Computing Rectification Functions for Finite Field Arithmetic Circuits using Computer Algebra Techniques

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This paper addresses the problem of rectification of faulty finite field arithmetic circuits that require computation of rectification patch functions at multiple nets. Contemporary approaches that utilize SAT solving and Craig interpolation are infeasible in rectifying arithmetic circuits. Our approach employs techniques from polynomial algebra to compute rectification patches. Given a set of m nets as targets for rectification, prior algebra-based techniques can only ascertain whether the targets admit rectification, but cannot compute rectification functions. In this work, we show how the algebraic computing model allows to explore the space of admissible rectification patches, collectively, for the m targets. The model also enables exploitation of don't care conditions across the m targets for synthesis of rectification patches. Experiments conducted over finite field circuits used in cryptography applications demonstrate the efficacy of our approach.

CCS Concepts: • Hardware → Electronic design automation.

1 INTRODUCTION

Debugging and rectification of digital logic circuits aims to correct a given defective implementation (*Impl*) to match its intended specification (*Spec*). The process constitutes identifying candidate nets in the circuit as targets for rectification, followed by a check to determine whether the circuit can be patched at these targets. If the targets admit correction, corresponding rectification functions are computed and synthesized to fix the circuit at these targets. This paper addresses the problem of *multi-fix rectification* (*MFR*) of faulty finite field arithmetic circuits at a given set of *m* targets. Rectification is performed against a given polynomial *Spec* over finite fields. Such circuits find application in cryptography and error-control codes.

Problem Statement and Objective: We are given the following: i) as the Spec, a multivariate polynomial f with coefficients in a finite field of 2^n elements (denoted \mathbb{F}_{2^n}), for a given $n \in \mathbb{Z}_{>0}$; ii) an irreducible polynomial $P_n(x)$ of degree n with coefficients in $\{0,1\}$ used to construct \mathbb{F}_{2^n} ; iii) a faulty Impl circuit C, with no assumptions on the number or the type of bugs present in C; and iv) a set $W = (w_1, \ldots, w_m)$ of m targets from C, pre-specified or selected using contemporary signal selection heuristics [4, 8, 9]. We further assume that it has been ascertained that C admits rectification at these m targets, using [13, 15]. The objective of our approach is to: i) compute a set of individual rectification functions $U = (u_1, \ldots, u_m)$ for the corresponding targets. Here, each u_i is a polynomial function $u_i : \mathbb{F}_2^{|X_{PI}|} \to \mathbb{F}_2$, where $\mathbb{F}_2 = \{0,1\}$, and X_{PI} denotes the set of primary inputs; ii) derive don't care conditions corresponding to the m rectification functions; and iii) synthesize the rectification polynomials into logic sub-circuit patches.

Prior Work: Contemporary approaches formulate rectification using QBF solving [6], using Craig interpolation or iterative SAT solving [15]. The MFR techniques in [8, 15, 16] iteratively and incrementally compute multiple single-fix functions that partially patch the circuit in each iteration. The more recent techniques further include more resource awareness in patch generation by reusing existing logic [4], employ improved heuristics for target selection [8], or resolve a combination of such objectives, such as the symbolic sampling approach of [9]. While successful for control-dominated applications, these techniques are computationally infeasible for rectification of arithmetic circuits.

In the context of arithmetic circuits, Symbolic Computer Algebra (SCA) techniques for integer arithmetic [5, 11] and finite field circuits [7, 12] have been considered for rectification. However, these algebraic approaches address only *single-fix rectification* – where irrespective of the type or number of bugs in the circuit, rectification is attempted at a single net. This is too restrictive and depending on the nature of the bugs, the circuit may not admit single-fix rectification at all. In such cases, correction has to be attempted at multiple targets, i.e. MFR is required. Recently, [13]

proposes an SCA based approach to *decide m-target rectifiability*. Given a set of *m*-targets, their approach can only ascertain whether *there exists* a set of patch functions that can patch the circuit at those targets. As theirs is only a decision procedure, it cannot *compute* rectification functions. Thus the problem of multi-fix rectification of data-path circuits remains unsolved, and theoretical and algorithmic solutions to compute and synthesize rectification patches for arithmetic circuits are still desired.

Approach and Contribution: The Spec and Impl are modeled in terms of polynomial ideals, and the rectification functions are computed using the Gröbner bases of these ideals [1]. We model this computation as a quantification procedure by utilizing concepts from computer algebra and algebraic geometry. In this regard, our approach goes beyond the Nullstellensatz-based results produced from the m-target rectifiability check presented in [13], and computes m individual rectification functions altogether. This allows us to efficiently explore the space of various admissible rectification functions, in turn, computing subsets of don't care conditions which help in simplifying the rectification patches. Synthesis of the corresponding polynomial patch functions, along with don't cares, demonstrates the efficacy of our approach in terms of improved area and delay characteristics of the patches. Overall, the computation of rectification functions at multiple targets, and modeling don't cares for MFR in polynomial algebra, are our novel contributions not presented in prior literature.

Paper Organization: The following section covers preliminary background. Section 2.1 reviews the polynomial modeling concepts. Rectification check formulation is described in Section 3, followed by the rectification function and don't care computations in Section 4. Experimental results are described in Section 5, and Section 6 concludes the paper.

2 PRELIMINARIES

Finite fields: Let $\mathbb B$ denote the Boolean domain, and $\neg, \land, \lor, \oplus$ the NOT, AND, OR and XOR operators, respectively. Let $\mathbb F_2=\{0,1\}$ be the field of 2 elements, and let $\mathbb F_q=\mathbb F_{2^n}$ denote the finite field of $q=2^n$ elements, for a given $n\in\mathbb Z_{>0}$. $\mathbb F_{2^n}$ is the n-dimensional extension of $\mathbb F_2$, and it is constructed as $\mathbb F_{2^n}=\mathbb F_2[x]\pmod{P_n(x)}$. Here $P_n(x)\in\mathbb F_2[x]$ is a given degree-n polynomial, irreducible in $\mathbb F_2$, with a root γ , i.e. $P_n(\gamma)=0$. Thus, $\mathbb F_2\subset\mathbb F_{2^n}, \forall n>1$. All fields of the type $\mathbb F_{2^n}$ have characteristic 2, and therefore -1=+1 in $\mathbb F_{2^n}$.

