n)} - H^{-1}((n - k)/n)} \right), \quad k = 3, \dots, n - 1$$

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for \$H\$ either the empirical or the distribution function based on the log-concave density estimator. Note that for any k, $\hat{\gamma}_{Falk}: R^n \to (-\infty,0)$. If $\hat{\gamma}_{Falk} \not\in [-1,0)$, then it is likely that the log-concavity assumption is violated.

Usage

```
falk(est, ks = NA)
```

Arguments

est Log-concave density estimate based on the sample as output by logConDens (a dlc object).

ks Indices k at which Falk's estimate should be computed. If set to NA defaults to

 $3, \ldots, n-1$.

Value

n x 3 matrix with columns: indices k, Falk's estimator based on the log-concave density estimate, and the ordinary Falk's estimator based on the order statistics.

Author(s)

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```

References

Mueller, S. and Rufibach K. (2009). Smooth tail index estimation. *J. Stat. Comput. Simul.*, **79**, 1155–1167.

Falk, M. (1995). Some best parameter estimates for distributions with finite endpoint. *Statistics*, **27**, 115–125.

See Also

Other approaches to estimate γ based on the fact that the density is log-concave, thus $\gamma \in [-1,0]$, are available as the functions pickands, falkMVUE, generalizedPick.

Examples

```
# generate ordered random sample from GPD
set.seed(1977)
n <- 20
gam <- -0.75
x <- rgpd(n, gam)</pre>
```

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```
## generate dlc object
est <- logConDens(x, smoothed = FALSE, print = FALSE, gam = NULL, xs = NULL)
# compute tail index estimator
falk(est)</pre>
```

falkMVUE

Compute original and smoothed version of Falk's estimator for a known endpoint

Description

Given an ordered sample of either exceedances or upper order statistics which is to be modeled using a GPD with distribution function F, this function provides Falk's estimator of the shape parameter $\gamma \in [-1,0]$ if the endpoint

$$\omega(F) = \sup\{x : F(x) < 1\}$$

of F is known. Precisely,

$$\hat{\gamma}_{\text{MVUE}} = \hat{\gamma}_{\text{MVUE}}(k, n) = \frac{1}{k} \sum_{j=1}^{k} \log \left(\frac{\omega(F) - H^{-1}((n-j+1)/n)}{\omega(F) - H^{-1}((n-k)/n)} \right), \quad k = 2, \dots, n-1$$

for H either the empirical or the distribution function based on the log-concave density estimator. Note that for any k, $\hat{\gamma}_{\text{MVUE}}: R^n \to (-\infty, 0)$. If $\hat{\gamma}_{\text{MVUE}} \notin [-1, 0)$, then it is likely that the log-concavity assumption is violated.

Usage

```
falkMVUE(est, omega, ks = NA)
```

Arguments

est	Log-concave density estimate based on the sample as output by logConDens (a dlc object).
omega	Known endpoint. Make sure that $\omega \geq X_{(n)}$.
ks	Indices k at which Falk's estimate should be computed. If set to NA defaults to

 $2, \ldots, n-1$.

Value

n x 3 matrix with columns: indices k, Falk's MVUE estimator using the log-concave density estimate, and the ordinary Falk MVUE estimator based on the order statistics.

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Author(s)

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Kaspar Rufibach acknowledges support by the Swiss National Science Foundation SNF, http://www.snf.ch
```

References

Mueller, S. and Rufibach K. (2009). Smooth tail index estimation. *J. Stat. Comput. Simul.*, **79**, 1155–1167.

Falk, M. (1994). Extreme quantile estimation in δ -neighborhoods of generalized Pareto distributions. *Statistics and Probability Letters*, **20**, 9–21.

Falk, M. (1995). Some best parameter estimates for distributions with finite endpoint. *Statistics*, **27**, 115–125.

See Also

Other approaches to estimate γ based on the fact that the density is log-concave, thus $\gamma \in [-1, 0]$, are available as the functions pickands, falk, generalizedPick.

Examples

```
# generate ordered random sample from GPD
set.seed(1977)
n <- 20
gam <- -0.75
x <- rgpd(n, gam)

## generate dlc object
est <- logConDens(x, smoothed = FALSE, print = FALSE, gam = NULL, xs = NULL)
# compute tail index estimators
omega <- -1 / gam
falkMVUE(est, omega)</pre>
```

generalizedPick

Compute generalized Pickand's estimator

Description

Given an ordered sample of either exceedances or upper order statistics which is to be modeled using a GPD with distribution function F, this function provides Segers' estimator of the shape parameter γ , see Segers (2005). Precisely, for $k=\{1,\ldots,n-1\}$, the estimator can be written as

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$$\hat{\gamma}_{\text{Segers}}^{k}(H) = \sum_{j=1}^{k} \left(\lambda(j/k) - \lambda((j-1)/k) \right) \log \left(H^{-1}((n - \lfloor cj \rfloor)/n) - H^{-1}((n-j)/n) \right)$$

for H either the empirical or the distribution function based on the log-concave density estimator and λ the mixing measure given in Segers (2005), Theorem 4.1, (i). Note that for any k, $\hat{\gamma}_{\text{Segers}}^k$: $R^n \to (-\infty, \infty)$. If $\hat{\gamma}_{\text{Segers}} \notin [-1, 0)$, then it is likely that the log-concavity assumption is violated.

