

Package ‘aae.pop’

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Description Simulate population dynamics from realistically complex matrix population models in a plug-and-play fashion. Supports aspatial and spatially implicit models with one or more species and time-varying covariates, stochasticity, density dependence, additions or removals of individuals, interspecific interactions, and metapopulations.

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<https://github.com/aae-stats/aae.pop>

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<i>add_remove</i>	<i>Specify additions or removals in models of population dynamics</i>
-------------------	---

Description

Specify additions or removals from the population vector that occur before (`add_remove_pre`) or after the update step (`add_remove_post`).

Usage

```
add_remove_pre(masks, funs)

add_remove_post(masks, funs)
```

Arguments

<code>masks</code>	a logical matrix or vector (or list of these) defining cells affected by <code>funs</code> . See Details and masks
<code>funs</code>	a function or list of functions with one element for each element of <code>masks</code> . See Details

Details

`add_remove_pre` specifies a function that operates on the population vector prior to the population update step. Examples might include fatalities (recorded in absolute numbers), removals, or additions to the population that occur prior to the update (shifting from one generation to the next).

`add_remove_post` is the same as `add_remove_pre` but operates on the population vector after the population update step.

masks are logical vectors with one element for each class. Additional details on masks are provided in [masks](#).

funs takes only one argument, the population abundances `n` prior (`add_remove_pre`) or following (`add_remove_post`) all other updates in a given iteration/generation. This allows direct additions or removals to the population vector, potentially based on external arguments (e.g., mass mortality events or harvesting).

Additional arguments to functions are supported and can be passed to [simulate](#) with the `args` argument.

Value

`add_remove_pre` or `add_remove_post` object specifying an additions/removals process for use with [dynamics](#)

Examples

```
# define a population matrix (columns move to rows)
nclass <- 5
popmat <- matrix(0, nrow = nclass, ncol = nclass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# remove up to 10 individuals from stages 4 and 5 prior to the
#   matrix update
removals <- add_remove_pre(
  masks = all_classes(popmat, dims = 4:5),
  funs = \((x) ifelse(x > 10, x - 10, 0))
)

# update the dynamics object
dyn <- update(dyn, removals)

# simulate trajectories
sims <- simulate(dyn, nsim = 100, options = list(ntime = 50))

# and plot
plot(sims)

# remove up to 10 individuals from stages 4 and 5 after to the
#   matrix update
```

```

removals <- add_remove_post(
  masks = all_classes(popmat, dims = 4:5),
  funs = \(x) ifelse(x > 10, x - 10, 0)
)

# update the dynamics object (can't update because that will
#   include the add_remove_pre as well)
dyn <- dynamics(popmat, removals)

# simulate trajectories
sims <- simulate(dyn, nsim = 100, options = list(ntime = 50))

# and plot
plot(sims)

```

covariates*Specify covariate dependence in models of population dynamics***Description**

Specify relationship between a vector or matrix of covariates and vital rates.

Usage

```

covariates(masks, funs)

format_covariates(x, aux = NULL, names = NULL)

```

Arguments

<code>masks</code>	a logical matrix or vector (or list of these) defining cells affected by <code>funs</code> . See Details and masks
<code>funs</code>	a function or list of functions with one element for each element of <code>masks</code> . See Details
<code>x</code>	a vector, matrix, or data.frame of time-varying covariate values with one element or row per time step
<code>aux</code>	additional, static arguments to be passed to a covariates function
<code>names</code>	optional vector of names for each covariate included in <code>x</code>

Details

Masks must be of the same dimension as the population dynamics matrix and specify cells influenced by covariates according to `funs`. Additional details on masks are provided in [masks](#).

Functions must take at least one argument, a vector or matrix representing the masked elements of the population dynamics matrix. Incorporating covariate values requires a second argument. Functions must return a vector or matrix with the same dimensions as the input, modified to reflect the effects of covariates on vital rates.

Additional arguments to functions are supported and can be passed to `simulate` with the `args`, `args.dyn`, or `args.fn` arguments.

`format_covariates` is a helper function that takes covariates and auxiliary values as inputs and returns a correctly formatted list that can be passed as `args` to `simulate`.

Value

`covariates` object specifying covariate effects on a matrix population model; for use with `dynamics`

Examples

```
# define a population matrix (columns move to rows)
nklass <- 5
popmat <- matrix(0, nrow = nklass, ncol = nklass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# can add covariates that influence vital rates
#   e.g., a logistic function
covars <- covariates(
  masks = transition(popmat),
  funs = function(mat, x) mat * (1 / (1 + exp(-10 * x)))
)

# simulate 50 random covariate values
xvals <- matrix(runif(50), ncol = 1)

# update the dynamics object and simulate from it.
#   Note that ntime is now captured in the 50 values
#   of xvals, assuming we pass xvals as an argument
#   to the covariates functions
dyn <- update(dyn, covars)
sims <- simulate(
  dyn,
  init = c(50, 20, 10, 10, 5),
  nsim = 100,
  args = list(
    covariates = format_covariates(xvals)
  )
)

# and can plot these simulated trajectories
plot(sims)
```

density_dependence *Specify density dependence in models of population dynamics*

Description

Specify density dependence in vital rates (`density_dependence`) and in total abundances (`density_dependence_n`).

Usage

```
density_dependence(masks, funs, nmask = NULL)

density_dependence_n(masks, funs)
```

Arguments

<code>masks</code>	a logical matrix or vector (or list of these) defining cells affected by <code>funs</code> . See Details and masks
<code>funs</code>	a function or list of functions with one element for each element of <code>masks</code> . See Details
<code>nmask</code>	logical vector or list of vectors defining elements of the population vector affected by each mask-function pair. Intended primarily for internal use when scaling up processes in metapopulation

Details

`density_dependence` specifies standard density dependence on vital rates, such as scramble or contest competition or allee effects.

`density_dependence_n` is an alternative parameterisation of density dependence that acts directly on population abundances. Note that `density_dependence_n` has been superseded by [add_remove_post](#).

