# Package 'merror'

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Title Accuracy and Precision of Measurements

**Description** N>=3 methods are used to measure each of n items.

The data are used to estimate simultaneously systematic error (bias) and random error (imprecision). Observed measurements for each method or device are assumed to be linear functions of the unknown true values and the errors are assumed normally distributed. Pairwise calibration curves and plots can be easily generated. Unlike the 'ncb.od' function, the 'omx' function builds a one-factor measurement error model using 'OpenMx' and allows missing values, uses full information maximum likelihood to estimate parameters, and provides both likelihood-based and bootstrapped confidence intervals for all parameters, in addition to Wald-type intervals.

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alpha.beta.sigma

Build an alpha-beta-sigma Matrix for Use with the cplot Function

### Description

Creates a  $3 \times N$  (no. of methods) matrix consisting of the estimated alphas, betas, and imprecision sigmas for use with the cplot function.

### Usage

```
alpha.beta.sigma(x)
```

### **Arguments**

Х

A  $k \times 3$  data, frame with parameter estimates in the second column where k is the number of methods  $m \times 3$ . The estimates should be arranged with the estimated m-1 betas first, followed by the m residual variances, the variance of the true values, the m-1 alphas, the mean of the true values. The omx function returns the fitted model in fit from which parameter estimates can be retrieved. See the examples below.

#### **Details**

This is primarily a helper function used by the omx function.

### Value

A  $3 \times N$  matrix consisting of alphas on the first row, betas on the second row, followed by raw imprecision sigmas.

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#### See Also

```
cplot, omx.
```

#### **Examples**

```
## Not run:
library(OpenMx)
library(merror)
data(pm2.5)
pm <- pm2.5
# OpenMx does not like periods in data column names
names(pm) <- c('ms_conc_1', 'ws_conc_1', 'ms_conc_2', 'ws_conc_2', 'frm')</pre>
# Fit model with FRM sampler as reference
omxfit <- omx(data=pm[,c(5,1:4)],bs.q=c(0.025,0.5,0.975),reps=100)
# Extract the estimates
alpha.beta.sigma(summary(omxfit$fit)$parameters[,c(1,5,6)])
# Make a calibration plot
cplot(pm[,c(5,1:4)],1,2,alpha.beta.sigma=
  alpha.beta.sigma(summary(omxfitfit)parameters[,c(1,5,6)])
# The easier way
cplot(pm[,c(5,1:4)],1,2,alpha.beta.sigma=omxfit$abs)
## End(Not run)
```

beta.bar

Compute the estimates of betas.

### Description

This function is used internally to compute the estimates of betas.

### Usage

```
beta.bar(x)
```

#### **Arguments**

х

A matrix or numeric data.frame consisting of an n (no. of items) by N (no. of methods) matrix of measuremnts.

### **Details**

```
See Jaech, p. 184.
```

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#### Value

A vector of length N (no. of methods) containing the estimates of beta.

#### Author(s)

Richard A. Bilonick

#### References

```
Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley.
```

#### See Also

```
cb.pd, ncb.od,1rt
```

### **Examples**

```
data(pm2.5)
beta.bar(pm2.5) # estimate betas (accuracy parameter)
```

cb.pd

Compute accuracy estimates and maximum likelihood estimates of precision for the constant bias measurement error model using paired data.

### Description

Compute accuracy estimates and maximum likelihood estimates of precision for the constant bias measurement error model using paired data.

### Usage

```
cb.pd(x, conf.level = 0.95, M = 40)
```

### **Arguments**

x n (no. of items) x N (no. of methods) matrix or data.frame containing the measurements. N must be >= 3 and n > N.

conf.level Chosen onfidence level.

Maximum no.of iterations to reach convergence.

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#### **Details**

Measurement Error Model:

```
x[i,k] = alpha[i] + beta[i]*mu[k] + epsilon[i,k]
```

where x[i,k] is the measurement by the ith method for the kth item, i = 1 to N, k = 1 to n, mu[k] is the true value for the kth item, epsilon[i,k] is the Normally distributed random error with variance sigma[i] squared for the ith method and the kth item, and alpha[i] and beta[i] are the accuracy parameters for the ith method.

The imprecision for the ith method is sigma[i]. If all alphas are zeroes and all betas are ones, there is no bias. If all betas equal 1, then there is a constant bias. Otherwise there is a nonconstant bias.