Polynomial representation: Let $R = \mathbb{F}_q[x_1,\ldots,x_d]$ be the polynomial ring in variables x_1,\ldots,x_d with coefficients in \mathbb{F}_q . A polynomial $f \in R$ is written as a finite sum of terms $f = c_1M_1 + c_2M_2 + \cdots + c_pM_p$, where c_1,\ldots,c_p are coefficients from \mathbb{F}_q and M_1,\ldots,M_p are monomials, i.e. power products of the type $x_1^{e_1} \cdot x_2^{e_2} \cdot \cdots \cdot x_d^{e_d}$, $e_j \in \mathbb{Z}_{\geq 0}$. A monomial order > (term order) is always imposed on R, and subject to >, we have that $M_1 > M_2 > \cdots > M_p$. Then, $lm(f) = M_1$ denotes the leading monomial of f, and $lt(f) = c_1M_1$ the leading term of f.

Polynomial Reduction: Let $F = \{f_1, ..., f_s\}$ be a set of polynomials in R and $f \in R$ be another polynomial. Then $f \xrightarrow{F}_+ r$ denotes the reduction of f modulo the set of polynomials F resulting in a remainder r, obtained by iteratively canceling terms in f by $lt(f_i), f_i \in F$, via polynomial division (cf. Algorithm 1.5.1 [1]).

Ideals and varieties: A given set of polynomials $F = \{f_1, \ldots, f_s\}$ from R, generates the **ideal** $J = \langle F \rangle \subseteq R$, defined as $J = \langle f_1, \ldots, f_s \rangle = \{h_1 \cdot f_1 + \cdots + h_s \cdot f_s \mid h_1, \ldots, h_s \in R\}$. Polynomials f_1, \ldots, f_s form the generators or the basis of ideal I

Let $a=(a_1,\ldots,a_d)\in\mathbb{F}_q^d$ be a point in the affine space, and f a polynomial in R. If f(a)=0, we say that f vanishes on a. In this work, we have to analyze the set of all common zeros of the polynomials of $F=\{f_1,\ldots,f_s\}$ that lie within the field \mathbb{F}_q – i.e. the set of all point $a\in\mathbb{F}_q^d$ such that $f_1(a)=\cdots=f_s(a)=0$. This zero set is called the **variety**, which depends not just on the given set of polynomials in F, but rather on the ideal generated by polynomials. We denote it by V(J), where: $V(J)=V_{\mathbb{F}_q}(J)=V_{\mathbb{F}_q}(f_1,\ldots,f_s)=\{a\in\mathbb{F}_q^d: \forall f\in J, f(a)=0\}.$

An ideal may have many different bases. A *Gröbner basis* (GB) is a basis with special properties that allows to solve many polynomial decision and quantification problems.

DEFINITION 2.1. [Gröbner Basis] [1]: For a monomial ordering >, a set of non-zero polynomials $G = \{g_1, g_2, \dots, g_t\}$ contained in an ideal J, is called a Gröbner Basis (GB) of $J \iff \forall f \in J$, $f \xrightarrow{g_1, \dots, g_t} 0$.

A polynomial f is a member of ideal J iff division of f by GB(J) gives the remainder 0. If $f \notin J$, then division by GB(J), $f \xrightarrow{GB(J)} r$, results in a non-zero remainder r that is unique. A Gröbner basis can be computed using Buchberger's algorithm (cf. Alg. 1.7.1 in [1]). A Gröbner basis can be further reduced. A reduced Gröbner basis (redGB) is canonical representation of the ideal J.

DEFINITION 2.2. [**Reduced Gröbner Basis**]: A redGB for a polynomial ideal J is a GB $G = \{q_1, \ldots, q_t\}$ such that:

- $lc(q_i) = 1, \forall q_i \in G$
- $\forall g_i \in G$, no monomial of g_i lies in $\langle lt(G \{g_i\}) \rangle$

Vanishing Polynomials: For any element $\varphi \in \mathbb{F}_q$, $\varphi^q = \varphi$ holds. Therefore, the polynomial $x^q - x$ vanishes everywhere in \mathbb{F}_q , and we call it a vanishing polynomial. We denote by $F_0 = \{x_1^q - x_1, \dots, x_d^q - x_d\}$ the set of all vanishing polynomials in R, and $J_0 = \langle F_0 \rangle$ denotes the ideal of all vanishing polynomials in R. Then $V_{\mathbb{F}_q}(J_0) = \mathbb{F}_q^d$, and for any ideal J, we have that $V_{\mathbb{F}_q}(J) = V_{\mathbb{F}_q}(J + J_0)$.

Ideal-Variety Correspondences: Given two ideals $J_1 = \langle f_1, \ldots, f_s \rangle$, $J_2 = \langle h_1, \ldots, h_r \rangle$, the **sum of ideals** is denoted as $J_1 + J_2 = \langle f_1, \ldots, f_s, h_1, \ldots, h_r \rangle$, their **product** is given as $J_1 \cdot J_2 = \langle f_i \cdot h_j : 1 \leq i \leq s, 1 \leq j \leq r \rangle$, and a **colon ideal** operation is defined as $J_1 : J_2 = \{f \in R \mid f \cdot g \in J_1, \forall g \in J_2\}$. Ideals and varieties are dual concepts: $V(J_1 + J_2) = V(J_1) \cap V(J_2)$, whereas $V(J_1 \cdot J_2) = V(J_1) \cup V(J_2)$. A colon ideal operation corresponds the set difference of two varieties, $V_{\mathbb{F}_q}(J_1 : J_2) = V_{\mathbb{F}_q}(J_1) \setminus V_{\mathbb{F}_q}(J_2)$. The complement of a variety $V_{\mathbb{F}_q}(J_1)$ denoted $\overline{V_{\mathbb{F}_q}(J_1)}$, can be computed using the colon ideal with vanishing polynomials as: $\overline{V_{\mathbb{F}_q}(J_1)} = \mathbb{F}_q^d \setminus V_{\mathbb{F}_q}(J_1) = V_{\mathbb{F}_q}(J_0) \setminus V_{\mathbb{F}_q}(J_1) = V_{\mathbb{F}_q}(J_0) = V_{\mathbb{F}_q}(J_0)$.