Masks must be of the same dimension as the population dynamics matrix and specify cells influenced by density dependence according to `funs`. In the case of `density_dependence_n`, masks are logical vectors with one element for each class. Additional details on masks are provided in [masks](#).

If using `density_dependence`, functions must take at least two arguments, a matrix `x` and a vector `n`, which represent the population dynamics matrix and the population abundances. Functions must return a matrix with the same dimensions as `x`, modified to reflect the effects of current abundances (`n`) on vital rates.

In the case of `density_dependence_n`, `funs` takes only one argument, the population abundances `n` following all other updates in a given iteration/generation. This allows rescaling of population abundances based on total abundance or through more complicated functions that depend on external arguments (e.g., mass mortality events or harvesting).

Additional arguments to functions are supported and can be passed to `simulate` with the `args`, `args.dyn`, or `args.fn` arguments.

Value

`density_dependence` object specifying covariate effects on a matrix population model; for use with `dynamics`

Examples

```
# define a population matrix (columns move to rows)
nklass <- 5
popmat <- matrix(0, nrow = nklass, ncol = nklass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# add some density dependence
dd <- density_dependence(
  masks = reproduction(popmat, dims = 4:5),
  funs = ricker(1000)
)

# update the dynamics object
dyn <- update(dyn, dd)

# simulate trajectories
sims <- simulate(dyn, nsim = 100, options = list(ntime = 50))

# and plot
plot(sims)
```

Description

Use pre-defined forms of density dependence based on common density-dependence functions.

Usage

```
beverton_holt(k, exclude = NULL)

ricker(k, exclude = NULL)
```

Arguments

- | | |
|----------------------|---|
| <code>k</code> | carrying capacity used to define models of density dependence. See details for currently implemented models and their parameters. |
| <code>exclude</code> | vector of classes to exclude from calculation of total population density. Defaults to <code>NULL</code> , in which case all classes are used |

Details

Additional functions are provided to define common forms of density dependence. Currently implemented models are the Ricker model and Beverton-Holt model, both with a single parameter k.

Value

functions that can be used with `density_dependence` to specify common models of density dependence

Examples

```
# define a population matrix (columns move to rows)
nklass <- 5
popmat <- matrix(0, nrow = nklass, ncol = nklass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# add some density dependence
dd <- density_dependence(
  masks = reproduction(popmat, dims = 4:5),
  funs = ricker(1000)
)

# update the dynamics object
dyn <- update(dyn, dd)

# simulate trajectories
sims <- simulate(dyn, nsim = 100, options = list(ntime = 50))

# and plot
plot(sims)
```

dispersal

Specify dispersal between populations in a metapopulation model

Description

Specify dispersal between populations, including stochasticity and density dependence in dispersal parameters

Usage

```
dispersal(
  kernel,
  stochasticity_masks = NULL,
```

```

stochasticity_funs = NULL,
density_masks = NULL,
density_funs = NULL,
proportion = FALSE
)

```

Arguments

<code>kernel</code>	numeric matrix specifying the probability of specific classes moving between two populations. Matrices have the same columns-move-to-rows structure as in the population dynamics matrices described in dynamics , so a non-zero value in cell (a, b) denotes a transition from class b in the source population to class a in the receiving population
<code>stochasticity_masks</code>	a logical matrix or list of logical matrices defining cells affected by <code>stochasticity_funs</code> . See Details and masks
<code>stochasticity_funs</code>	a function or list of functions with one element for each element of <code>stochasticity_masks</code> . See Details
<code>density_masks</code>	a logical matrix or list of logical matrices defining cells affected by <code>density_funs</code> . See Details and masks
<code>density_funs</code>	a function or list of functions with one element for each element of <code>density_masks</code> . See Details
<code>proportion</code>	logical indicating whether <code>kernel</code> is specified in absolute probabilities or as a proportion of the source population (defaults to FALSE). If TRUE, values in <code>kernel</code> are calculated as a proportion of the total probability an individual exits that class at any given time step

Value

dispersal object specifying probabilities of movement between populations in a metapopulation matrix model; for use with [metapopulation](#)

Examples

```

# define some populations, all with identical vital rates
nclass <- 5
popmat <- matrix(0, nrow = nclass, ncol = nclass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- lapply(
  1:3,
  function(i) dynamics(popmat)
)

# define metapopulation structure with populations
#   1 and 3 dispersing into population 2

```

```

pop_structure <- matrix(0, nrow = 3, ncol = 3)
pop_structure[1, 2] <- 1
pop_structure[3, 2] <- 1

# define dispersal between populations
dispersal_matrix <- matrix(0, nrow = nclass, ncol = nclass)
dispersal_matrix[survival(dispersal_matrix, dims = 20:25)] <- 0.2
pop_dispersal1 <- dispersal(dispersal_matrix, proportion = TRUE)
pop_dispersal2 <- dispersal(dispersal_matrix, proportion = FALSE)
pop_dispersal <- list(pop_dispersal1, pop_dispersal2)

# create metapopulation object
metapop <- metapopulation(pop_structure, dyn, pop_dispersal)

# simulate without covariates
sims <- simulate(metapop, nsim = 10)

# and plot the simulated trajectories
plot(sims)

```

dynamics*Create and update population dynamics objects***Description**

Define population dynamics from a matrix and additional objects that determine covariate effects, density dependence, and forms of stochasticity.

Usage

```

dynamics(matrix, ...)

## S3 method for class 'dynamics'
update(object, ...)

is.dynamics(x)

```

Arguments

matrix	a matrix of vital rates specifying transitions between ages or stages. Specified in the format <code>ntp1 = A</code> <code>A</code> is the matrix and <code>nt</code> is the vector of abundances, so that values in a given column and row denote a transition from that column to that row
...	additional objects used to define population dynamics. Must be one or more of <code>covariates</code> , <code>replicated_covariates</code> , <code>environmental_stochasticity</code> , <code>demographic_stochasticity</code> , <code>density_dependence</code> , <code>add_remove_pre</code> , or <code>add_remove_post</code> . Note that <code>density_dependence_n</code> is equivalent to <code>add_remove_post</code> .
object	a <code>dynamics</code> object
x	an object to pass to <code>is.dynamics</code>

Details

A call to `dynamics` defines an object of class `dynamics`, which can be used to simulate population trajectories with the `simulate` function. The `plot` function is supported and will generate a general life-cycle diagram based on the defined population dynamics.