ME (method of moments estimator) and MLE are the same for N=3 instruments except for a factor of (n-1)/n: MLE = (n-1)/n \* ME

Using paired differences forces Constant Bias model (beta[1] = beta[2] = ... = beta[N]). Also, the process variance CANNOT be estimated.

#### Value

conf.level	Confidence level used.
sigma.table	Table of accuracy and precision estimates and confidence intervals.
n.items	No. of items.
N.methods Grubbs.initial.	
	N vector of initial imprecision estimates using Grubbs' method
sigma2	N vector of variances that measure the method imprecision.
sigma2.se2	N vector of squared standard errors of the estimated imprecisions (variances).
alpha.cb	N vector of estimated alphas for constant bias model.
alpha.ncb	N vector of estimated alphas for nonconstant bias model
beta	N vector of hypothesized betas for the constant bias model - all ones.
df	N vector of estimated degrees of freedom.
chisq.low	N vector of chi-square values for the lower tail (used to compute the ci upper bound).
chisq.low	N vector of chi-square values for the upper tail (used to compute the ci lower bound).
1b	N vector of lower bounds for confidence intervals
ub	N vector of upper bounds for confidence intervals

#### Author(s)

Richard A. Bilonick

#### References

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#### See Also

```
ncb.od, 1rt
```

### **Examples**

```
data(pm2.5)
cb.pd(pm2.5)
```

cplot

Scatter plot of observations for a pair of devices with calibration curve.

### Description

Creates a scatter plot for any pair of observations in the data.frame and superimposes the calibration curve.

#### Usage

```
cplot(df, i, j, leg.loc="topleft", regress=FALSE, lw=1, t.size=1, alpha.beta.sigma=NULL)
```

### Arguments

df n (no. of items) x N (no. of methods) matrix or data.frame containing the measurements. N must be >= 3 and n > N.
 i Select column i for device i.
 j Select column j for device j not equal to i.

leg.loc Location of the legend.

regress If TRUE, add both naive regression lines (for comparison only).

lw Line widths.t.size Text size.

alpha.beta.sigma

By default, cplot computes the bias (alpha, beta) and imprecision (sigma) estimates using ncb.od. You can override this by specifying a 3 x N matrix of values with alpha on the first row, beta on the second row, and sigma on the third row, in the same order as the methods.

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#### **Details**

By default, cplot displays the corresponding calibration curve for devices i and j based on the parameter estimates for alpha, beta, and sigma computed using ncb. od. You can overide this calibration curve by providing argument alpha.beta.sigma with different estimates. Both naive regression lines (device i regressed on device j, and device j regressed on device i) by setting "regress=TRUE". Note, however, that the calibration curve will fall somewhere between these two regression lines, depending on the the ratio of the imprecision standard deviations (sigmas). (This may not hold if there are missing measurement data values given that ordinary regression requires deleting any item with one or more missing values.)

#### Value

Produces a scatter plot with the calibration curve and titles that includes the calibration equation and the scale-bias adjusted imprecision standard deviations.

#### Author(s)

Richard A. Bilonick

#### References

Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley.

#### See Also

```
merror.pairs
```

### **Examples**

```
library(merror)
data(pm2.5)
# Make various calibration plots for pm2.5 measurements
par(mfrow=c(2,2))
cplot(pm2.5,2,1)
cplot(pm2.5,3,1)
cplot(pm2.5,4,1)
# Add the naive regression lines JUST for comparison
cplot(pm2.5,5,1,regress=TRUE,t.size=0.9)
# This is redundant but illustrates using the
# argument alpha.beta.sigma
a <- ncb.od(pm2.5)$sigma.table$alpha.ncb[1:5]</pre>
b <- ncb.od(pm2.5)$sigma.table$beta[1:5]</pre>
s <- ncb.od(pm2.5)$sigma.table$sigma[1:5]</pre>
alpha.beta.sigma <- t(data.frame(a,b,s))</pre>
cplot(pm2.5,2,1,alpha.beta.sigma=alpha.beta.sigma)
cplot(pm2.5,2,1,alpha.beta.sigma=alpha.beta.sigma,regress=TRUE)
```

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```
data(pm2.5)
## Not run:
# Use omx function to specify the data for alpha.beta.sigma
pm <- pm2.5

# omx uses OpenMx which does not like periods in data column names
names(pm) <- c('ms_conc_1','ws_conc_2','ws_conc_2','frm')