As varieties over finite fields are a finite set of points in \mathbb{F}_q^d , in this work we interpret the desired rectification functions as varieties. Thus, we use the above concepts of intersection, union, and complement of varieties to operate on functions; however, we compute them algebraically using the Gröbner bases of corresponding ideals.

GB computations in \mathbb{F}_q exhibit exponential complexity. For efficient GB computations on polynomials derived from a circuit, [10] proposed the use of a specialized term order that exploits the topology of the circuit. In this term order, the variables (nets of the circuit) are ordered based on a reverse topological traversal of the circuit from POs to PIs. This specific term order '>' is called the *Reverse Topological Term Order (RTTO)*. Our MFR approach also uses RTTO > for polynomial representation and manipulation.

2.1 Modeling Circuits with Polynomial Ideals

A multivariate polynomial f over \mathbb{F}_{2^n} is given as a Spec, where n is the operand word-length (data-path size). A combinational circuit C is given as its (faulty) implementation. The function implemented by C is modeled with a system of polynomials over $R = \mathbb{F}_{2^n}[Z,A,X]$, where $X = \{x_1,\ldots,x_d\}$ corresponds to all the bit-level variables (nets) in the circuit. Let $X_{PO} \subset X$, and $X_{PI} \subset X$ denote the set of all primary output variables, and primary input variables from C, respectively. Further, $Z = \{z_0,\ldots,z_{n-1}\}$ and $A = \{a_0,\ldots,a_{n-1}\}$ represent the output and input operand words of the circuit, respectively, where $z_i \in X_{PO}$ and $a_i \in X_{PI}$. As C comprises Boolean logic gates, the gates are represented by polynomials $\pmod{2}$, i.e. over $\mathbb{F}_2(\subset \mathbb{F}_{2^n})$, using the mapping $\mathbb{B} \mapsto \mathbb{F}_2$:

$$z = \neg a \mapsto z + a + 1; \qquad z = a \land b \mapsto z + a \cdot b;$$

$$z = a \lor b \mapsto z + a + b + a \cdot b; \qquad z = a \oplus b \mapsto z + a + b;$$
(1)

Algebraically, the correspondences between the bit-level and word-level variables of the circuit are represented as:

$$f_1: Z = z_0 + \gamma \cdot z_1 + \dots + \gamma^{n-1} \cdot z_{n-1},$$

$$f_2: A = a_0 + \gamma \cdot a_1 + \dots + \gamma^{n-1} \cdot a_{n-1},$$
(2)

where $P_n(\gamma) = 0$. Since $\mathbb{F}_2 \subset \mathbb{F}_{2^n}$, the polynomials in Eqn. (1) can also be interpreted as polynomials over \mathbb{F}_{2^n} . Thus, the circuit is represented by a set of polynomials $F = \{f_1, \dots, f_s\} \subset R$. Let $J = \langle F \rangle$ be the ideal generated by this set. Let $F_0 = \{x_i^2 - x_i, Y^{2^n} - Y \mid x_i \in \text{bit-level variables}, Y \in \text{word-level variables}\}$ be the set of all vanishing polynomials, and $J_0 = \langle F_0 \rangle$ the corresponding ideal. Then, ideal $J + J_0 = \langle F \cup F_0 \rangle$ models the functionality of $Impl\ C$.

One can verify the correctness of the circuit C by checking if the given Spec is implied by the ideal representing C. In other words, $f \equiv C \iff f \xrightarrow{GB(J+J_0)} + 0$ [10]. In the manuscript, we use the circuit of Fig. 1, which is borrowed from [13], as a running example to demonstrate our algebraic approach for MFR.

Example 2.1. The circuit C in Fig. 1 is a faulty implementation of a 3-bit (n=3) Mastrovito multiplier. The field \mathbb{F}_{2^3} is constructed using $P_3(x) = x^3 + x + 1$ with γ as a root, i.e. $P_3(\gamma) = 0$. The Spec polynomial is $f: Z + A \cdot B$, where Z is the output word, and A, B the input words. Impose RTTO > on the polynomials, i.e. a lex term order on all polynomials with the variables of C ordered reverse topologically from POs to PIs: $\{Z\} > \{A > B\} > \{z_0 > z_1 > z_2\} > \cdots > \{d_1 > d_2 > d_3 > r_0 > d_5 > rr_1\} > \{r_1 > rr_3 > rr_2\} > \{r_2 > r_3 > rr_4\} > \{r_4 > d_4\} > \{a_0 > a_1 > a_2 > b_0 > b_1 > b_2\}.$

Under RTTO >, the following polynomials represent C:

$$\begin{split} f_1: Z + z_0 + \gamma \cdot z_1 + \gamma^2 \cdot z_2; & f_{22}: rr_1 + rr_3 + rr_2; \\ f_2: A + a_0 + \gamma \cdot a_1 + \gamma^2 \cdot a_2; & f_{23}: r_1 + r_2 + r_3; \\ f_3: B + b_0 + \gamma \cdot b_1 + \gamma^2 \cdot b_2; & f_{26}: r_3 + r_4 + d_4; \\ & f_4: z_0 + d_0 + e_1; & f_{27}: rr_3 + rr_4 + b_2; \dots \\ & \dots & f_{30}: rr_4 + a_2 + b_2 + a_2b_2; \end{split}$$

where the polynomials f_{26} , f_{27} correspond to the introduced bugs. Then $F = \{f_1, \ldots, f_{30}\}$, $F_0 = \{a_0^2 - a_0, \ldots, z_2^2 - z_2, A^8 - A, B^8 - B, Z^8 - Z\}$. So, ideal $J + J_0 = \langle F \cup F_0 \rangle$ encapsulates the function implemented by C.