A compiled `dynamics` object can be updated to change any of the included processes with the `update` function.

Value

`dynamics` object containing a matrix population model and all associated processes

Examples

```
# define a population
nklass <- 5
popmat <- matrix(0, nrow = nklass, ncol = nklass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# and plot this
if (rlang::is_installed("DiagrammeR")) {
  plot(dyn)
}
```

emps

Calculate expected minimum population size (EMPS) for a `simulate` object

Description

Calculate expected minimum population size (EMPS) for a `simulate` object

Usage

```
emps(sims, subset = NULL, times = NULL, fun = mean, ...)
```

Arguments

<code>sims</code>	an object returned from <code>simulate</code>
<code>subset</code>	integer vector denoting the population classes to include in calculation of population abundance. Defaults to all classes
<code>times</code>	integer vector specifying generations to include in calculation of extinction risk. Defaults to all simulated generations
<code>fun</code>	function used to calculate average over all replicate trajectories. Defaults to <code>mean</code> . Alternatives might include <code>median</code> or <code>min</code>
<code>...</code>	additional arguments passed to <code>fun</code>

Details

Expected minimum population size (EMPS) is the average minimum value of all replicate trajectories. This value represents an expected lower bound on population sizes over all generations, accounting for variation among replicates. Abundances can be specified for all population classes or for a subset of classes.

Value

a single value representing the expected minimum population size for a simulation

Examples

```
# define a basic population
nstage <- 5
popmat <- matrix(0, nrow = nstage, ncol = nstage)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# simulate with the default updater
sims <- simulate(dyn, nsim = 1000)

# calculate expected minimum population size
emps(sims)

# calculate expected minimum population size for 4 and 5 year
#   olds only
emps(sims, subset = 4:5)

# calculate expected minimum population size but ignore first 10 years
emps(sims, times = 11:51)

# calculate expected minimum population size based on median
emps(sims, fun = median)
```

exps

Calculate expected population size for a [simulate](#) object based on generic functions (ExPS)

Description

Calculate expected population size for a [simulate](#) object based on generic functions (ExPS)

Usage

```
exps(
  sims,
  subset = NULL,
  times = NULL,
  fun_within = mean,
  fun_among = mean,
  ...
)
```

Arguments

sims	an object returned from simulate
subset	integer vector denoting the population classes to include in calculation of population abundance. Defaults to all classes
times	integer vector specifying generations to include in calculation of extinction risk. Defaults to all simulated generations
fun_within	function used to summarise a single trajectory. Must return a single value. Defaults to mean
fun_among	function used to summarise over all replicate trajectories. Defaults to mean. Alternatives might include median or min
...	additional arguments passed to fun_within and fun_among. If these conflict, a wrapper function could be used to define expected arguments for each function

Details

Expected population size (ExPS) is a highly flexible generalisation of [emps](#) and represents a two-level summary that first summarises individual population trajectories and then summarises these values over all replicates. Abundances can be specified for all population classes or for a subset of classes.

Value

a single value representing the expected statistic applied to the population sizes generated with [simulate](#)

Examples

```
# define a basic population
nstage <- 5
popmat <- matrix(0, nrow = nstage, ncol = nstage)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# simulate with the default updater
```

```

sims <- simulate(dyn, nsim = 1000)

# calculate expected population size
expss(sims)

# calculate expected population size for 4 and 5 year
#   olds only
expss(sims, subset = 4:5)

# calculate expected population size but ignore first 10 years
expss(sims, times = 11:51)

# calculate expected population size based on median
expss(sims, fun_among = median)

# calculate expected maximum population size based on median
expss(sims, fun_within = max, fun_among = median)

# calculate exps with conflicting quantile functions, handling
#   conflicting arguments with wrapper functions
quant1 <- function(x, p1, ...) {
  quantile(x, prob = p1)
}
quant2 <- function(x, p2, ...) {
  quantile(x, prob = p2)
}
expss(
  sims,
  fun_within = quant1, fun_among = quant2, p1 = 0.25, p2 = 0.75
)

```

get_cdf

Calculate the cumulative distribution function of a summary statistic across all iterations of a [simulate](#) object

Description

Calculate the cumulative distribution function of a summary statistic across all iterations of a [simulate](#) object

Usage

```
get_cdf(sims, subset = NULL, times = NULL, n = 100, fn = min, ...)
```

Arguments

- | | |
|---------------|---|
| sims | an object returned from simulate |
| subset | integer vector denoting the population classes to include in calculation of population abundance. Defaults to all classes |

times	integer vector specifying generations to include in calculation of extinction risk. Defaults to all simulated generations
n	integer specifying number of threshold values to use in default case when threshold is not specified. Defaults to 100
fn	function to apply to each iteration. Defaults to min
...	additional arguments passed to fn

Details

`get_cdf` is a faster and more general alternative to the `risk_curve` function. `get_cdf` can be used to calculate the cumulative distribution of any summary statistic. For example, the cumulative distribution of the minimum population size is equivalent to a risk curve. Summary statistics for `get_cdf` are extracted from a `simulate` object and represent the cumulative distribution of that statistic over all replicate trajectories at any time step within a set period. Abundances can be specified for all population classes or for a subset of classes.