Usage

```
generalizedPick(est, c, gam0, ks = NA)
```

Arguments

est	Log-concave density estimate based on the sample as output by logConDens (a dlc object).
С	Number in $(0,1)$, determining the spacings that are used.
gam0	Number in $R \setminus 0.5$, specifying the mixing measure.
ks	Indices k at which Falk's estimate should be computed. If set to NA defaults to $4, \ldots, n$.

Value

n x 3 matrix with columns: indices k, Segers' estimator using the smoothing method, and the ordinary Segers' estimator based on the order statistics.

Author(s)

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Kaspar Rufibach acknowledges support by the Swiss National Science Foundation SNF, http://www.snf.ch
```

References

Mueller, S. and Rufibach K. (2009). Smooth tail index estimation. *J. Stat. Comput. Simul.*, **79**, 1155–1167.

Segers, J. (2005). Generalized Pickands estimators for the extreme value index. *J. Statist. Plann. Inference*, **128**, 381–396.

See Also

Other approaches to estimate γ based on the fact that the density is log-concave, thus $\gamma \in [-1, 0]$, are available as the functions pickands, falk, falkMVUE.

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Examples

```
# generate ordered random sample from GPD
set.seed(1977)
n <- 20
gam <- -0.75
x <- rgpd(n, gam)

## generate dlc object
est <- logConDens(x, smoothed = FALSE, print = FALSE, gam = NULL, xs = NULL)
# compute tail index estimators
generalizedPick(est, c = 0.75, gam0 = -1/3)</pre>
```

gpd

The Generalized Pareto Distribution

Description

Density function, distribution function, quantile function and random generation for the generalized Pareto distribution (GPD) with shape parameter γ and scale parameter σ .

Usage

```
dgpd(x, gam, sigma = 1)
pgpd(q, gam, sigma = 1)
qgpd(p, gam, sigma = 1)
rgpd(n, gam, sigma = 1)
```

Arguments

x, q	Vector of quantiles.
p	Vector of probabilities.
n	Number of observations.
gam	Shape parameter, real number.
sigma	Scale parameter, positive real number.

Details

The generalized Pareto distribution function (Pickands, 1975) with shape parameter γ and scale parameter σ is

$$W_{\gamma,\sigma}(x) = 1 - (1 + \gamma x/\sigma)_+^{-1/\gamma}.$$

If $\gamma = 0$, the distribution function is defined by continuity. The density is denoted by $w_{\gamma,\sigma}$.

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Value

dgpd gives the values of the density function, pgpd those of the distribution function, and qgpd those of the quantile function of the GPD at x, q, and p, respectively. rgpd generates n random numbers, returned as an ordered vector.

Author(s)

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```

References

Pickands, J. (1975). Statistical inference using extreme order statistics. *Annals of Statistics*, 3, 119-131.

See Also

Similar functions are provided in the R-packages evir and evd.

lambdaGenPick

Auxiliary function to compute Segers' estimator

Description

This function computes

$$\lambda_{\delta,\rho}^c$$

given in Theorem 4.1 of Segers (2005) and is called by generalizedPick. It is not intended to be called by the user.

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Segers, J. (2005). Generalized Pickands estimators for the extreme value index. *J. Statist. Plann. Inference*, **128**, 381–396.

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See Also

Called by generalizedPick.

pickands

Compute original and smoothed version of Pickands' estimator

Description

Given an ordered sample of either exceedances or upper order statistics which is to be modeled using a GPD, this function provides Pickands' estimator of the shape parameter $\gamma \in [-1,0]$. Precisely, for $k=4,\ldots,n$

$$\hat{\gamma}_{\text{Pick}}^k = \frac{1}{\log 2} \log \left(\frac{H^{-1}((n - r_k(H) + 1)/n) - H^{-1}((n - 2r_k(H) + 1)/n)}{H^{-1}((n - 2r_k(H) + 1)/n) - H^{-1}((n - 4r_k(H) + 1)/n)} \right)$$

for \$H\$ either the empirical or the distribution function \hat{F}_n based on the log–concave density estimator and

$$r_k(H) = \lfloor k/4 \rfloor$$

if H is the empirical distribution function and

$$r_k(H) = k/4$$

if
$$H = \hat{F}_n$$
.

Usage

```
pickands(est, ks = NA)
```

Arguments

ks

est Log-concave density estimate based on the sample as output by logConDens (a dlc object).

Indices k at which Falk's estimate should be computed. If set to NA defaults to $4, \ldots, n$.

Value

n x 3 matrix with columns: indices k, Pickands' estimator using the log-concave density estimate, and the ordinary Pickands' estimator based on the order statistics.

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References

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Pickands, J. (1975). Statistical inference using extreme order statistics. *Annals of Statistics* 3, 119–131.

See Also

Other approaches to estimate γ based on the fact that the density is log-concave, thus $\gamma \in [-1,0]$, are available as the functions falk, falkMVUE, generalizedPick.

Examples

```
# generate ordered random sample from GPD
set.seed(1977)
n <- 20
gam <- -0.75
x <- rgpd(n, gam)

## generate dlc object
est <- logConDens(x, smoothed = FALSE, print = FALSE, gam = NULL, xs = NULL)
# compute tail index estimators
pickands(est)</pre>
```

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