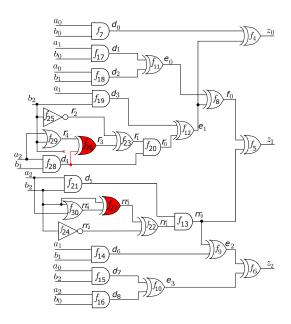


Fig. 1. A faulty Impl of the circuit C: a 3-bit finite field multiplier (n=3) with bugs introduced at net r_3 (AND gate replaced with an XOR gate and one of the inputs mis-connected to d_4 instead of b_2) and net rr_3 (AND gate replaced with an XOR gate).

3 RECTIFICATION CHECK

In [13], the authors presented techniques which utilize the aforementioned polynomial ideal setup to derive the necessary and sufficient conditions for the existence of a multi-fix rectification at the given set of targets. We rephrase and restate Thm. V.1 from [13], and briefly discuss its key aspects. Subsequently, we formulate the computation of rectification functions by utilizing the outcome of their decision procedure.

THEOREM 3.1. [Multi-fix Rectification Theorem] A Spec polynomial f, a faulty Impl C represented using the ideal $J + J_0 = \langle F \cup F_0 \rangle \subset R$, and a set of targets $W = (w_1, ..., w_m) \subset \{X - X_{PI}\}$ are given. RTTO > is imposed on R. Let $W_c = \{(0, 0, ..., 0), ..., (1, 1, ..., 1)\}$, $|W_c| = 2^m$, denote the set of all possible $\{0, 1\}$ assignments to targets W. This is akin to

computing cofactors of the circuit functions with respect to the targets W. Each cofactor tuple $W_c[l]$ serves as one set of assignments to m targets at their respective indexes in W. The following ideals are constructed:

•
$$J_l = \langle F_l \rangle = \langle f_1, \dots, f_{w_1} : w_1 + W_c[l][1], \dots, f_{w_m} : w_m + W_c[l][m], \dots, f_s \rangle, \forall l \in 1, \dots 2^m$$
.

Reduce f by $F_l \cup F_0$ to obtain remainders rem_l : $f \xrightarrow{F_l \cup F_0}_+ rem_l$, for $1 \le l \le 2^m$. Then, the circuit C is rectifiable at the target set W if and only if union of varieties $\bigcup_{l=1}^{2^m} V(rem_l) = \mathbb{F}_2^{|X_{PI}|}$.

The above check for union of varieties can be performed as product of ideals, i.e. by checking if $\prod_{l=1}^{2^m} rem_l \xrightarrow{b} 0$. RTTO > is known to have the property that makes the division $f \xrightarrow{F_l \cup F_0} rem_l$ mimic gate level substitution in polynomial algebra. Thus, after reduction, all non-primary input variables in the circuit are canceled and the final remainder has only X_{PI} variables in its support.

Example 3.1. Continuing on with the Ex. 2.1, we demonstrate the rectification check presented in [13] for $W = (r_3, r_3)$. Constructing the J_1 ideals:

- $J_1 = \langle F_1 \rangle$, where $F_1[f_{26}: r_3 + 0]$, $F_1[f_{27}: rr_3 + 0]$, $(r_3 = 0, rr_3 = 0)$
- $J_2 = \langle F_2 \rangle$, where $F_2[f_{26}: r_3 + 0]$, $F_2[f_{27}: rr_3 + 1]$, $(r_3 = 0, rr_3 = 1)$
- $J_3 = \langle F_3 \rangle$, where $F_3[f_{26}: r_3 + 1]$, $F_3[f_{27}: rr_3 + 0]$, $(r_3 = 1, rr_3 = 0)$
- $J_4 = \langle F_4 \rangle$, where $F_4[f_{26}: r_3 + 1]$, $F_4[f_{27}: rr_3 + 1]$, $(r_3 = 1, rr_3 = 1)$

Reducing the Spec $f: Z + A \cdot B$ modulo these ideals, we get:

- $\begin{array}{l} \bullet \ rem_1 = f \ \dfrac{F_1 \cup F_0}{F_2 \cup F_0} + (\gamma + 1)a_2b_1b_2 + (\gamma^2 + \gamma)a_2b_2 \\ \bullet \ rem_2 = f \ \dfrac{F_2 \cup F_0}{F_3 \cup F_0} + (\gamma + 1)a_2b_1b_2 \\ \bullet \ rem_3 = f \ \dfrac{F_3 \cup F_0}{F_3 \cup F_0} + (\gamma + 1)a_2b_1b_2 + a_2b_1 + (\gamma^2 + \gamma)a_2b_2 \end{array}$

- $rem_4 = f \xrightarrow{F_4 \cup F_0} (\gamma + 1)a_2b_1b_2 + a_2b_1$

When we compute $\prod_{l=1}^{2^m} rem_l \xrightarrow{b}_+$, we obtain remainder 0, thus confirming that the target set $W = (r_3, r_{r_3})$ indeed admits correction.