Value

a data.frame containing a prob column that indicates the probability the population will fall below the threshold value in the value column

Examples

```
# define a basic population
nstage <- 5
popmat <- matrix(0, nrow = nstage, ncol = nstage)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# simulate with the default updater
sims <- simulate(dyn, nsim = 1000)

# calculate distribution of minimum population sizes (default)
get_cdf(sims)

# calculate distribution of maximum population sizes
get_cdf(sims, fn = max)

# calculate distribution of the 90th percentile of
#   population sizes
get_cdf(sims, fn = quantile, prob = 0.9)

# calculate distribution of minimum population sizes
#   but ignore first 10 years
get_cdf(sims, fn = max, times = 11:51)
```

get_pdf	<i>Calculate the probability density of a summary statistic across all iterations of a <code>simulate</code> object</i>
---------	---

Description

Calculate the probability density of a summary statistic across all iterations of a `simulate` object

Usage

```
get_pdf(sims, subset = NULL, times = NULL, n = 100, fn = min, ...)
```

Arguments

sims	an object returned from <code>simulate</code>
subset	integer vector denoting the population classes to include in calculation of population abundance. Defaults to all classes
times	integer vector specifying generations to include in calculation of extinction risk. Defaults to all simulated generations
n	integer specifying number of threshold values to use in default case when threshold is not specified. Defaults to 100
fn	function to apply to each iteration. Defaults to <code>min</code>
...	additional arguments passed to <code>fn</code>

Details

`get_pdf` and `get_cdf` are faster and more general alternatives to the `risk_curve` function. `get_pdf` can be used to calculate the probability distribution of any summary statistic. For example, the probability distribution of the minimum population size is the density-based equivalent of a risk curve (the function `get_cdf` can be used to get the true equivalent). Summary statistics for `get_pdf` are extracted from a `simulate` object and represent the distribution of that statistic over all replicate trajectories at any time step within a set period. Abundances can be specified for all population classes or for a subset of classes.

Value

a data.frame containing a `prob` column that indicates the probability density that abundances will be in the vicinity of the threshold value in the `value` column

Examples

```
# define a basic population
nstage <- 5
popmat <- matrix(0, nrow = nstage, ncol = nstage)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)
```

```

# define a dynamics object
dyn <- dynamics(popmat)

# simulate with the default updater
sims <- simulate(dyn, nsim = 1000)

# calculate distribution of minimum population sizes (default)
get_pdf(sims)

# calculate distribution of maximum population sizes
get_pdf(sims, fn = max)

# calculate distribution of the 90th percentile of
#   population sizes
get_pdf(sims, fn = quantile, prob = 0.9)

# calculate distribution of minimum population sizes
#   but ignore first 10 years
get_pdf(sims, fn = max, times = 11:51)

```

Description

Helper functions to isolate particular components of a population dynamics model, such as the reproduction terms, transition/growth terms, or particular life stages from an abundance vector, such as pre- or post-reproductive stages.

Usage

```

reproduction(matrix, dims = NULL)

survival(matrix, dims = NULL)

transition(matrix, dims = NULL)

all_cells(matrix, dims = NULL)

all_classes(matrix, dims = NULL)

combine(...)

```

Arguments

<code>matrix</code>	a population dynamics matrix for which a particular mask is required. Only used to determine mask dimensions, so can be any matrix with appropriate dimensions
---------------------	--

<code>dims</code>	a numeric value or vector identifying subsets of cells to include in a given mask
<code>...</code>	a set of masks or masking functions to be combined into a single mask by one of the <code>combine</code> methods

Value

mask object used to define the cells affected by a process included in [dynamics](#)

Examples

```
# define a population
nclass <- 5
popmat <- matrix(0, nrow = nclass, ncol = nclass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# pull out reproductive elements
reproduction(popmat)

# what if only 4 and 5 year olds reproduce?
reproduction(popmat, dims = 4:5)

# define survival elements
survival(popmat)

# what if 1 and 2 year olds always transition?
survival(popmat, dims = 3:5)

# and transitions
transition(popmat)

# combine transitions and reproduction of 4 and 5 year olds
combine(reproduction(popmat, dims = 4:5), transition(popmat))

# can also mask the population vector in this way
# pull out all classes
all_classes(popmat)

# and just 3-5 year olds
all_classes(popmat, dims = 3:5)
```

Description

Define population dynamics for multiple populations of a single species linked by dispersal (a metapopulation).

Usage

```
metapopulation(structure, dynamics, dispersal)

is.metapopulation(x)
```

Arguments

structure	binary or logical matrix denoting dispersal links between populations. Columns move to rows, so a 1 or TRUE in cell (a, b) denotes movement from population b to population a
dynamics	a dynamics object or list of dynamics objects with one element for each population (each column/row of <code>structure</code>). If a single dynamics object is provided, it is recycled over all required populations
dispersal	object created with dispersal . dispersal objects describe movements between populations and can include class-specific movements and density-dependent movements. dispersal objects must be a list with one element for each link in <code>structure</code> . These links are interpreted in column-major order, so that <code>dispersal</code> objects must be ordered by links in column 1, then column 2, and so on
x	an object to pass to <code>is.metapopulation</code>

Details

The `metapopulation` function connects multiple populations through known dispersal probabilities, handling standardisations of dispersal probabilities (if required) and updating masks and functions for all processes defined within each population. Further details on the definition of dispersal terms are provided in [dispersal](#).

Covariates can be included in metapopulation models. The default behaviour is for all populations to share a single set of covariates, with covariate associations and masks defined separately for each population. A workaround to the assumption of shared covariates is included in the examples, below. Including covariates on dispersal probabilities requires covariate associations and masks defined on the combined metapopulation model. This approach is possible but currently untested.

Value

`metapopulation` object containing a matrix metapopulation model; for use with [simulate](#)

Examples

```
# define some populations, all with identical vital rates
nclass <- 5
popmat <- matrix(0, nrow = nclass, ncol = nclass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- lapply(
  1:3,
  function(i) dynamics(popmat)
```

```

)
# define metapopulation structure with populations
#   1 and 3 dispersing into population 2
pop_structure <- matrix(0, nrow = 3, ncol = 3)
pop_structure[1, 2] <- 1
pop_structure[3, 2] <- 1

# define dispersal between populations
dispersal_matrix <- matrix(0, nrow = nclass, ncol = nclass)
dispersal_matrix[survival(dispersal_matrix, dims = 20:25)] <- 0.2
pop_dispersal1 <- dispersal(dispersal_matrix, proportion = TRUE)
pop_dispersal2 <- dispersal(dispersal_matrix, proportion = FALSE)
pop_dispersal <- list(pop_dispersal1, pop_dispersal2)

# create metapopulation object
metapop <- metapopulation(pop_structure, dyn, pop_dispersal)

# simulate without covariates
sims <- simulate(metapop, nsim = 2)

# simulate with shared covariates
# define a covariates function
covar_fn <- function(mat, x) {
  mat * (1 / (1 + exp(-0.5 * (x + 10))))
}

# and some covariates
xsim <- matrix(rnorm(20), ncol = 1)

# update the population dynamics objects with covariates
dyn <- lapply(
  dyn,
  update,
  covariates(masks = transition(dyn[[1]]$matrix), funs = covar_fn)
)

# (re)create metapopulation object
metapop <- metapopulation(pop_structure, dyn, pop_dispersal)
sims <- simulate(
  metapop,
  nsim = 2,
  args = list(covariates = format_covariates(xsim))
)

# simulate with separate covariates
# (requires re-definition of covariate functions)
new_fn <- function(i) {
  force(i)
  function(mat, x) {
    mat * (1 / (1 + exp(-0.5 * (x[i] + 10))))
  }
}

