

### Some properties of MLE (without proof)

- MLE may be biased or unbiased
- MLE is consistent estimator.
- If an efficient estimator exists, it is the MLE estimator.

An efficient estimator  $\hat{\theta}$  exists  $\Rightarrow$

$$\frac{\partial}{\partial \theta} L(\mathbf{x} / \theta) = c(\hat{\theta} - \theta)$$

at  $\theta = \hat{\theta}$ ,

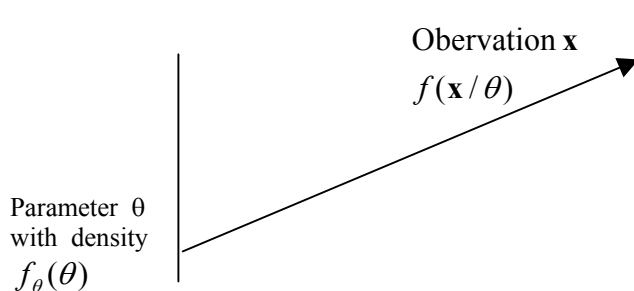
$$\left. \frac{\partial L(\mathbf{x} / \theta)}{\partial \theta} \right|_{\hat{\theta}} = c(\hat{\theta} - \hat{\theta}) = 0$$

$\Rightarrow \hat{\theta}$  is the MLE estimator.

### Bayesian Estimators :

We may have some prior information about  $\theta$  in a sense that some values of  $\theta$  are more likely. (*a priori* information). We can represent this prior information in the form of a prior density function.

In the following we omit the suffix in density functions just for notational simplicity.



The likelihood function will now be the conditional density  $f(\mathbf{x} / \theta)$ .

$$f(\mathbf{x}, \theta) = f(\theta) f(\mathbf{x} | \theta)$$

Also we have the Bayes rule

$$f(\theta | \mathbf{x}) = \frac{f(\theta) f(\mathbf{x} | \theta)}{f(\mathbf{x})}$$

where  $f(\theta | \mathbf{x})$  is the *a posteriori* density function

The parameter  $\theta$  is a random variable and the estimator  $\hat{\theta}(\mathbf{x})$  is another random variable.

Estimation error  $\varepsilon = \hat{\theta} - \theta$ .

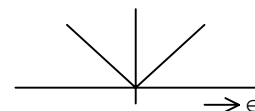
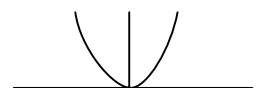
We associate a cost function  $C(\hat{\theta}, \theta)$  with every estimator  $\hat{\theta}$ . It represents positive penalty with each wrong estimation.

Thus  $C(\hat{\theta}, \theta)$  is a non negative function.

The three most popular cost functions are:

Quadratic cost function  $(\hat{\theta} - \theta)^2$

Absolute cost function  $|\hat{\theta} - \theta|$

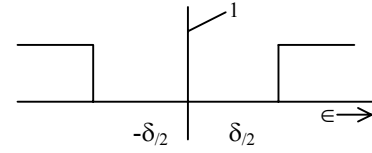


Hit or miss cost function (also called uniform cost function)  
(minimising means minimising on an average)

Bayesian Risk function or average cost

$$\bar{C} = EC(\theta, \hat{\theta}) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} C(\theta, \hat{\theta}) f(\mathbf{x}, \theta) d\mathbf{x} d\theta$$

The estimator seeks to minimize the Bayesian Risk.



Case I. QUADRATIC COST FUNCTION

$$C = (\theta - \hat{\theta})^2$$

Estimation problem is

$$\text{Minimize} \quad \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (\theta - \hat{\theta})^2 f(\mathbf{x}, \theta) d\mathbf{x} d\theta$$

with respect to  $\hat{\theta}$ .

This is equivalent to minimizing

$$\begin{aligned} & \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (\theta - \hat{\theta})^2 f(\theta | \mathbf{x}) f(\mathbf{x}) d\theta d\mathbf{x} \\ &= \int_{-\infty}^{\infty} \left( \int_{-\infty}^{\infty} (\theta - \hat{\theta})^2 f(\theta | \mathbf{x}) d\theta \right) f(\mathbf{x}) d\mathbf{x} \end{aligned}$$

Since  $f(\mathbf{x})$  is always +ve, the above integral will be minimum if the inner integral is minimum. This results in the problem:

$$\text{Minimize} \quad \int_{-\infty}^{\infty} (\theta - \hat{\theta})^2 f(\theta | \mathbf{x}) d\theta$$

with respect to  $\hat{\theta}$ .