The concepts presented in [13] are limited to proving the existence of rectification functions. However, our investigation further reveals that their result can be extended to characterize the desired rectification functions. Intuitively, the concept can be elaborated as follows. The variety of rem_l for any l corresponds to the set of all assignments to primary inputs X_{PI} (minterms) where the Spec f agrees with the Impl C. Thus, the condition of Thm. 3.1 implies that the union of individual varieties of rem_l 's comprises the set of all minterms where f and C evaluate the same. Thus, for every primary input assignment, there exists a cofactor tuple assignment $W_c[l]$ to W such that f and C match. Consequently, there exists a set of functions $U = (u_1, \ldots, u_m)$ that can be computed to rectify every error minterm. We exploit and explore this concept to compute rectification functions in the following section. However, as discussed before, their variety $V(rem_l) \subseteq \mathbb{F}_2^{|X_{PI}|}$. We can compute a polynomial $pr_l \in \mathbb{F}_2^{|X_{PI}|}$ such that $V(pr_1) = V(rem_1) [7].$

The authors discuss how rectifiability of C against its Spec at a given set of m-distinct targets $W = (w_1, \ldots, w_m) \subset$ $\{\{X\} - \{X_{PI}\}\}\$ can be ascertained algebraically.

COMPUTING RECTIFICATION FUNCTIONS

For a given set of targets W, due to the presence of don't cares (DC), there may exist more than one set U of rectification functions which will rectify the circuit. In this section, we describe the notion of DC in the MFR setup which can be exploited for the simplification of rectification patches. Exploring all the DC conditions for m targets might be computationally infeasible; we present two different approaches to overcome this. First, we present an approach to compute an on- and off-set for each rectification function by heuristically resolving all the DC conditions. Following this, we present an approach to explore and compute a subset of the DC conditions, along with on- and off-sets, for each rectification function.

Algorithm 1 Rectification of finite field arithmetic circuits

```
Require: Spec: f, buggy Impl: C modeled as a polynomial ideal F = \{f_1 \dots, f_s\} under RTTO >
Assume: C doesn't admit single-fix rectification // [12]
Ensure: Rectification of C to match f
 1: procedure rectification
        remainder = verify(f, F + F_0) // Sec.??
        O_a = analyze(remainder) //Sec. V.1 [12]
        I_n = PotentialNets() //Sec.??
        m = 2; rectified = False; O_A = \emptyset; F_w = \emptyset
 5:
 6:
            O_a^i = uniquePartition(O_a, m)
 7:
            if O_a^i \notin O_A then
 8:
                O_A = O_A \cup O_a^i
 9:
                 \mathcal{M}^i = intersectionCover(O_a^i)
10:
                f_w = pickTargets(\mathcal{M}^i, m)
11:
                if f_w \notin F_w then
12:
                     F_w = F_w \cup f_w
13:
                     MFRSetup() //Sec.??
14:
                     if MFRCheck(F') == 0 then //Sec.3
15:
16:
                         rectified = True
                         patch = rectFunction() //Sec.4
17:
                     else
18:
19:
                         goto 11
                else
20:
                     goto 7
21:
            else
22:
                 m + +
23:
        while ((!rectified) && m \leq |O_a|)
24:
25:
        return patch
```

4.1 Greedy Approach for MFR

To illustrate the greedy approach, consider the case with m=2, where $W_c=\{(0,0),(0,1),(1,0),(1,1)\}$, and we must compute rectification functions u_1 and u_2 . For brevity, let $V_{W_c[i]}=V(rem_i)$, for $1 \le i \le 2^m$; in this case, $V_{(0,0)}=V(rem_1)$, $V_{(0,1)}=V(rem_2)$, and so on.

Recall that $V_{(0,0)}$ comprises the set of points where the Impl and Spec evaluate the same for the corresponding assignments (0,0) to the targets. This implies that at these points, the rectification functions u_1 and u_2 should evaluate to 0. Table 1 shows the required evaluations of u_1 and u_2 for the points in each variety, following the same reasoning. The on-set of the rectification function for a target corresponds to the union of the varieties (sets) where the function evaluates to 1, and the off-set corresponds to the union of the varieties (sets) where the function evaluates to 0. In this case, the on-set of u_1 consists of the set of points in $V_{(1,0)} \cup V_{(1,1)}$, and the off-set of u_1 consists of the set of points in $V_{(0,0)} \cup V_{(0,1)}$. Similarly, the on-set and off-set of u_2 consists of the points in $V_{(0,1)} \cup V_{(1,1)}$ and $V_{(0,0)} \cup V_{(1,0)}$, respectively. The functions u_1 and u_2 could be synthesized using these on- and off-sets.

Table 1. Function evaluations

Variety	u_1	u_2
$V_{(0,0)}$	0	0
$V_{(0,1)}$	0	1
$V_{(1,0)}$	1	0
V _(1,1)	1	1

However, the above argument is only correct when $V_{(0,0)}$, $V_{(0,1)}$, $V_{(1,0)}$, $V_{(1,1)}$ are pairwise disjoint, which may not be true in practice. For example, for a point contained in $V_{(0,0)} \cap V_{(0,1)}$, (u_1, u_2) must evaluate either to (0,0), or to (0,1) in order for the *Impl* to evaluate to the same value as the *Spec*; this point would be in both the on- and off-set of u_2 in

the method previously described. A decision procedure is necessary to determine the evaluation of (u_1, u_2) at these intersections. We present a greedy approach which resolves such ambiguities by imposing an order on the sets. An example of our greedy approach to evaluate (u_1, u_2) for an order $V_{(0,0)} > V_{(0,1)} > V_{(1,0)} > V_{(1,1)}$ is as follows:

First, we place all the points from $V_{(0,0)}$ into the off-sets of (u_1,u_2) . Next, we place all the points from $V_{(0,1)} \setminus V_{(0,0)}$ into the off-set of u_1 and the on-set of u_2 . We perform the set difference to avoid placing the points in $V_{(0,0)} \cap V_{(0,1)}$ into both the on-set and off-set of u_2 . Next, we place all the points from $V_{(1,0)} \setminus (V_{(0,0)} \cup V_{(0,1)})$ into the on-set of u_1 , and the off-set of u_2 . Finally, we place the remaining points from $V_{(1,1)} \setminus (V_{(0,0)} \cup V_{(0,1)} \cup V_{(1,0)})$ into the on-set of (u_1,u_2) . The resulting on- and off-sets for u_1 and u_2 are shown below.