```

```

new_fn <- lapply(
  1:3,
  new_fn
)

# update the population dynamics objects with covariates
dyn <- lapply(
  dyn,
  update,
  covariates(masks = transition(dyn[[1]]$matrix), funs = covar_fn)
)

# (re)create metapopulation object
metapop <- metapopulation(pop_structure, dyn, pop_dispersal)

# and simulate with one column of predictors for each population
xsim <- matrix(rnorm(60), ncol = 3)
sims <- simulate(
  metapop,
  nsim = 2,
  args = list(covariates = format_covariates(xsim))
)

```

multispecies*Create a population dynamics object with multiple species***Description**

Define population dynamics for multiple species from a set of single-species [dynamics](#) objects and defined pairwise interactions.

Usage

```

multispecies(...)

is.multispecies(x)

is.interaction(x)

```

Arguments

...	pairwise_interaction objects defining a set of pairwise interactions between species
x	an object to pass to <code>is.multispecies</code>

Value

`multispecies` object containing a multispecies matrix population model; for use with [simulate](#)

Examples

```

# define population matrices for three species
sp1_mat <- rbind(
  c(0, 0, 2, 4, 7), # reproduction from 3-5 year olds
  c(0.25, 0, 0, 0, 0), # survival from age 1 to 2
  c(0, 0.45, 0, 0, 0), # survival from age 2 to 3
  c(0, 0, 0.70, 0, 0), # survival from age 3 to 4
  c(0, 0, 0, 0.85, 0) # survival from age 4 to 5
)
sp2_mat <- rbind(
  c(0, 0, 4), # reproduction from 3 year olds
  c(0.25, 0, 0), # survival from age 1 to 2
  c(0, 0.45, 0) # survival from age 2 to 3
)
sp3_mat <- rbind(
  c(0, 0, 2, 4, 7, 10), # reproduction from 3-6 year olds
  c(0.25, 0, 0, 0, 0, 0), # survival from age 1 to 2
  c(0, 0.45, 0, 0, 0, 0), # survival from age 2 to 3
  c(0, 0, 0.70, 0, 0, 0), # survival from age 3 to 4
  c(0, 0, 0, 0.85, 0, 0), # survival from age 4 to 5
  c(0, 0, 0, 0, 0.75, 0) # survival from age 5 to 6
)

# define population dynamics objects for each species
sp1_dyn <- dynamics(sp1_mat)
sp2_dyn <- dynamics(sp2_mat)
sp3_dyn <- dynamics(sp3_mat)

# define multispecies interactions as masks/functions
# - species 1 influencing transition probabilities of species 3
mask_1v3 <- transition(sp3_mat)

# basic Beverton-Holt function
fun_1v3 <- function(x, n) {
  # n is the population vector of the source population (sp 1)
  x / (1 + x * sum(n[3:5]) / 100) # focus on adults
}

# - species 3 influencing reproduction of species 2
mask_3v2 <- reproduction(sp2_mat, dims = 3)

# basic Ricker function
fun_3v2 <- function(x, n) {
  # n is the population vector of the source population (sp 3)
  x * exp(1 - sum(n[1:2]) / 50) / exp(1) # focus on juveniles
}

# combine masks and functions into pairwise_interaction objects
sp_int1v3 <- pairwise_interaction(sp3_dyn, sp1_dyn, mask_1v3, fun_1v3)
sp_int3v2 <- pairwise_interaction(sp2_dyn, sp3_dyn, mask_3v2, fun_3v2)

# compile a multispecies dynamics object

```

```
multisp_dyn <- multispecies(sp_int1v3, sp_int3v2)

# simulate
sims <- simulate(multisp_dyn, nsim = 100)

# and can plot these simulated trajectories for each species
plot(sims, which = 1)
```

pairwise_interaction *Specify interactions between two species*

Description

Define population dynamics for multiple species from a set of single-species `dynamics` objects and defined pairwise interactions.

Usage

```
pairwise_interaction(target, source, masks, funs)
```

Arguments

target	population whose vital rates are affected by the pairwise interaction
source	population whose abundances affect the vital rates of <code>target</code>
masks	masks defining which vital rates are influenced by each function
funs	functions that take vital rates and abundances of the source population as inputs and return scaled vital rates

Value

`pairwise_interaction` object specifying links between species; for use with `multispecies`

pr_extinct *Calculate (quasi-)extinction risk for a `simulate` object*

Description

Calculate (quasi-)extinction risk for a `simulate` object

Usage

```
pr_extinct(sims, threshold = 0, subset = NULL, times = NULL)
```

Arguments

<code>sims</code>	an object returned from simulate
<code>threshold</code>	integer or numeric denoting the threshold population size below which a population is considered functionally extinct. Defaults to 0
<code>subset</code>	integer vector denoting the population classes to include in calculation of population abundance. Defaults to all classes
<code>times</code>	integer vector specifying generations to include in calculation of extinction risk. Defaults to all simulated generations

Details

Quasi-extinction risk is the probability of decline below some specified abundance threshold. This probability is extracted from a [simulate](#) object as the proportion of replicate trajectories that fall below this threshold at any time step within a set period. Abundances can be specified for all population classes or for a subset of classes.