# Fit one-factor measurement error model with FRM sampler as reference
omxfit <- omx(data=pm[,c(5,1:4)],bs.q=c(0.025,0.5,0.975),reps=100)

# Make a calibration plot using the results from omx instead of the default ncb.od
cplot(pm[,c(5,1:4)],1,2,alpha.beta.sigma=omxfit$abs)

## End(Not run)</pre>
```

errors.cb

Extracts the estimated measurement errors assuming there is a constant bias and using the original data.

### **Description**

Extracts the estimated measurement errors assuming there is a constant bias and using the original data values.

#### Usage

```
errors.cb(x)
```

### **Arguments**

Х

A matrix or numeric data frame consisting of an n (no. of items) by N (no. of methods) matrix of measuremnts. N must be  $\geq 3$  and n > N.

#### **Details**

Errors should have a zero mean and should be Normally distributed with constant variance for a given method.

#### Value

errors.cb

n x N matrix of estimated measurement errors.

#### Author(s)

Richard A. Bilonick

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#### References

```
Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley
```

### See Also

```
cb.pd, ncb.od,lrt
```

### **Examples**

```
data(pm2.5)
errors.cb(pm2.5)
```

errors.nb

Extracts the estimated measurement errors assuming there is no bias and using the original data.

### **Description**

Extracts the estimated measurement errors assuming there is no bias and using the original data values.

### Usage

```
errors.nb(x)
```

### Arguments

Х

A matrix or numeric data.frame consisting of an n (no. of items) by N (no. of methods) matrix of measuremnts. N must be >= 3 and n > N.

### **Details**

Errors should have a zero mean and should be Normally distributed with constant variance for a given method.

#### Value

errors.nb

n x N matrix of estimated errors.

#### Author(s)

Richard A. Bilonick

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#### References

Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley.

#### See Also

```
cb.pd, ncb.od,1rt
```

#### **Examples**

```
data(pm2.5)
errors.nb(pm2.5)
```

errors.ncb

Extracts the estimated measurement errors assuming there is a nonconstant bias and using the original data values.

### Description

Extracts the estimated measurement errors assuming there is a nonconstant bias and using the original data values.

### Usage

```
errors.ncb(x)
```

### **Arguments**

Х

A matrix or numeric data.frame consisting of an n (no. of items) by N (no. of methods) matrix of measuremnts. N must be >= 3 and n > N.

#### **Details**

Errors should have a zero mean and should be Normally distributed with constant variance for a given method.

#### Value

errors.ncb

n x N matrix of estimated errors.

#### Author(s)

Richard A. Bilonick

#### References

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#### See Also

```
cb.pd, ncb.od,lrt
```

#### **Examples**

```
data(pm2.5)
errors.ncb(pm2.5)
```

lrt

Likelihood ratio test for all betas equalling one.

### **Description**

Likelihood ratio test statistic - H0: all betas = one.

#### Usage

```
lrt(x, M = 40)
```

#### **Arguments**

x n (no. of items) x N (no. of methods) matrix or data.frame containing the

measurements. N must be greater than 3 and n > N.

Maximum no. of iterations for convergence.

#### **Details**

See Jaech, pp. 204-205.

### Value

n.items No.of items.
N.methods No. of methods.'

beta.bars N vector of estimated betas. lambda Chi-square test statistic.

df Degrees of freedom for the test (N-1).'

p.value Empirical significance level for the observed test statistic.'

### Author(s)

Richard A. Bilonick

#### References

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#### See Also

```
ncb.od,cb.pd,pm2.5
```

#### **Examples**

```
data(pm2.5)
lrt(pm2.5) # compare all 5 samplers (4 personal and 1 frm)
lrt(pm2.5[,1:4]) # compare only the personal samplers
stem(lrt(pm2.5)$beta.bars) # examine the estimated betas
```

merror.pairs

A modified "pairs" plot with all axes haveing the same range.

### Description

Creates all pairwise scatter plots.

### Usage

```
merror.pairs(df,labels=names(df))
```

### **Arguments**

df n (no. of items) x N (no. of methods) matrix or data.frame containing the

measurements. N must be  $\geq 3$  and n > N.

labels Provide labels for each device down the diagnoal of the pairs plot.

#### **Details**

Creates all pairwise scatter plots with the same range for all axes and adds the diagonal line denote the "line of equality" or "no bias".).

### Value

Produces a scatter plot with the calibration curve and titles that include the calibration equation and the scale-bias adjusted imprecision standard deviations.

### Author(s)

Richard A. Bilonick