$$\Rightarrow \frac{\partial}{\partial \hat{\theta}} \int_{-\infty}^{\infty} (\hat{\theta} - \theta)^2 f(\theta | \mathbf{x}) d\theta = 0$$

$$\Rightarrow -2 \int_{-\infty}^{\infty} (\hat{\theta} - \theta) f(\theta | \mathbf{x}) d\theta = 0$$

$$\Rightarrow \hat{\theta} \int_{-\infty}^{\infty} f(\theta | \mathbf{x}) d\theta = \int_{-\infty}^{\infty} \theta f(\theta | \mathbf{x}) d\theta$$

$$\Rightarrow \hat{\theta} = \int_{-\infty}^{\infty} \theta f(\theta | \mathbf{x}) d\theta$$

$\therefore \hat{\theta}$  is the conditional mean or mean of the a posteriori density. Since we are minimizing quadratic cost it is also called *minimum mean square error estimator* (MMSE).

Salient Points

- Information about distribution of  $\theta$  available.
- *a priori* density function  $f(\mathbf{x} | \theta)$  is available. This denotes how observed data depend on  $\theta$
- We have to determine a posteriori density  $f(\theta | \mathbf{x})$ . This is determined from the

Estimated density of the observed data

$$f(\theta | \mathbf{x}) = \frac{f(\theta)f(\mathbf{x} | \theta)}{f(\mathbf{x})}$$

Case II

HIT OR MISS COST FUNCTION

Risk  $\bar{C} = EC(\theta, \hat{\theta}) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} C(\theta, \hat{\theta}) f(\mathbf{x}, \theta) d\mathbf{x} d\theta$

$$\begin{aligned} &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} c(\theta, \hat{\theta}) f(\theta | \mathbf{x}) f(\mathbf{x}) d\theta d\mathbf{x} \\ &= \int_{-\infty}^{\infty} \left( \int_{-\infty}^{\infty} c(\theta, \hat{\theta}) f(\theta | \mathbf{x}) d\theta \right) f(\mathbf{x}) d\mathbf{x} \end{aligned}$$



We have to minimize

$$\int_{-\infty}^{\infty} C(\theta, \hat{\theta}) f(\theta | \mathbf{x}) d\theta \quad \text{with respect to } \hat{\theta}.$$

This is equivalent to minimizing

$$= 1 - \int_{\hat{\theta} - \frac{\Delta}{2}}^{\hat{\theta} + \frac{\Delta}{2}} f(\theta | \mathbf{x}) d\theta$$

This minimization is equivalent to maximization of

$$\int_{\hat{\theta} - \frac{\Delta}{2}}^{\hat{\theta} + \frac{\Delta}{2}} f(\theta | \mathbf{x}) d\theta \cong \Delta f(\hat{\theta} | \mathbf{x}) \quad \text{when } \Delta \text{ is very small}$$

This will be maximum of  $f(\hat{\theta} | \mathbf{x})$  is maximum. That means select that value of  $\hat{\theta}$  that maximizes the a posteriori density. So this is known as maximum a posteriori estimation (MAP) principle.

This estimator is denoted by  $\hat{\theta}_{MAP}$ .

Example

Let  $X_1, X_2, \dots, X_N$  be an iid Gaussian sequence with unity Variance and unknown mean  $\theta$ . Further  $\theta$  is known to be a 0-mean Gaussian with Unity Variance. Find the MAP estimator for  $\theta$ .

Solution

We are given

$$\begin{aligned} f_{\theta}(\theta) &= \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}\theta^2} \\ f(\mathbf{x} / \theta) &= \frac{1}{(\sqrt{2\pi})^N} e^{-\sum_{i=1}^N \frac{(x_i - \theta)^2}{2}} \end{aligned}$$

There fore  $f(\theta | \mathbf{x}) = \frac{f(\theta)f(\mathbf{x}|\theta)}{f(\mathbf{x})}$

We have to find  $\theta$ , such that  $f(\theta | \mathbf{x})$  is maximum.

Now  $f(\theta | \mathbf{x})$  is maximum when  $f(\theta)f(\mathbf{x}|\theta)$  is maximum.

$\Rightarrow \ln f(\theta)f(\mathbf{x}|\theta)$  is maximum

$\Rightarrow -\frac{1}{2}\theta^2 - \sum_{i=1}^N \frac{(x_i - \theta)^2}{2}$  is maximum

$$\Rightarrow \theta - \sum_{i=1}^N (x_i - \theta) \Big|_{\theta=\hat{\theta}_{MAP}} = 0$$

$$\Rightarrow \hat{\theta}_{MAP} = \frac{1}{N+1} \sum_{i=1}^N x_i$$