Value

a single numeric value representing the probability a population will decline below the threshold size

Examples

```
# define a basic population
nstage <- 5
popmat <- matrix(0, nrow = nstage, ncol = nstage)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# simulate with the default updater
sims <- simulate(dyn, nsim = 1000)

# calculate quasi-extinction risk at a threshold population size
#   of 100 individuals
pr_extinct(sims, threshold = 100)

# repeat previous but focused on 4 and 5 year olds only
pr_extinct(sims, threshold = 100, subset = 4:5)

# repeat previous but ignore first 10 years
pr_extinct(sims, threshold = 100, times = 11:51)
```

`replicated_covariates` *Specify replicate-specific covariate dependence in models of population dynamics*

Description

Specify relationship between a vector or matrix of covariates and vital rates, but with a different covariate value for each replicate (i.e., each value of `nsim` in `simulate`)

Usage

```
replicated_covariates(masks, funs)
```

Arguments

<code>masks</code>	a logical matrix or vector (or list of these) defining cells affected by <code>fun</code> s. See Details and <code>masks</code>
<code>fun</code> s	a function or list of functions with one element for each element of <code>masks</code> . See Details

Details

Masks must be of the same dimension as the population dynamics matrix and specify cells influenced by covariates according to `fun`s. Additional details on masks are provided in `masks`.

Functions must take at least one argument, a vector or matrix representing the masked elements of the population dynamics matrix. Incorporating covariate values requires a second argument. Functions must return a vector or matrix with the same dimensions as the input, modified to reflect the effects of covariates on vital rates.

Additional arguments to functions are supported and can be passed to `simulate` with the `args` argument.

`format_covariates` is a helper function that takes covariates and auxiliary values as inputs and returns a correctly formatted list that can be passed as `args` to `simulate`.

`replicated_covariates` operates identically to `covariates` except that it allows for a different value of the covariate applied to each replicate trajectory. This specification can incorporate complex structures, such as temporal dynamics in environmental stochasticity and correlated uncertainty in vital rates.

Value

`replicated_covariates` object specifying replicate-specific covariate effects on a matrix population model; for use with `dynamics`

Examples

```

# define a population matrix (columns move to rows)
nklass <- 5
popmat <- matrix(0, nrow = nklass, ncol = nklass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# can add covariates that influence vital rates
#   e.g., a logistic function
covars <- replicated_covariates(
  masks = transition(popmat),
  funs = \(mat, x) mat * (1 / (1 + exp(-10 * x)))
)

# simulate 50 random covariate values for each replicate (each
#   value of nsim, set to 100 below)
xvals <- matrix(runif(50 * 100), ncol = 100)

# update the dynamics object and simulate from it.
#   Note that ntime is now captured in the 50 values
#   of xvals, assuming we pass xvals as an argument
#   to the covariates functions
dyn <- update(dyn, covars)
sims <- simulate(
  dyn,
  init = c(50, 20, 10, 10, 5),
  nsim = 100,
  args = list(
    replicated_covariates = format_covariates(xvals)
  )
)

# and can plot these simulated trajectories
plot(sims)

```

risk_curve

Calculate (quasi-)extinction risk at multiple thresholds for a [simulate](#) object

Description

Calculate (quasi-)extinction risk at multiple thresholds for a [simulate](#) object

Usage

```
risk_curve(sims, threshold = NULL, subset = NULL, times = NULL, n = 100)
```

Arguments

sims	an object returned from simulate
threshold	integer or numeric vector denoting the set of threshold population sizes used to define the risk curve. Defaults to n evenly spaced values from 0 to the maximum observed abundance
subset	integer vector denoting the population classes to include in calculation of population abundance. Defaults to all classes
times	integer vector specifying generations to include in calculation of extinction risk. Defaults to all simulated generations
n	integer specifying number of threshold values to use in default case when threshold is not specified. Defaults to 100

Details

Risk curves represent [pr_extinct](#) at multiple threshold population sizes simultaneously. This gives an expression of risk of population declines below a range of values. Risk curves are extracted from a [simulate](#) object as the proportion of replicate trajectories that fall below each threshold value at any time step within a set period. Abundances can be specified for all population classes or for a subset of classes.

The [get_cdf](#) function is a much faster way to generate risk curves for almost all use cases. The exception is when the threshold argument is used to specify threshold values that are not evenly spaced.

Value

a named vector containing the threshold values (names) and the probability the population will fall below these threshold values

Examples

```
# define a basic population
nstage <- 5
popmat <- matrix(0, nrow = nstage, ncol = nstage)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# simulate with the default updater
sims <- simulate(dyn, nsim = 100)

# calculate risk curve
risk_curve(sims, n = 10)
```

rng*Random number generators not available in existing R packages*

Description

Draw random numbers from unusual distributions, such as on the unit or non-negative real line with known means and standard deviations.

Usage

```
rmultiunit(
  n,
  mean,
  sd,
  Sigma = NULL,
  Omega = NULL,
  perfect_correlation = FALSE
)

rmultiunit_from_real(
  n,
  mean_real,
  sd_real = NULL,
  Sigma_chol = NULL,
  perfect_correlation = FALSE
)

runit_from_real(n, mean_real, sd_real)

runit(n, mean, sd)

unit_to_real(unit_mean, unit_sd)
```

Arguments

<code>n</code>	number of random draws to simulate. Each draw is a vector of values with length equal to <code>length(mean)</code> and <code>length(sd)</code> and the resulting output has <code>n</code> rows and <code>length(mean)</code> columns
<code>mean</code>	vector of mean values on the unit scale
<code>sd</code>	vector of positive standard deviations
<code>Sigma</code>	optional covariance matrix with dimensions of <code>length(mean)</code> by <code>length(mean)</code> defining covariances between each pair of values in <code>mean</code> . Note that only the correlation structure is retained from <code>Sigma</code> , so that standard deviations are still required
<code>Omega</code>	optional correlation matrix with dimensions of <code>length(mean)</code> by <code>length(mean)</code> defining correlations between each pair of values in <code>mean</code>

perfect_correlation	logical, if TRUE and Sigma and Omega are NULL, then all values in each replicate (row) are perfectly correlated with known mean and standard deviation. If FALSE, then all values in each replicate are completely uncorrelated
mean_real	vector of mean values converted to real-line equivalents
sd_real	vector of standard deviations converted to real-line equivalents
Sigma_chol	Cholesky decomposition of covariance matrix converted to real-line equivalent
unit_mean	vector of mean values on the unit interval
unit_sd	vector of standard deviations on the unit interval

Details

The `r*unit` family of functions support simulation of values on the unit interval based on a known mean, sd, and correlation structure. `runit` and `runit_from_real` are vectorised univariate functions, and `rmultiunit` and `rmultiunit_from_real` are multivariate versions of these same functions. `runit` and `rmultiunit` provide simulated values on the unit line with specified means, standard deviations, and correlation/covariance structure (in the case of `rmultiunit`).