```
panel.merror
```

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### **Examples**

```
data(pm2.5)
# All pairwise plots after square root transformation to Normality
merror.pairs(sqrt(pm2.5))
```

mle

Compute maximum likelihood estimates of precision.

### Description

This is an internal function that computes the maximum likelihood estimates of precision for the constant bias model using paired data.

### Usage

```
mle(v, r, ni)
```

### Arguments

Variance-Covariance matrix for the n x N items by methods measurement data.

r Initial estimates of imprecision, usually Grubbs.

ni No. of items measured.

### Value

An N vector containing the maximum likelihood estimates of precision.

### Author(s)

Richard A. Bilonick

#### References

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mle.se2	Compute squared standard errors for imprecision estimates for the constant bias model using paired data.

### Description

This is an internal function that computes squared standard errors for imprecision estimates of the constant bias model using paired data.

### Usage

```
mle.se2(v, r, ni)
```

### **Arguments**

v Variance-Covariance matrix for the n x N items by methods measuremen	it data.
--	----------

r Initial estimates of imprecision, usually Grubbs

ni No. of items measured

### **Details**

Computes the squared standard errors for the squared precisions. Before calling this function, compute the MLE's

#### Value

An N+1 symmetric H matrix. See p. 201 of Jaech, 1985, eq. 6.4.2.

### Author(s)

Richard A. Bilonick

### References

J. L. Jaech, Statistical Analysis of Measurement Errors, Wiley, New York: 1985.

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-	
ncb.od	Compute accuracy estimates and maximum likelihood estimates of precision for the nonconstant bias measurement error model using original data.

#### **Description**

Compute accuracy estimates and maximum likelihood estimates of precision for the nonconstant bias measurement error model using original data.

#### Usage

```
ncb.od(x, beta = beta.bar(x), M = 40, conf.level = 0.95)
```

#### **Arguments**

x n (no. of items) x N (no. of methods) matrix or data.frame containing the measurements. N must be >= 3. Missing values are not allowed.

beta N vector of betas, either estimated by beta.bar function or hypothesized.

Maximum number of iterations for convergence.

conf. level Chosen confidence level which must be greater than zero and less than one.

#### **Details**

Measurement Error Model:

```
x[i,k] = alpha[i] + beta[i]*mu[k] + epsilon[i,k]
```

where x[i,k] is the measurement by the ith method for the kth item, i = 1 to N, k = 1 to n, mu[k] is the true value for the kth item, epsilon[i,k] is the normally distributed random error with variance sigma[i] squared for the ith method and the kth item, and alpha[i] and beta[i] are the accuracy parameters for the ith method. The product of the betas is constrained to equal one (equivalently, the geometric average of the beta's is constrained to one). When the betas are all equal to one, the average of the alphas equals zero (equivalently, the sum of the alphas is constrained to zero).

The imprecision for the ith method is sigma[i]. If all alphas are zeroes and all betas are ones, there is no bias. If all betas equal 1, then there is a constant bias. If some of the betas differ from one there is a nonconstant bias. Note that the individual betas are not unique - only ratios of the betas are unique. If you divide all the betas by beta\_i, then the betas represent the scale bias of the other devices/methods relative to device/method i. Also, when the betas differ from one, the sigmas are not directly comparable because the measurement scales (size of the units) differ. To make the sigmas comparable, divide them by their corresponding beta. This result is shown as bias.adj.sigma.

By using the original data values, the betas can be estimated and also the process variance, that is, the variance of the true values.

Technically, the alphas and betas describe the measurements in terms of the unknown true values (i.e., the unknown true values can be thought of as a latent variable). The "true values" are AL-WAYS unknown (unless you have a real, highly accurate reference method/device). The real goal is

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to calibrate one device/method in terms of another. This is easily accomplished because each measurement is a function of the same unknow true values. By solving the measurement error model (in expectation) for mu and substituting, any two devices/methods i=1 and i=2 can be be related as:

```
\label{eq:expansion} \begin{split} E[x[1,k]] &= alpha[1] - alpha[2]*beta[1]/beta[2] + beta[1]/beta[2]*E[x[2,k]] \\ \text{or equivalently} \end{split}
```

E[x[2,k]] = alpha[2] - alpha[1]\*beta[2]/beta[1] + beta[2]/beta[1]\*E[x[1,k]].

Use cplot to display this calibration curve and the corresponding scale-bias adjusted imprecision standard deviations.

The omx function is to be preferred to ncb.od. omx can accommodate missing measurement data values and can provide both likelihood-based confidence intervals and bootstrapped intervals for all parameters and relevant functions of parameters.

#### Value

conf.level Confidence level used.

sigma.table Table of accuracy and precision estimates and confidence intervals.

n.itemsNo. of items.N.methodsNo. of methods

sigma2 N vector of variances that measure the method imprecision.

alpha.cb N vector of estimated alphas for constant bias model.

N vector of estimated alphas for nonconstant bias model.

beta N vector of estimated or hypothesized betas.

df N vector of estimated degrees of freedom.

N vector of lower bounds for confidence intervals.N vector of upper bounds for confidence intervals.

bias.adj.sigma

sigma adjusted for scale bias: sigma/beta.

H N+1 symmetric H matrix (see p. 201, Jaech).

errors.nb  $\mbox{n x N matrix of estimated measurement errors for no bias model.}$ 

errors.cb n x N matrix of estimated measurement errors for constant bias model.

errors.ncb n x N matrix of estimated measurement errors for nonconstant bias model

### Author(s)

Richard A. Bilonick

#### References

Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley.

```
cb.pd, 1rt
```

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#### **Examples**

```
library(merror)
data(pm2.5)
ncb.od(pm2.5)  # nonconstant bias model using original data values
ncb.od(pm2.5,beta=rep(1,5)) # constant bias model using original data values
```

omx

Compute full information maximum likelihood estimates of accuracy and precision for the nonconstant bias measurement error model using 'OpenMx'.

### **Description**

Compute full information maximum likelihood (FIML) estimates of accuracy (bias) and precision (imprecision) for the nonconstant bias measurement error model. 'OpenMx' functions are used to construct and fit a one latent factor model. Likelihood-based confidence intervals and bootstrapped confidence interval are can be determined for all model parameters and relevant functions of the model parameters.

### Usage

```
omx(data, rvEst=rep(1,ncol(data)), mubarEst=mean(data[,1]), interval=0.95,
  reps=500,bs.q=c(0.025,0.975), bs=TRUE)
```

### Arguments

data	$n$ (no. of items) $\times N$ (no. of methods) matrix or data.frame containing the measurements. $N$ must be $\geq 3$ . Missing values are allowed.
rvEst	A vector of $N$ residual variance starting values, one for each corresponding method.
mubarEst	A scalar starting value for estimating the the true mean value.
interval	Confidence level for likelihood-based confidence intervals. Should be a scalar value greater than 0 and less than 1.
reps	Number of bootstrap samples. Ignored if bs=FALSE.
bs.q	A vector of desired quantiles for bootstrapped samples. Default is ci.q=c(0.025,0.975).
bs	A boolean indicating whether bootstapped samples are to be generated. Default is TRUE.

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#### **Details**

Measurement Error Model:

$$x_{ik} = \alpha_i + \beta_i \mu_k + \epsilon_{ik}$$

where  $x_{ik}$  is the measurement by the ith of N methods for the kth of n items, i=1 to  $N\geq 3$ , k=1 to  $n,\mu_k$  is the true value for the kth item,  $\epsilon_{ik}$  is the normally distributed random error with variance  $\sigma_i^2$  for the ith method and the kth item, and  $\alpha_i$  and  $\beta_i$  are the accuracy parameters for the ith method. The beta for the first column of data) is set to one. The corresponding alpha is set to 0. These constraints or similar are required for model identification.

The imprecision for the ith method is  $\sigma_i$ . If all alphas are zeroes and all betas are ones, there is no bias. If all betas equal 1, then there is a constant bias. If some of the betas differ from one there is a nonconstant bias. Note that the individual betas are not unique - only ratios of the betas are unique. If you divide all the betas by  $\beta_i$ , then the betas represent the scale bias of the other devices/methods relative to device/method i. Also, when the betas differ from one, the sigmas are not directly comparable because the measurement scales (size of the units) differ. To make the sigmas comparable, divide them by their corresponding beta.

Technically, the alphas and betas describe the measurements in terms of the unknown true values (i.e., the unknown true values can be thought of as a latent variable). The "true values" are AL-WAYS unknown (unless you have a real, highly accurate reference method/device). The real goal is to calibrate one device/method in terms of another. This is easily accomplished because each measurement is a linear function of the same unknown true values. For methods 1 and 2, the calibration curve is given by:

$$E[x_{1k}] = (\alpha_1 - \alpha_2 \beta_1 / \beta_2) + (\beta_1 / \beta_2) E[x_{2k}]$$

or equivalently

$$E[x_{2k}] = (\alpha_2 - \alpha_1 \beta_2 / \beta_1) + (\beta_2 / \beta_1) E[x_{1k}]$$

Use cplot, with the alpha.beta.sigma argument specified, to display this calibration curve, calibration equation, and the corresponding scale-bias adjusted imprecision standard deviations.

Note that likelihood confidence intervals and bootstrapped confidence intervals can be returned. Wald-type intervals based on the standard errors are also available by using the confint function on the returned fit object. See examples.

#### Value

fit	'OpenMx' fit object containing the results (FIML parameter estimates, etc)
ci	$Likelihood-based\ confidence\ intervals\ for\ all\ parameters\ and\ certain\ useful\ functions\ of\ parameters.$
boot	$Object\ created\ by\ `mxBootstrap'\ 'OpenMx'\ function.\ Not\ returned\ if\ bs=FALSE.$
q.boot	data.frame containing the standard error and quantile estimates based on bootstrapped samples. Not returned if bs=FALSE.

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abs  $A \ 3 \times N \ \text{matrix of the estimated alphas, betas, and the raw imprecision standard}$ 

deviations for each of the N methods. The results can be passed to the merror

cplot to produce a calibration plot.

bsReps Number of bootstrapped samples. Default is 500. Not returned if bs=FALSE.

model The 'OpenMx' one-factor model.

#### Note

The following names are used to describe the estimates:

- 1) a1, a2, a3 and so forth denote the alphas (intercept).
- 2) b1, b2, b3 and so forth denote the betas (scale or slope).
- 3) ve1, ve2, ve3 and so forth denote the raw (uncorrected for scale) residual random error variances (imprecision variances).
- 4) sel denotes the imprecison standard deviation for the reference method.
- 5) base2, base3 and so forth denote the scale bias-adjusted imprecision standard deviations on the scale of the reference method.
- 6) mubar is the estimated mean of the true values on the scale of the reference method.
- 7) sigma2 is the estimated variance of the true values on the scale of the reference method.
- 8) sigma is the estimated standard deviation of the true values on the scale of the reference method.

#### Author(s)

Richard A. Bilonick

#### See Also

