



# Electrical and Computer Engineering ECE3712 Electromagnetic Fields and Waves

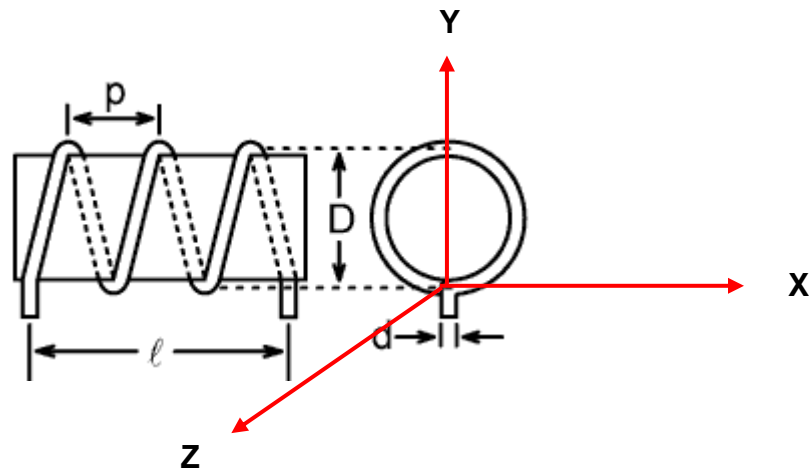


## MATLAB Project on Magnetostatics

Dennis Silage, PhD  
*silage@temple.edu*

A circular cross-section solenoid is often modeled as multiple *rings of current* ignoring the pitch of the actual turns of the current carrying wire. In this Project the circular cross-section solenoid has a pitch  $p$  which is not to be ignored, a length  $\ell$  and a diameter  $D$ , as shown in the Figure. The wire diameter  $d$  can be considered  $\ll D$  and ignored. The number of turns  $N = \ell / p$  and is a whole integer number.

The first turn of the circular cross-section solenoid begins at the origin  $(0, 0, 0)$ , is wound counter-clockwise in the  $-z$  direction ending at  $(0, 0, -\ell)$ , carries a DC current  $I$  and is in air ( $\mu = \mu_0$ ).



Using the discrete summation solution in MATLAB of the integral form of the Biot-Savart Law with discrete DC current carrying lengths  $\Delta L$ , the resulting  $\mathbf{H}$  at an arbitrary point  $P(x,y,z)$  can be determined:

$$\mathbf{H} = \int \frac{I d\mathbf{L} \times \mathbf{a}_R}{4\pi R^2}$$

$$\mathbf{H} = \sum \frac{I \Delta \mathbf{L} \times \mathbf{a}_R}{4\pi R^2}$$

**Task 1:** This Project should use Cartesian coordinates for the general geometrical solution for  $\mathbf{a}_R$  and  $R$  from the location of the discrete current  $I\Delta\mathbf{L}$  to the arbitrary point  $P(x,y,z)$  (see Task 2).

- The general geometrical solution must be carefully determined and discussed in the Project Report.

**Task 2:** The point  $P(x,y,z)$  for the determine the resulting  $\mathbf{H}$  should be entered as a variable for  $x$ ,  $y$  and  $z$  should range from:

$$-D/4 \leq x \leq D/4 \quad -6\ell \leq z \leq 5\ell \quad D/4 \leq y \leq 3D/4$$

Out of range entries should be *flagged*. For the diameter  $D$  and length  $\ell$  use your birth date in cm and birth month in cm with the smaller (or equal) number as  $D$  and the larger (or equal) number as  $\ell$ . For example, June 16<sup>th</sup> means  $D = 6$  cm and  $\ell = 16$  cm.

The number of turns  $N$  is the last two digits of your TU ID modulo 8 + 3. For example, if the last two digits are 66 then  $N = 2 + 3 = 5$ .

Then the pitch  $p = \ell / N$  and, for example, would be  $16 \text{ cm} / 5 = 3.2 \text{ cm}$ .

The current  $I$  is the last three digits of your TU ID modulo 12 + 6 in mA. For example, if  $N = 666$ ,  $I = 6 + 6 = 12 \text{ mA}$ .

- Describe the parameters  $D$ ,  $\ell$ ,  $p$ ,  $N$  and  $I$  in the Project Report.
- Describe the entry and calculation of  $\mathbf{H}$  at an in-range point  $P(x,y,z)$  in the Project Report.

You should use a value for  $\Delta L$  that can approximate the integral formulation for  $\mathbf{H}$  from the discrete summation. To show this, and only as an example, you can compare the  $\Delta L = 0.1$  cm solution to that obtained for  $\Delta L = 0.01$  cm and  $\Delta L = 0.001$  cm for the resultant  $\mathbf{H}$  at an arbitrary point, for example,  $P = (0, D/2, -\ell/2)$  the center of the solenoid.

- Calculate and critically describe of the resultant  $\mathbf{H}$  at an arbitrary point when  $\Delta L$  is varied over at least three orders of magnitude in the Project Report.

Note that your choice of  $\Delta L$  requires an integer number of steps in the discrete summation, so the length of the winding  $L$  should be calculated and discussed in

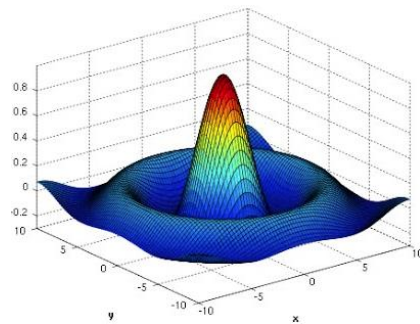
the Project Report. You can also use both a coarser and finer  $\Delta L$  to clearly demonstrate and discuss the *trade-offs* of calculation time versus precision for the discrete summation solution for  $\mathbf{H}$  at an arbitrary point, for example,  $P = (0, D/2, -\ell/2)$  the center of the solenoid.

- The length  $\Delta L$  is an arc of a circle but this complication can be ignored if  $\Delta L$  is small enough. Show this degree of the approximation of the arc length to the straight-line segment in the Project Report for the choices of  $\Delta L$  and the solenoid parameters  $D$ ,  $\ell$ ,  $p$  and  $N$ .

**Task 3:** Plot your results for the resulting  $\mathbf{H}$  in Cartesian coordinates. Plot the results for  $\mathbf{H}$  for:

1.  $x$  as a variable  $-D/4 \leq x \leq D/4$  and fixed  $y = D/2$  and  $z = -\ell/2$
2.  $z$  as a variable  $-6\ell \leq z \leq 5\ell$  and  $y = D/2$  and  $x = 0$

- For these data describe the uniformity (deviation from a constant) of the resultant  $\mathbf{H}$  in the Project Report
- You are required to investigate and utilize methods of plotting 3D data in MATLAB for the resultant  $\mathbf{H}$  in the Project Report, including surface and contour plots, as part of an engineering analysis, see:



<https://www.mathworks.com/help/matlab/examples/creating-3-d-plots.html>

Queries and concerns for your project should be directed to the Instructor in a timely manner *well before* the Project deadline.

This project is to be written using the *Project Report Format* and uploaded to *Canvas* by no later than 11:59 PM Wednesday April 25, 2018. A hard copy is due no later than 3:30 PM Thursday April 26, 2018 in class (the last day of classes).

Late submission will result in a *grade reduction of one-half a letter grade per day*.

This project is an example of the advanced magnetostatic solution for  $\mathbf{H}$  of a practical circular cross-section solenoid with pitch.