The `*_from_real` versions of these functions are helpers that use pre-transformed estimates of parameters on the real line, calculated with `unit_to_real`. These functions are exported because `unit_to_real`, called within `runit` and `rmultiunit`, is slow. Separating this into a separate step allows less frequent calculations of this transformation using function or dynamic versions of `args` in `simulate`.

`unit_to_real` converts means and standard deviations from their values on the unit line to their equivalent values on the real line.

The use of the different versions of these functions is illustrated in the Macquarie perch example on the package [website](<https://aae-stats.github.io/aae.pop/>).

Value

a vector or matrix of random draws from the `r*unit` set of functions

Examples

```
# rmultiunit generates multivariate draws constrained to
#   the unit interval, with known mean, standard deviation,
#   and (optionally) covariance/correlation structure
rmultiunit(n = 10, mean = c(0.25, 0.5, 0.75), sd = c(0.1, 0.4, 0.25))

# add in a correlation structure
omega_set <- cbind(
  c(1, 0.25, 0.01),
  c(0.25, 1, 0.5),
  c(0.01, 0.5, 1)
)
rmultiunit(
  n = 10,
  mean = c(0.25, 0.5, 0.75),
  sd = c(0.1, 0.4, 0.25),
```

```

Omega = omega_set
)

```

simulate*Simulate single or multispecies population dynamics in R***Description**

Simulate population dynamics for one or more species defined by **dynamics** objects.

Usage

```

## S3 method for class 'dynamics'
simulate(
  object,
  nsim = 1,
  seed = NULL,
  ...,
  init = NULL,
  options = list(),
  args = list(),
  .future = FALSE
)

is.simulation(x)

is.simulation_list(x)

```

Arguments

object	a dynamics object created with dynamics or from a subsequent call to multispecies or metapopulation . Alternatively, object can be the output of a call to simulate in the case of summary
nsim	the number of replicate simulations (default = 1)
seed	optional seed used prior to initialisation and simulation to give reproducible results
...	ignored; included for consistency with simulate generic method
init	an array of initial conditions with one row per replicate and one column per population stage. If obj has been created with multispecies , initial conditions can be provided as a list or array with one element or slice per species, or as a matrix, in which case all species are assumed to share the same initial conditions. Defaults to NULL, in which case initial conditions are generated randomly according to options()\$aae.pop_initialisation

options	a named list of simulation options. Currently accepted values are: - ntime the number of time steps to simulate, ignored if obj includes a covariates (default = 50) - keep_slices logical defining whether to keep intermediate population abundances or (if FALSE) to return only the final time slice - tidy_abundances a function to handle predicted abundance data that may be non-integer. Defaults to identity; suggested alternatives are floor, round, or ceiling - initialise_args a list of arguments passed to the function used to initialise abundance trajectories. Only used if init = NULL. Defaults to options()\$aae.pop_lambda, which specifies lambda for Poisson random draws. The default initialisation function is defined by options()\$aae.pop_initialisation. - update a function to update abundances from one time step to the next. Defaults to options()\$aae.pop_update.
args	named list of lists passing arguments to processes defined in object, including interaction for multispecies objects. Lists (up to one per process) can contain a mix of static, dynamic, and function arguments. Dynamic arguments must be lists with one element per time step. Function arguments must be functions that calculate arguments dynamically in each generation based on from the population dynamics object, population abundances, and time step in each generation. All other classes (e.g., single values, matrices, data frames) are treated as static arguments. Covariates contained in numeric vectors, matrices, or data frames can be formatted as dynamic arguments with the format_covariates function. args for multispecies objects must have one element per species (defaults will expand automatically if not provided)
.future	flag to determine whether the future package should be used to manage updates for multispecies models (an embarrassingly parallel problem)
x	an object to pass to is.simulation or is.simulation.list

Value

simulation object containing replicate simulations from a matrix population model. **plot** and **subset** methods are defined for **simulation** objects

Examples

```
# define a population matrix (columns move to rows)
nklass <- 5
popmat <- matrix(0, nrow = nklass, ncol = nklass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# can extract standard population matrix summary stats
lambda <- Re(eigen(popmat)$values[1])

# define a dynamics object
dyn <- dynamics(popmat)
```

```

# simulate from this (50 time steps, 100 replicates)
sims <- simulate(dyn, nsim = 100, options = list(ntime = 50))

# plot the simulated trajectories
plot(sims)

# add some density dependence
dd <- density_dependence(
  masks = reproduction(popmat, dims = 4:5),
  funs = ricker(1000)
)

# update the dynamics object
dyn <- update(dyn, dd)

# simulate again
sims <- simulate(dyn, nsim = 100, options = list(ntime = 50))

# and plot
plot(sims)

# what if we want to add initial conditions?
sims <- simulate(
  dyn,
  init = c(50, 20, 10, 10, 5),
  nsim = 100,
  options = list(ntime = 50),
)

# and plot again
plot(sims)

# note that there is only one trajectory now because
#   this simulation is deterministic.
#
# let's change that by adding some environmental stochasticity
envstoch <- environmental_stochasticity(
  masks = list(
    reproduction(popmat, dims = 4:5),
    transition(popmat)
  ),
  funs = list(
    \x rpois(n = length(x), lambda = x),
    \x runif(n = length(x), min = 0.9 * x, max = pmin(1.1 * x, 1))
  )
)

# update the dynamics object and simulate from it
dyn <- update(dyn, envstoch)
sims <- simulate(
  dyn,
  init = c(50, 20, 10, 10, 5),