```
ncb.od, alpha.beta.sigma
```

### **Examples**

```
## Not run:
library(OpenMx)
library(merror)

data(pm2.5)

pm <- pm2.5

# OpenMx does not like periods in data column names
names(pm) <- c('ms_conc_1','ws_conc_1','ms_conc_2','ws_conc_2','frm')

# Fit model with FRM sampler as reference
omxfit <- omx(data=pm[,c(5,1:4)],bs.q=c(0.025,0.5,0.975),reps=100)

# Look at results
summary(omxfit$fit)$parameters[,c(1,5,6)] # Parameter estimates and standard errors
round(omxfit$ci[,1:3],3) # Likelihood-based intervals</pre>
```

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```
# Estimated standard errors and quantiles based on bootstrapped samples
round(omxfit$q.boot,3)

# Wald-type intervals
# - note variances not standard deviations and different ordering
confint(omxfit$fit)

omxfit$abs # Use with cplot

# Make a calibration plot using the results from omx instead of the default ncb.od
cplot(pm[,c(5,1:4)],1,2,alpha.beta.sigma=omxfit$abs)

## End(Not run)
```

panel.merror

Draw diagonal line (line of equality) on merror.pairs plots

### **Description**

This function is used internally by the function merror.pairs.

### Usage

```
panel.merror(x, y, \ldots)
```

### **Arguments**

x A vector of measurements for one device, of length n.

y A vector of measurements for another device, of length n.

... Additional arguments.

### Value

Draws the diagonal line that represents the "line of equality", i.e., the "no bias model".

### Author(s)

Richard A. Bilonick

```
merror.pairs
```

pm2.5

pm2.5

PM 2.5 Concentrations from SCAMP Collocated Samplers

### **Description**

Five filter-based samplers for measuring PM 2.5 concentrations were collocated and provided 77 complete sets of concentrations. This data was collected by the Stuebenville Comprehensive Air Monitoring Program (SCAMP) to check the accuracy and precision of the instruments.