$$\begin{split} &V(u_{1on}) = (V_{(1,1)} \setminus (V_{(0,0)} \cup V_{(0,1)} \cup V_{(1,0)})) \cup (V_{(1,0)} \setminus (V_{(0,0)} \cup V_{(0,1)})) \\ &V(u_{1off}) = (V_{(0,0)}) \cup (V_{(0,1)} \setminus V_{(0,0)}) \\ &V(u_{2on}) = (V_{(0,1)} \setminus V_{(0,0)}) \cup (V_{(1,1)} \setminus (V_{(0,0)} \cup V_{(0,1)} \cup V_{(1,0)})) \\ &V(u_{2off}) = (V_{(0,0)}) \cup (V_{(1,0)} \setminus (V_{(0,0)} \cup V_{(0,1)})) \end{split}$$

This approach with the given order greedily places points into the off-sets of the rectification functions (u_1, u_2) where possible, and only places points into the on-sets of the rectification functions when necessary. Subject to the given order, the on-sets of the rectification functions are thus minimized. For the experiments in this paper, we always use the order $V_{W_c[i]} > V_{W_c[j]}$ for i < j, as in the above example, though any order would yield valid rectification functions.

Generalizing our greedy approach for *m* targets, we first construct the following composite sets (varieties):

$$S_{l} = \begin{cases} V_{W_{c}[1]}, & \text{if } l = 1\\ V_{W_{c}[l]} \setminus (\bigcup_{j=1}^{l-1} V_{W_{c}[j]}), & 2 \le l \le 2^{m} \end{cases}$$
(3)

The resulting on-set and off-set functions for each target i, where $1 \le i \le m$ are:

$$V(u_{i_{on}}) = \bigcup S_l, \ \forall l \mid W_c[l][i] = 1$$

$$V(u_{i_{off}}) = \bigcup S_l, \ \forall l \mid W_c[l][i] = 0$$

$$(4)$$

4.2 Don't Care Conditions for MFR

Let $U_d \subseteq U$ denote a subset of the target rectification functions. We are interested in the DC conditions which arise for these functions at points where they may evaluate to any value, for some fixed evaluation of the remaining functions in the set $\{U \setminus U_d\}$. For example, consider a point in $V_{(0,0)} \cap V_{(0,1)}$ for a circuit with two targets. As discussed previously, u_1 must evaluate to 0 at this point, but $U_d = \{u_2\}$ may evaluate either to 0 or to 1, so this is a DC point for u_2 .

Not every intersection of varieties yields DC points which follow the conditions described above. Consider a point in $V_{(0,0)} \cap V_{(1,1)}$. Here, (u_1, u_2) must evaluate either to (0,0) or to (1,1). If this point were assigned to the DC set of u_2 , for example, the Spec and Impl would only evaluate the same if u_1 evaluated to the same value as u_2 . Thus, u_1 would become a function of u_2 at this point. This point cannot be placed into the on-set, off-set, or DC-set of u_1 before u_2 is evaluated. To avoid inter-dependencies between the rectification functions, we do not classify points in such intersections as DC points. We rely on our greedy heuristic to evaluate these points.

Finally, consider a point in $V_{(0,0)} \cap V_{(0,1)} \cap V_{(1,0)}$. This point cannot be a DC point for both targets simultaneously since the evaluation (1,1) here will result in an incorrect rectification function. However, because $V_{(0,0)} \cap V_{(0,1)} \cap V_{(1,0)} \subset V_{(0,0)} \cap V_{(0,1)}$, we could treat this point as a DC point for u_2 and evaluate u_1 to 0. Alternatively, because $V_{(0,0)} \cap V_{(0,1)} \cap V_{(0,1)} \subset V_{(0,0)} \cap V_{(1,0)}$, we could treat this point as a DC point for u_1 and evaluate u_2 to 0. Thus, we have a choice to place this point in the DC-set of either targets, but not both.

Finding every intersection containing DC points for every target can be very expensive for circuits with more than a few targets. We therefore propose an approach to compute a subset of the DC points by considering only the set of pairwise intersections of varieties which contain DC points for exactly one target, denoted as DC_{pair} .

Table 2. Time is in seconds; I = Benchmark Index, n = Datapath Size, m = target word size, AM = Maximum resident memory utilization in Mega Bytes (Average across benchmarks), $\#G = \text{Number of gates} \times 10^3$, #BO = Number of faulty outputs, #BS = Required time for PolyBori setup (ring declaration/poly collection/spec collection), #BO = Required time for verification, #BO = Mumber of faulty outputs, #BS = Required time for PolyBori setup (ring declaration/poly collection/spec collection), #BO = Required time for verification, #BO = Required time for function computation using the greedy approach, #BO = Required time for function computation with don't cares

Mastrovito							Montgomery						Point Addition								
I	n	m	AM	#G	#BO	PBS	RC	GFC	DFC	#G	#BO	PBS	RC	GFC	DFC	#G	#BO	PBS	RC	GFC	DFC
1	16	5	100	0.8	6	0.05	0.01	1.7	4.7	0.9	16	0.05	0.44	190	277*	0.9	7	0.07	0.02	6.6	20
2	32	5	120	2.8	8	0.14	0.02	2	8	2.8	32	0.16	0.1	114	180*	2.9	13	0.2	0.06	36	85*
3	64	3	160	11.2	5	0.61	3.59	5	15	9.6	47	0.53	0.14	7	14	10.6	64	0.8	0.18	10	35
4	96	2	240	24.5	5	1.45	0.12	0.4	0.7	21	96	1.35	3.14	87	111*	24.8	96	2.53	0.5	7.7	90
5	128	2	370	43.2	5	3.23	0.24	0.8	1.2	35.8	128	2.92	2.06	28	393*	43.2	128	6.42	4.38	49	62*
6	163	5	550	69.8	6	6.21	0.4	4.4	7.7	57.5	128	5.38	1.53	131	220*	71.6	22	15.9	1.53	3.2	8
7	233	2	750	119	3	12.7	0.66	0.3	1.7	112	233	12.6	2.69	6	40	122	233	19.7	1.44	6.4	32
8	409	2	2400	384	2	190	2.22	0.3	9	340	409	136	6.15	2.7	5.2	368	409	224	5.3	7.7	8*
9	571	2	5000	827	5	2143	5.96	0.3	26	663	427	1386	49	1.6	30	813	5	2492	13.2	1.2	20