```

```
nsim = 100,
options = list(ntime = 50),
)

# can also add covariates that influence vital rates
# e.g., a logistic function
covars <- covariates(
  masks = transition(popmat),
  funs = \(mat, x) mat * (1 / (1 + exp(-10 * x)))
)

# simulate 50 random covariate values
xvals <- matrix(runif(50), ncol = 1)

# update the dynamics object and simulate from it.
# Note that ntime is now captured in the 50 values
# of xvals, assuming we pass xvals as an argument
# to the covariates functions
dyn <- update(dyn, covars)
sims <- simulate(
  dyn,
  init = c(50, 20, 10, 10, 5),
  nsim = 100,
  args = list(covariates = format_covariates(xvals))
)

# a simple way to add demographic stochasticity is to change
# the "updater" that converts the population at time t
# to its value at time t + 1. The default in aae.pop
# uses matrix multiplication of the vital rates matrix
# and current population. A simple tweak is to update
# with binomial draws. Note that this also requires a
# change to the "tidy_abundances" option so that population
# abundances are always integer values.
sims <- simulate(
  dyn,
  init = c(50, 20, 10, 10, 5),
  nsim = 100,
  options = list(
    update = update_binomial_leslie,
    tidy_abundances = floor
  ),
  args = list(covariates = format_covariates(xvals))
)

# and can plot these again
plot(sims)
```

<code>stochasticity</code>	<i>Specify environmental and demographic stochasticity in models of population dynamics</i>
----------------------------	---

Description

Specify environmental stochasticity (random variation in vital rates) and demographic stochasticity (random variation in population outcomes).

Usage

```
environmental_stochasticity(masks, funs)

demographic_stochasticity(masks, funs)
```

Arguments

<code>masks</code>	a logical matrix or vector (or list of these) defining cells affected by <code>fun</code> s. See Details and masks
<code>fun</code> s	a function or list of functions with one element for each element of <code>masks</code> . See Details

Details

Masks must be of the same dimension as the population dynamics matrix (in the case of environmental stochasticity) or have one element for each class (in the case of demographic stochasticity). Masks specify cells influenced by stochasticity according to `fun`s. Additional details on masks are provided in [masks](#).

Functions must have at least one argument, a population dynamics matrix for environmental stochasticity or a vector of population abundances for demographic stochasticity. Functions must return an output of the same dimensions as the input, modified to reflect the effects of stochasticity on vital rates or population abundances.

Additional arguments to functions are supported and can be passed to [simulate](#) with the `args`, `args.dyn`, or `args.fn` arguments.

Value

`environmental_stochasticity` or `demographic_stochasticity` object specifying the way in which stochasticity should be included in a matrix population model; for use with [dynamics](#)

Examples

```
# define a population matrix (columns move to rows)
nclass <- 5
popmat <- matrix(0, nrow = nclass, ncol = nclass)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
```

```

dyn <- dynamics(popmat)

# note that there is only one trajectory now because
#   this simulation is deterministic.
#
# let's change that by adding some environmental stochasticity
envstoch <- environmental_stochasticity(
  masks = list(
    reproduction(popmat, dims = 4:5),
    transition(popmat)
  ),
  funs = list(
    \((x) rpois(n = length(x), lambda = x),
    \((x) runif(n = length(x), min = 0.9 * x, max = pmin(1.1 * x, 1))
  )
)

# update the dynamics object and simulate from it
dyn <- update(dyn, envstoch)
sims <- simulate(
  dyn,
  init = c(50, 20, 10, 10, 5),
  nsim = 100,
  options = list(ntime = 50),
)

# a simple way to add demographic stochasticity is to change
#   the "updater" that converts the population at time t
#   to its value at time t + 1. The default in aae.pop
#   uses matrix multiplication of the vital rates matrix
#   and current population. A simple tweak is to update
#   with binomial draws. Note that this also requires a
#   change to the "tidy_abundances" option so that population
#   abundances are always integer values.
sims <- simulate(
  dyn,
  init = c(50, 20, 10, 10, 5),
  nsim = 100,
  options = list(
    update = update_binomial_leslie,
    tidy_abundances = floor
  )
)

```

Description

Define how population abundances are updated from one time step to the next. Functions can take any form but will only be vectorised across replicates in limited situations.

Usage

```
update_crossprod(pop, mat)

update_binomial_leslie(pop, mat)

update_multinomial(pop, mat)
```

Arguments

<code>pop</code>	current state of the population
<code>mat</code>	matrix of vital rates used to update population state

Details

Updaters can be changed through the `options` argument to `simulate` and can also be changed globally for an R session by changing the global option with, e.g., `options(aae.pop_update = update_binomial_leslie)`

`update_crossprod` updates abundances with a direct matrix multiplication that does not include any form of demographic stochasticity. This is the fastest update option and will vectorise across replicates if the population matrix is not expanded by [environmental_stochasticity](#) or [density_dependence](#).

`update_binomial_leslie` updates abundances with a direct RNG draw that combines update with demographic stochasticity, assuming a Leslie matrix.

`update_multinomial` updates abundances with a direct RNG draw that combines update with demographic stochasticity, allowing for general matrix forms (slower than `update_binomial_leslie`).

Value

a matrix containing population abundances in each stage of a matrix population model. Contains one row for each replicate population trajectory and one column for each population stage

Examples

```
# define a basic population
nstage <- 5
popmat <- matrix(0, nrow = nstage, ncol = nstage)
popmat[reproduction(popmat, dims = 4:5)] <- c(10, 20)
popmat[transition(popmat)] <- c(0.25, 0.3, 0.5, 0.65)

# define a dynamics object
dyn <- dynamics(popmat)

# simulate with the default updater
sims <- simulate(dyn)

# simulate with a multinomial updater
sims <- simulate(dyn, options = list(update = update_multinomial))
```

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