### Usage

```
data(pm2.5)
```

#### **Format**

A data frame with 77 sets of PM 2.5 concentrations (micrograms per cubic meter) from the following 5 samplers:

```
    ms.conc.1 - personal sampler 1 - filter MS
    ws.conc.1 - personal sampler 1 - filter WS
    ms.conc.2 - personal sampler 2 - filter MS
    ws.conc.2 - personal sampler 2 - filter WS
    frm - Federal Reference Method sampler
```

### **Source**

Stuebenville Comprehensive Air Monitoring Program (SCAMP)

### **Examples**

```
data(pm2.5)
boxplot(pm2.5)
merror.pairs(pm2.5)

# estimates of accuracy and precision
# for nonconstant bias model using
# original data values
ncb.od(pm2.5)
```

precision.grubbs.cb.pd

Computes Grubbs' method of moments estimators of precision for the constant bias model using paired differences.

### Description

This is an internal function that computes Grubbs' method of moments estimators of precision for the constant bias model using paired differences

### Usage

```
precision.grubbs.cb.pd(x)
```

#### **Arguments**

A matrix or numeric data.frame consisting of an n (no. of items) by N (no. of methods) matrix of measuremnts. N must be >= 3 and n > N.

### **Details**

See Jaech 1985, Chapters 3 & 4, p. 144 in particular.

### Value

Estimated squared imprecision estimates (variances).

### Author(s)

Richard A. Bilonick

#### References

Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley.

```
precision.grubbs.ncb.od, ncb.od, cb.pd,lrt
```

precision.grubbs.ncb.od

precision.grubbs.ncb.od

Computes Grubbs' method of moments estimators of precision for the nonconstant bias model using original data values.

### Description

This is an internal function that computes Grubbs' method of moments estimators of precision for the nonconstant bias model using original data values.

#### Usage

```
precision.grubbs.ncb.od(x, beta.bar.x = beta.bar(x))
```

### **Arguments**

x A matrix or numeric data frame consisting of an n (no. of items) by N (no. of

methods) matrix of measuremnts. N must be  $\geq 3$  and n > N.

beta.bar.x Either estimates of beta or hypothesized values (one for each method in an N

vector).

### **Details**

See Jaech, p. 184.

#### Value

Grubbs' method of moments estimates of the squared imprecision (variances).

### Author(s)

Richard A. Bilonick

#### References

Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley.

```
precision.grubbs.cb.pd, ncb.od, cb.pd,lrt
```

24 precision.mle.ncb.od

precision.mle.ncb.od Computes iterative approximation to mle precision estimates for nonconstant bias model using original data.

#### **Description**

This is an internal function that computes iterative approximation to mle precision estimates for nonconstant bias model using original data.

#### Usage

```
precision.mle.ncb.od(x, M = 20, beta.bars = beta.bar(x), jaech.errors = FALSE)
```

#### **Arguments**

x A matrix or numeric data frame consisting of an n (no. of items) by N (no. of

methods) matrix of measuremnts. N must be  $\geq 3$  and n > N.

Maximum no. of iterations for convergence.

beta.bars Estimates or hypothesized values for the betas.

jaech.errors TRUE replicates the minor error in Jaech's Fortran code to allow comparison

with his examples.

### Details

Provides iterative approximation to MLE precision estimates for NonConstant Bias model using Original Data. See Jaech, p. 185-186.

#### Value

sigma2 Estimated squared imprecisions (variances) for methods.

sigma.mu2 Estimated process variance.

#### Author(s)

Richard A. Bilonick

#### References

Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley.

```
precision.grubbs.ncb.od,precision.grubbs.cb.pd
```

process.sd 25

process.sd

Compute process standard deviation

### **Description**

This function computes the process standard deviation and is used internally by the function precision.grubbs.ncb.od.

### Usage

```
process.sd(x)
```

### **Arguments**

Х

A matrix or numeric data.frame consisting of an n (no. of items) by N (no. of methods) matrix of measuremnts.

#### **Details**

The process standard deviation is the standard deviation of the true values uncontaminated by measurement error. See Jaech, p. 185.

#### Value

A scalar containing the method of moments estimate of the process standard deviation.

#### Author(s)

Richard A. Bilonick

### References

Jaech, J. L. (1985) Statistical Analysis of Measurement Errors. New York: Wiley.

### See Also

```
precision.grubbs.ncb.od
```

### **Examples**

```
data(pm2.5)
process.sd(pm2.5) # estimate of the sd of the "true values using the method of moments")
```

26 process.var.mle

process.var.mle

Compute process variance.