Let $d(W_c[j], W_c[k])$ denote the Hamming distance between the cofactor tuples $W_c[j]$ and $W_c[k]$. We compute the set of varieties which contain DC points for one target, denoted DC_{pair} , from the equation below, where $1 \le j, k \le 2^m$.

$$DC_{pair} = \{V_{W_c[j]} \cap V_{W_c[k]} \mid d(W_c[j], W_c[k]) = 1\}$$
(5)

Since the Hamming distance d = 1 between the cofactor tuples $W_c[j]$ and $W_c[k]$ for each intersection of varieties in DC_{pair} , exactly one rectification function may evaluate either to 0 or to 1. The remaining rectification functions require fixed evaluations of 1 or 0. Therefore, each intersection of varieties in DC_{pair} yields DC points for exactly one rectification function in U, and either on- or off-set points for the remaining rectification functions in U. We use DC_{pair} to compute the DC points for each rectification function, as described in the next section.

4.2.1 Computing Rectification Functions with Don't Cares. Once the set DC_{pair} has been found, a few steps remain to compute the on-, off-, and don't-care sets for each target. First, we follow an approach identical to the greedy approach to evaluate points not located inside DC_{pair} . We construct new composite sets S_l^d for $1 \le l \le 2^m$, which are identical to the composite sets (varieties) created for the previous approach, except that all the points from DC_{pair} set are removed.

$$S_{l}^{d} = \begin{cases} V_{W_{c}[1]} \setminus DC_{pair}, & \text{if } l = 1\\ V_{W_{c}[l]} \setminus ((\bigcup_{j=1}^{l} V_{W_{c}[j]}) \cup DC_{pair}), & 2 \le l \le 2^{m} \end{cases}$$

$$(6)$$

Points in these composite sets are assigned to the on- and off-set for each rectification function in the same way as Eqn. (4), substituting S_l with S_l^d .

Next, we must evaluate points within DC_{pair} as on-, off-, or DC points for each rectification function. We select the first pairwise intersection of varieties in DC_{pair} and assign the points according to the cofactor tuples, as described previously. Since the intersections within DC_{pair} may not be disjoint, we then take the next pairwise intersection, remove the points from the first intersection which have already been assigned, then assign these points according to the cofactor tuples. We continue this for each subsequent intersection of varieties from DC_{pair} , remembering to remove all previously assigned points at each step.

For example, for a circuit with two targets, $DC_{pair} = \{V_{(0,0)} \cap V_{(0,1)}, V_{(0,0)} \cap V_{(1,0)}, V_{(0,1)} \cap V_{(1,1)}, V_{(1,0)} \cap V_{(1,1)}\}$. We place the points in $V_{(0,0)} \cap V_{(0,1)}$ into the off-set of u_1 and the DC set of u_2 . We then place the points in $V_{(0,0)} \cap V_{(0,1)} \cap V_{(0,0)} \cap$

4.3 Synthesizing Rectification Functions

The above techniques show how to construct a rectification function by reasoning about the varieties of rem_l . However, algebraically, we compute these functions using their corresponding ideals. Specifically, we show how the remainders computed in Thm. 3.1 can be utilized for rectification function computation. Even though the remainders rem_l have

coefficients in \mathbb{F}_{2^n} (higher field), their varieties are in $\mathbb{F}_2^{|X_{PI}|}$ as they correspond to bit-level assignments to X_{PI} . However, in [7], it was shown that it is a property of such ideals ($\langle rem_l, J_0 \rangle$) that their reduced Gröbner bases (Def. 2.2) have coefficients only in \mathbb{F}_2 . Further, it was shown that, given an ideal I with coefficients in \mathbb{F}_2 with generators $\{g_1, \ldots, g_t\}$, a polynomial p can always be constructed as $p = (1 + g_1)(1 + g_2) \dots (1 + g_t) + 1$, such that V(p) = V(I). Consequently, the rectification function operations are restricted to algebraic computations in $\mathbb{F}_2[X_{PI}] \equiv \mathbb{B}$.

To compute the patch u_i , we perform the following steps:

- Compute reduced Gröbner bases of $\langle rem_l, J_0 \rangle$.
- Construct a singleton polynomial p such that $V(p) = V(\langle rem_l, J_0 \rangle)$.
- Impose an order on the sets for DC_{pair} and composite set computations.
- Compute DC_{pair} using Eqn. (5), and then obtain the composite sets in Eqn. (6) which are then assigned to DC-, on- and off-sets of the rectification functions (Sec. 4.2).
- In order to perform the variety union, intersection, and difference operations, we use ideal product, sum, and colon operations, respectively, on the singleton polynomial *p* representation of the ideal.
- The above procedure delivers $u_{i_{DC}}$ and $u_{i_{on}}$ as singleton polynomials in $\mathbb{F}_2[X_{PI}]$. Translate $u_{i_{DC}}$ and $u_{i_{on}}$ into Boolean functions by interpreting the product, sum, and '+1' as Boolean AND, XOR, and INV gates, respectively. Optimize the on-set $u_{i_{on}}$ w.r.t. to the DC-set $u_{i_{DC}}$.

