Object Detection Radar System

Abstract

This project implements a cost∎effective 2∎D ultrasonic radar using an Arduino Uno, HC■SR04 sensor and m

Key Components

- Arduino Uno
- HC■SR04 Ultrasonic Sensor
- SG90 Micro■servo
- Processing (PC Software)
- 5■V Power Supply

Working Principle

At each sweep angle the Arduino triggers the ultrasonic module, measures the echo time, converts it to distance

Results & Observations

System successfully detects objects within 4 m with ±1 m accuracy. Sweep rate is 4 m Hz at 1° resolution. Date of the successfully detects objects within 4 m with ±1 m accuracy.

Future Enhancements

- Add multiple sensors for 360° coverage
- Use Bluetooth to make the unit wireless
- Integrate machine
 ■learning to classify obstacle types