### Description

This is an internal function to compute the process variance.

### Usage

```
process.var.mle(sigma2, s, beta.bars, N, n)
```

### Arguments

sigma2 Estimated imprecisions for each method in an N vector.

s Variance-covariance N x N matrix.

beta.bars Estimates or hypothesized values for the N betas.

No. of methods.

n No. of items.

### **Details**

See Jaech p. 186 equations 6.37 - 6.3.10.

### Value

Estimated process variance.

### Author(s)

Richard A. Bilonick

### References

```
process.var.mle.jaech.err
```

Compute process variance but with minor error in Jaech Fortran code.

### Description

This is an internal function to compute the process variance that replicates the minor error in Jaech's Fortran code. This allows comparing merror estimates to those shown in Jaech 1985.

### Usage

```
process.var.mle.jaech.err(sigma2, s, beta.bars, N, n)
```

### **Arguments**

	T 1		C 1	.1 1' NT .
sigma2	Estimated	1mprecisions	tor each	method in an N vector.

s Variance-covariance N x N matrix.

beta.bars Estimates or hypothesized values for the N betas

N No. of methods.

No. of items.

### **Details**

See Jaech p. 186 equations 6.37 - 6.3.10. Jaech p. 288 line 2330 has s[i,j] instead of s[j,j]. Jaech p. 288 line 2410 omits "- 1/d2".

#### Value

Estimated process variance but replicating minor error in Jaech's Fortran code.

### Author(s)

Richard A. Bilonick

#### References

28 redshift

redshift

Spectroscopic and Photometric Galaxy Redshift Measurements

### **Description**

The redshift observations were taken from DEEP 2 Galaxy Redshift Survey.

### Usage

```
data(redshift)
```

#### **Format**

Redshift measurements are usually denoted by z.

A data frame with one spectroscopic redshift measurement and six different photometric measurements (by researcher) for 1432 galaxies:

z\_spec Spectroscopic redshift

z fink Photometric redshift - S. Finklestein

z font Photometric redshift - A. Fontana

**z\_pfor** Photometric redshift - J. Pforr

z\_salv Photometric redshift - M. Salvator

z\_wikl Photometric redshift - T. Wiklind

**z\_wuyt** Photometric redshift - S. Wuyts

#### Details

Because the photometric methods depend on the same color information, a one-factor measurement error model incuding both the spectroscopic and photomentric measurements would not be a viable model because the photometric measurements would tend to be correlated. A two-factor model would be needed but would require at minimum replicated spectroscopic measurements.

#### Source

<a href="https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/20140013340.pdf">https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/20140013340.pdf</a>

#### References

Newman, Jeffrey A., Michael C. Cooper, Marc Davis, S. M. Faber, Alison L. Coil, Puragra Guhathakurta, David C. Koo et al. "The DEEP2 Galaxy Redshift Survey: Design, observations, data reduction, and redshifts." The Astrophysical Journal Supplement Series 208, no. 1 (2013): 5.

sigma\_mle 29

#### **Examples**

```
library(OpenMx)
library(merror)
data(redshift)
merror.pairs(redshift)
# estimates of accuracy and precision
   parameters for a one-factor
   measurement error model
head(redshift)
merror.pairs(redshift)
## Not run:
red <- omx(redshift[,-1],reps=200) # Drop the spectroscopic measurements
summary(red$fit)
red$ci
red$q.boot
cplot(redshift[,-1],1,2,alpha.beta.sigma=red$abs)
## End(Not run)
```

sigma\_mle

Computes the ith iteration for computing the squared imprecision estimates.

### Description

This is an internal function that computes the ith iteration for computing the squared imprecision estimates.

### Usage

```
sigma_mle(i, s, sigma2, sigma.mu2, beta.bars, N, n)
```

#### **Arguments**

1	Iteration i	٠.

s Variance-covariance N x N matrix.

sigma2 Estimated imprecisions for each method in an N vector

sigma.mu2 Estimated process varinace.

beta.bars Estimates or hypothesized values for the N betas.

N No. of methods.

n No. of items.

30 sigma\_mle

### **Details**

See Jaech p. 185-186 equations 6.3.1 - 6.3.6.

### Value

Estimated squared imprecisions (variances) for the ith iteration.

### Author(s)

Richard A. Bilonick

### References

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```