Example 4.1. Continuing with Ex. 3.1:

- $rem_3 = (\gamma + 1)a_2b_1b_2 + a_2b_1 + (\gamma^2 + \gamma)a_2b_2$
- $redGB(\langle rem_3, J_0 \rangle) = \{a_2b_1, a_2b_2\}$
- $p_{rem_3} = (1 + a_2b_1) * (1 + a_2b_2) + 1 = a_2b_1b_2 + a_2b_1 + a_2b_2$ - $Here, V(p_{rem_3}) = V(\langle rem_3, J_0 \rangle)$
- Similarly, polynomials p_{rem_l} for each rem_l can be computed.

The rectification polynomials for the targets (r_3, r_{r_3}) computed using the greedy approach (Sec. 4.1)

$$\begin{array}{ll} u_{1on} = a_2b_1b_2; & u_{1off} = a_2b_1b_2 + 1; & r_3 = u_{1patch} = (a_2 \wedge b_1 \wedge b_2); \\ u_{2on} = a_2b_2; & u_{2off} = a_2b_2 + 1; & rr_3 = u_{2patch} = (a_2 \wedge b_2). \end{array}$$

The rectification polynomials for the targets (r_3, rr_3) computed using the on-set and don't care simplification (Sec. 4.2.1)

$$u_{1_{dc}} = a_2b_1b_2 + a_2b_2;$$
 $u_{1_{on}} = a_2b_1b_2;$ $r_3 = u_{1_{patch}} = a_2 \wedge b_2;$ $u_{2_{dc}} = a_2b_2 + 1;$ $u_{2_{on}} = a_2b_2;$ $rr_3 = u_{2_{patch}} = 1.$

5 EXPERIMENTAL RESULTS

The benchmark suit includes two modular multipliers (Mastrovito and Montgomery), and a circuit that performs Point Addition over NIST standard Elliptic curves. These benchmarks are taken from [10] and synthesized using the *abc* tool with a gate library comprising two input gates. Table 2 presents the results of our approach when performing MFR against their respective polynomial specifications. We introduce bugs by means of gate and wiring modifications in the synthesized netlists such that multiple output bits are affected in the design (column #BO). We introduce multiple such modifications at various topological levels: some closer to PIs, some in the middle of the circuit, and some near POs. In our experiments, the number of targets is chosen from $m = \{2, 3, 5\}$. Our approach isn't limited by this set m and can perform MFR for any given number of targets.

Our approach is implemented as a custom software in Python programming language. We use PolyBori's [3] ZDD based API to implement the division, $f \xrightarrow{F_l' \cup F_0'} rem_l$, $1 \le l \le 2^m$. Subsequently, the remainders generated from these divisions are utilized in the decision procedure, as well as the function computations. Further, we use sis [14] and abc [2] to perform logic optimization and synthesis. Specifically, in sis we run a script to perform kernel extraction and full simplify to optimize the rectification functions computed in Sec.4.2. We use abc to perform structural simplify simp

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and extract the synthesis results for *area* and *delay*. The experiments are performed on a 3.5GHz Intel(R) Core TM i7-4770K Quad-Core CPU with 32 GB RAM.

Table 2 presents the characteristics of the benchmark suit and the execution time for the computations using our approach. Column PBS denotes the time taken to build the respective ZDD models (commensurates with the operand word-length n). Execution time for rectification check (RC) and function computation (GFC and DFC) depend on various factors such as: i) the number of bugs; ii) the number of targets; iii) location of the bugs; iv) location of the targets; v) the number of affected outputs; and vi) size of the patch function being computed in terms of number of gates. Collectively, these factors decide the size of the remainder rem_l , and the number of remainders l. We omit the comparison with the contemporary approaches as they fail (timeout = 3 hrs) to rectify circuits beyond 16-bits, which is the smallest benchmark from our results table.

Table 3 presents the synthesis results post *abc* mapping for GFC and DFC approaches in terms of area (number of gates) and the longest topological delay. The asterisk (*) in the DFC columns denotes the cases where *full simplify* (*sis*) fails to utilize the pairwise intersection don't care network for the on-set function simplification. In these cases, *sis* aborts simplification as the BDD size exceeds 480,000 nodes. For these entries, the patch functions are synthesized using *abc* which ignores the don't care network. The time taken for GFC is less than the time taken for DFC computations. However, synthesis results computed using DFC where *sis* completed simplification successfully are of better quality than the one computed using GFC for most of the cases.

6 CONCLUSION

This paper presents an automated symbolic computer algebra approach to perform MFR of faulty finite field arithmetic circuits at a given set of targets. Our approach reasons about the rectification functions by means of algebraic varieties in finite fields, and computes these functions using Gröbner bases of ideals corresponding to the circuit. We present two MFR approaches, a heuristic which greedily tries to resolve the rectification functions for the targets, and a variety intersection heuristic that explores a subset of don't cares condition for the target functions. Our approach is able to compute rectification functions for circuits with large (NIST-standard) operand widths n. As part of future work, we are working on function computation in terms of internal nets. Further, we are also investigating the extension of this approach to integer arithmetic circuits.

Table 3. Synthesis results for mapped patch network; I = Benchmark Index, GFC = Greedy function computation, DFC = Function computation
with don't cares, $A = $ Area in terms of number of gates , $D =$ Longest delay

		Mastı	ovito]	Mont	gomery		Point Addition				
	GFC		DFC		GFC		DFC)	GFC		DFC		
Ι	A	D	A	D	A D		A	D	A	D	A	D	
1	19	3	17	3	27788	50	27941*	62*	761	40	265	12	
2	34	5	35	4	19340	65	19384*	57*	8882	69	9063*	60*	
3	1675	29	1577	46	1511	30	560 18		3040	32	3733	41	
4	86	11	21	5	55085	50	55568*	52*	6642	89	6193	70	
5	283	21	103	12	25819	44	26744*	35*	27544	36	27289*	35*	
6	222	17	99	7	27035	68	27409*	61*	66	8	39	7	
7	9	4	9	4	8094	25	4948	28	4345	30	5169	34	
8	16	4	11	4	844	13	4	2	2707	24	2611*	23*	
9	21	7	18	6	299	19	287	19	622	22	210	16	

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